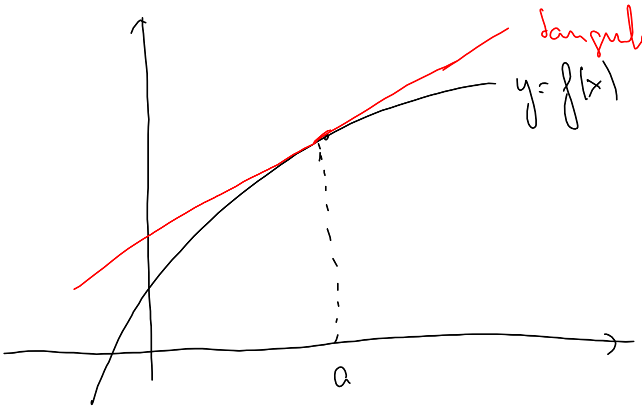
Affinavbildning

$\vec{F}: \mathbb{R}^n \to \mathbb{R}^m \; : \; \vec{F}(\vec{x}) = A\vec{x} + \vec{c}$ $\vec{y} = A\vec{x} + \vec{c}$

matrise

$y = ax + c$ linjer.



$$y = f'(a)(x-a) + f(a)$$

$$\vec{y} = \vec{F}'(\vec{a})(\vec{x}-\vec{a}) + \vec{F}(\vec{a})$$

$$= \underbrace{\vec{F}'(\vec{a})}_{A}\vec{x} + \underbrace{\vec{F}(\vec{a}) - \vec{F}'(\vec{a})\vec{a}}_{C}$$

Definisjon: Anta at $\vec{F}: \mathbb{R}^n \to \mathbb{R}^m$ er deriverbar i punktet $\vec{a}$. Da kalles

$$T_{\vec{a}}\vec{F} = \vec{F}'(\vec{a})(\vec{x}-\vec{a}) + \vec{F}(\vec{a})$$

lineariseringen til $\vec{F}$ i punktet $\vec{a}$.

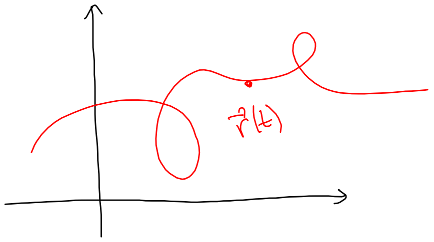
Setning: Anta at $\vec{F}: \mathbb{R}^n \to \mathbb{R}^m$ er deriverbar i punktet $\vec{a}$. Da finnes det én entydig affinavbildning $\vec{G}: \mathbb{R}^n \to \mathbb{R}^m$ slik at

$$\lim_{|\vec{r}| \to 0} \frac{\vec{F}(\vec{a}+\vec{r}) - \vec{G}(\vec{a}+\vec{r})}{|\vec{r}|} = 0$$

og det er lineariseringen $\vec{G} = T_{\vec{a}}\vec{F}$.

Moral: $\vec{G}$ er nesten lik $\vec{F}$ i nærheten av $\vec{a}$.

Parametriserte kurver

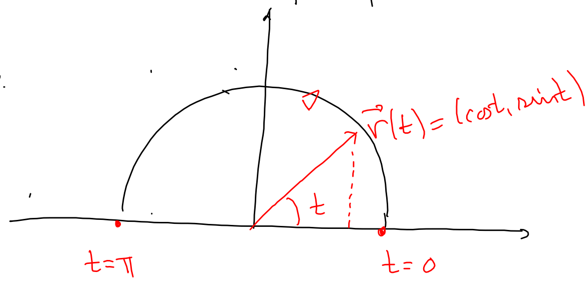


Definisjon: En parametrisert kurve i $\mathbb{R}^n$ er en kontinuerlig funksjon $\vec r : I \to \mathbb{R}$ der $I \subseteq \mathbb{R}$ er et intervall.

Parametriserte kurver kalles også vektorvaluerte funksjoner.

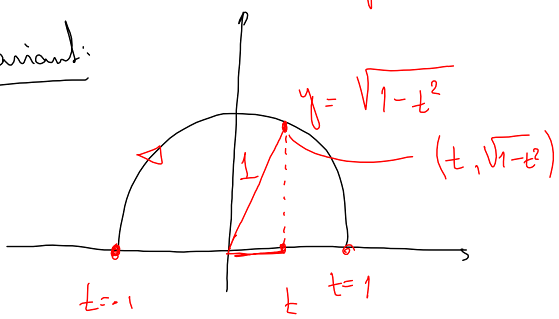
F.eks: $I = (a,b)$
$I = [a,b]$
$I = [a,\infty)$
$I = (-\infty,\infty)$

Eks:



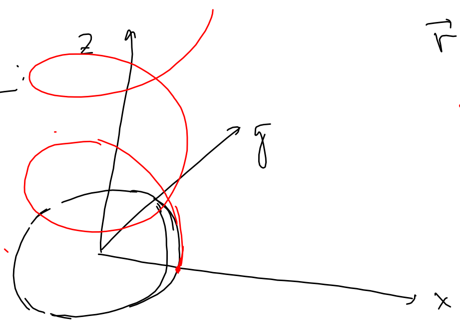
$\vec r(t) = \cos t\,\vec i + \sin t\,\vec j = (\cos t, \sin t)$, $I = [0,\pi]$

Variant:



$\vec r(t) = t\,\vec i + \sqrt{1-t^2}\,\vec j$
$= (t, \sqrt{1-t^2})$, $I = [-1,1]$

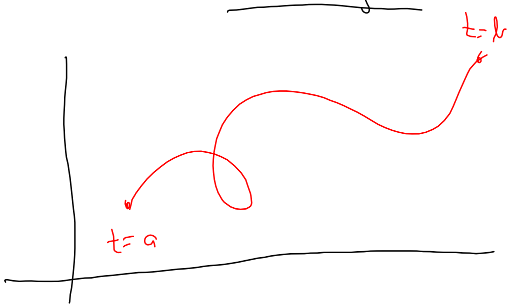
Eksempel:



$\vec r(t) = \cos t\,\vec i + \sin t\,\vec j + t\,\vec k$

Spiral:

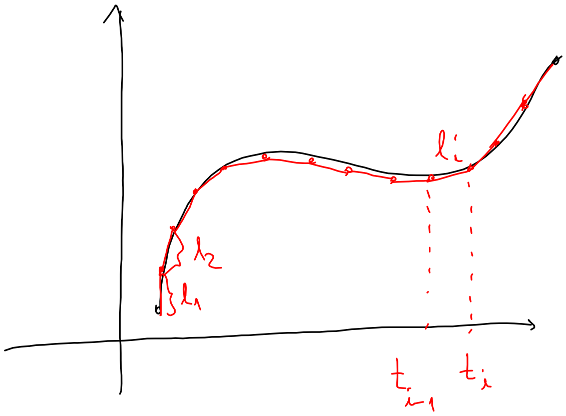
Buelengde



$\vec r(t) = (x_1(t), x_2(t), \dots, x_n(t))$

Hvor lang er kurven?

$$L(a,b) = \int_a^b \sqrt{x_1'(t)^2 + x_2'(t)^2 + \dots + x_n'(t)^2}\,dt$$



Lengden til den buede kurven:

$$l_1+l_2+\dots+l_n=\sum_{i=1}^{n} l_i$$

$$l_i = |\vec r(t_i)-\vec r(t_{i-1})|$$

$$= \sqrt{(x_1(t_i)-x_1(t_{i-1}))^2+\dots+(x_n(t_i)-x_n(t_{i-1}))^2}$$

$$= \sqrt{\underbrace{\left(\frac{x_1(t_i)-x_1(t_{i-1})}{t_i-t_{i-1}}\right)^2}_{\approx\, x_1'(t_{i-1})^2}+\dots+\underbrace{\left(\frac{x_n(t_i)-x_n(t_{i-1})}{t_i-t_{i-1}}\right)^2}_{\approx\, x_n'(t_{i-1})^2}}\,(t_i-t_{i-1})$$

$$\approx \sqrt{x_1'(t_{i-1})^2+x_2'(t_{i-1})^2+\dots+x_n'(t_{i-1})^2}\,(t_i-t_{i-1})$$

Hele lengden: $L(a,b)\approx \sum_{i=1}^{n} l_i = \sum_{i=1}^{n}\underbrace{\sqrt{x_1'(t_{i-1})^2+x_2'(t_{i-1})^2+\dots+x_n'(t_{i-1})^2}\,(t_i-t_{i-1})}$

(Riemannsum til funksjonen $\sqrt{x_1'(t)^2+x_2'(t)^2+\dots+x_n'(t)^2}$)

$$\longrightarrow \int_a^b \sqrt{x_1'(t)^2+x_2'(t)^2+\dots+x_n'(t)^2}\,dt$$

Definisjon: Anta at $\vec r(t)=(x_1(t),\dots,x_n(t))$, $t\in[a,b]$, er en parametrisert kurve der $x_1',\dots,x_n'$ er kontinuerlige. Da er buelengden av kurven definert ved

$$L(a,b)=\int_a^b \sqrt{x_1'(t)^2+x_2'(t)^2+\dots+x_n'(t)^2}\,dt.$$

Eksempel: Finn buelengden til

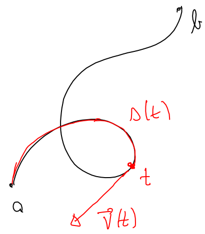
$$\vec{r}(t) = \cos t\,\vec{i} + \sin t\,\vec{j} + t\vec{k} = (\cos t, \sin t, t), \quad t \in [0, 2\pi]$$

$$L(0,2\pi) = \int_0^{2\pi} \sqrt{x'(t)^2 + y'(t)^2 + z'(t)^2}\,dt = \int_0^{2\pi} \sqrt{\underbrace{(-\sin t)^2 + (\cos t)^2}_{1} + 1^2}\,dt$$

$$= \int_0^{2\pi} \sqrt{2}\,dt = 2\pi\sqrt{2} = \underline{\underline{2\sqrt{2}\,\pi}}$$

Fart: Anta at t står for tid og la

$$s(t) = \int_a^t \sqrt{x_1'(s)^2 + x_2'(s)^2 + \dots + x_n'(s)^2}\,ds$$

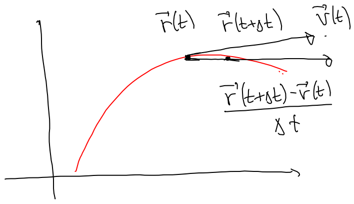


(strekningen ved tiden t).

Farten $v(t)$ er den deriverte av $s(t)$:

$$v(t) = s'(t) = \sqrt{x_1'(t)^2 + x_2'(t)^2 + \dots + x_n'(t)^2}$$

Hastighet er fart med retning:



$$\lim_{\Delta t \to 0} \frac{\vec{r}(t+\Delta t) - \vec{r}(t)}{\Delta t} = \underbrace{\vec{v}(t)}_{\text{hastighet}}$$

Definisjonen: Anta at $\vec{r}(t) = (x_1(t), x_2(t), \dots, x_n(t))$ er en parametrisert kurve der $x_1, x_2, \dots, x_n$ er deriverbar. Da er den deriverte $\vec{r}\,'(t)$ definert ved

$$\vec{r}\,'(t) = \lim_{\Delta t \to 0} \frac{\vec{r}(t+\Delta t) - \vec{r}(t)}{\Delta t} = \lim_{\Delta t \to 0} \left(\frac{x_1(t+\Delta t) - x_1(t)}{\Delta t}, \dots, \frac{x_n(t+\Delta t) - x_n(t)}{\Delta t} \right)$$

$$= (x_1'(t), x_2'(t), \dots, x_n'(t))$$

Dersom t står for tid og $\vec{r}(t)$ står for posisjon kaller vi $\vec{r}\,'(t)$ for hastighet og skriver også $\vec{v}(t) = \vec{r}\,'(t)$

↑ velocity.

Sammenheng mellom fart og hastigheten:

$$\vec{v}(t) = (x_1'(t), x_2'(t), \dots, x_n'(t))$$

$$|\vec{v}(t)| = \sqrt{x_1'(t)^2 + x_2'(t)^2 + \dots + x_n'(t)^2} = v(t)$$

Regneregler for derivasjon: $\vec{r}(t)$ og $\vec{s}(t)$ er to deriverbare funksjoner:

(i) $(\vec{r}(t) + \vec{s}(t))' = \vec{r}\,'(t) + \vec{s}\,'(t)$

(ii) $(\vec{r}(t) - \vec{s}(t))' = \vec{r}\,'(t) - \vec{s}\,'(t)$

(iii) $(c(t)\vec{r}(t))' = c'(t)\vec{r}(t) + c(t)\vec{r}\,'(t)$

(iv) $(\vec{r}(t) \cdot \vec{s}(t))' = \vec{r}\,'(t) \cdot \vec{s}(t) + \vec{r}(t) \cdot \vec{s}\,'(t)$

(v) $(\vec{r}(t) \times \vec{s}(t))' = \vec{r}\,'(t) \times \vec{s}(t) + \vec{r}(t) \times \vec{s}\,'(t)$ i $\mathbb{R}^3$.

Onsdag: Forelesn. 3.1 - 3.2 - 3.3 + MATLAB