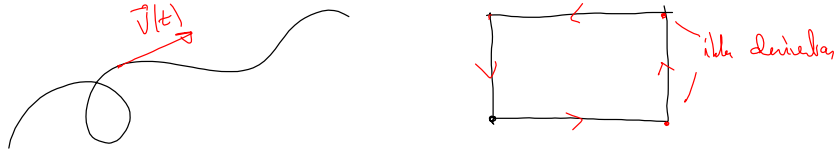


Kurve

$\vec{r}: [a, b] \rightarrow \mathbb{R}^n$ kontinuert, $\vec{r}'(t)$

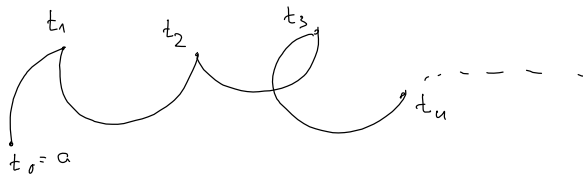
Definition: En parametriseret kurve $\vec{r}: [a, b] \rightarrow \mathbb{R}^n$ kaldes glatt dersom den derivable $\vec{r}'(t)$ eksisterer for alle $t \in (a, b)$ og er kontinuert på dette intervallet.



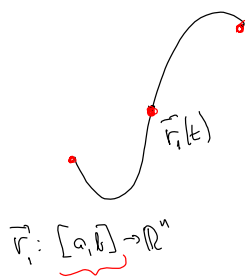
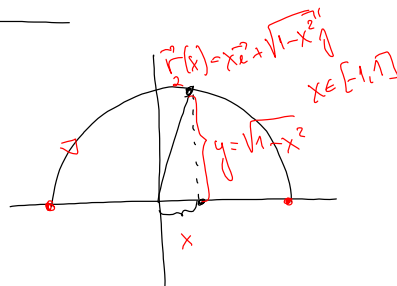
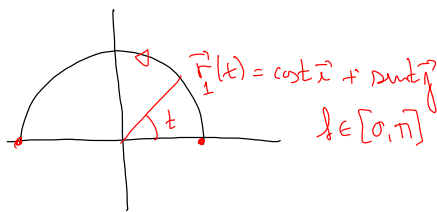
Definition: En parametriseret kurve $\vec{r}: [a, b] \rightarrow \mathbb{R}^n$ kaldes stykkevis glatt dersom den er kontinuert og det findes en opdeling

$$a = t_0 < t_1 < t_2 < \dots < t_m = b$$

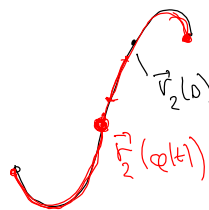
sv $[a, b]$ slik at $\vec{r}: [t_{i-1}, t_i] \rightarrow \mathbb{R}^n$ er en glatt kurve.



Når er to kurver geometrisk ligo?



$\vec{r}_1: [a, b] \rightarrow \mathbb{R}^n$



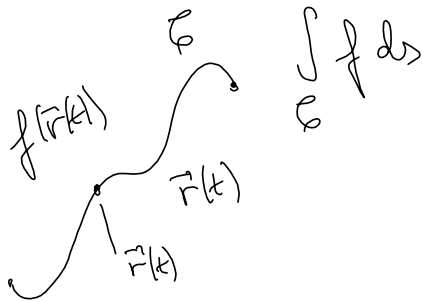
$\vec{r}_2: [c, d] \rightarrow \mathbb{R}^n$

Definition: To parametriserede kurver $\vec{r}_1: [a, b] \rightarrow \mathbb{R}^n$ og $\vec{r}_2: [c, d] \rightarrow \mathbb{R}^n$ kaldes stykkevis ligo dersom, det findes en funktion

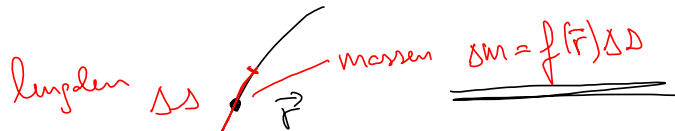
$\phi: [a, b] \rightarrow [c, d]$ slik at

- (i) $\vec{r}_1(t) = \vec{r}_2(\phi(t))$ for alle $t \in [a, b]$.
- (ii) ϕ er strengt monoton og $\phi([a, b]) = [c, d]$
- (iii) ϕ er derivabel i alle punkter $t \in (a, b)$ og $\phi'(t) \neq 0$.

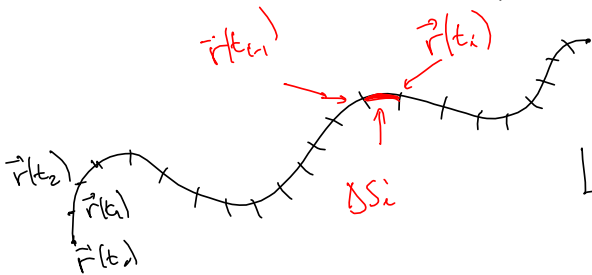
Linjearintegraler for skalarfunktioner



Tenk et kornen er en båd med varierende hastighed og et i skål søge ud den totale masse.



$$a = t_0 < t_1 < t_2 < \dots < t_n = b$$



$$m_i = f(r(t_{i-1})) \Delta s_i$$

$$L(a, t) = \int_a^t \underbrace{\sqrt{x_1^2 + \dots + x_n^2}}_{v(s)} ds = \int_a^t v(s) ds$$

$$\Delta s_i = L(a, t_i) - L(a, t_{i-1}) = \int_{t_{i-1}}^{t_i} v(s) ds \approx v(t_{i-1})(t_i - t_{i-1})$$

$$m_i \approx f(r(t_{i-1})) v(t_{i-1})(t_i - t_{i-1})$$

Total masse: $M = \sum m_i \approx \sum f(r(t_{i-1})) v(t_{i-1})(t_i - t_{i-1})$

Riemannsum $f(r(t)) v(t)$

$$\rightarrow \int_a^b f(r(t)) v(t) dt$$

Definitionen: Antag at $\vec{r}: [a, b] \rightarrow \mathbb{R}^n$ er en stykkevis glat kurve og at $f: \mathbb{R}^n \rightarrow \mathbb{R}$ er en kontinuert funktion. De definerer linjeintegral $\int_C f ds$ ved

$$\int_C f ds = \int_a^b f(\vec{r}(t)) v(t) dt$$

Hvad er C?: Fordi de to kurver \vec{r}_1 og \vec{r}_2 er to forskellige men ekvivalente parametriseringer, så

$$\int_a^b f(\vec{r}_1(t)) v_1(t) dt = \int_c^d f(\vec{r}_2(t)) v_2(t) dt$$

Eksempel: Lad $\vec{r}(t) = t\vec{x} + t^2\vec{y}$, $t \in [0, 1]$, $f(x, y) = xy$
 $\vec{v}(t) = \vec{r}'(t) = \vec{x} + 2t\vec{y}$, $v(t) = |\vec{v}(t)| = \sqrt{1^2 + (2t)^2} = \sqrt{1+4t^2}$

$$\begin{aligned} \int_C f ds &= \int_0^1 f(\vec{r}(t)) v(t) dt = \int_0^1 t \cdot t^2 \sqrt{1+4t^2} dt = \int_0^1 t^3 \sqrt{1+4t^2} dt \\ &= \int_1^5 t^2 \sqrt{u} \frac{1}{8} du = \int_1^5 \frac{u-1}{4} \sqrt{u} \frac{1}{8} du \\ &= \frac{1}{32} \int_1^5 (u^{3/2} - u^{1/2}) du = \dots \end{aligned}$$

$$\begin{aligned} u &= 1+4t^2 \\ du &= 8t dt \\ \frac{1}{8} du &= t dt \\ t^2 &= \frac{u-1}{4} \end{aligned}$$

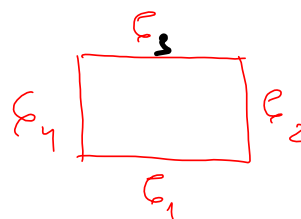
Regne-regler: (i) $\int_C a f ds = a \int_C f ds$

(ii) $\int_C (f+g) ds = \int_C f ds + \int_C g ds$

(iii) $\int_C (f-g) ds = \int_C f ds - \int_C g ds$

(iv) $\int_C f ds = \int_{C_1} f ds + \int_{C_2} f ds + \dots + \int_{C_n} f ds.$

$\int_C f ds = \int_{C_1} f ds + \dots$



Theorem: Dersom \vec{r}_1 og \vec{r}_2 er to skivklare parametriseringer, så er

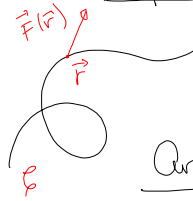
$$\int_{C_1} f ds = \int_{C_2} f ds$$

↑
parametrisert
med \vec{r}_1

↑
parametrisert
med \vec{r}_2

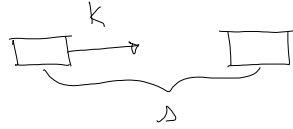
"Bare kurven teller,
ikke parametriseringen"

Prinzipiell for velbrukt.



$$\int_C \vec{F} \cdot d\vec{r}$$

Arbeid = kraft x vei

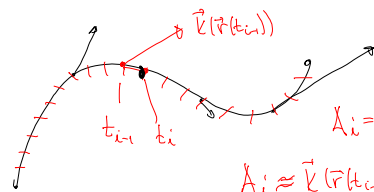


$$A = K \cdot D$$



$$A = K \cos \alpha \cdot D$$

$$A = |\vec{K}| |\vec{D}| \cos \alpha = \vec{K} \cdot \vec{D}$$



$$A_i = \vec{K}(\vec{r}(t_{i+1})) \cdot (\vec{r}(t_i) - \vec{r}(t_{i+1}))$$


$$A_i \approx \vec{K}(\vec{r}(t_{i+1})) \cdot \vec{r}'(t_{i+1}) (t_i - t_{i+1})$$

Totall arbeid: $A = \sum A_i = \sum \underbrace{\vec{K}(\vec{r}(t_{i+1})) \cdot \vec{r}'(t_{i+1})}_{\text{Riemannsum}} (t_i - t_{i+1})$

$$\rightarrow \int_a^b \vec{K}(\vec{r}(t)) \cdot \vec{r}'(t) dt$$

Definisjon: Anta at $\vec{r}: [a, b] \rightarrow \mathbb{R}^n$ er en stykkevis glatt kurve og at $\vec{F}: \mathbb{R}^n \rightarrow \mathbb{R}^n$ er kontinuert. Da er linjeintegral $\int_C \vec{F} \cdot d\vec{r}$ definert ved

$$\int_C \vec{F} \cdot d\vec{r} = \int_a^b \vec{F}(\vec{r}(t)) \cdot \vec{r}'(t) dt = \int_a^b \vec{F}(\vec{r}(t)) \cdot \vec{v}(t) dt$$

Eksempel: $\vec{r}(t) = \underbrace{\cos t}_{x(t)} \vec{i} + \underbrace{\sin t}_{y(t)} \vec{j}, t \in [0, \pi]$ 

$$\vec{F}(x, y) = -y \vec{i} + xy \vec{j}$$

$$\vec{v}(t) = \vec{r}'(t) = -\sin t \vec{i} + \cos t \vec{j}$$

$$\int_C \vec{F} \cdot d\vec{r} = \int_a^b (-\sin t \vec{i} + \cos t \sin t \vec{j}) \cdot (-\sin t \vec{i} + \cos t \vec{j})$$

$$= \int_a^b [\sin^2 t + \underbrace{\cos^2 t \sin t}_{u = \cos t}] dt = \dots$$