Modeling and simulation of multicellular and multiscale systems using the cellular Potts model Alvaro Köhn-Luque

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Department of Biostatistics Oslo Centre for Biostatistics and Epidemiology Faculty of Medicine University of Oslo

Monday 6 Nov 10:15 - 12:00, **Lecture**: Modelling multicellular systems using the cellular Potts model.

Tuesday 3 Nov (FV414) 10:15 - 12:00, **Hands-on 1**: Getting started with the software Morpheus. 12:15 - 14:00, **Hands-on 2**: Simulation and analysis of simple models.

1] James A Glazier and Francois Graner. Simulation of the differential adhesion driven rearrangement of biological cells. Physical Review E, 47(3):2128, 1993. [2] Francois Graner and James A Glazier. Simulation of biological cell sort- ing using a two-dimensional extended potts model. Physical review letters, 69(13):2013, 1992.

Modeling and simulation of multicellular and multiscale systems using the cellular Potts model Joachim Mossige

endrejm@uio.no Twitter: @eJoeFlow

Department of Physics University of Oslo v402

Monday 6 Nov

10:15 - 12:00, Lecture: Modelling multicellular systems using the cellular Potts model.

Tuesday 9 Nov (FV414)

10:15 - 12:00, **Hands-on 1**: Getting started with the software Morpheus. 12:15 - 14:00, **Hands-on 2**: Simulation and analysis of simple models.

What is morphogenesis?

Wikipedia: From Greek morphê (shape) and genesis (creation), literally "the generation of form".

Biological process that causes a cell, tissue, organ or organism to develop its shape.

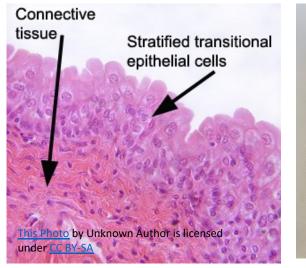
Morphogenesis is the study of how living things develop.

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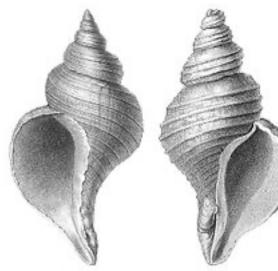
Biological process that causes a cell, tissue, organ or organism to develop its shape.

Morphogenesis is the study of how living things develop.



Tissue: epithelial







Organ: kidney

Gastropod shell

Organism: unicellular (e.g. bacteria) or multicellular (e.g. a dog)

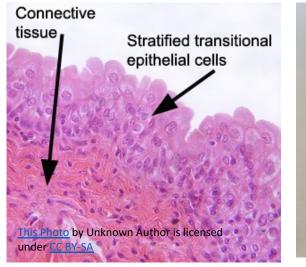
Discuss: How do these tissues, organs, organisms develop into these forms?

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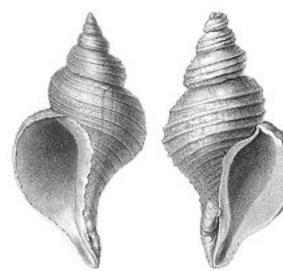
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Tissue: epithelial







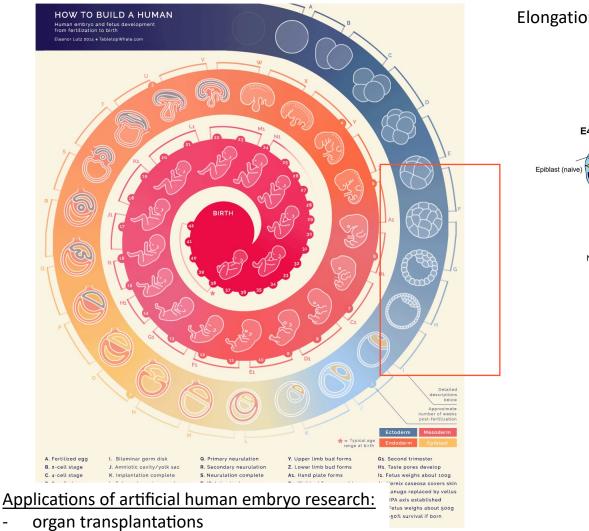
Organ: kidney

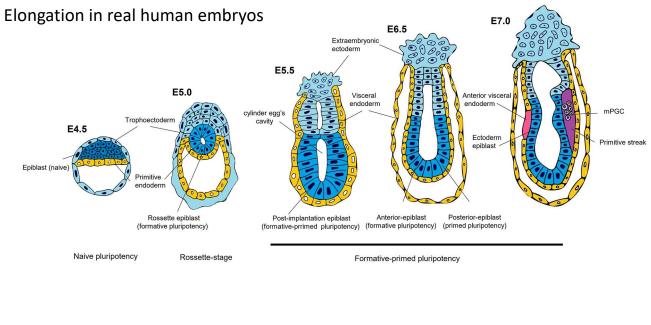
Gastropod shell

Organism: unicellular (e.g. bacteria) or multicellular (e.g. a dog)

Discuss: How do these tissues, organs, organisms develop into these forms? Cell division, apoptosis (programmed cell death), differentiation (specialization), collective <u>cell migration</u>

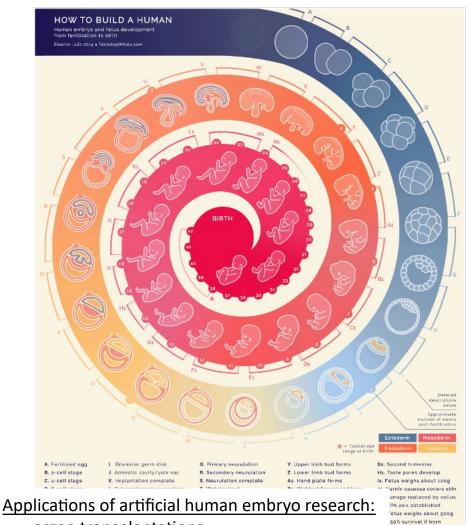
Morphogenesis: How do human embryos develop



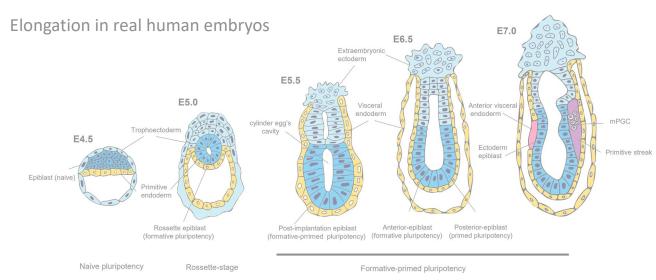


- drug screening (also: toxins)
- understand early embryonic development

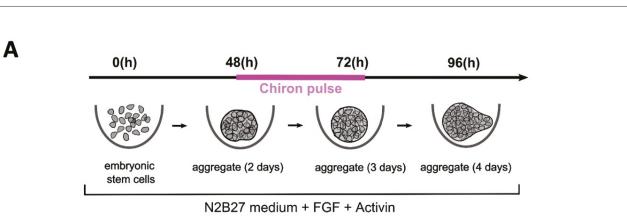
We can even grow (artificial)human embryos in the lab (from stem cells)

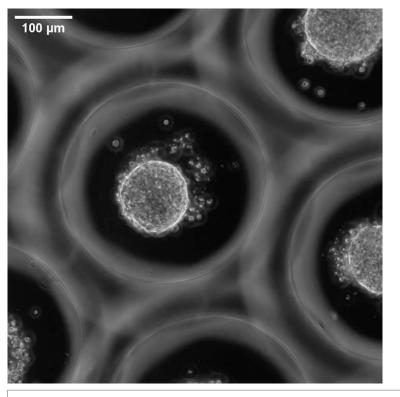


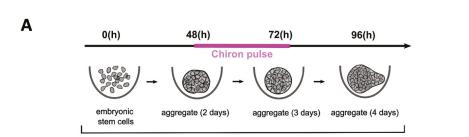
- organ transplantations
- drug screening (also: toxins)
- understand early embryonic development



Elongation in artificial human embryos

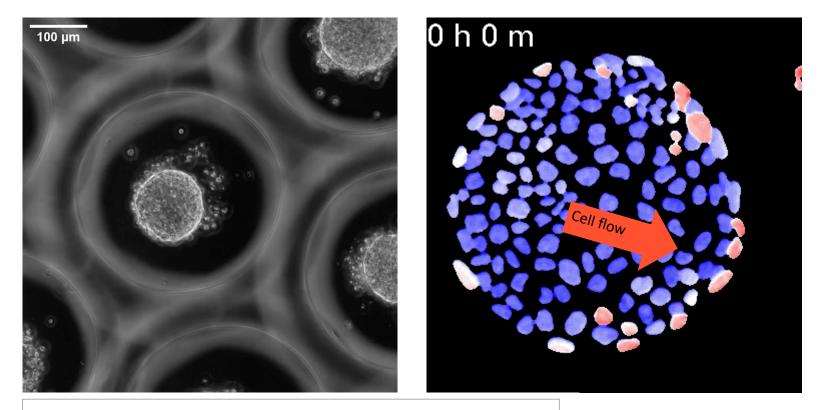


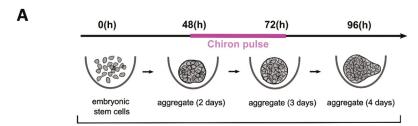




N2B27 medium + FGF + Activin

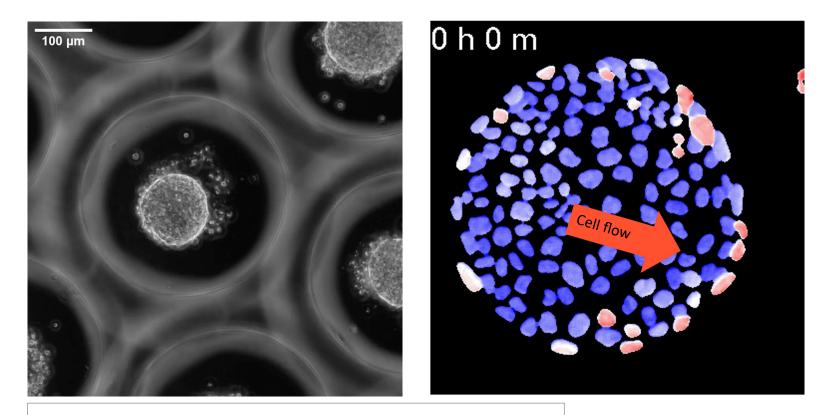
Hashmi, A., Tlili, S., Perrin, P., Lowndes, M., Peradziryi, H., Brickman, J. M., ... & Lenne, P. F. (2022). Cell-state transitions and collective cell movement generate an endoderm-like region in gastruloids. Elife, 11, e59371.

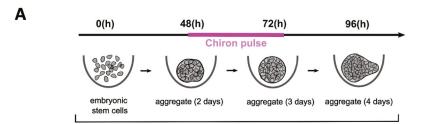




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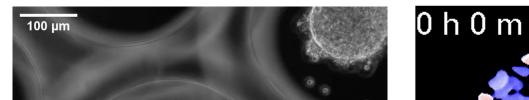


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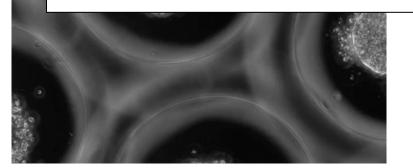


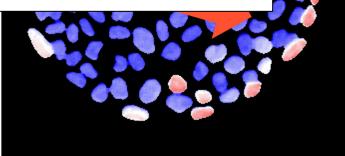
Collective motion flow in nature: Herds of sheep

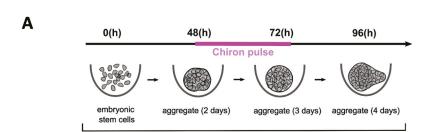


Limitations of current knowledge:

- Measurements are 2d, while embryos are highly 3d
- Animal embryos (mice etc.) do not represent human embryos





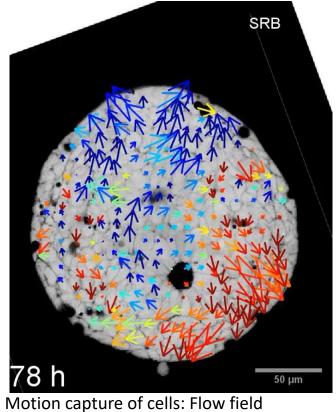


N2B27 medium + FGF + Activin

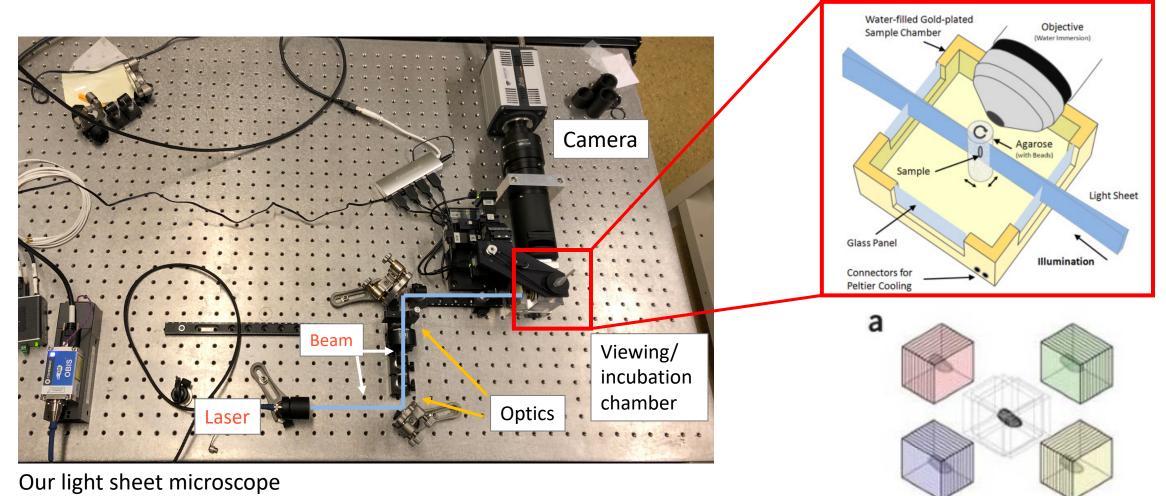
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Collective motion flow in nature: Herds of sheep

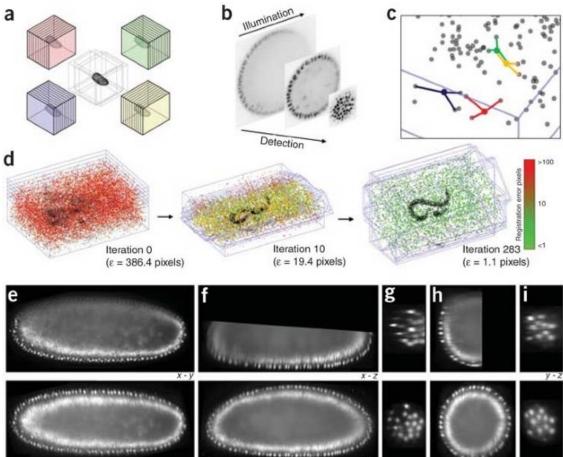


We built a light sheet microscope to visualize 3d motion of cells and how embryos grow



Top image from openspim.org. Bottom image: Preibisch, S., Saalfeld, S., Schindelin, J., & Tomancak, P. (2010). Software for bead-based registration of selective plane illumination microscopy data. Nature methods, 7(6), 418-419.

We built a light sheet microscope to visualize 3d motion of cells and how embryos develop



Visualization of fruit fly embryo development

Agarose Sample Glass Panel Illumination Connectors for Peltier Cooling а

Water-filled Gold-plated

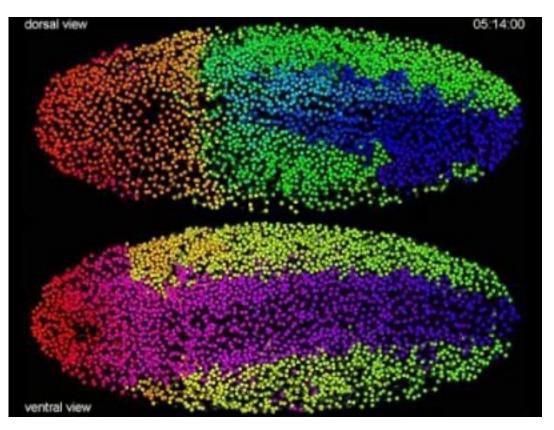
Sample Chamber

Objective

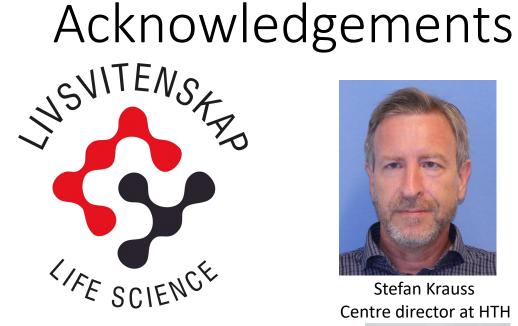
Light Sheet

Preibisch, S., Saalfeld, S., Schindelin, J., & Tomancak, P. (2010). Software for bead-based registration of selective plane illumination microscopy data. *Nature methods*, 7(6), 418-419.

What SPIM can do: Fruit fly (Drosophila) embryogenesis



"Digital fruit fly embryo" obtained with light-sheet microscopy Source: <u>https://www.youtube.com/watch?v=QU4YXD9GxFo</u> Credit: Kristin Branson, Fernando Amat, Bill Lemon and Philipp Keller (HHMI/Janelia)





Kayoko Shoji, postdoc at HTH



Stefan Krauss Centre director at HTH



Håkon Høgset, postdoc at HTH



Dag K. Dysthe, Dept. Phys



Luiza Agheluta-Bauer, Dept. Phys

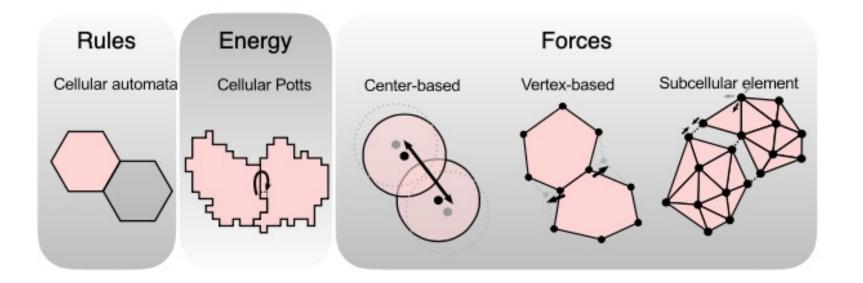


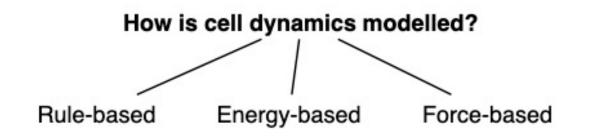
Alexander R. Jensenius Centre director at RITMO



Dongho Kwak, buddy and soon-to-be PhD at RITMO

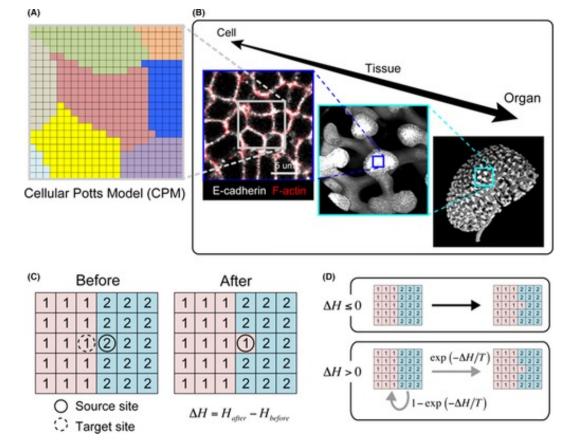
Different cell-based modeling approaches





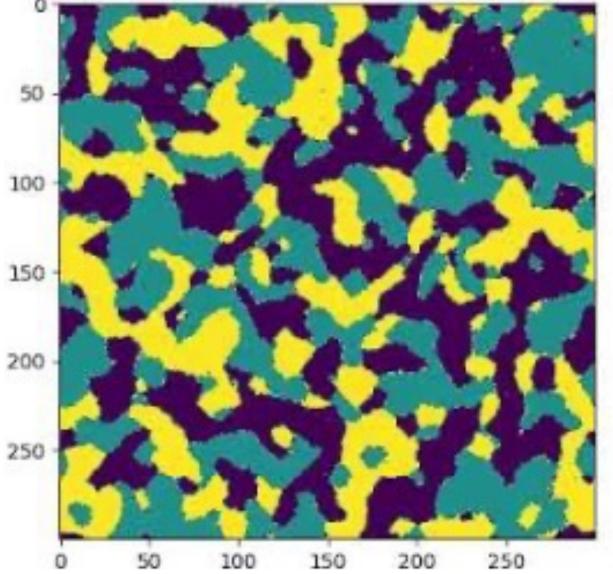
Cellular Potts Model (CPM): Capabilities

- Energy based: Physically sound
 - Minimizes the energy of each cell in each time step
 - Interaction with cell surroundings
 - other cells, ECM, or substrate
 - Volume changes:
 - Cell growth or shrinkage (apoptosis)
- Easy to implement
 - We will use Morpheus (no coding)
- Capabilities:
 - Cell sorting (Computer lab exercise)
 - Pattern formation
 - Tumor growth (Computer lab exercise)
 - Morphogenesis
 - Wound healing
 - Model response to a chemical gradient
 - Model response to forces



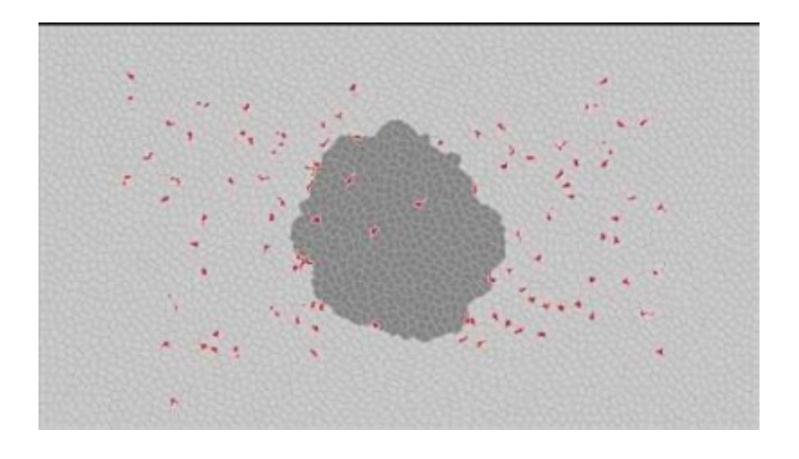
Hirashima, T., Rens, E. G., & Merks, R. M. (2017). Cellular Potts modeling of complex multicellular behaviors in tissue morphogenesis. Development, growth & differentiation, 59(5), 329-339.

What CPM can do: Cell sorting



What CPM can do: Tumor growth

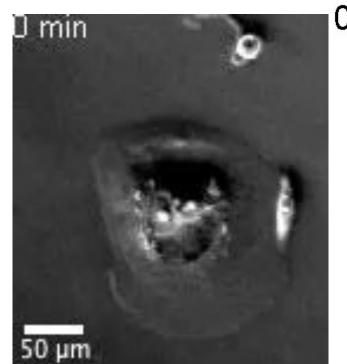
- Growing tumor (dark grey) in stromal tissue (light grey)
- T cells (red) are infiltrating the growing tumor.
- Note: tumor cell division is accelerated in this simulation for visualization purposes and occurs much faster than in a realistic setting.



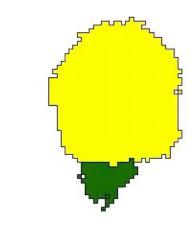
Niculescu, I., Textor, J., & De Boer, R. J. (2015). Crawling and gliding: a computational model for shape-driven cell migration. *PLoS computational biology*, *11*(10), e1004280. Source code: <u>https://github.com/ingewortel/artistoo</u>

What CPM can do: Study how senescent cells* affects the movement of active cells

- *Cells that stop growing and successively expands
- Combining experiments with simulations
- Finding: The adhesion between normal (MDA-MB-231) cells and senescent cells is much weaker than the adhesion between normal cells.
- The distance traveled by normal cells along senescent cells is much longer than the distance traveled along other normal cells.
- Proposed explanation: Expansion of the senescent cell membrane could decrease the number of cell adhesion molecules per area.



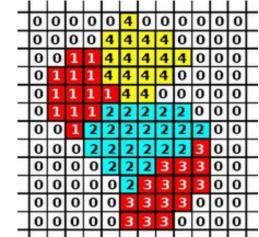
0 min



Gabuardi, T. L., Lee, H. G., & Lee, K. J. (2022). Role of senescent cells in the motile behavior of active, non-senescent cells in confluent populations. Scientific reports, 12(1), 3857.

Cellular Potts Model (CPM): How it works ③

- Cells (or groups of cells) are represented as deformable objects on a lattice
- Each cell occupies one lattice site or several sites
- The energy *H* of a cell results from adhesion with neighbors
 - Adhesion with different cell types (1,2,3,4)
 - Adhesion with ECM or medium (0)
- + the resistance to volume changes



During CPM simulation, the energy function H is minimized in each time stepped in CPM. From Wikipe

$$H = \sum_{i,j \text{ neighbors}} J\left(au(\sigma_i), au(\sigma_j)
ight) \left(1 - \delta(\sigma_i, \sigma_j)
ight) + \lambda \sum_{\sigma_i} \left(v(\sigma_i) - V(\sigma_i)
ight)^2,$$

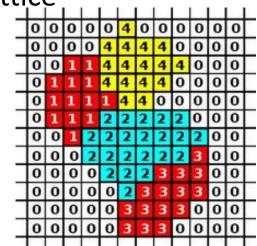
Adhesion with neighbors (surface energy)

 $\overline{\sigma_i}$ Resistance to volume changes (Volume energy)

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 - Adhesion with different cell types (1,2,3,4)
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- + the resistance to volume changes (neglect in this lecture)



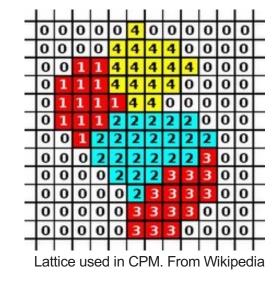
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$$H = \sum_{i,j \text{ neighbors}} J\left(\tau(\sigma_i), \tau(\sigma_j)\right) \left(1 - \delta(\sigma_i, \sigma_j)\right) + \lambda \sum_{\sigma_i} \frac{\left(v(\sigma_i) - V(\sigma_i)\right)^2}{\left(v(\sigma_i) - V(\sigma_i)\right)^2},$$
Adhesion with neighbors (surface energy) (volume energy) neglecting volumetric changes in this lecture

Hirashima, T., Rens, E. G., & Merks, R. M. (2017). Cellular Potts modeling of complex multicellular behaviors in tissue morphogenesis. Development, growth & differentiation, 59(5), 329-339.

Energy function: What the terms mean

- Cell index: σ
- Cell type: $\tau(\sigma)$
- Surface energy between a randomly picked cell and a neighbor: *J*
- lattice sites: *i*, *j*



$$H = \sum_{i,j \text{ neighbors}} J\left(\tau(\sigma_i), \tau(\sigma_j)\right) \left(1 - \delta(\sigma_i, \sigma_j)\right) + \lambda \sum_{\substack{\sigma_i \\ \text{Resistance to volume changes} \\ (\text{surface energy})} \left(\frac{1 - \delta(\sigma_i, \sigma_j)}{1 - \delta(\sigma_i, \sigma_j)}\right) + \lambda \sum_{\substack{\sigma_i \\ \text{Resistance to volume changes} \\ \text{neglecting volume changes}}\right)$$

neglecting volumetric changes in this lecture

 $H = \sum_{i,j \text{ neighbors}} J(\tau(\sigma_i), \tau(\sigma_j)) (1 - \delta(\sigma_i, \sigma_j)) + \lambda \sum_{\sigma_i \text{ Resistance to volume changes}} (v(\sigma_i) - V(\sigma_i))^2,$ Adhesion with neighbors
CPM algorithm: What is the probability that a cell

moves from one lattice site to the next?

1. Choose a random (source) site, $i \bigcirc$

•
$$\tau = 2$$

(C	(c) Before							After						
	1	1	1	2	2	2		1	1	1	2	2		
	1	1	1	2	2	2		1	1	1	2	2		
	1	1	(1)	2	2	2		1	1	1	1	2		
	1	1	1	2	2	2		1	1	1	2	2		
	1	1	1	2	2	2		1	1	1	2	2		
		_	Sou			۵	H =	H _a	fter –	H				

222

before

 $H = \sum_{i,j \text{ neighbors}} J\left(\tau(\sigma_i), \tau(\sigma_j)\right) \left(1 - \delta(\sigma_i, \sigma_j)\right) + \lambda \sum_{\sigma_i} \left(v(\sigma_i) - V(\sigma_i)\right)^2,$ Adhesion with neighbors $\sigma_i \text{ Resistance to volume changes}$

2

before

CPM algorithm: What is the probability that a cell moves from one lattice site to the next?

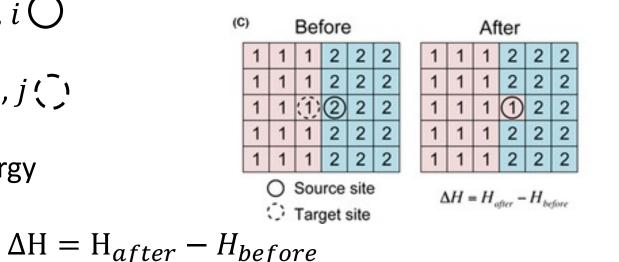
- 1. Choose a random (source) site, $i \bigcirc$
 - $\tau = 2$
- 2. Choose a neighbor (target) site, $j \bigcirc j$
 - $\tau = 1$

(0	3)		Bet	fore	9				Af	ter	
	1	1	1	2	2	2	1	1	1	2	2
	1	1	1	2	2	2	1	1	1	2	2
	1	1	(1)	2	2	2	1	1	1	1	2
	1	1	1	2	2	2	1	1	1	2	2
	1	1	1	2	2	2	1	1	1	2	2
		-	Sou		L	∆ <i>H</i> =	= H _c	fter –	Н		

 $H = \sum_{i,j \text{ neighbors}} J\left(\tau(\sigma_i), \tau(\sigma_j)\right) \left(1 - \delta(\sigma_i, \sigma_j)\right) + \lambda \sum_{\sigma_i} \left(v(\sigma_i) - V(\sigma_i)\right)^2,$ Adhesion with neighbors

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- 2. Choose a neighbor (target) site, $j \bigcirc j$
 - $\tau = 1$
- 3. Calculate the difference in energy



associated with copying the target site index (with index 1) onto the source site (with index 2)

 $H = \sum_{i,j \text{ neighbors}} J\left(\tau(\sigma_i), \tau(\sigma_j)\right) \left(1 - \delta(\sigma_i, \sigma_j)\right) + \lambda \sum_{\sigma_i} \left(v(\sigma_i) - V(\sigma_i)\right)^2,$ Adhesion with neighbors

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(C)	^(c) Before								Af	ter		
1	1	1	2	2	2		1	1	1	2	2	2
1	1	1	2	2	2		1	1	1	2	2	2
1	1	(1)	2	2	2		1	1	1	1	2	2
1	1	1	2	2	2		1	1	1	2	2	2
1	1	1	2	2	2		1	1	1	2	2	2
	00	Sou			•		۵	H =	= H _a	fter –	H	fore
J												

$$\Delta H = H_{after} - H_{before}$$

associated with copying the target site index (with index 1) onto the source site (with index 2)

If the energy cost is negative or zero, $\Delta H \leq 0$: always accept the copy

Hirashima, T., Rens, E. G., & Merks, R. M. (2017). Cellular Potts modeling of complex multicellular behaviors in tissue morphogenesis. Development, growth & differentiation, 59(5), 329-339.

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(C)		Be	fore	9	After									
1	1	1	2	2	2		1	1	1	2	2	2		
1	1	1	2	2	2		1	1	1	2	2	2		
1	1	(1)	2	2	2		1	1	1	1	2	2		
1	1	1	2	2	2		1	1	1	2	2	2		
1	1	1	2	2	2		1	1	1	2	2	2		
	00	Sou			•		۵	H =	= H	fter –	H_{ba}	fore		
I														

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associated with copying the target site index (with index 1) onto the source site (with index 2)

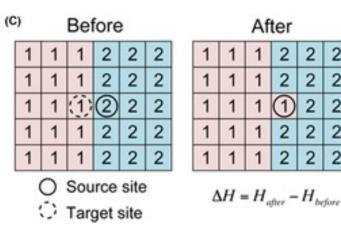
If the energy cost is negative or zero, $\Delta H \leq 0$: always accept the copy If the energy cost positive, $\Delta H > 0$: accept the copy with probability P (ΔH ,T) = $e^{-\Delta H/T}$

Energy minimization function

Hirashima, T., Rens, E. G., & Merks, R. M. (2017). Cellular Potts modeling of complex multicellular behaviors in tissue morphogenesis. Development, growth & differentiation, 59(5), 329-339.

$H = \sum_{i,j \text{ neighbors}} J\left(\tau(\sigma_i), \tau(\sigma_j)\right) \left(1 - \delta(\sigma_i, \sigma_j)\right) + \lambda \sum_{\substack{\sigma_i \\ \text{Resistance to volume changes}}} \left(v(\sigma_i) - V(\sigma_i)\right)^2,$ Exercise! What's the probability that this copy attempt is accepted? What is ΔH ? (c) Before After

- 1. Choose a random (source) site, $i \bigcirc$
 - $\tau = 2$
- 2. Choose a neighbor (target) site, *j* ()
 - $\tau = 1$
- 3. Calculate the difference in energy



$$= H_{after} - H_{before}$$
• cell type 1 and 2 is 2α , i.e. $J(\tau_1, \tau_2) = J(\tau_1, \tau_2) = 2\alpha$
• cell type 1 with itself is α , i.e. $J(\tau_1, \tau_1) = \alpha$
• cell type 2 with itself is α i.e. $J(\tau_1, \tau_1) = \alpha$

associated with copying the target site index (with index 1) onto the source site (with index 2)

1. If the energy cost is negative or zero, $\Delta H \leq 0$: always accept the copy

 ΔH

2. If the energy cost positive, $\Delta H > 0$:

accept the copy with probability P (ΔH ,T) = $e^{-\Delta H/T}$

Energy minimization function

$$H = \sum_{i,j \text{ neighbors}} J\left(\tau(\sigma_i), \tau(\sigma_j)\right) \left(1 - \delta(\sigma_i, \sigma_j)\right) + \lambda \sum_{\substack{\sigma_i \\ \text{Resistance to volume changes}}} \left(v(\sigma_i) - V(\sigma_i)\right)^2,$$

Solution: The copy is accepted with probability $P(\Delta H,T) = e^{-2\alpha/T}$

- 1. Energy $H_{before} = 3 \cdot \alpha + 2\alpha = 5\alpha$
- 2. Energy $H_{after} = 3 \cdot 2\alpha + 1 \cdot \alpha = 7\alpha$

(0	(C) Before 1 1 1 2 2 2 1 1 1 2 2 2 1 1 1 2 2 2 1 1 1 2 2 2 1 1 1 2 2 2 1 1 1 2 2 2						After							
	1	1	1	2	2	2	1	1	1	2	2	2		
	1	1	1	2	2	2	1	1	1	2	2	2		
	1	1	(1)	2	2	2	1	1	1	1	2	2		
	1	1	1	2	2	2	1	1	1	2	2	2		
	1	1	1	2	2	2	1	1	1	2	2	2		
		-	Sou Tar				۵	H =	H _a	fter -	Hbe	fore		

Adhesion energy *J* between

- cell type 1 and 2 is 2α , i.e. $J(\tau_1, \tau_2) = J(\tau_1, \tau_2) = 2\alpha$
- cell type 1 with itself is α , i.e. $J(\tau_1, \tau_1) = \alpha$
- cell type 2 with itself is α , i.e. $J(\tau_2, \tau_2) = \alpha$

$$H = \sum_{i,j \text{ neighbors}} J\left(\tau(\sigma_i), \tau(\sigma_j)\right) \left(1 - \delta(\sigma_i, \sigma_j)\right) + \lambda \sum_{\substack{\sigma_i \\ \text{Resistance to volume changes}}} \left(v(\sigma_i) - V(\sigma_i)\right)^2,$$

Solution: The copy is accepted with probability P (ΔH ,T) = $e^{-2\alpha/T}$

- 1. Energy $H_{before} = 3 \cdot \alpha + 2\alpha = 5\alpha$
- 2. Energy $H_{after} = 3 \cdot 2\alpha + 1 \cdot \alpha = 7\alpha$
- 3. $\Rightarrow \Delta H = H_{after} H_{before} = 2\alpha > 0$ Since H is not < 0 (not necessarily copied)

C)		Bet	fore	9		After							
1	1	1	2	2	2	1	1	1	2	2	2		
1	1	1	2	2	2	1	1	1	2	2	2		
1	1	(1)	2	2	2	1	1	1	1	2	2		
1	1	1	2	2	2	1	1	1	2	2	2		
1	1	1	2	2	2	1	1	1	2	2	2		
	-	Sou			•	4	H =	H	fter -	H_{bc}	fore		

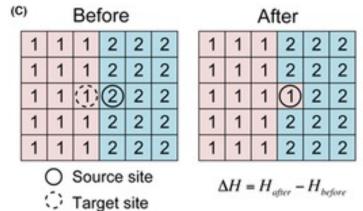
Adhesion energy *J* between

- cell type 1 and 2 is 2α , i.e. $J(\tau_1, \tau_2) = J(\tau_1, \tau_2) = 2\alpha$
- cell type 1 with itself is α , i.e. $J(\tau_1, \tau_1) = \alpha$
- cell type 2 with itself is α , i.e. $J(\tau_2, \tau_2) = \alpha$

$$H = \sum_{i,j \text{ neighbors}} J\left(\tau(\sigma_i), \tau(\sigma_j)\right) \left(1 - \delta(\sigma_i, \sigma_j)\right) + \lambda \sum_{\substack{\sigma_i \\ \text{Resistance to volume changes}}} \left(v(\sigma_i) - V(\sigma_i)\right)^2,$$

Solution: The copy is accepted with probability $P(\Delta H,T) = e^{-2\alpha/T}$

- 1. Energy $H_{before} = 3 \cdot \alpha + 2\alpha = 5\alpha$
- 2. Energy $H_{after} = 3 \cdot 2\alpha + 1 \cdot \alpha = 7\alpha$
- 3. $\Rightarrow \Delta H = H_{after} H_{before} = 2\alpha > 0$ Since H is not < 0 (not necessarily copied)



4. Rather, the probability of the copy attempt is $P(\Delta H, T) = exp(-\Delta H/T) = e(-2\alpha/T)$

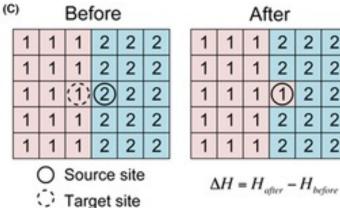
Adhesion energy J between

- cell type 1 and 2 is 2α , i.e. $J(\tau_1, \tau_2) = J(\tau_1, \tau_2) = 2\alpha$
- cell type 1 with itself is α , i.e. $J(\tau_1, \tau_1) = \alpha$
- cell type 2 with itself is α , i.e. $J(\tau_2, \tau_2) = \alpha$

$$H = \sum_{i,j \text{ neighbors}} J\left(\tau(\sigma_i), \tau(\sigma_j)\right) \left(1 - \delta(\sigma_i, \sigma_j)\right) + \lambda \sum_{\substack{\sigma_i \\ \text{Adhesion with neighbors}}} \left(v(\sigma_i) - V(\sigma_i)\right)^2,$$

Discussion: What happens when T goes to 1) infinity and 2) zero

- 1. Energy $H_{before} = 3 \cdot \alpha + 2\alpha = 5\alpha$
- 2. Energy $H_{after} = 3 \cdot 2\alpha + 1 \cdot \alpha = 7\alpha$
- 3. $\Rightarrow \Delta H = H_{after} H_{before} = 2\alpha > 0$ Since H is not < 0 (not necessarily copied)
- 4. Rather, the probability is $P = exp(-\Delta H/T) = e(-2\alpha/T)$
- 5. Discuss what happens when $T \rightarrow \infty$ and $T \rightarrow 0$



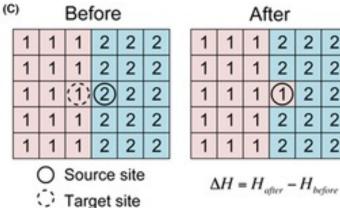
$$H = \sum_{i,j \text{ neighbors}} J\left(\tau(\sigma_i), \tau(\sigma_j)\right) \left(1 - \delta(\sigma_i, \sigma_j)\right) + \lambda \sum_{\substack{\sigma_i \\ \text{Resistance to volume changes}}} \left(v(\sigma_i) - V(\sigma_i)\right)^2,$$

Discussion: What happens when T goes to 1) infinity and 2) zero

1. Energy $H_{before} = 3 \cdot \alpha + 2\alpha = 5\alpha$ 2. Energy $H_{after} = 3 \cdot 2\alpha + 1 \cdot \alpha = 7\alpha$ 3. $\Rightarrow \Delta H = H_{after} - H_{before} = 2\alpha > 0$

Since H is not < 0 (not necessarily copied)

- 4. Rather, the probability is $P = exp(-\Delta H/T) = e(-2\alpha/T)$
- 5. Discuss what happens when $T \rightarrow \infty$ and $T \rightarrow 0$
- 6. $T \to \infty : \to P(\Delta H, T) \to e(0) = 1$
- 7. $T \to 0: \to P(\Delta H, T) \to e(-\infty) = 0$
- 8. What does this mean?



$$H = \sum_{i,j \text{ neighbors}} J\left(\tau(\sigma_i), \tau(\sigma_j)\right) \left(1 - \delta(\sigma_i, \sigma_j)\right) + \lambda \sum_{\substack{\sigma_i \\ \text{Resistance to volume changes}}} \left(v(\sigma_i) - V(\sigma_i)\right)^2,$$

Discussion: What happens when T goes to 1) infinity and 2) zero

1. Energy
$$H_{before} = 3 \cdot \alpha + 2\alpha = 5\alpha$$

2. Energy $H_{after} = 3 \cdot 2\alpha + 1 \cdot \alpha = 7\alpha$

3.
$$\Rightarrow \Delta H = H_{after} - H_{before} = 2\alpha > 0$$

Since H is not < 0 (not necessarily copied)

4. Rather, the probability is
$$P = exp(-\Delta H/T) = e(-2\alpha/T)$$

5. Discuss what happens when $T \rightarrow \infty$ and $T \rightarrow 0$

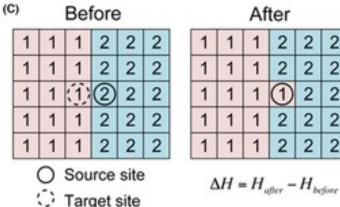
6.
$$T \to \infty : -> P(\Delta H, T) \to e(0) = 1$$

7.
$$T \to 0: \to P(\Delta H, T) \to e(-\infty) = 0$$

8. What does this mean?

9. This means that when we increase the Boltzmann temperature, T, it is more likely that cells move to new positions even if this is energetically unfavorable





 $H= \sum J\left(au(\sigma_i), au(\sigma_j)
ight)\left(1-\delta(\sigma_i,\sigma_j)
ight)+\lambda\sum \left(v(\sigma_i)-V(\sigma_i)
ight)^2,$ i, j neighbors Adhesion with neighbors Resistance to volume changes

Exercise! Plot P (y-axis) vs. ΔH (x-axis; -2 < ΔH < 10) for different T-values (0, 2, 5, 100) (C) Before After 2 2 2 2 2 $P(\Delta H,T) = exp(-\Delta H/T)$

2 2 2 2 1 2 2 1 2 2 2 2 2 O Source site $\Delta H = H_{after} - H_{before}$ C Target site

2

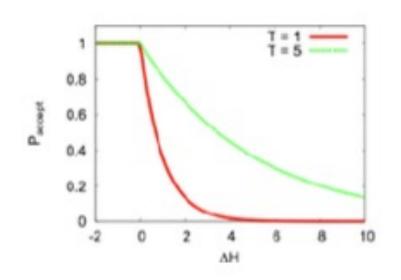
2

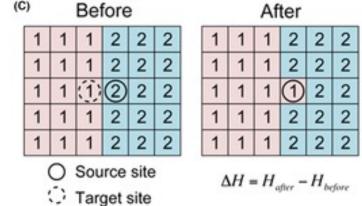
 $H = \sum_{i,j \text{ neighbors}} J\left(\tau(\sigma_i), \tau(\sigma_j)\right) \left(1 - \delta(\sigma_i, \sigma_j)\right) + \lambda \sum_{\substack{\sigma_i \\ \text{Resistance to volume changes}}} \left(v(\sigma_i) - V(\sigma_i)\right)^2,$

Solution! Plot P (y-axis) vs. ΔH (x-axis; -2 < ΔH < 10) for different T-values (0, 2, 5, 100) $P(\Delta H, T) = exp(-\Delta H/T)$

Probability to accept copy depends on ΔH:

 $P(\Delta H) = \begin{cases} 1 & \text{if } \Delta H \leq 0\\ e^{-\frac{\Delta H}{T}} & \text{otherwise} \end{cases}$



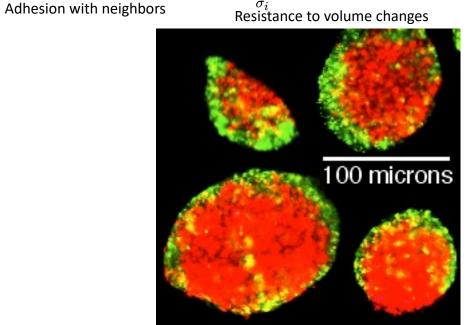


- if the cost is negative, always accept the copy
- The probability that the copy will be accepted increases with T
- T is the Boltzmann temperature, not physical temperature

Hirashima, T., Rens, E. G., & Merks, R. M. (2017). Cellular Potts modeling of complex multicellular behaviors in tissue morphogenesis. Development, growth & differentiation, 59(5), 329-339.

Special case 1: Cell sorting

 Cells with a lower J value for their membrane are more likely to stick together than cells with a higher J value
 Simulate different sorting patterns by varying the J value



 $H= \sum J\left(au(\sigma_i), au(\sigma_j)
ight)\left(1-\delta(\sigma_i,\sigma_j)
ight)+\lambda\sum \left(v(\sigma_i)-V(\sigma_i)
ight)^2,$

Morphogenesis. (2023, October 25). In Wikipedia. https://en.wikipedia.org/wiki/Morphogenesis

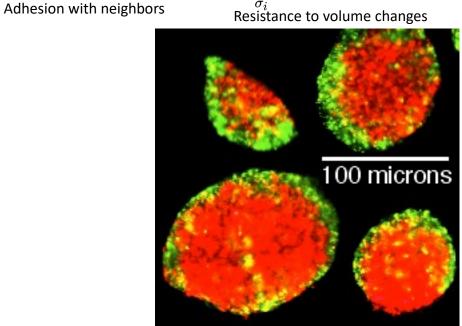
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Special case 1: Cell sorting

We can define the surface tension between yellow and red cells as [2]

$$\gamma_{\tau_1,\tau_2} = J_{\tau_1,\tau_2} - \frac{J_{\tau_1,\tau_1} + J_{\tau_2,\tau_2}}{2}$$

to determine whether contact energies favor homotypic ($\gamma_{\tau_1,\tau_2} > 0$) or heterotypic ($\gamma_{\tau_1,\tau_2} < 0$) cell bonds.



 $H= \sum J\left(au(\sigma_i), au(\sigma_j)
ight)\left(1-\delta(\sigma_i,\sigma_j)
ight)+\lambda\sum \left(v(\sigma_i)-V(\sigma_i)
ight)^2,$

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Exercise! Cell sorting

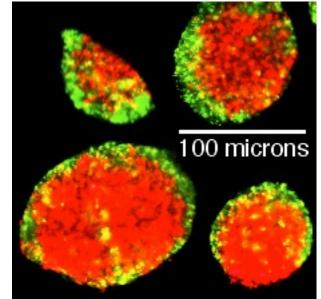
We can define the surface tension between yellow and red cells as [1,2]

$$\gamma_{\tau_1,\tau_2} = J_{\tau_1,\tau_2} - \frac{J_{\tau_1,\tau_1} + J_{\tau_2,\tau_2}}{2}$$

to determine whether contact energies favor homotypic ($\gamma_{\tau_1,\tau_2} > 0$) or heterotypic ($\gamma_{\tau_1,\tau_2} < 0$) cell bonds.

Define: *m* for medium, *y* for yellow and *r* for red cells.

- To get engulfment of red cells by yellow cells, should $\gamma_{y,r} > 0$ or should $\gamma_{y,r} < 0$?
- Which one is right: $\gamma_{r,m} > \gamma_{y,m} > 0$ or : $\gamma_{y,m} > \gamma_{r,m} > 0$



Resistance to volume changes

 $H= \sum J\left(au(\sigma_i), au(\sigma_j)
ight)\left(1-\delta(\sigma_i,\sigma_j)
ight)+\lambda\sum \left(v(\sigma_i)-V(\sigma_i)
ight)^2,$

Adhesion with neighbors

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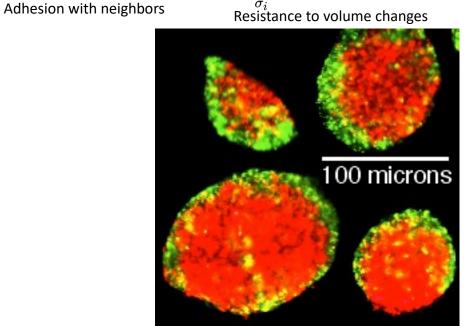
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$$\gamma_{\tau_1,\tau_2} = J_{\tau_1,\tau_2} - \frac{J_{\tau_1,\tau_1} + J_{\tau_2,\tau_2}}{2}$$

to determine whether contact energies favor homotypic ($\gamma_{\tau_1,\tau_2} > 0$) or heterotypic ($\gamma_{\tau_1,\tau_2} < 0$) cell bonds.

Define: *m* for medium, *y* for yellow and *r* for red cells.

- To get engulfment of red cells by yellow cells, should $\gamma_{y,r} > 0$ or should $\gamma_{y,r} < 0$?
- Which one is right: $\gamma_{r,m} > \gamma_{y,m} > 0$ or : $\gamma_{y,m} > \gamma_{r,m} > 0$



 $H= \sum J\left(au(\sigma_i), au(\sigma_j)
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Exercise! Cell sorting

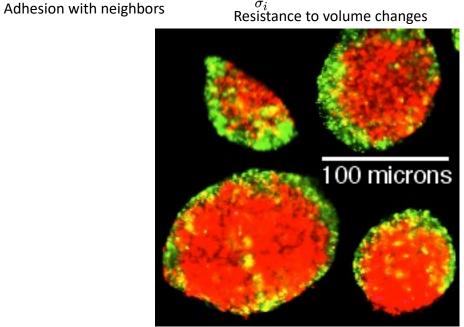
We can define the surface tension between yellow and red cells as

$$\gamma_{\tau_1,\tau_2} = J_{\tau_1,\tau_2} - \frac{J_{\tau_1,\tau_1} + J_{\tau_2,\tau_2}}{2}$$

to determine whether contact energies favor homotypic ($\gamma_{\tau_1,\tau_2} > 0$) or heterotypic ($\gamma_{\tau_1,\tau_2} < 0$) cell bonds.

Define: *m* for medium, *y* for yellow and *r* for red cells.

- To get engulfment of red cells by yellow cells, should $\gamma_{y,r} > 0$ or should $\gamma_{y,r} < 0$?
- Which one is right: $\gamma_{r,m} > \gamma_{y,m} > 0$ or : $\gamma_{y,m} > \gamma_{r,m} > 0$



 $H= \sum J\left(au(\sigma_i), au(\sigma_j)
ight)\left(1-\delta(\sigma_i,\sigma_j)
ight)+\lambda\sum \left(v(\sigma_i)-V(\sigma_i)
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Solution! Cell sorting

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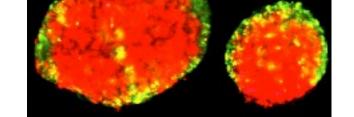
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- Which one is right: $\gamma_{r,m} > \gamma_{y,m} > 0$ or : $\gamma_{y,m} > \gamma_{r,m} > 0$

Cells organize to minimize the total surface tension of the system

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i, j neighbors



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Adhesion with neighbors

 $H= \sum J\left(au(\sigma_i), au(\sigma_j)
ight)\left(1-\delta(\sigma_i,\sigma_j)
ight)+\lambda\sum \left(v(\sigma_i)-V(\sigma_i)
ight)^2,$

Resistance to volume changes

100 microns

Exercise! Cell sorting

We can define the surface tension between yellow and red cells as

$$\gamma_{\tau_1,\tau_2} = J_{\tau_1,\tau_2} - \frac{J_{\tau_1,\tau_1} + J_{\tau_2,\tau_2}}{2}$$

to determine whether contact energies favor homotypic ($\gamma_{\tau_1,\tau_2} > 0$) or heterotypic ($\gamma_{\tau_1,\tau_2} < 0$) cell bonds.

Define: *m* for medium, *y* for yellow and *r* for red cells.

- To get engulfment of red cells by yellow cells, should $\gamma_{y,r} > 0$ or should $\gamma_{y,r} < 0$?
- Which one is right: $\gamma_{r,m} > \gamma_{y,m} > 0$ or : $\gamma_{y,m} > \gamma_{r,m} > 0$
- How about engulfment of yellow cells by red cells?
- How about simple cell sorting and mosaic cell ordering?

Resistance to volume changes

100 microns

 $H= \sum J\left(au(\sigma_i), au(\sigma_j)
ight)\left(1-\delta(\sigma_i,\sigma_j)
ight)+\lambda\sum \left(v(\sigma_i)-V(\sigma_i)
ight)^2,$

Adhesion with neighbors

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$$\gamma_{\tau_1,\tau_2} = J_{\tau_1,\tau_2} - \frac{J_{\tau_1,\tau_1} + J_{\tau_2,\tau_2}}{2}$$

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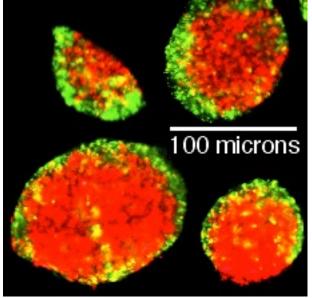
Define: *m* for medium, *y* for yellow and *r* for red cells.

- To get engulfment of red cells by yellow cells, should $\gamma_{y,r} > 0$ or should $\gamma_{y,r} < 0$?
- Which one is right: $\gamma_{r,m} > \gamma_{y,m} > 0$ or : $\gamma_{y,m} > \gamma_{r,m} > 0$
- How about engulfment of yellow cells by red cells? $\gamma_{y,r} > 0$, $\gamma_{y,m} > \gamma_{r,m} > 0$
- How about simple cell sorting and mosaic cell ordering?

i, j neighbors

 $H= \sum J\left(au(\sigma_i), au(\sigma_j)
ight)\left(1-\delta(\sigma_i,\sigma_j)
ight)+\lambda\sum \left(v(\sigma_i)-V(\sigma_i)
ight)^2,$

Adhesion with neighbors



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$$\gamma_{\tau_1,\tau_2} = J_{\tau_1,\tau_2} - \frac{J_{\tau_1,\tau_1} + J_{\tau_2,\tau_2}}{2}$$

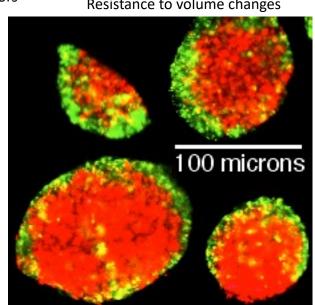
to determine whether contact energies favor homotypic ($\gamma_{\tau_1,\tau_2} > 0$) or heterotypic ($\gamma_{\tau_1,\tau_2} < 0$) cell bonds.

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- Which one is right: $\gamma_{r,m} > \gamma_{\gamma,m} > 0$ or : $\gamma_{\gamma,m} > \gamma_{r,m} > 0$ •
- How about engulfment of yellow cells by red cells? $\gamma_{y,r} > 0$, $\gamma_{y,m} > \gamma_{r,m} > 0$
- How about simple cell sorting and mosaic cell ordering? •

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Adhesion with neighbors

i, j neighbors

 $H= \sum J\left(au(\sigma_i), au(\sigma_j)
ight)\left(1-\delta(\sigma_i,\sigma_j)
ight)+\lambda\sum \left(v(\sigma_i)-V(\sigma_i)
ight)^2,$

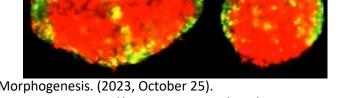
Resistance to volume changes

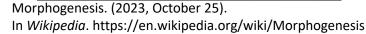
$$\gamma_{\tau_1,\tau_2} = J_{\tau_1,\tau_2} - \frac{J_{\tau_1,\tau_1} + J_{\tau_2,\tau_2}}{2}$$

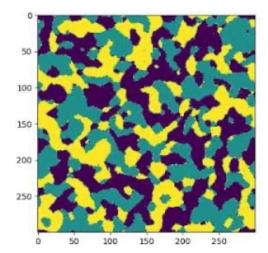
to determine whether contact energies favor homotypic ($\gamma_{\tau_1,\tau_2} > 0$) or heterotypic ($\gamma_{\tau_1,\tau_2} < 0$) cell bonds.

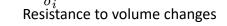
Define: *m* for medium, *y* for yellow and *r* for red cells.

- To get engulfment of red cells by yellow cells, should $\gamma_{v,r} > 0$ or should $\gamma_{v,r} < 0$?
- Which one is right: $\gamma_{r,m} > \gamma_{y,m} > 0$ or : $\gamma_{y,m} > \gamma_{r,m} > 0$ •
- How about engulfment of yellow cells by red cells? $\gamma_{y,r} > 0$, $\gamma_{y,m} > \gamma_{r,m} > 0$
- How about simple cell sorting (video) and mosaic cell ordering? $\gamma_{y,r} > 0$, $\gamma_{y,m} = \gamma_{r,m} > 0$









100 microns

 $H= \sum J\left(au(\sigma_i), au(\sigma_j)
ight)\left(1-\delta(\sigma_i,\sigma_j)
ight)+\lambda\sum \left(v(\sigma_i)-V(\sigma_i)
ight)^2,$

Adhesion with neighbors

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Morpheus

Simulation exercise:

https://www.uio.no/studier/emner/matnat/fys/FYS4715/h23/morph ogenesis/

- Installation:
 - Instructions on gitlab: https://morpheus.gitlab.io/faq/installation/macos/
 - Install Homebrew (in Terminal): /bin/bash -c "\$(curl -fsSL https://raw.githubusercontent.com/Homebrew/install/master/install.sh)"
 - brew tap morpheus-lab/Morpheus
 - brew install Morpheus
 - If you encounter problems, ask UIO GPT (much faster than IT Dept.)