

AST 3220, project 1, spring 2023

Problem 1

CE for quintessence

$$\begin{aligned}\dot{S}_\phi &= -3H(S_\phi + P_\phi) = -3H\left(S_\phi + \frac{P_\phi}{S_\phi} S_\phi\right) \\ &= -3H(1 + w_\phi) S_\phi\end{aligned}$$

This is a separable differential equation:

$$\frac{dS_\phi}{dt} = -3H(1+w_\phi) S_\phi = -3 \frac{da}{a H} (1+w_\phi) S_\phi$$

$$\Rightarrow \frac{dS_\phi}{S_\phi} = -3(1+w_\phi) \frac{da}{a}$$

$$\Rightarrow \int_{S_{\phi 0}}^{S_\phi} \frac{dS_\phi'}{S_\phi'} = -3 \int_{a_0}^a (1+w_\phi) \frac{da'}{a'}$$

Substitution:

$$1+z' = \frac{a_0}{a'} \Rightarrow a' = \frac{a_0}{1+z'}$$

$$a' = a \Rightarrow 1+z' = \frac{a_0}{a} = 1+z$$

$$a' = a_0 \Rightarrow 1+z' = 1 \Rightarrow z' = 0$$

$$da' = -\frac{a_0}{(1+z')^2} dz'$$

Then

$$\begin{aligned}\ln\left(\frac{S_\phi}{S_{\phi 0}}\right) &= -3 \int_0^z [1+w_\phi(z')] \frac{(1+z')}{a_0} \left[-\frac{a_0}{(1+z')^2} dz'\right] \\ &= 3 \int_0^z \frac{1+w_\phi(z')}{1+z'} dz'\end{aligned}$$

and the result in the text follows.

Problem 2 We have

$$S_{\phi} = \frac{1}{2} \dot{\phi}^2 + V(\phi)$$

$$P_{\phi} = \frac{1}{2} \dot{\phi}^2 - V(\phi)$$

Then $S_{\phi} + P_{\phi} = \dot{\phi}^2$

and $\dot{S}_{\phi} = \frac{d}{dt} \left[\frac{1}{2} \dot{\phi}^2 + V(\phi) \right]$

$$= \frac{1}{2} \cdot 2 \dot{\phi} \ddot{\phi} + \frac{dV}{d\phi} \cdot \frac{d\phi}{dt}$$
$$= \dot{\phi} \ddot{\phi} + \dot{\phi} V'(\phi)$$

Insert in the CE:

$$\dot{\phi} \ddot{\phi} + \dot{\phi} V'(\phi) = -3H \dot{\phi}^2$$

and after dividing by $\dot{\phi}^{(*)}$ and rearranging the terms,

$$\underline{\underline{\ddot{\phi} + 3H \dot{\phi} + V'(\phi) = 0}}$$

*) We have to assume $\dot{\phi} \neq 0$ for do that.
But if $\dot{\phi} = 0$, $\phi = \text{constant}$,

$$S_{\phi} = V(\phi) = \text{constant},$$

and $P_{\phi} = -V(\phi) = -S_{\phi}$

so the scalar field is then equivalent to a cosmological constant, which we are not interested in.

Problem 3

$$\text{FI: } (k=0)$$

$$\begin{aligned} \left(\frac{\dot{a}}{a}\right)^2 &= \frac{8\pi G}{3} (\rho_m + \rho_r + \rho_\phi) \\ &= \frac{k^2}{3} \left(\rho_m + \rho_r + \frac{1}{2} \dot{\phi}^2 + V(\phi) \right) \end{aligned}$$

$$\begin{aligned} \text{FII: } \frac{\ddot{a}}{a} &= -\frac{4\pi G}{3} \left[\rho_m + \rho_r + \rho_\phi + 3p_m^0 + 3p_r^{\omega_r} + 3p_\phi \right] \\ &= -\frac{k^2}{6} \left[\rho_m + \rho_r (1 + 3\omega_r) + \frac{1}{2} \dot{\phi}^2 + V(\phi) + \frac{3}{2} \dot{\phi}^2 - 3V(\phi) \right] \\ &= -\frac{k^2}{6} \left[\rho_m + \rho_r (1 + 3\omega_r) + 2\dot{\phi}^2 - 2V(\phi) \right] \end{aligned}$$

$$\text{Since } H = \frac{\dot{a}}{a},$$

$$\dot{H} = \frac{d}{dt} \left(\frac{\dot{a}}{a} \right) = \frac{\ddot{a}a - \dot{a}^2}{a^2} = \frac{\ddot{a}}{a} - \left(\frac{\dot{a}}{a} \right)^2$$

$$= \cancel{\frac{k^2}{3} \left[\rho_m + \rho_r + \frac{1}{2} \dot{\phi}^2 + V(\phi) \right]}$$

$$= -\frac{k^2}{6} \left[\rho_m + \rho_r (1 + 3\omega_r) + 2\dot{\phi}^2 - 2V(\phi) \right]$$

$$= -\frac{k^2}{3} \left[\rho_m + \rho_r + \frac{1}{2} \dot{\phi}^2 + V(\phi) \right]$$

$$= -\frac{k^2}{6} \left[\rho_m + \rho_r + 3\omega_r \rho_r + 2\dot{\phi}^2 - 2V(\phi) + 2\rho_m + 2\rho_r + \dot{\phi}^2 + 2V(\phi) \right]$$

$$= -\frac{k^2}{6} \left[3\rho_m + 3\rho_r + 3\omega_r \rho_r + 3\dot{\phi}^2 \right]$$

$$= -\frac{k^2}{2} \left[\rho_m + \rho_r (1 + \omega_r) + \dot{\phi}^2 \right]$$

Problem 4

We have

$$\Omega_i = \frac{S_i}{S_c} = \frac{S_i}{\frac{3H^2}{k^2}} = \frac{k^2 S_i}{3H^2}$$

Using the definition of the x_i 's:

$$\begin{aligned} x_1^2 + x_2^2 &= \frac{k^2 \dot{\phi}^2}{6H^2} + \frac{k^2 V}{3H^2} \\ &= \frac{k^2}{3H^2} \left(\frac{1}{2} \dot{\phi}^2 + V \right) = \frac{k^2 S_\phi}{3H^2} \\ &= \underline{\underline{\Omega_\phi}} \end{aligned}$$

$$x_3^2 = \frac{k^2 S_r}{3H^2} = \underline{\underline{\Omega_r}}$$

From FI with $k=0$

$$H^2 = \frac{k^2}{3} (S_m + S_r + S_\phi)$$

$$\begin{aligned} \Rightarrow 1 &= \frac{k^2}{3H^2} S_m + \frac{k^2}{3H^2} S_r + \frac{k^2}{3H^2} S_\phi \\ &= \Omega_m + x_3^2 + x_1^2 + x_2^2 \end{aligned}$$

$$\Rightarrow \underline{\underline{\Omega_m = 1 - x_1^2 - x_2^2 - x_3^2}}$$

Problem 5

Equation (8) :

$$\dot{H} = - \frac{k^2}{2} [s_m + s_r(1 + \omega_r) + \dot{\phi}^2]$$

$$\omega_r = \frac{1}{3}, \quad \text{so}$$

$$\dot{H} = - \frac{k^2}{2} [s_m + \frac{4}{3}s_r + \dot{\phi}^2]$$

$$\Rightarrow \frac{\dot{H}}{H^2} = - \frac{k^2}{2H^2} (s_m + \frac{4}{3}s_r + \dot{\phi}^2)$$

$$= - \frac{1}{2} \cdot 3 \frac{k^2}{3H^2} (s_m + \frac{4}{3}s_r + \dot{\phi}^2)$$

$$= - \frac{3}{2} \left(\frac{k^2}{3H^2} s_m + \frac{4}{3} \cdot \frac{k^2}{3H^2} s_r + \frac{k^2}{3H^2} \dot{\phi}^2 \right)$$

$$= - \frac{3}{2} \left(s_m + \frac{4}{3} x_3^2 + 2x_1^2 \right)$$

$$= - \frac{3}{2} \left(1 - x_1^2 - x_2^2 - x_3^2 + \frac{4}{3} x_3^2 + 2x_1^2 \right)$$

$$= - \frac{3}{2} \left(1 + x_1^2 - x_2^2 + \frac{1}{3} x_3^2 \right)$$

$$= - \frac{1}{2} \left(3 + 3x_1^2 - 3x_2^2 + x_3^2 \right)$$

Problem 6

$$x_1 = \frac{R\dot{\phi}}{\sqrt{6}H}$$

and

$$\frac{d}{dN} = \frac{1}{H} \frac{d}{dt}, \quad \text{so}$$

$$\frac{dx_1}{dN} = \frac{1}{H} \frac{d}{dt} \left(\frac{R\dot{\phi}}{\sqrt{6}H} \right) = \frac{R}{\sqrt{6}} \frac{1}{H} \frac{d}{dt} \left(\frac{\dot{\phi}}{H} \right)$$

$$= \frac{R}{\sqrt{6}} \frac{1}{H^2} \ddot{\phi} + \frac{R}{\sqrt{6}} \frac{\dot{\phi}}{H} \frac{d}{dt} \left(\frac{1}{H} \right)$$

$$= \frac{R}{\sqrt{6}H^2} \left(-3H\dot{\phi} - V'(\phi) \right) - \frac{R}{\sqrt{6}} \frac{\dot{\phi}}{H} \frac{\dot{H}}{H^2}$$

↑ from eq. (6) ↗ eq. (16)

$$= -3 \frac{R\dot{\phi}}{\sqrt{6}H} - \frac{RV'}{\sqrt{6}H^2} - x_1 \left(-\frac{1}{2} \right) (3 + 3x_1^2 - 3x_2^2 + x_3^2)$$

$$= -3x_1 - \frac{RV'}{\sqrt{6}H^2} + \frac{1}{2}x_1(3 + 3x_1^2 - 3x_2^2 + x_3^2)$$

We also have

$$\frac{\sqrt{6}}{2} \lambda x_2^2 = \frac{\sqrt{6}}{2} \left(-\frac{V'}{RV} \right) \frac{R^2 V}{3M^2}$$

$$= -\frac{\sqrt{6}}{6} \frac{RV'}{H^2} = -\frac{1}{\sqrt{6}} \frac{RV'}{H^2},$$

So

$$\frac{dx_1}{dN} = -3x_1 + \frac{\sqrt{6}}{2} \lambda x_2^2 + \frac{1}{2}x_1(3 + 3x_1^2 - 3x_2^2 + x_3^2)$$

Next one:

$$\begin{aligned}\frac{dx_2}{dN} &= \frac{1}{H} \frac{d}{dt} \left(\frac{R\sqrt{V'}}{\sqrt{3}H} \right) \\ &= \frac{R}{\sqrt{3}} \frac{1}{H} \frac{d}{dt} \left(\frac{\sqrt{V'}}{H} \right) \\ &= \frac{R}{\sqrt{3}H^2} \frac{d}{dt} \sqrt{V'} + \frac{R}{\sqrt{3}H} \sqrt{V'} \frac{d}{dt} \left(\frac{1}{H} \right) \\ &= \frac{R}{\sqrt{3}H^2} \frac{1}{2\sqrt{V'}} \frac{dV'}{dt} \dot{\phi} + x_2 \cdot \left(-\frac{\dot{H}}{H^2} \right) \\ &= \frac{R V' \dot{\phi}}{2\sqrt{3} H^2 \sqrt{V'}} + \frac{1}{2} x_2 (3 + 3x_1^2 - 3x_2^2 + x_3^2)\end{aligned}$$

Checking that

$$\begin{aligned}\frac{R V' \dot{\phi}}{2\sqrt{3} H^2 \sqrt{V'}} &= -\frac{\sqrt{6}}{2} \lambda x_1 x_2 \\ -\frac{\sqrt{6}}{2} \lambda x_1 x_2 &= -\frac{\sqrt{6}}{2} \left(-\frac{V'}{kV} \right) \frac{R \dot{\phi}}{\sqrt{6}H} \frac{R\sqrt{V'}}{\sqrt{3}H} \\ &= \frac{1}{2\sqrt{3}} \frac{R^2 V' \sqrt{V'} \dot{\phi}}{R V H^2} \\ &= \frac{R V' \dot{\phi}}{2\sqrt{3} H^2 \sqrt{V'}}\end{aligned}$$

So

$$\frac{dx_2}{dN} = -\frac{\sqrt{6}}{2} \lambda x_1 x_2 + \frac{1}{2} x_2 (3 + 3x_1^2 - 3x_2^2 + x_3^2)$$

Finally :

$$\begin{aligned}\frac{dx_3}{dN} &= \frac{1}{H} \frac{d}{dt} \left(\frac{k\sqrt{s_r}}{\sqrt{3}H} \right) \\ &= \frac{k}{\sqrt{3}} \frac{1}{H} \frac{d}{dt} \frac{\sqrt{s_r}}{H} = \frac{k}{\sqrt{3}H^2} \frac{1}{2\sqrt{s_r}} \dot{s}_r + \frac{k\sqrt{s_r}}{\sqrt{3}H} \frac{d}{dt} \frac{1}{H} \\ &= x_3\end{aligned}$$

From the CE for radiation:

$$\begin{aligned}\dot{s}_r &= -3H(s_r + p_r) \\ &= -3H(1 + w_r^{1/2})s_r = -4Hs_r\end{aligned}$$

So

$$\begin{aligned}\frac{dx_3}{dN} &= \frac{k}{\sqrt{3}H^2} \frac{1}{2\sqrt{s_r}} (-4Hs_r) + x_3 \left(-\frac{\dot{H}}{H^2} \right) \\ &= -2 \frac{k\sqrt{s_r}}{\sqrt{3}H} + \frac{1}{2} x_3 (3 + 3x_1^2 - 3x_2^2 + x_3^2) \\ &= x_3\end{aligned}$$

$$= -2x_3 + \frac{1}{2} x_3 (3 + 3x_1^2 - 3x_2^2 + x_3^2)$$

Problem 7

$$\lambda = \text{constant} \quad \cancel{\neq \lambda}$$

$$\Rightarrow -\frac{V'}{kV} = \lambda$$

$$\frac{dV}{d\phi} = -\lambda k V$$
$$\int_{V_0}^{V(\phi)} \frac{dV}{V} = -\lambda k \int_0^{\phi} d\phi'$$

$$\ln\left[\frac{V(\phi)}{V_0}\right] = -\lambda k \phi$$

$$\Rightarrow \underline{V(\phi) = V_0 e^{-\lambda k \phi}} \quad \text{): exponential potential}$$

For this potential

$$V' = -\lambda k V_0 e^{-\lambda k \phi} = -\lambda k V$$

$$V'' = -\lambda k V' = \lambda^2 k^2 V$$

So

$$\Pi = \frac{V V''}{(V')^2} = \frac{V \cdot \lambda^2 k^2 V}{\lambda^2 k^2 V^2} = \underline{\underline{1}}$$

Problem 8

$$\frac{d\lambda}{dN} = \frac{1}{H} \frac{d}{dt} \left(-\frac{v'}{Rv} \right)$$

$$= -\frac{1}{RH} \frac{d}{dt} \left(\frac{v'}{v} \right) \frac{dt}{d\phi}$$

$$= -\frac{\dot{\phi}}{RH} \frac{v''v - (v')^2}{v^2}$$

$$= -\frac{\dot{\phi}}{RH} \frac{(v')^2}{v^2} \left[\frac{v''v}{(v')^2} - 1 \right]$$

$$= -\frac{\sqrt{6}H}{R} x_1 \frac{1}{RH} \left(\frac{v'}{v} \right)^2 (\tau - 1)$$

$$\dot{\phi} = \frac{\sqrt{6}H}{R} x_1$$

$$= -\sqrt{6} x_1 \left(\frac{v'}{Rv} \right)^2 (\tau - 1)$$

$$= -\sqrt{6} \lambda^2 (\tau - 1) x_1$$

Problem 9

My codes are of limited value for you because I am the only FORTRAN77-programmer still alive, but they are included at the end of this document to please those of you with an interest in medieval history

In my plots I have $-\ln(1+z)$ along the axis, but this is the same as N :

$$N = \ln\left(\frac{a}{a_0}\right) = \ln\left(\frac{1}{1+z}\right) = -\ln(1+z)$$

N is zero today, and negative at earlier times.

While the densities evolve very similarly in the two models, the EoS parameter does not.

Problem 10

When solving the equations numerically, we find $x_i(N)$,

so we get $w_{\phi}(N)$ straightforwardly

Since $N = -\ln(1+z)$,

$$dN = -\frac{1}{1+z} dz$$

$$\Rightarrow \frac{dz}{1+z} = -dN$$

So

$$\begin{aligned} & \int_0^z dz' \frac{3[1+w_{\phi}(z')]}{1+z'} \\ &= - \int_0^{-\ln(1+z)} 3[1+w_{\phi}(N)] dN \\ &= 3 \int_{-\ln(1+z)}^0 [1+w_{\phi}(N)] dN \end{aligned}$$

I use Gauss-Legendre integration, and I interpolate in the numerical solution to find w_{ϕ} on the integration grid rather than solving the differential equations again.

The Hubble parameter looks very similar in the two models (see figure 5), and they are markedly different from Λ CDM at early times.

Closer to our time they all look the same, and we should expect that since the models need to fit the luminosity distance data.

Problem 11

Equation (3.61) in the lecture notes:

$$t_0 = \int_0^{\infty} \frac{dz}{(1+z)H(z)}$$
$$= - \int_0^{-\infty} \frac{dN}{H(N)} = \int_{-\infty}^0 \frac{dN}{H(N)}$$

For the power-law potential:

$$H_0 t_0 = 0,99$$

Exponential:

$$H_0 t_0 = 0,97$$

Λ CDM:

$$H_0 t_0 = 0,96$$

∴ Power-law potential gives oldest universe, but only marginally.

Problem 12 The luminosity distance
is given by

$$d_L = \frac{c(1+z)}{H_0} \int_0^z \frac{dz'}{H(z')/H_0}$$

We can change the integration
variable from z to N again
if we wish to.

See figure 6 for the plot.

Problem 13 Here it is a good idea
to have stored the results
from problem 12 so you
just need to interpolate
in them to find d_L at
the required redshifts.

I found

$$\chi^2 = 34.5$$

for the power-law potential,
and

$$\chi^2 = 98.4$$

for the exponential potential,
so the power-law potential
fits the data best (and the
exponential potential is actually
a horrible fit)

Problem 14

With just one parameter, Ω_{mo} , to optimize, a brute-force approach is feasible:

Just calculate χ^2 for lots of values of Ω_{mo} between 0 and 1 and see which one gives the lowest χ^2 .

I found

$$\chi^2_{\min} = 29.7 \quad \text{for } \Omega_{mo} = 0.30$$

This is a better fit than any of the two quiescence models. However, the comparison is not fair as I have found the value of Ω_{mo} which gives the best fit, whereas no optimization was done for the quiescence models. Maybe we could have found better values for the parameters in those models if we had tried.

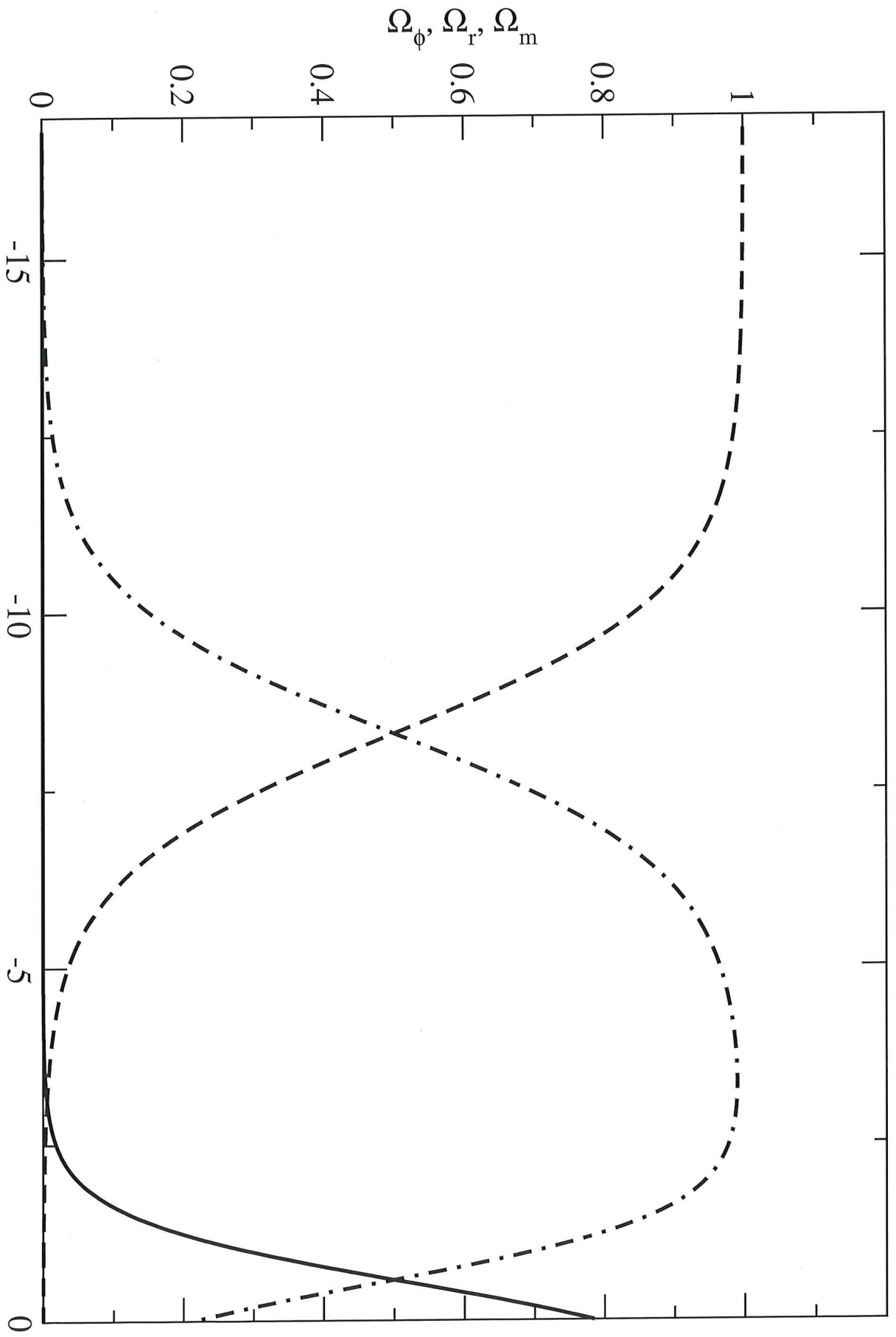


Figure 1: Ω_m (dash-dotted line), Ω_r (dotted line), Ω_ϕ (full line) and Ω_ϕ (full line) for the power-law perturbation

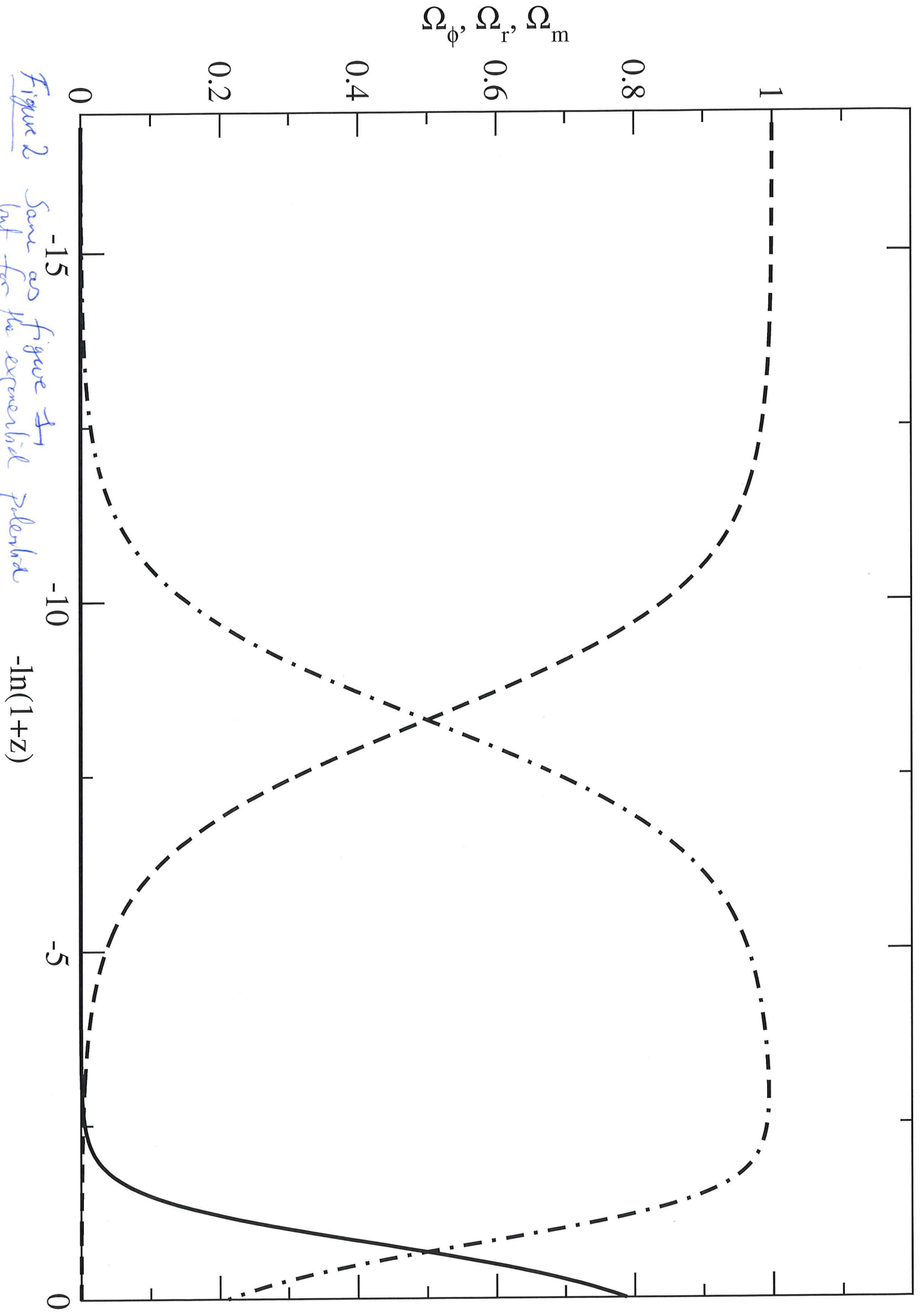


Figure 2 Same as figure 1 but for the exponential potential

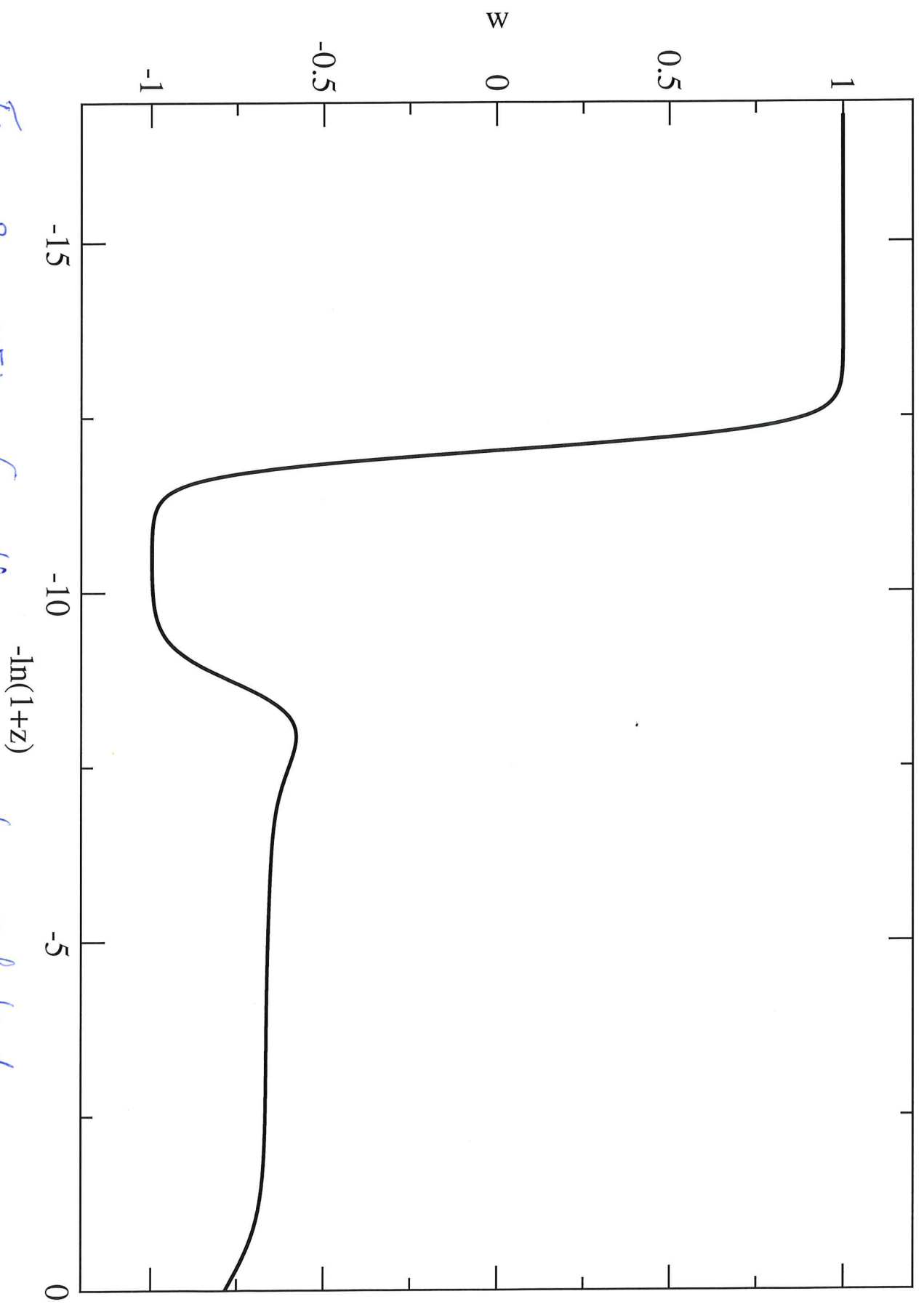


Figure 3: w^{\dagger} for the Potts-lens potential

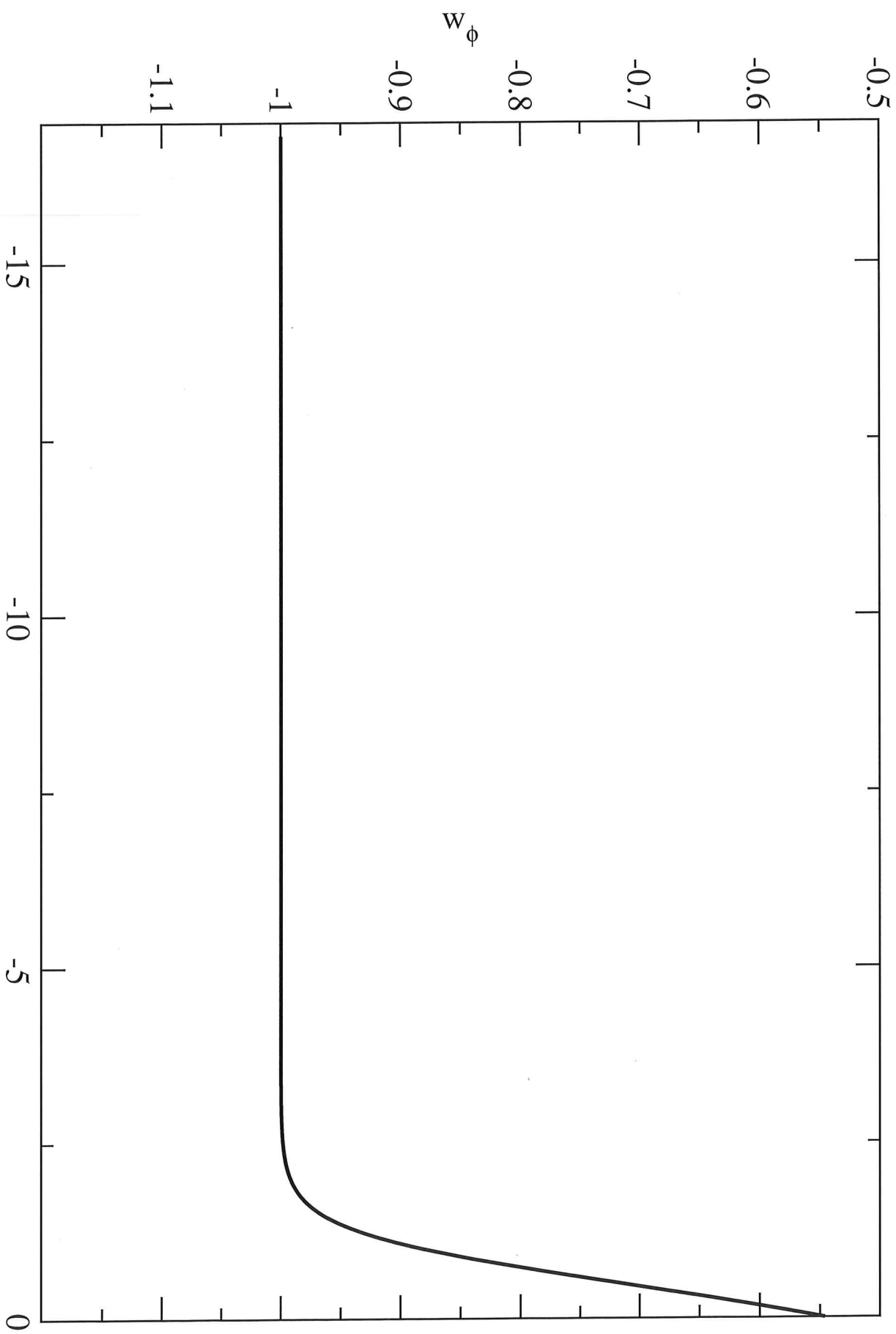


Figure 4: w_ϕ for the $-\ln(1+z)$ exponential potential

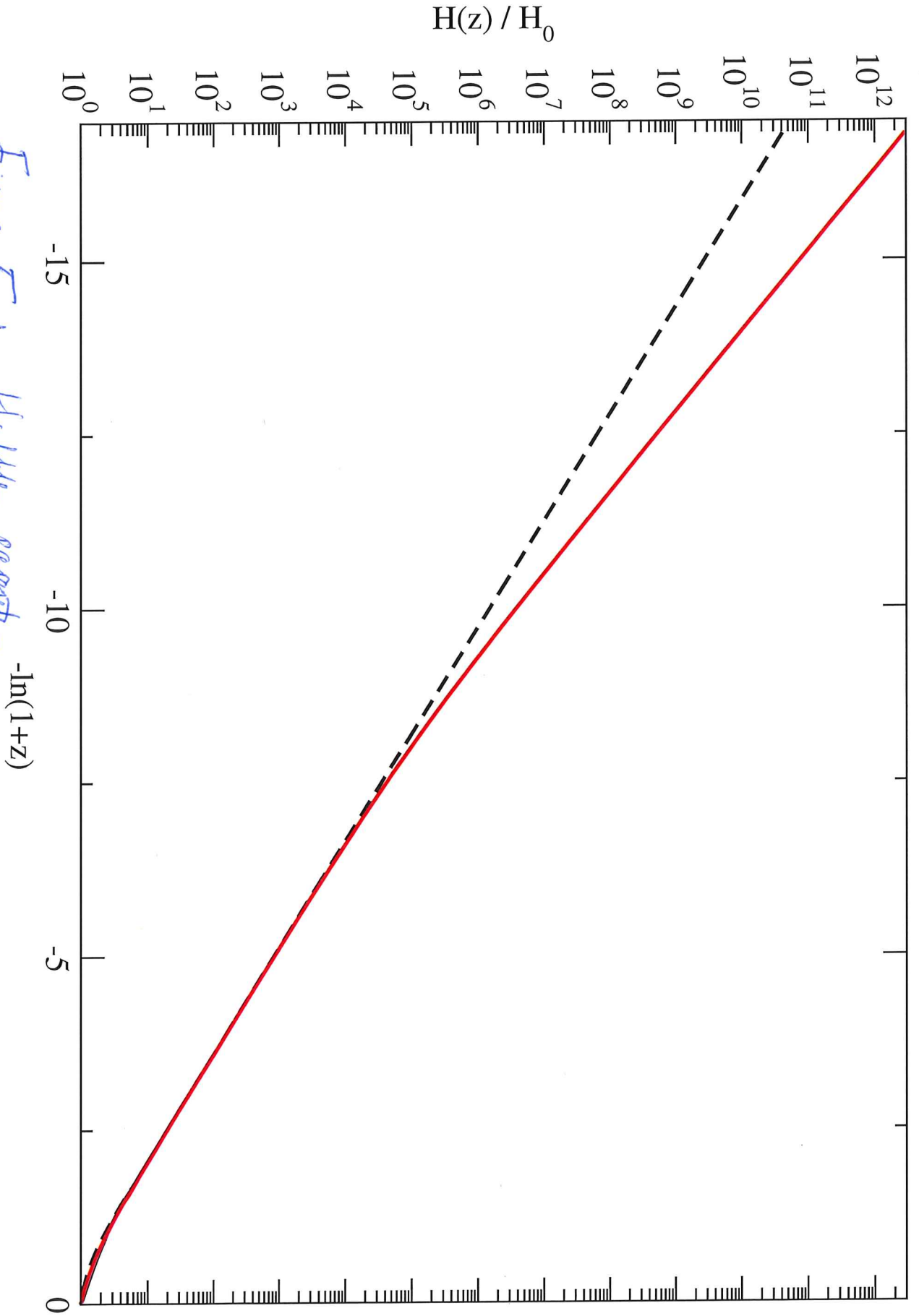


Figure 5: Hubble parameter for power-law and exp. potentials (not visible separately) and the Λ CDM model (dashed line)

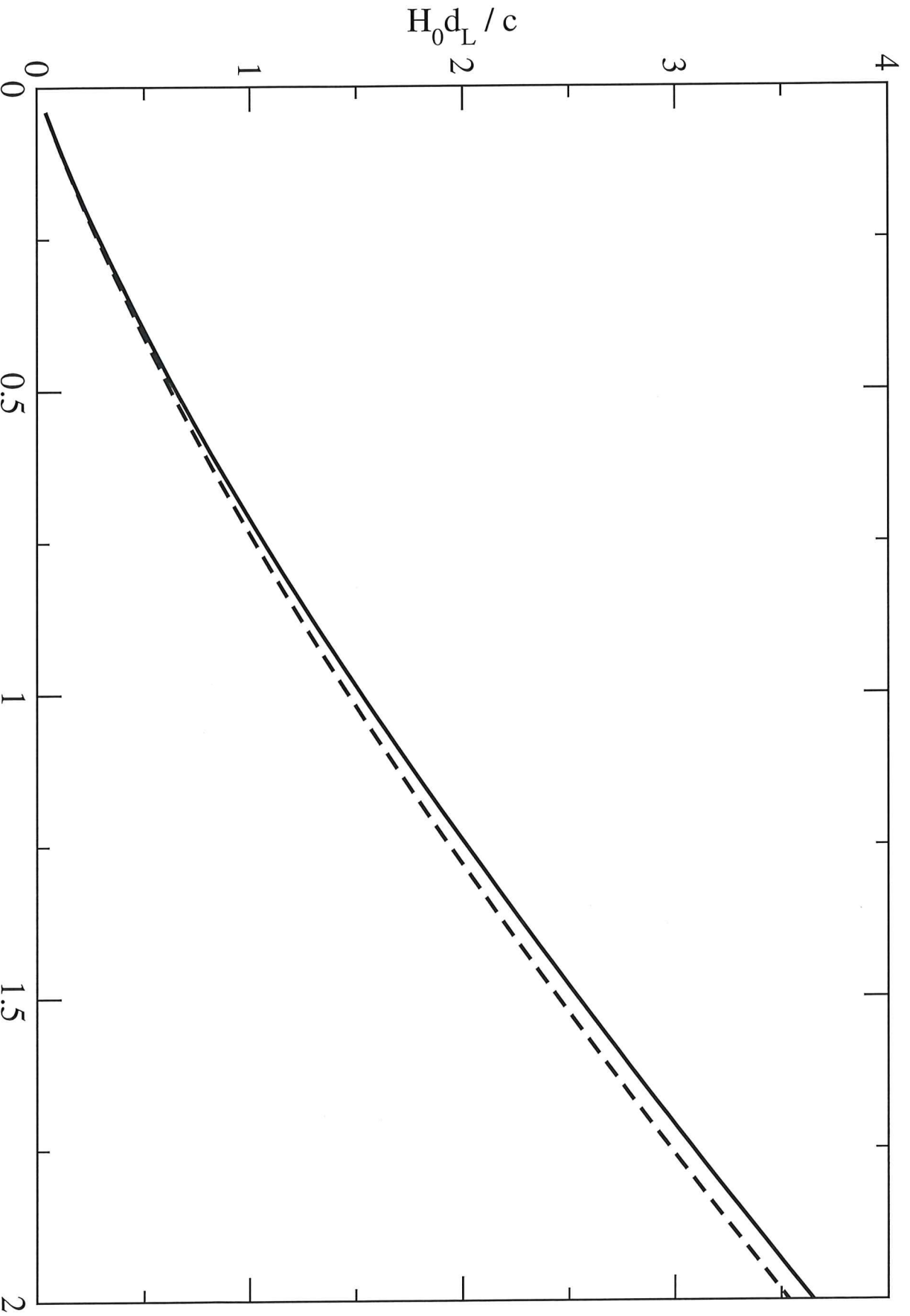


Figure 6: Luminosity distance (in units of c/H_0) for the power-law potential (full line) and the exponential potential (dashed line)

```

program powerlaw_quintessence
implicit none
integer      np,nvar,N,M
integer      nok,nbad,i,j,nint,nz,ndat
parameter    (M=4,np=1000,nint=100,nz=50,ndat=31)
double precision ystart(M),x1,x2,eps,h1,hmin
double precision y(M,np+1),x(np+1)
double precision ophi(np+1),or(np+1),om(np+1)
double precision wphi(np+1)
double precision xg(nint),dxg(nint)
double precision ophi0,or0,om0
double precision wint,Hubble(np+1),wp
double precision HLCDM,H0t0,hub,cH0
double precision term1,term2,term3
double precision dL(nz),z(nz), Nlow
double precision zdat(ndat),dLdat(ndat),err(ndat)
double precision chi2,dLtheor
external     derivs,rkqs

```

! Setting parameter values

```

hub=0.7d0
cH0=2.998d0/hub      ! in Gpc

```

! Number of differential equations to solve

```

nvar = M

```

! Setting up grid where the solution is to be found

```

do i = 1, np+1
  x(i)=-dlog(1.d0+2.d7)+dlog(1.d0+2.d7)*(i-1)/np
end do

```

! Initial conditons

```

ystart(1) = 5.d-5
ystart(2) = 1.d-8
ystart(3) = 0.9999d0
ystart(4) = 1.d9

```

```

y(1,1) = ystart(1)
y(2,1) = ystart(2)
y(3,1) = ystart(3)
y(4,1) = ystart(4)

```

! Accuracy, step size and minimum step size, required by the ODE solver

```

eps = 1.d-7
h1 = 1.d-5
hmin = 1.d-8

```

! Loop over grid, find solutions on each grid point

```

do i = 2, np+1
  x1 = x(i-1)
  x2 = x(i)
  call odeint(ystart,nvar,x1,x2,eps,h1,hmin,nok,
*          nbad,derivs,rkqs)

  do j = 1, nvar
    y(j,i) = ystart(j)
  end do
end do

```

! Generate data for plots

```

do i = 1, np+1
  ophi(i)=y(1,i)**2+y(2,i)**2
  or(i) = y(3,i)**2
  om(i) = 1.d0-ophi(i)-or(i)
  wphi(i)= (y(1,i)**2-y(2,i)**2)/ophi(i)
end do

open(8,file='densities_power_law.dat')
open(9,file='EoS_power_law.dat')
open(10,file='weff_power_law.dat')
do i = 1, np+1
  write(8,*)x(i),ophi(i),or(i),om(i)
  write(9,*)x(i),wphi(i)
  write(10,*)x(i),y(1,i)**2-y(2,i)**2+y(3,i)**2/3.d0
end do
close(8)
close(9)
close(10)

```

! Calculating the Hubble parameter

```

ophi0=ophi(np+1)
or0=or(np+1)
om0=om(np+1)

do i = 1, np+1
  wint=0.d0
  call gauleg(x(i),0.d0,xg,dxg,nint)
  do j = 1,nint
    call interp1d(x,wphi,np+1,3,xg(j),wp)
    wint=wint+(1.d0+wp)*dxg(j)
  end do
  term1=or0*dexp(-4.d0*x(i))
  term2=om0*dexp(-3.d0*x(i))
  term3=ophi0*dexp(3.d0*wint)
  hubble(i)=dsqrt(term1+term2+term3)
end do

```

! Output results for plotting

```

open(8,file='hubble_power_law.dat')

```

```

do i = 1, np+1
  write(8,*)x(i),hubble(i)
end do
close(8)

```

! Calculating the Hubble parameter in LCDM for comparison

```

open(8,file='hubble_LCDM.dat')
do i = 1,np+1
  term1=om0*dexp(-3.d0*x(i))
  term2=1.d0-om0
  HLCDM=dsqrt(term1+term2)
  write(8,*)x(i),HLCDM
end do
close(8)

```

! Calculating the age

```

H0t0=0.d0
call gauleg(x(1),x(np+1),xg,dxg,nint)
do i = 1, nint
  call interp1d(x,hubble,np+1,3,xg(i),term1)
  H0t0=H0t0+dxg(i)/term1
end do
write(*,*)'H0*t0 = ', H0t0

```

! Calculating luminosity distance

```

do i = 1, nz
  z(i) = 2.d0*i/nz
  Nlow=-dlog(1.d0+z(i))
  dL(i) = 0.d0
  call gauleg(Nlow,0.d0,xg,dxg,nint)
  do j = 1, nint
    call interp1d(x,hubble,np+1,3,xg(j),term1)
    dL(i)=dL(i)+dexp(-xg(j))*dxg(j)/term1
  end do
  dL(i) = dL(i)*dexp(-Nlow)
end do

```

! Output of results for plotting

```

open(8,file='dL_power_law.dat')
do i = 1, nz
  write(8,*)z(i),dL(i)
end do
close(8)

```

! Loading SN1a data

```

open(8,file='sndata.txt')
do i = 1, ndat
  read(8,*)zdat(i),dLdat(i),err(i)
end do
close(8)

```


! Calculating chi^2

```
chi2 = 0.d0
open(8,file='expcompare_power_law.dat')
do i = 1, ndat
  call interp1d(z,dL,nz,3,zdat(i),dLtheor)
  dLtheor=dLtheor*ch0
  write(8,*)zdat(i),dLtheor
  chi2=chi2+(dLtheor-dLdat(i))**2/err(i)**2
end do
close(8)
write(*,*)chi2

end
```

! The following routines make up the ODE solver, and they are taken from
! "Numerical Recipes in FORTRAN" by Press, Teukolsky, Vetterling and
! Flannery

```
subroutine derivs(x,y,dydx)
  implicit none
  double precision x,y(4),dydx(4)
  double precision s62,term

  s62=dsqrt(6.d0)/2.d0
  term = 3.d0+3.d0*y(1)*y(1)-3.d0*y(2)*y(2)+y(3)*y(3)

  dydx(1)=-3.d0*y(1)+s62*y(4)*y(2)*y(2)+.5d0*y(1)*term
  dydx(2)=-s62*y(4)*y(1)*y(2)+.5d0*y(2)*term
  dydx(3)=-2.d0*y(3)+.5d0*y(3)*term
  dydx(4)=-2.d0*s62*y(4)*y(4)*y(1)

  return
end
```

```
SUBROUTINE odeint(ystart,nvar,x1,x2,eps,h1,hmin,nok,nbad,derivs,
*rkqs)
  INTEGER nbad,nok,nvar,KMAXX,MAXSTP,NMAX
  double precision eps,h1,hmin,x1,x2,ystart(nvar),TINY
  EXTERNAL derivs,rkqs
  PARAMETER (MAXSTP=10000,NMAX=50,KMAXX=200,TINY=1.d-30)
  INTEGER i,kmax,kount,nstp
  double precision dxsav,h,hdid,hnext,x,xsav,dydx(NMAX),xp(KMAXX),
*y(NMAX),
*yp(NMAX,KMAXX),yscal(NMAX)
  COMMON /path/ kmax,kount,dxsav,xp,yp
  x=x1
  h=sign(h1,x2-x1)
```

```

nok=0
nbad=0
kount=0
do 11 i=1,nvar
  y(i)=ystart(i)
11 continue
  if (kmax.gt.0) xsav=x-2.d0*dxsav
  do 16 nstp=1,MAXSTP
    call derivs(x,y,dydx)
    do 12 i=1,nvar
      yscal(i)=dabs(y(i))+dabs(h*dydx(i))+TINY
12 continue
      if(kmax.gt.0)then
        if(dabs(x-xsav).gt.dabs(dxsav)) then
          if(kount.lt.kmax-1)then
            kount=kount+1
            xp(kount)=x
            do 13 i=1,nvar
              yp(i,kount)=y(i)
13 continue
              xsav=x
            endif
          endif
        endif
        if((x+h-x2)*(x+h-x1).gt.0.d0) h=x2-x
        call rkqs(y,dydx,nvar,x,h,eps,yscal,hdid,hnext,derivs)
        if(hdid.eq.h)then
          nok=nok+1
        else
          nbad=nbad+1
        endif
        if((x-x2)*(x2-x1).ge.0.d0)then
          do 14 i=1,nvar
            ystart(i)=y(i)
14 continue
            if(kmax.ne.0)then
              kount=kount+1
              xp(kount)=x
              do 15 i=1,nvar
                yp(i,kount)=y(i)
15 continue
              endif
            return
          endif
          if(dabs(hnext).lt.hmin) pause
          *'stepsize smaller than minimum in odeint'
          h=hnext
16 continue
          pause 'too many steps in odeint'
          return
        END

```

C (C) Copr. 1986-92 Numerical Recipes Software Vs1&v%1jw#<?4210(9p#.

SUBROUTINE rkck(y,dydx,n,x,h,yout,yerr,derivs)

```

INTEGER n,NMAX
double precision h,x,dydx(n),y(n),yerr(n),yout(n)
EXTERNAL derivs
PARAMETER (NMAX=50)
CU  USES derivs
    INTEGER i
    double precision ak2(NMAX),ak3(NMAX),ak4(NMAX)
    double precision ak5(NMAX),ak6(NMAX)
    double precision ytemp(NMAX),A2,A3,A4,A5,A6,B21,B31,B32,B41
    double precision B42,B43,B51,B52,B53
    double precision B54,B61,B62,B63,B64,B65,C1,C3
    double precision C4,C6,DC1,DC3,DC4,DC5,DC6
    PARAMETER (A2=.2d0,A3=.3d0,A4=.6d0,
    *A5=1.d0,A6=.875d0,B21=.2d0,B31=3.d0/40.d0,
    *B32=9.d0/40.d0,B41=.3d0,B42=-.9d0,
    *B43=1.2d0,B51=-11.d0/54.d0,B52=2.5d0,
    *B53=-70.d0/27.d0,B54=35.d0/27.d0,
    *B61=1631.d0/55296.d0,B62=175.d0/512.d0,
    *B63=575.d0/13824.d0,B64=44275.d0/110592.d0,
    *B65=253.d0/4096.d0,C1=37.d0/378.d0,
    *C3=250.d0/621.d0,C4=125.d0/594.d0,
    *C6=512.d0/1771.d0,DC1=C1-2825.d0/27648.d0,
    *DC3=C3-18575.d0/48384.d0,
    *DC4=C4-13525.d0/55296.d0,DC5=-277.d0/14336.d0,
    *DC6=C6-.25d0)
    do 11 i=1,n
        ytemp(i)=y(i)+B21*h*dydx(i)
11    continue
        call derivs(x+A2*h,ytemp,ak2)
        do 12 i=1,n
            ytemp(i)=y(i)+h*(B31*dydx(i)+B32*ak2(i))
12    continue
            call derivs(x+A3*h,ytemp,ak3)
            do 13 i=1,n
                ytemp(i)=y(i)+h*(B41*dydx(i)+B42*ak2(i)+B43*ak3(i))
13    continue
                call derivs(x+A4*h,ytemp,ak4)
                do 14 i=1,n
                    ytemp(i)=y(i)+h*(B51*dydx(i)+B52*ak2(i)+B53*ak3(i)+B54*ak4(i))
14    continue
                    call derivs(x+A5*h,ytemp,ak5)
                    do 15 i=1,n
                        ytemp(i)=y(i)+h*(B61*dydx(i)+B62*ak2(i)+B63*ak3(i)+B64*ak4(i)+
    *B65*ak5(i))
15    continue
                        call derivs(x+A6*h,ytemp,ak6)
                        do 16 i=1,n
                            yout(i)=y(i)+h*(C1*dydx(i)+C3*ak3(i)+C4*ak4(i)+C6*ak6(i))
16    continue
                            do 17 i=1,n
                                yerr(i)=h*(DC1*dydx(i)+DC3*ak3(i)+DC4*ak4(i)+DC5*ak5(i)+DC6*
    *ak6(i))
17    continue
                            return
                            END

```

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```

SUBROUTINE rkqs(y,dydx,n,x,htry,eps,yscal,hdid,hnext,derivs)
INTEGER n,NMAX
double precision eps,hdid,hnext,htry,x,dydx(n),y(n),yscal(n)
EXTERNAL derivs
PARAMETER (NMAX=50)
CU  USES derivs,rkck
INTEGER i
double precision errmax,h,xnew,yerr(NMAX),ytemp(NMAX),SAFETY,PGROW,PSHRNK,
*ERRCON
PARAMETER (SAFETY=0.9d0,PGROW=-.2d0,PSHRNK=-.25d0,
*ERRCON=1.89d-4)
h=htry
1  call rkck(y,dydx,n,x,h,ytemp,yerr,derivs)
errmax=0.d0
do 11 i=1,n
errmax=max(errmax,dabs(yerr(i)/yscal(i)))
11 continue
errmax=errmax/eps
if(errmax.gt.1.d0)then
h=SAFETY*h*(errmax**PSHRNK)
if(h.lt.0.1d0*h)then
h=.1d0*h
endif
xnew=x+h
if(xnew.eq.x)pause 'stepsize underflow in rkqs'
goto 1
else
if(errmax.gt.ERRCON)then
hnext=SAFETY*h*(errmax**PGROW)
else
hnext=5.d0*h
endif
hdid=h
x=x+h
do 12 i=1,n
y(i)=ytemp(i)
12 continue
return
endif
END
```

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! Routines for interpolation, from the same source

```

SUBROUTINE interp1d(x,fx,np,npol,x1,fx1)
!-----
!  input arrays: x(np),fx(np)  ->FUNCTION f(x)
!  value  x1 the point
```

```

!   output value   fx1           -> f(x1)
!   mp: x(mp)< x1 <x(mp+1)
!   mp=1 IF x1 < x(1)
!   mp=np IF x1 > x(np)
!   npol= # of interpolation points
!-----
IMPLICIT REAL*8(a-h,o-z)
REAL*8 x(np),fx(np),x1,fx1,df
INTEGER mp,np,l,npol
IF(x1.EQ.x(1))THEN
  fx1=fx(1)
ELSEIF(x1.EQ.x(np))THEN
  fx1=fx(np)
ELSE
  CALL LOCATE(x,NP,x1,MP)
  L=MIN(MAX(MP-(npol-1)/2,1),NP+1-npol)
!   IF(mp.EQ.0.OR.mp.EQ.np)THEN
!     IF(mp.EQ.0)THEN
!       WRITE(6,*)'warning x1= ',x1,' and x(',1,')= ',x(1)
!     ELSE
!       WRITE(6,*)'warning x1= ',x1,' and x(',np,')= ',x(np)
!     ENDIF
!     WRITE(6,*)np,npol
!     DO i=1,np
!       WRITE(6,*)i,x(i),fx(i)
!     ENDDO
!   ENDIF
  CALL POLINT(x(L),fx(L),3,x1,fx1,df)
ENDIF
RETURN
END

```

```

SUBROUTINE locate(xx,n,x,j)
IMPLICIT REAL*8(A-H,0-Z)
INTEGER n,j,jl,ju,jm
REAL*8 x,xx(n)
jl=0
ju=n+1
10 IF(ju-jl.GT.1) THEN
  jm=(ju+jl)/2
  IF((xx(n).GT.xx(1)).EQV.(x.GT.xx(jm))) THEN
    jl=jm
  ELSE
    ju=jm
  ENDIF
  GOTO 10
ENDIF
j=jl
RETURN
END

```

```

SUBROUTINE polint(xa,ya,n,x,y,dy)
INTEGER n,NMAX
double precision dy,x,y,xa(n),ya(n)
PARAMETER (NMAX=10)
INTEGER i,m,ns
double precision den,dif,dift,ho,hp,w,c(NMAX),d(NMAX)
ns=1
dif=dabs(x-xa(1))
do 11 i=1,n
  dift=dabs(x-xa(i))
  if (dift.lt.dif) then
    ns=i
    dif=dift
  endif
  c(i)=ya(i)
  d(i)=ya(i)
11 continue
y=ya(ns)
ns=ns-1
do 13 m=1,n-1
  do 12 i=1,n-m
    ho=xa(i)-x
    hp=xa(i+m)-x
    w=c(i+1)-d(i)
    den=ho-hp
    if(den.eq.0.d0)pause 'failure in polint'
    den=w/den
    d(i)=hp*den
    c(i)=ho*den
12 continue
  if (2*ns.lt.n-m)then
    dy=c(ns+1)
  else
    dy=d(ns)
    ns=ns-1
  endif
  y=y+dy
13 continue
return
END

```

! Routine for Gauss-Legendre integration, also from the same source

```

SUBROUTINE gauleg(x1,x2,x,w,n)
INTEGER n
double precision x1,x2,x(n),w(n)
DOUBLE PRECISION EPS
PARAMETER (EPS=3.d-14)
INTEGER i,j,m
DOUBLE PRECISION p1,p2,p3,pp,xl,xm,z,z1

m=(n+1)/2
xm=0.5d0*(x2+x1)
xl=0.5d0*(x2-x1)
do i=1,m

```

1

```
z=dcos(3.141592654d0*(i-.25d0)/(n+.5d0))
continue
p1=1.d0
p2=0.d0
do j=1,n
  p3=p2
  p2=p1
  p1=((2.d0*j-1.d0)*z*p2-(j-1.d0)*p3)/j
end do
pp=n*(z*p1-p2)/(z*z-1.d0)
z1=z
z=z1-p1/pp
if(dabs(z-z1).gt.EPS)goto 1
x(i)=xm-xl*z
x(n+1-i)=xm+xl*z
w(i)=2.d0*xl/((1.d0-z*z)*pp*pp)
w(n+1-i)=w(i)
end do
return
END
```