



UiO : **Fysisk institutt**

Det matematisk-naturvitenskapelige fakultet

# Lecture 5



# Today

- Conservation of energy
  - From the time invariance of the Lagrangian
  - Introducing, for the very first time: the Hamiltonian!  
(or maybe not)
- More general Lagrangians
  - Adding a total time derivative (useful trick)
  - Allowing for velocity dependence in potential

# Recap

- With the Lagrange function

$$L(q, \dot{q}, t) = K(q, \dot{q}, t) - V(q, t)$$

we can find the equations of motion for the system from Lagrange's equation

$$\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}_i} \right) - \frac{\partial L}{\partial q_i} = 0, \quad i = 1, \dots, d$$

# Recap

- Cyclic coordinates are coordinates  $q_i$  that do not appear in the Lagrangian
- The corresponding **conjugate momentum**  $p_i$  is conserved

$$p_i \equiv \frac{\partial L}{\partial \dot{q}_i}$$

- If  $Q$  is the parameter of a transformation leaving the Lagrangian invariant the conserved quantity  $K$  is

$$K = \sum_i \frac{\partial L}{\partial \dot{q}_i} Q_i$$

# Summary

- The Hamiltonian  $H$  for a Lagrangian with no explicit time dependence is a constant of motion

$$H = \sum_i \frac{\partial L}{\partial \dot{q}_i} \dot{q}_i - L$$

- When constraints are time-independent the Hamiltonian is given by  $H = K+V$ .
- Total time derivative terms in the Lagrangian can be ignored.
- For velocity dependent potentials (forces)

$$F_j = \frac{d}{dt} \left( \frac{\partial U}{\partial \dot{q}_i} \right) - \frac{\partial U}{\partial q_i}$$