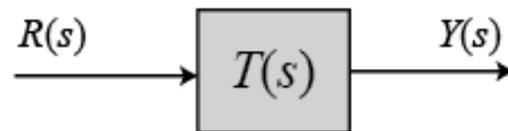


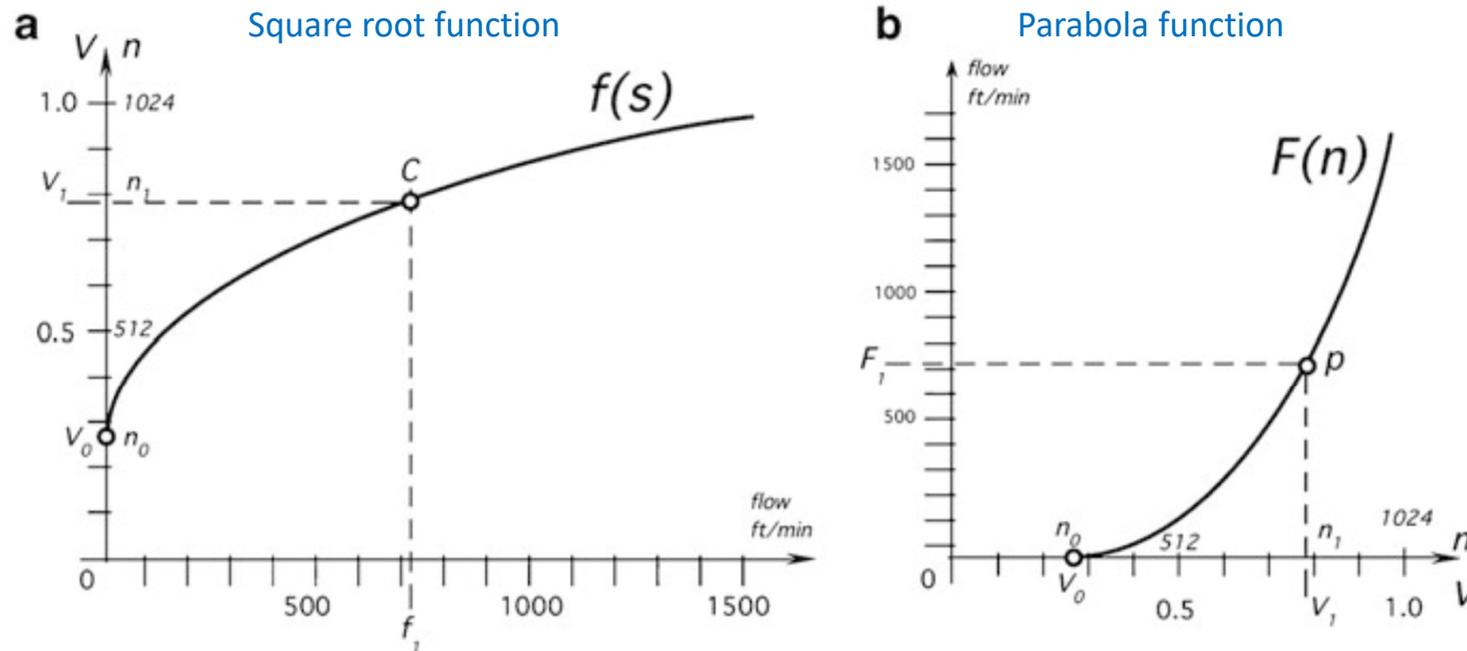
# Transfer functions

FYS 3231 /4231



# Thermo-anemometer

- Finn overføringsfunksjonen (transferfunksjonen)
- Inverter den for å bruke sensoren i reelle målinger



**Fig. 2.1** Transfer function (a) and inverse transfer function (b) of thermo-anemometer

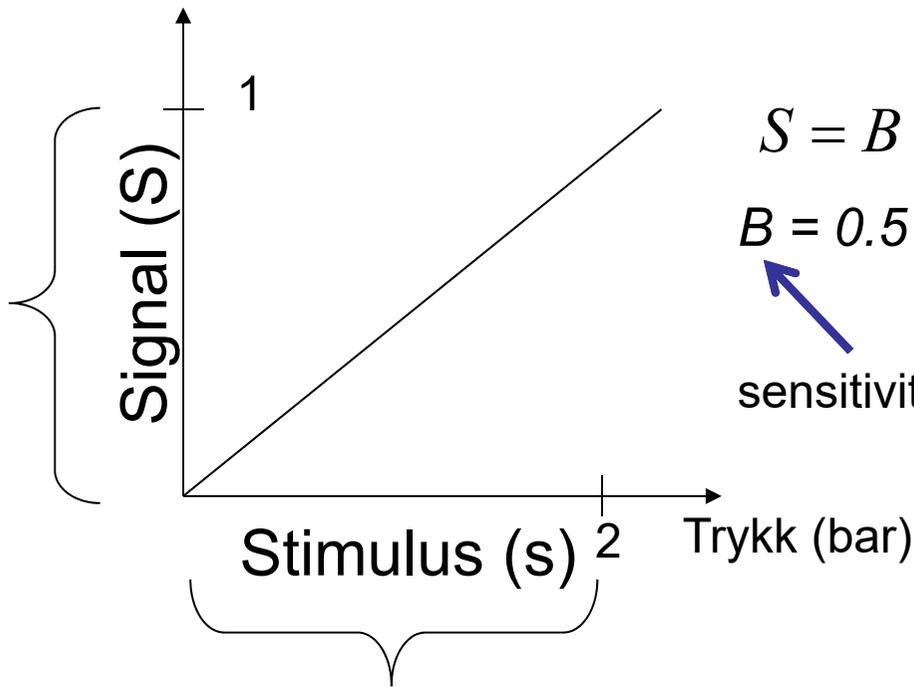
# Lineær respons

$$S = S_0 + B(s - s_0)$$

Hvis det er vanskelig  
å teste ved  $s = 0$  (f.eks.  
et kelvin-termometer)

Full Scale Output : 1V

Spenning (V)



$$S = B \cdot s$$

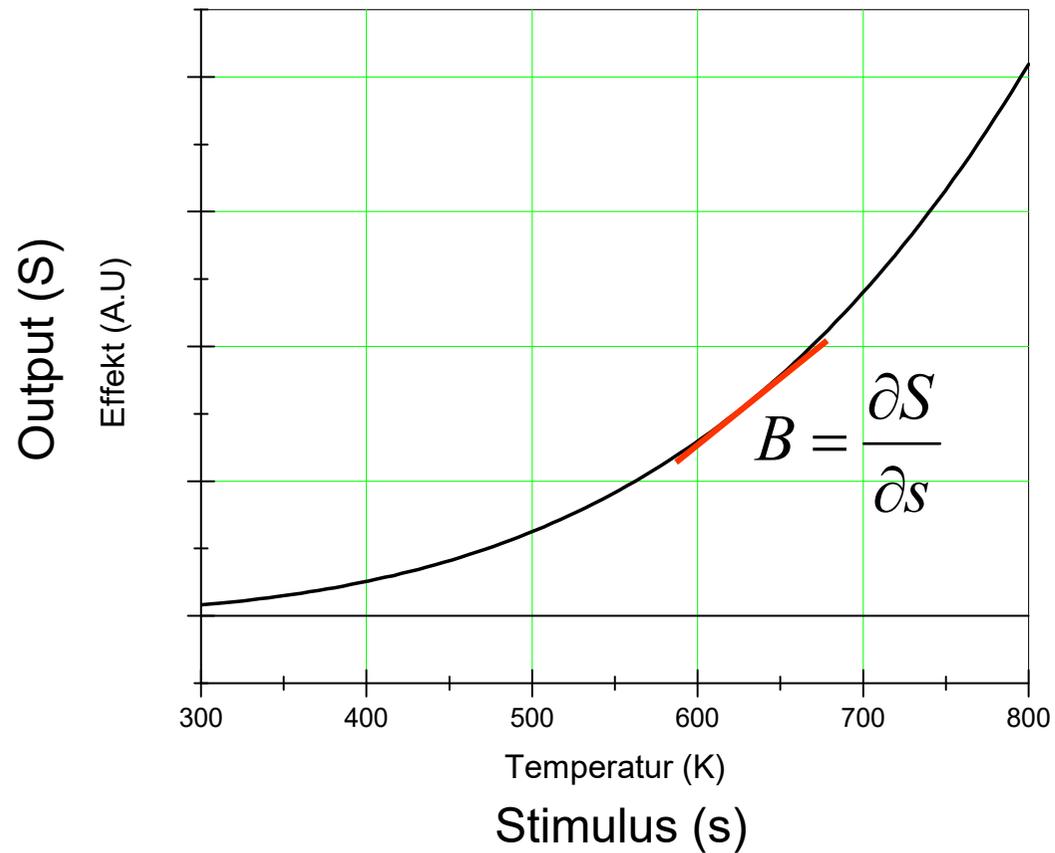
$$B = 0.5 \text{ V/bar}$$

sensitivitet

Full Scale Input : 2 bar

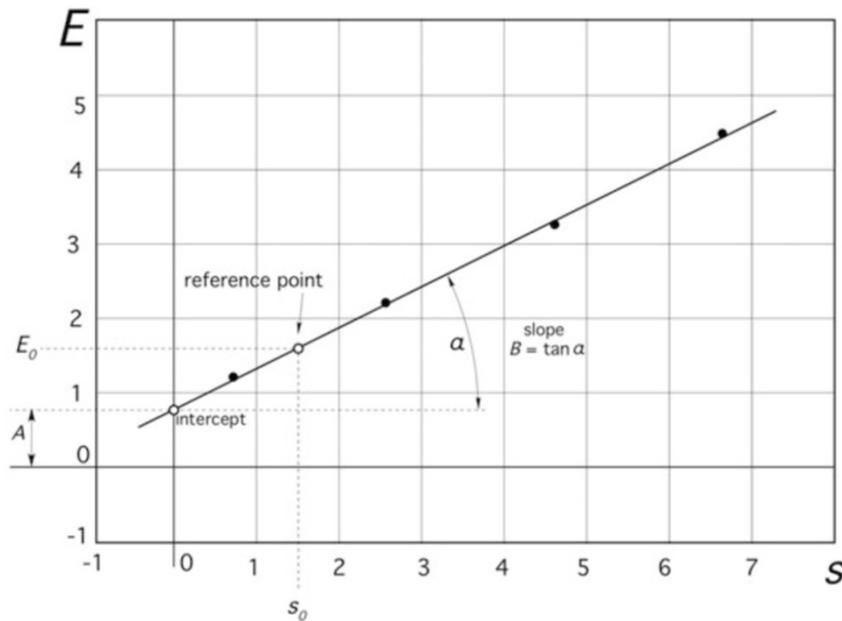
Ekspensielle  
Logaritmiske  
Power-functions

# Følsomhet / sensitivitet

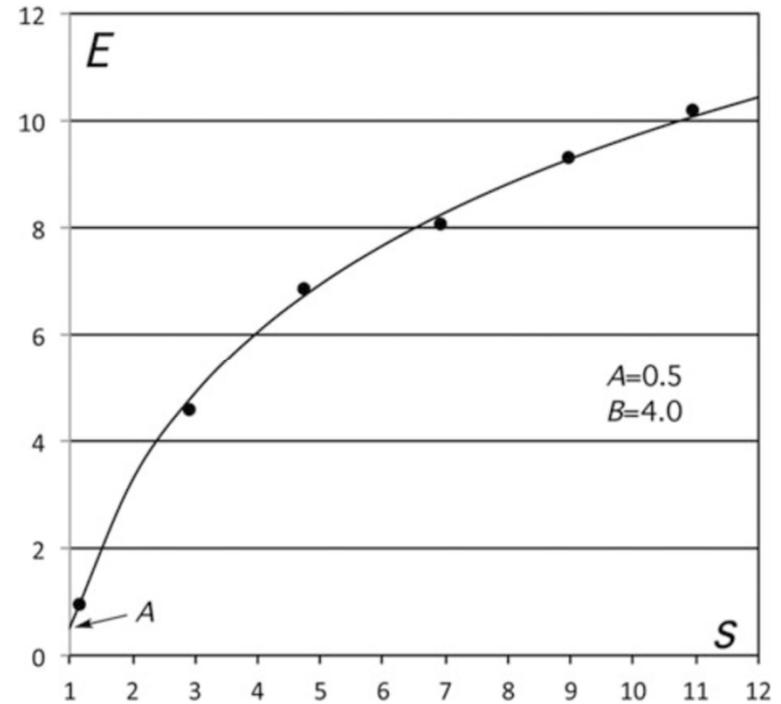


# Kurvfitpasning

**Fig. 2.3** Approximation by logarithmic function. *Dots* indicate experimental data



**Fig. 2.2** Linear transfer function. *Black dots* indicate experimental data

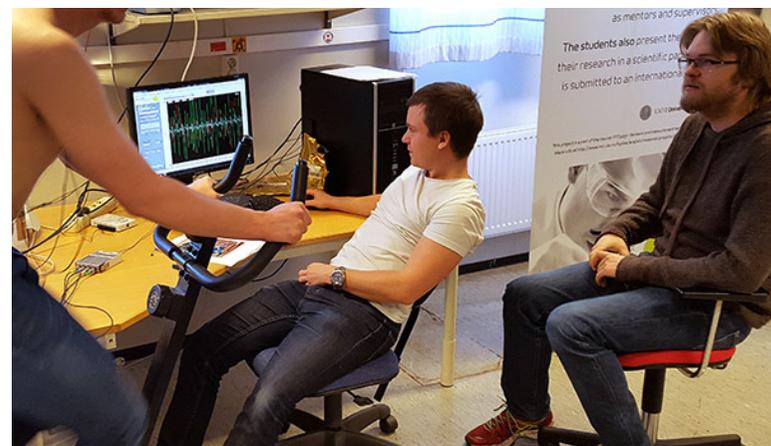
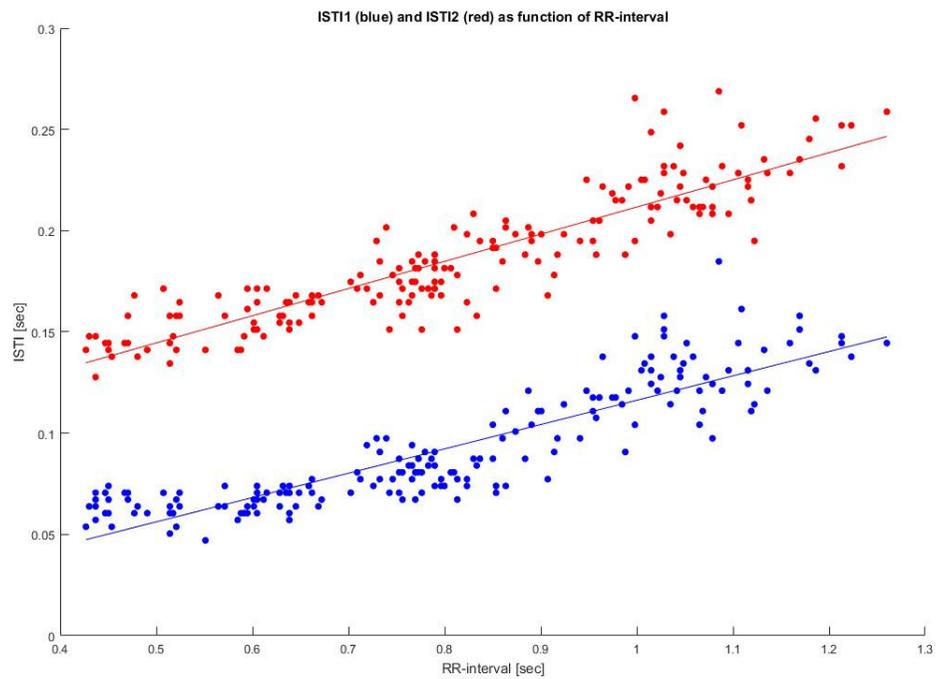
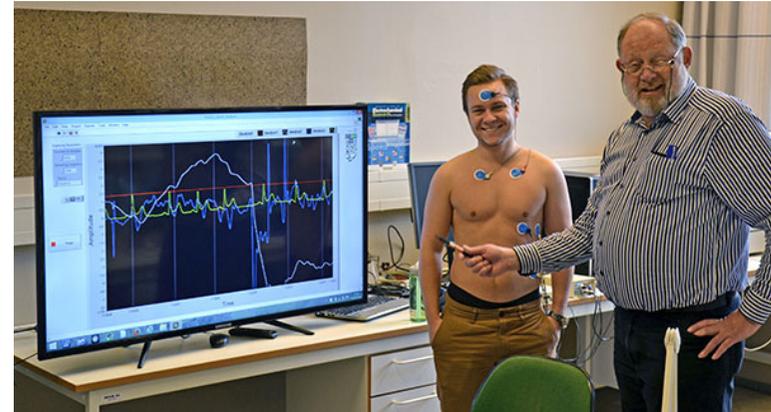
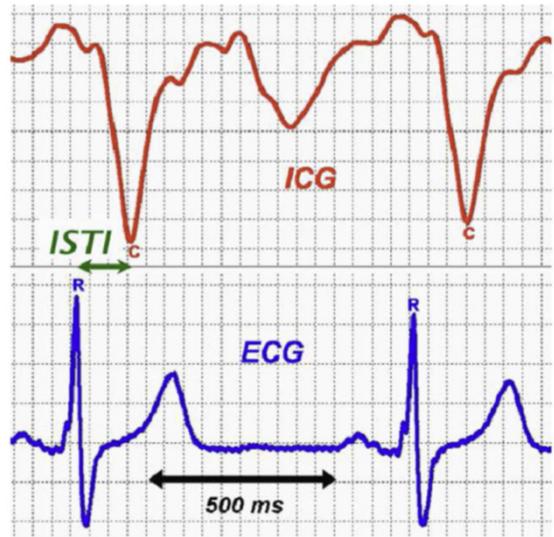


sensitivity  
↓

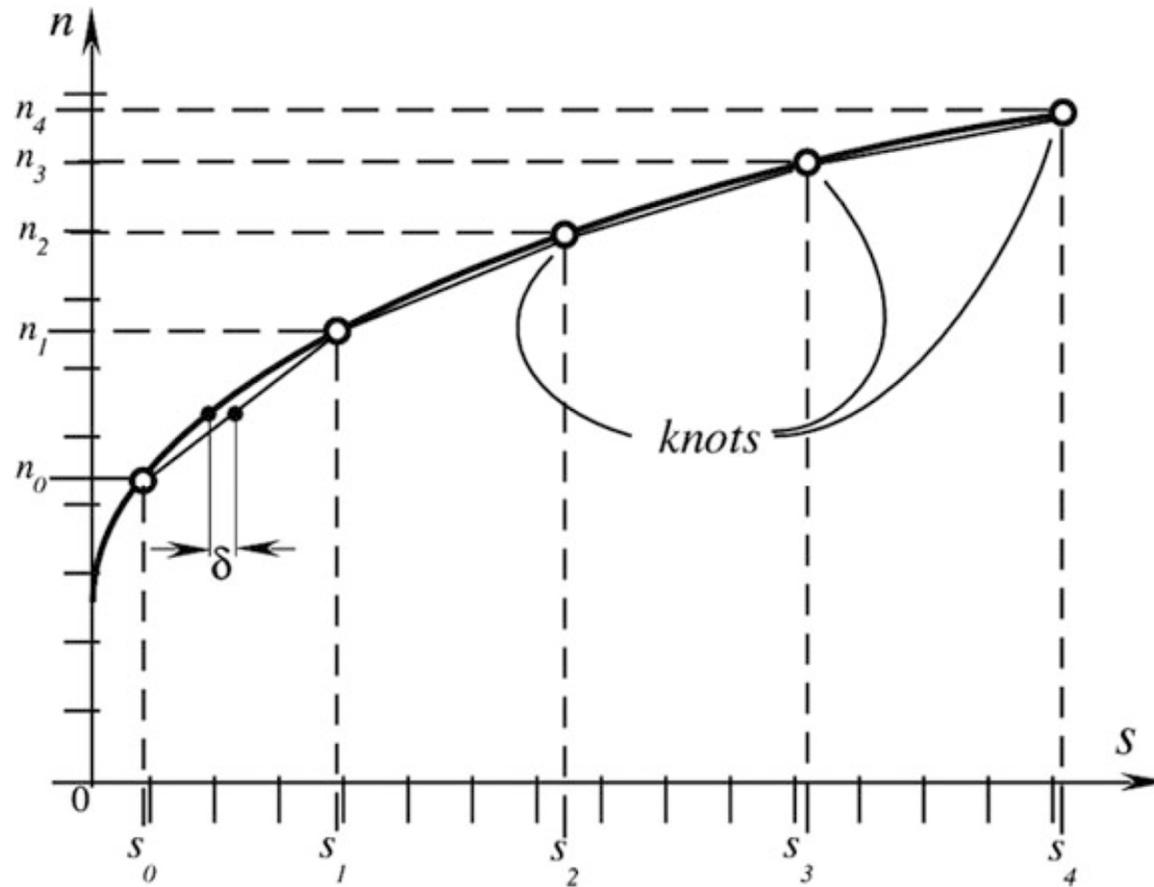
$$E = A + B \ln s,$$

$$s = e^{\frac{E-A}{B}},$$

# ICG (Sensorama 2015)



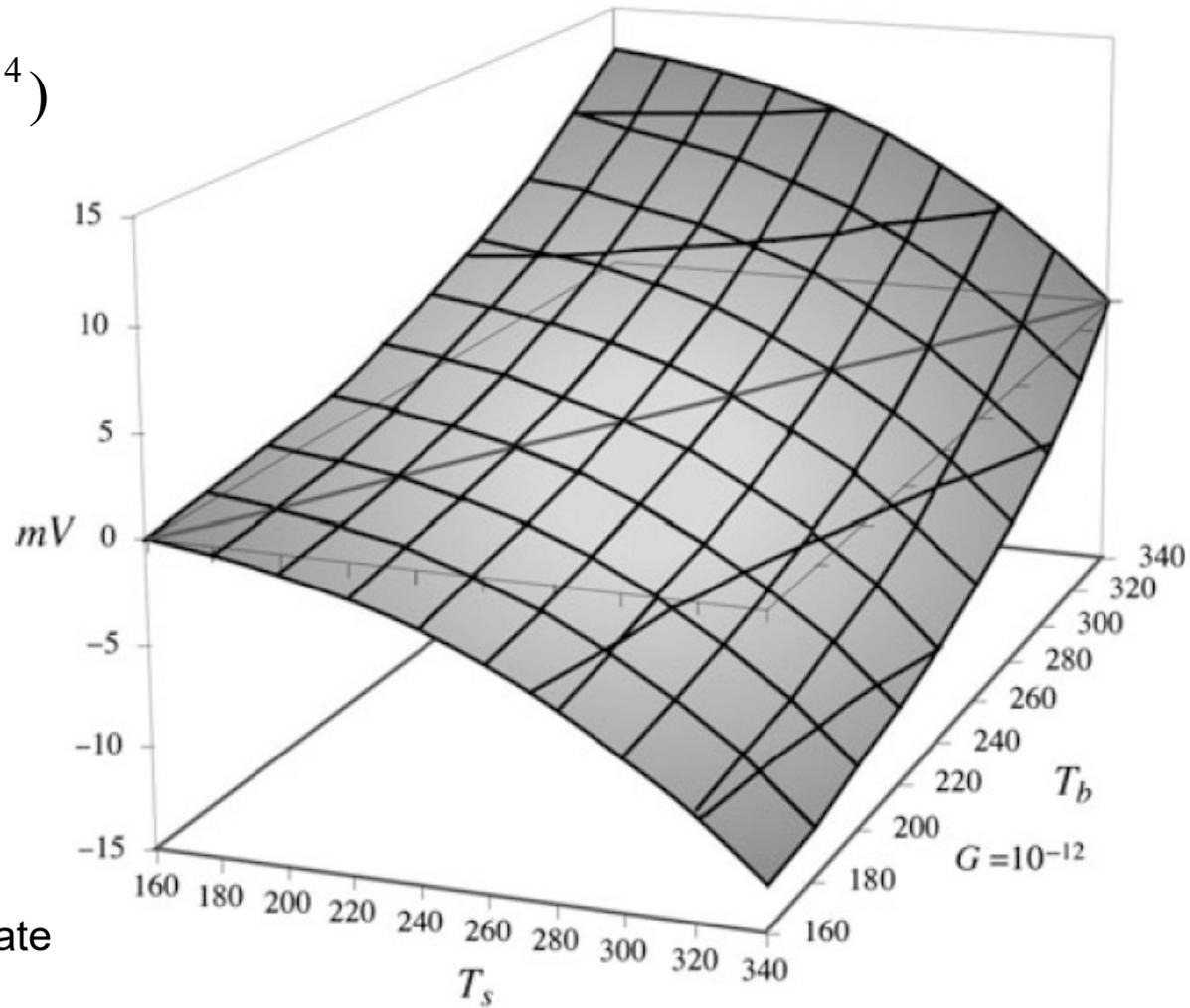
# Linear piecewise approximation



**Fig. 2.6** Linear piecewise approximation

# Multidimensjonale transferfunksjoner

$$V = G(T_b^4 - T_s^4)$$



T<sub>s</sub> = sensoroverflate  
T<sub>b</sub> = objekt

**Fig. 2.3** Two-dimensional transfer function of a thermal radiation sensor

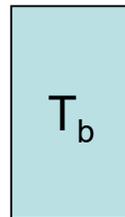
# Ekspontiell respons - pyrometer

Utstrålt effekt

$$V = G(T_b^4 - T_s^4)$$

Følsomhet

$$B = \frac{\partial V}{\partial T_b} = 4GT_b^3$$



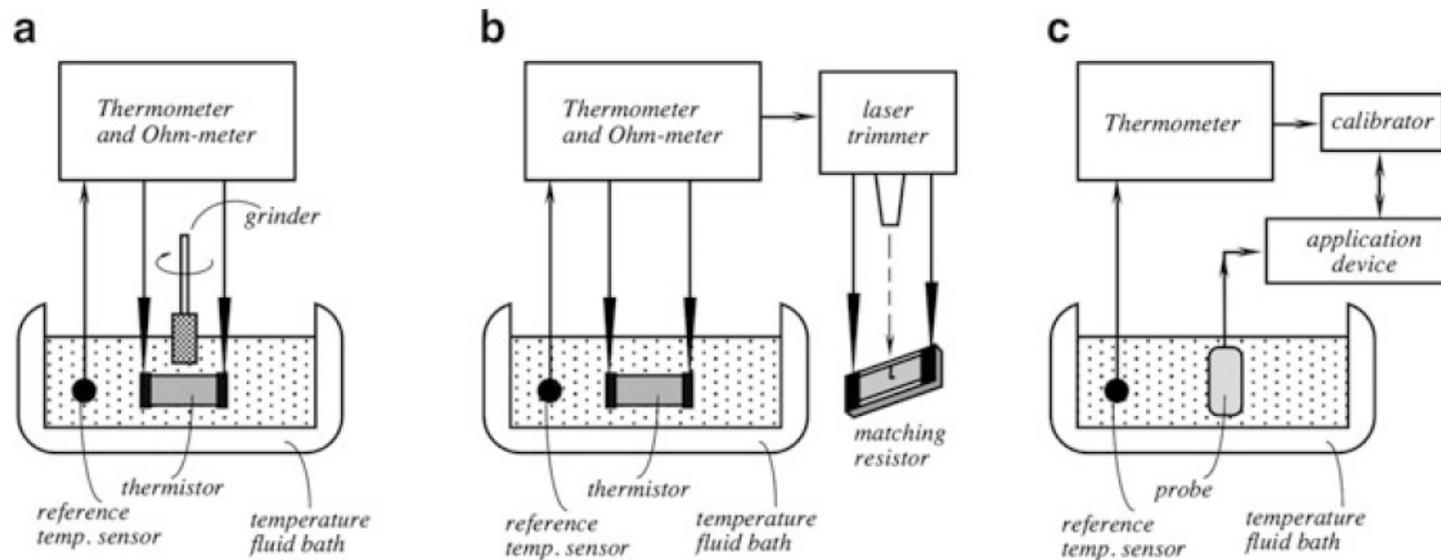
Pyrometer's  
**EMISSIVITY  
CALCULATOR**

Determine true temperature  
with Pyrometer's exclusive  
ePyroCal Emissivity Calculator.  
**Click here >>**

[www.pyrometer.com](http://www.pyrometer.com)

# Kalibrering – finne transferfunksjonen

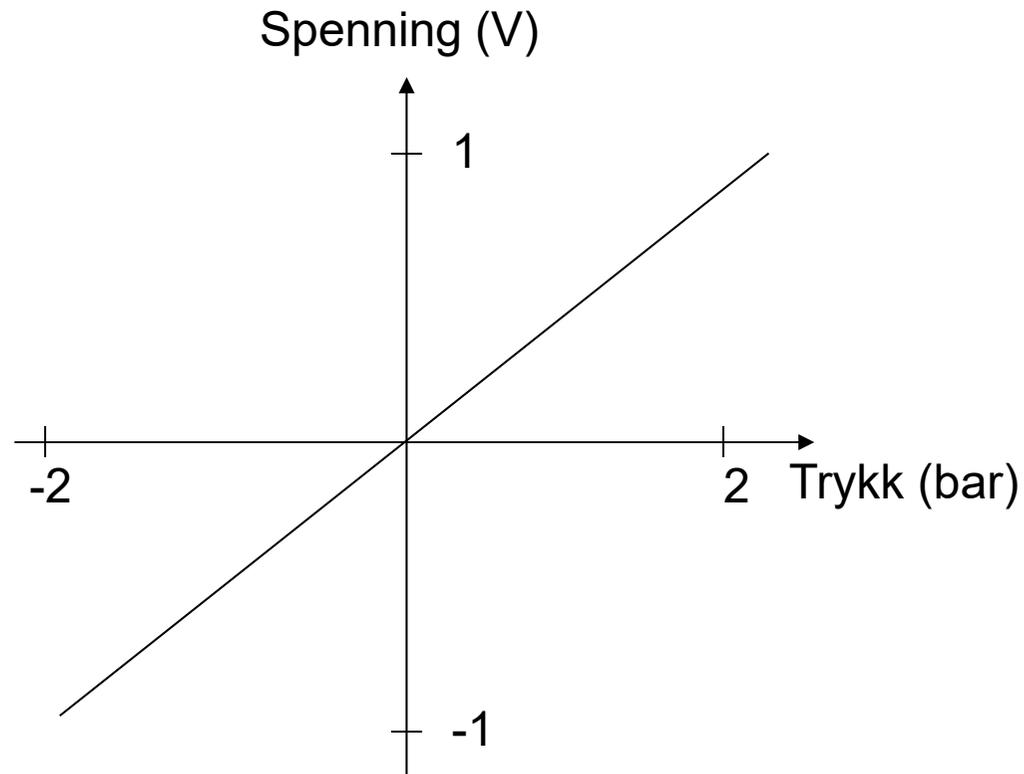
1. Calculation of the transfer function or its approximation to fit the selected calibration points (curve fitting by computing coefficients of a selected approximation).
2. Adjustment of the data acquisition system to trim (modify) the measured data by making them to fit into a normalized or “ideal” transfer function. An example is scaling of the acquired data.
3. Modification (trimming) of the sensor’s properties to fit the predetermined transfer function.
4. Creating a sensor-specific reference device with matching properties at particular calibrating points.



**Fig. 2.4** Calibrations of a thermistor: grinding (a), trimming of a reference resistor (b), calculating the transfer function (c)

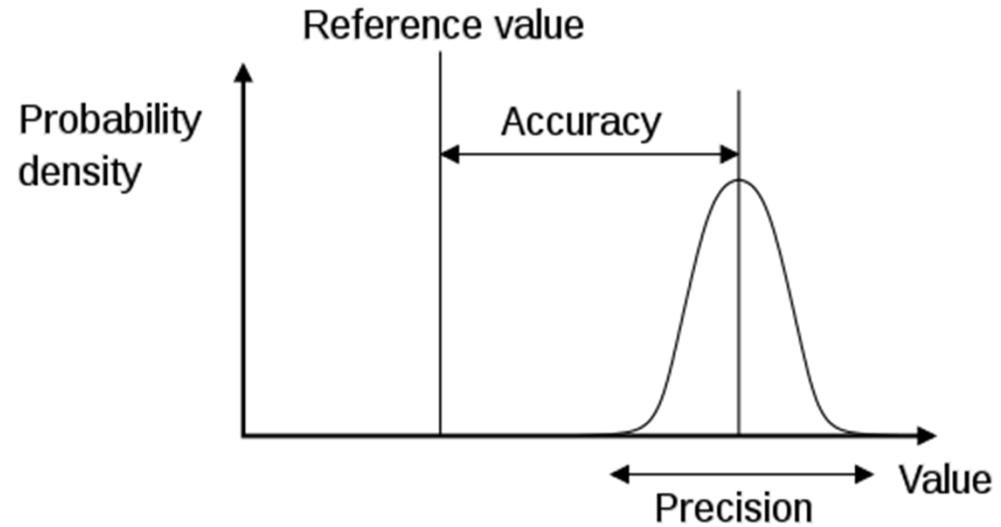
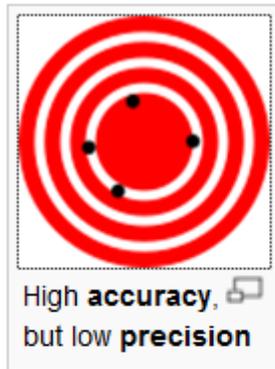
# Span og range

Output range  $\pm 1V$   
Output span 2V



Input range:  $\pm 2$  bar  
Input span: 4 bar

# Nøyaktighet og presisjon



[http://en.wikipedia.org/wiki/Accuracy\\_and\\_precision](http://en.wikipedia.org/wiki/Accuracy_and_precision)

# Nøyaktighet

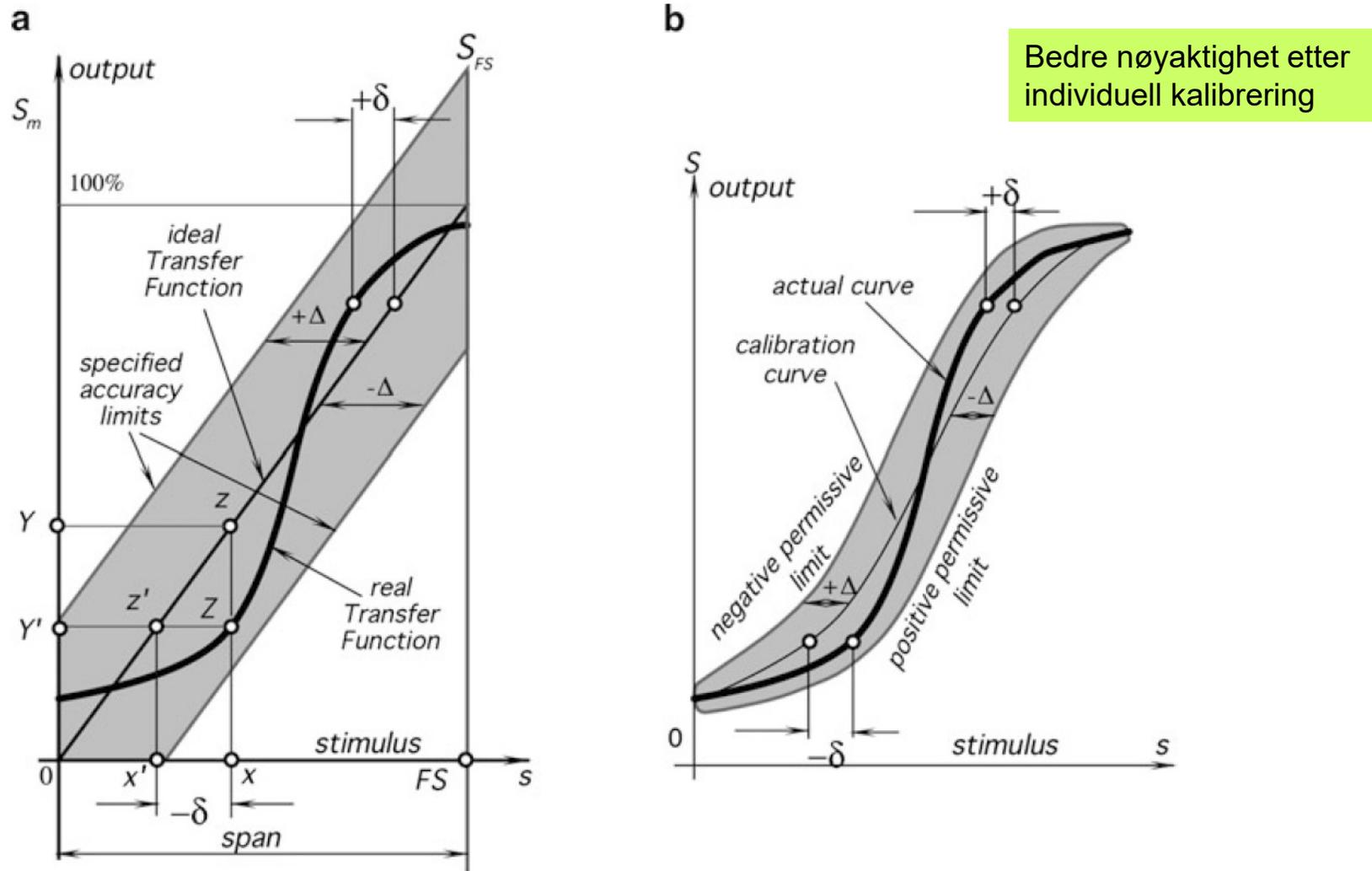


Fig. 2.9 Transfer function (a) and accuracy limits (b). Error is specified in terms of input values

# Kalibreringsfeil

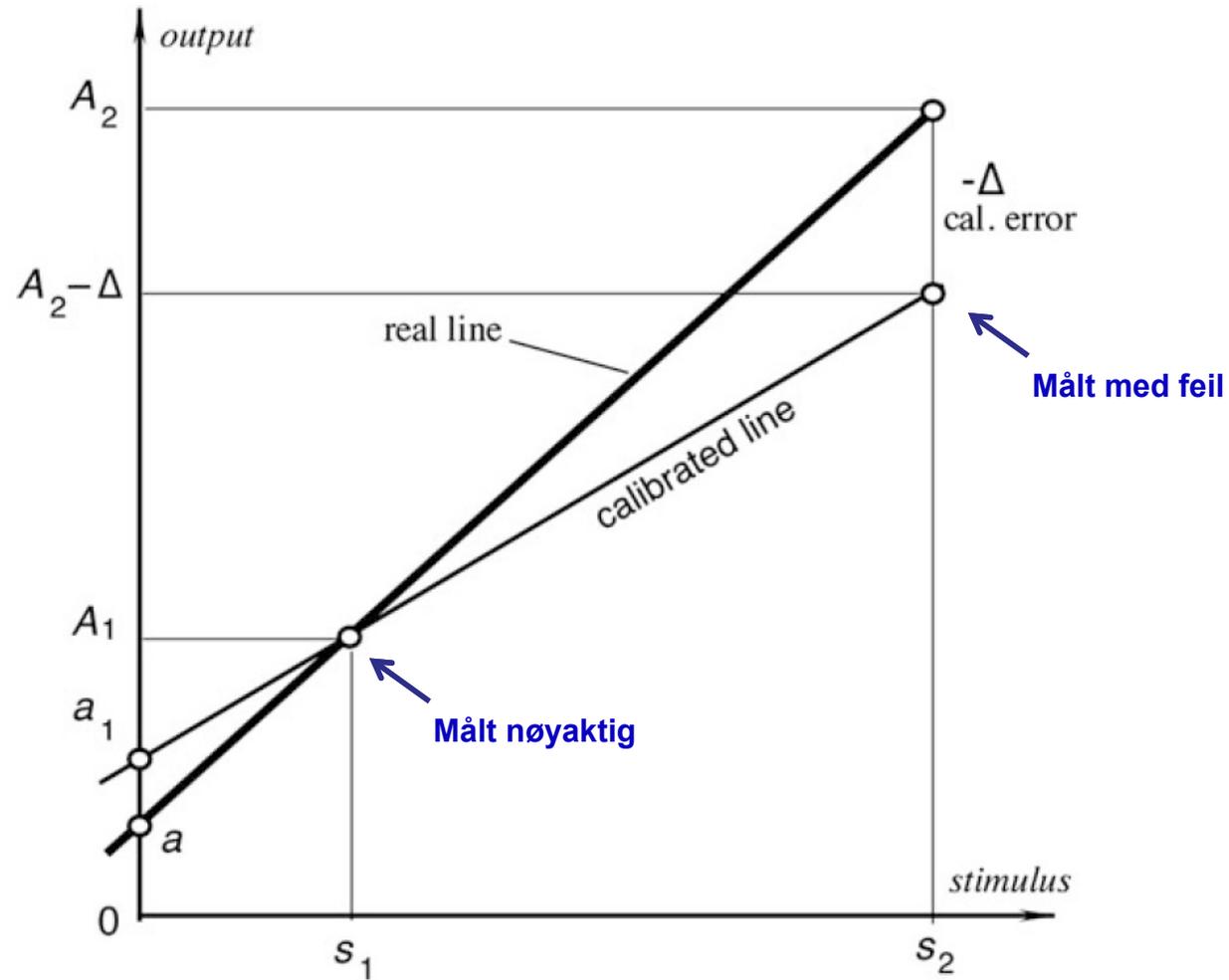
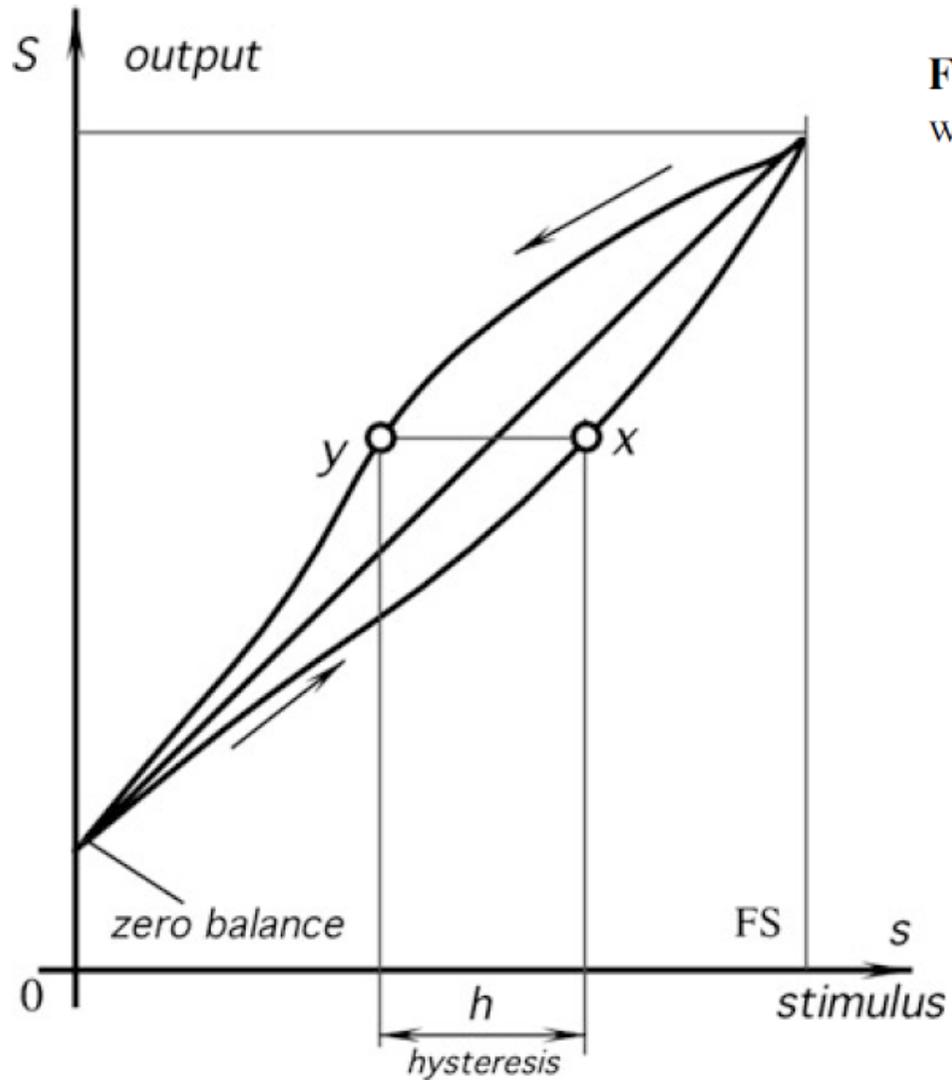


Fig. 2.10 Calibration error

# Hysteresis



**Fig. 2.11** Transfer function with hysteresis

# Chua lectures by HP



## Leon Chua Lecture #3

September 22, 2015

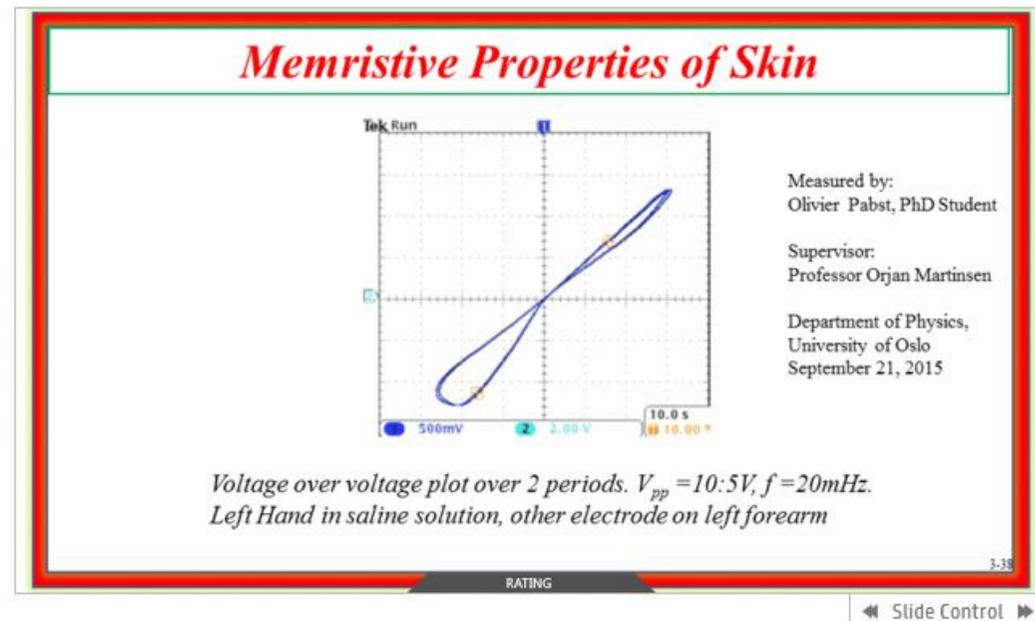


18:33 / 1:30:19

Quality 600k

Table of contents

- Memristor is defined by a State - Dependence
- Memristor does not store energy
- The Ideal Memristor does not have a DC V-I
- Some Memristor Circuits have Hamiltonian
- Not all Hamiltonian Systems are Conservative



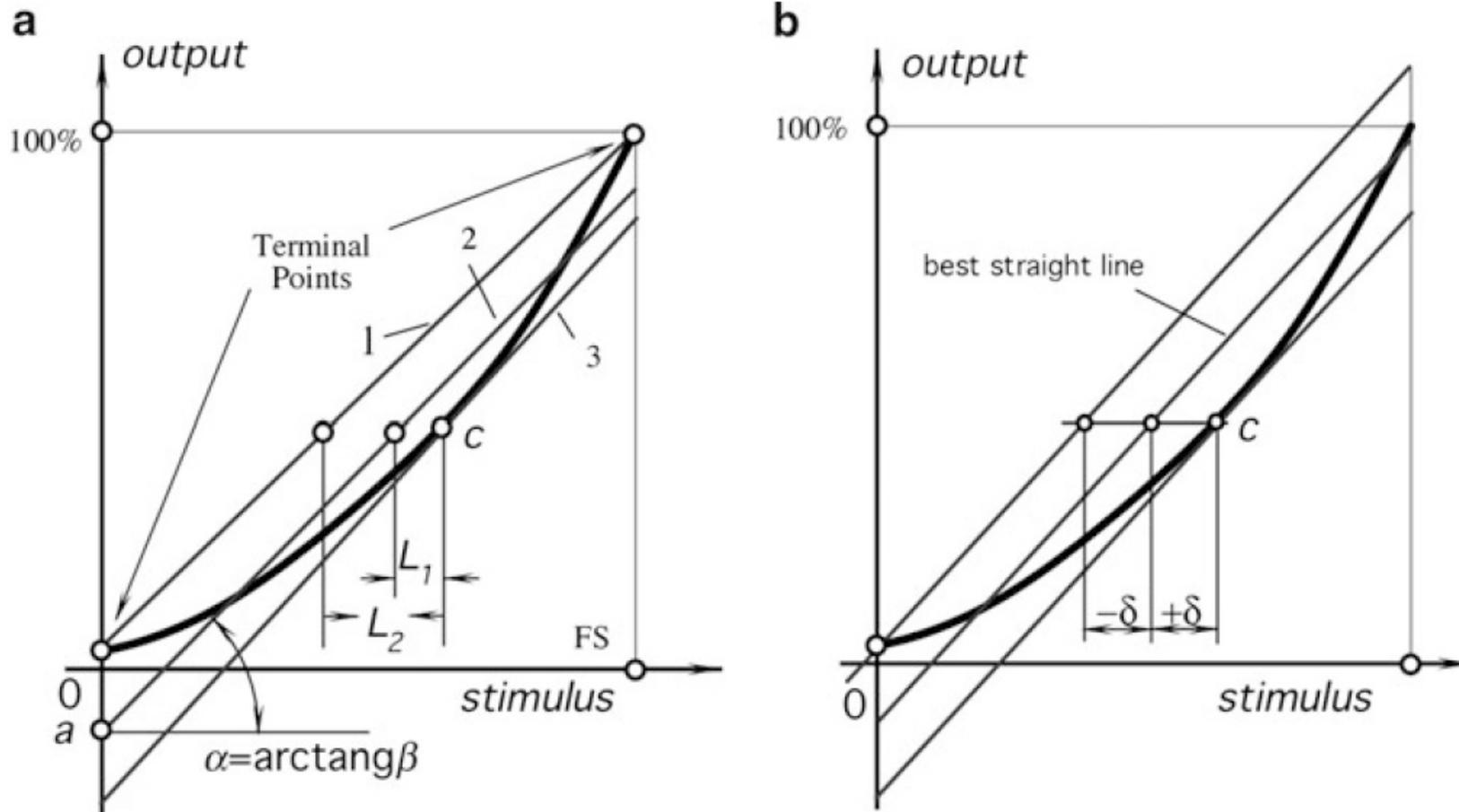
Data by Oliver Pabst

# Ulinearitet

Måles ved endepunktene.  
Linja kan flyttes for å oppnå  
bedre nøyaktighet i ønsket område  
(eks. febertermometer)

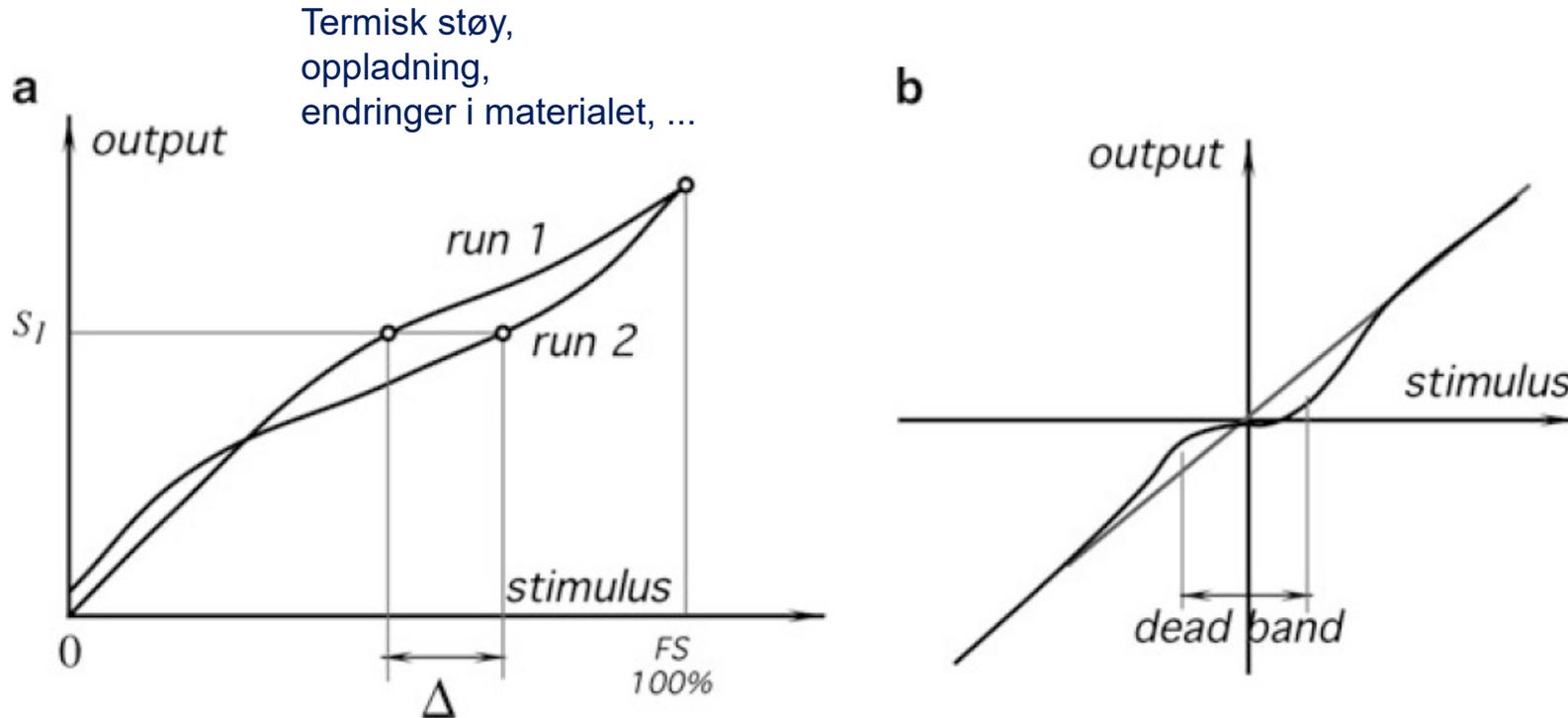
(for sensorer hvor det antas linearitet)

Best straight line  
Independent linearity



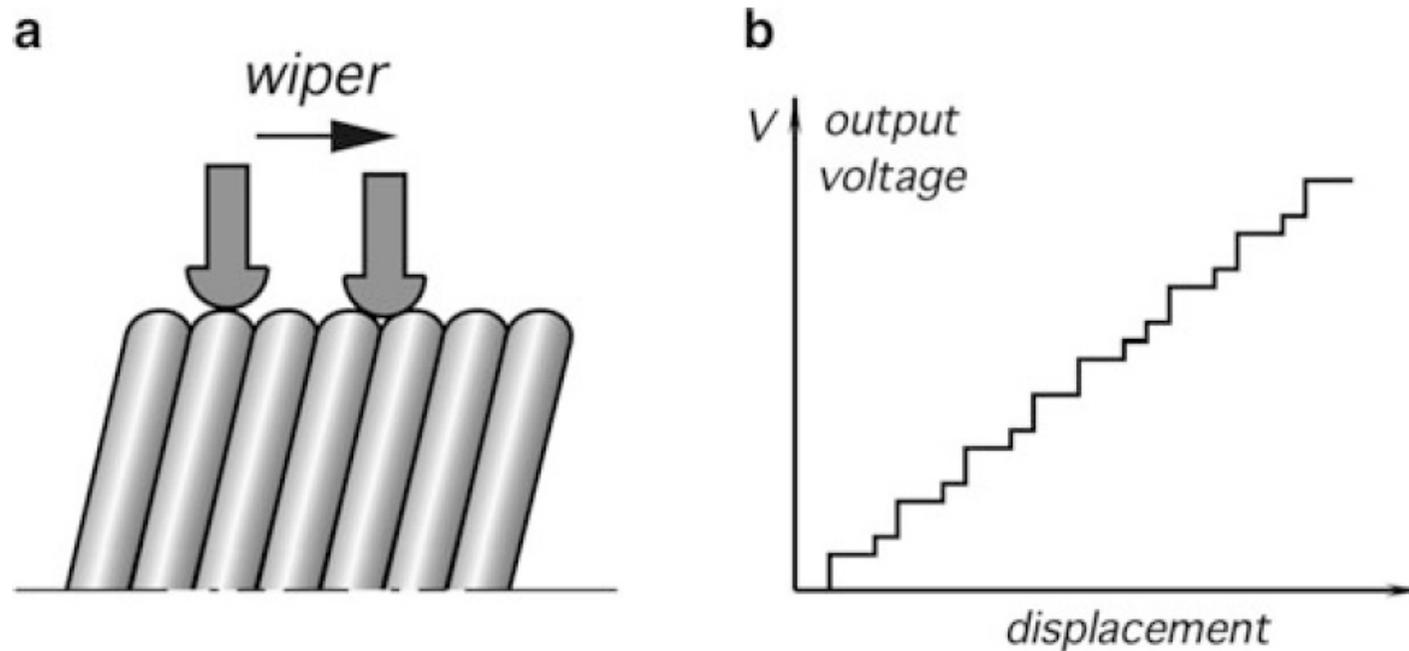
**Fig. 2.12** Linear approximations of a nonlinear transfer function (a); and independent linearity; (b)

# Repeteterbarhet / dødbånd



**Fig. 2.14** Repeatability error (a). The same output signal  $S_1$  corresponds to two different input signals Dead-band zone in a transfer function (b)

# Oppløsning - fysisk



**Fig. 7.2** Uncertainty caused by wire-wound potentiometer A wiper may contact one or two wires at a time (a); uneven voltage steps (b)

# Oppløsning - støybegrenset

**Fig. 5.45** Types of noise  
noise-free signal (a); additive  
noise (b); multiplicative  
noise (c)

