

# Sensor characteristics

FYS3231/4231

# Mobile technology



## Typical smartphone today:

Imaging camera—takes still photo and video.

Microphone—detects sound mostly in the audible frequency range.

Accelerometer—detects motion of the MCD and direction of the gravity force.

Gyroscope—measures spatial orientation of the MCD.

Magnetometer (compass)—detects strength and direction of magnetic fields.

GPS—an RF receiver and processor for identifying global coordinates.

Proximity detector—detects closeness of the MCD to the user's body.

## Emerging application areas

*Industrial* for detecting noncontact temperature, thermal imaging, humidity, air flow, ionizing radiation, smell, dielectric constant of objects, material composition, range (distance), air pressure, produce freshness, etc.

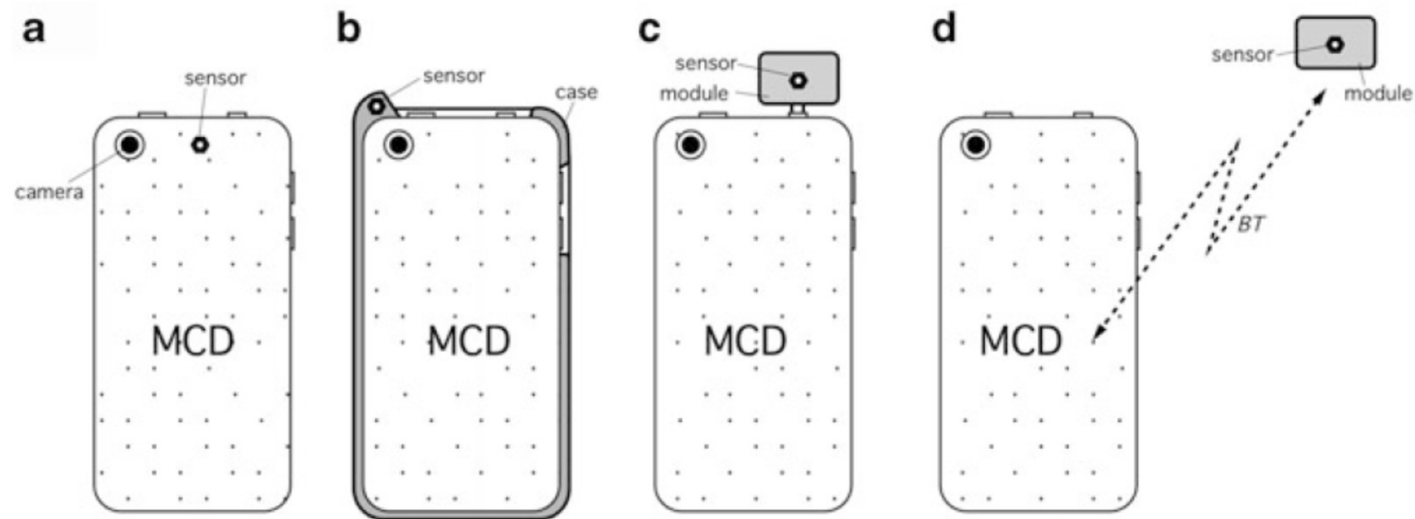
*Medical* for the inner (core) and skin body temperatures, thermal imaging, arterial blood pressure, EKG, blood factors (glucose, cholesterol, hemoglobin oxygen saturation), deep body imaging, smell (e-nose), behavior modification, etc.

*Military* for night vision, detecting poisonous gases, proximity, ionizing radiation, explosives, chemical and biological agents, etc.

*Consumer* for the body core temperature, heart rate, radon gas, pregnancy detection, breathalyzer for alcohol and hydrogen sulfide, food composition, behavior modification, proximity, UV level, electromagnetic pollution, surface temperature, etc.

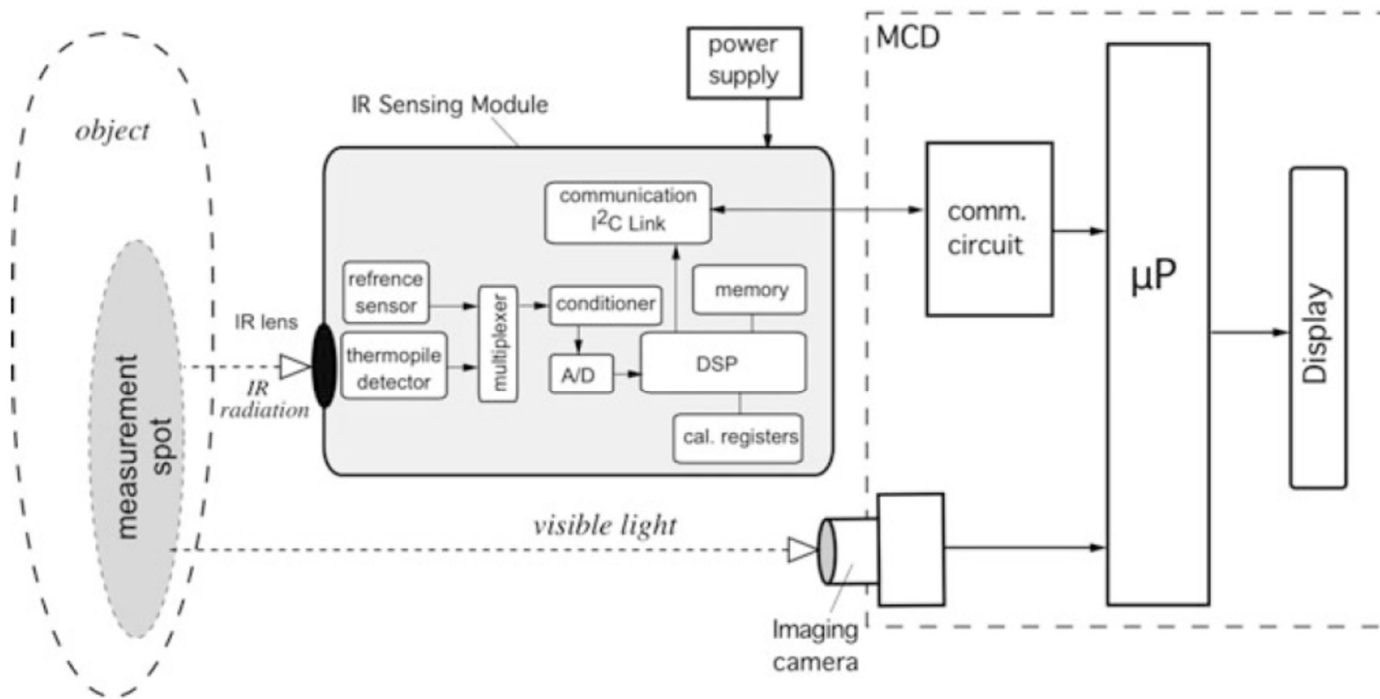
**Table 3.1** “10 Commandments” of mobile sensor design

1	Intelligent sensor: built-in signal conditioner and DSP
2	Built-in communication circuit ( $I^2C$ , NFC, Bluetooth, etc.)
3	Integrated supporting components (optics, thermostat, blower, etc.)
4	High selectivity of the sensed signal (reject interferences)
5	Fast response
6	Miniature size to fit a mobile device
7	Low power consumption
8	High stability in changing environment
9	Lifetime stability: no periodic recalibration or replacement
10	Low cost at sufficiently high volumes



**Fig. 3.1** Four possible ways of coupling sensing module to mobile communication device

# IR-sensor for mobile unit















**Fig. 3.2** Block-diagram of thermal radiation (IR) sensing module for MCD

# Matematiske modeller

Les selv ...

**Table 3.4** Mechanical, thermal, and electrical analogies

Kirchhoffs lover

Mechanical	Thermal	Electrical	
Mass  $F = M \frac{d(v)}{dt}$	Capacitance  $C$ $Q = C \frac{dT}{dt}$	Inductor  $L$ $V = L \frac{di}{dt}$	Capacitor  $i = C \frac{dV}{dt}$
Spring  $k$ $F = k \int v dt$	Capacitance  $C$ $T = \frac{1}{C} \int Q dt$	Capacitor  $C$ $V = \frac{1}{C} \int i dt$	Inductor  $L$ $i = \frac{1}{L} \int V dt$
Damper  $b$ $F = bv$	Resistance  $R$ $Q = \frac{1}{R} (T_2 - T_1)$	Resistor  $R$ $V = Ri$	Resistor  $R$ $i = \frac{1}{R} V$

Eks 1: Innkapslet varme-element:  $\frac{dT_h}{dt} + \frac{T_h}{rC} = \frac{Q_1}{C} + \frac{T_a}{rC}$

Eks 2: Masse, fjær demper (akselerometer):  $M \frac{d^2x}{dt^2} + b \frac{dx}{dt} + kx = M \frac{d^2y}{dt^2}$