

FYS 3120/4120 Classical Mechanics and Electromagnetism  
Spring semester 2006

## Problem set 1

### Problem 1.1

A double pendulum, with lengths  $L_1$  and  $L_2$ , performs oscillations in the vertical

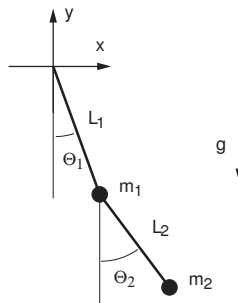


Figure 1: Double pendulum

$x, y$ -plane, as shown in Figure 1. Use the two angles  $\theta_1$  and  $\theta_2$  as generalized coordinates. Find the Lagrangian  $L = T - V$ , with  $T$  as the total kinetic energy and  $V$  as the potential energy, expressed as a function of  $\theta_1$ ,  $\theta_2$  and the time derivatives  $\dot{\theta}_1$  and  $\dot{\theta}_2$ .

### Problem 1.2

A body with mass  $m$  moves frictionlessly on an inclined plane, as shown in Fig-

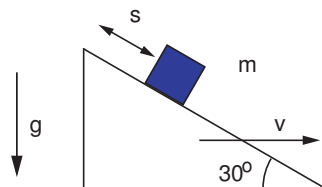


Figure 2: Motion on a moving inclined plane

ure 2. The plane is moving with a constant velocity  $v$  in the horizontal direction. Use the distance  $s$  that the body moves relative to the inclined plane as generalized

coordinate. Show that the body is subject to a time-dependent constraint, in the sense that the position vector of the body depends both on the generalized coordinate  $s$  and on time  $t$ ,  $\mathbf{r} = \mathbf{r}(s, t)$ . Find the Lagrangian  $L = T - V$  as a function of  $s$ ,  $\dot{s}$  and  $t$ .

**Problem 1.3**

An Atwood's fall machine consists of three parts with masses  $m_1$ ,  $m_2$  and  $m_3$ ,

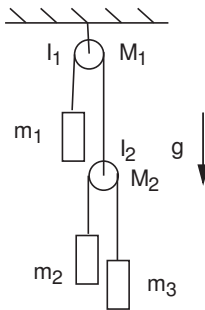


Figure 3: A fall machine

that move vertically, and two rotating pulleys, with moments of inertia about their centers  $I_1$  and  $I_2$ . The radii of the pulleys are  $r_1$  and  $r_2$ , and their masses  $M_1$  and  $M_2$ . Find the number of degrees of freedom of the composite system and choose appropriate generalized coordinates. Find the Lagrangian of the system as functions of the coordinates and their time derivatives. (Friction is neglected.)

**Problem 1.4**

A rotating top is set into motion on a horizontal floor. Count the number of

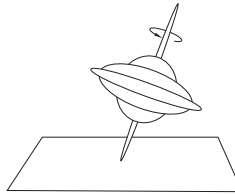


Figure 4: A rotating top

degrees of freedom of the top.

