

Problem set 3

3.1 Spin operators and Pauli matrices

a) We set $\mathbf{n} = (n_1, n_2, n_3)$, then

$$\mathbf{n} \cdot \boldsymbol{\sigma} = n_1 \sigma_1 + n_2 \sigma_2 + n_3 \sigma_3 = \begin{pmatrix} n_3 & n_1 - in_2 \\ n_1 + in_2 & -n_3 \end{pmatrix} \quad (1)$$

The eigenvalue equation is:

$$\det(\sigma_{\mathbf{n}} - \lambda \mathbb{1}) = 0 \Rightarrow \det \begin{pmatrix} n_3 - \lambda & n_1 - in_2 \\ n_1 + in_2 & -n_3 - \lambda \end{pmatrix} = 0$$

$$\begin{aligned} -(n_3 - \lambda)(n_3 + \lambda) - |n_1 + in_2|^2 &= 0 \\ \Rightarrow -n_3^2 + \lambda^2 - (n_1^2 + n_2^2) &= 0 \\ \Rightarrow \lambda^2 &= n_1^2 + n_2^2 + n_3^2 \\ \Rightarrow \lambda &= \pm |\mathbf{n}|^2 = \pm 1 \end{aligned}$$

The corresponding eigenstate equation for $\lambda = 1$ is:

$$\sigma_{\mathbf{n}} \Psi_{\mathbf{n}} = \Psi_{\mathbf{n}}$$

By switching to spherical coordinates, we get $\mathbf{n} = (n_1, n_2, n_3) = (\cos \phi \sin \theta, \sin \phi \sin \theta, \cos \theta)$. Inserting this into the matrix (1), the equation gets the form:

$$\begin{pmatrix} \cos \theta & (\cos \phi - i \sin \phi) \sin \theta \\ (\cos \phi + i \sin \phi) \sin \theta & -\cos \theta \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} = \begin{pmatrix} \cos \theta & e^{-i\phi} \sin \theta \\ e^{i\phi} \sin \theta & -\cos \theta \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} = \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix}$$

Which corresponds to these equations:

$$\begin{aligned} \psi_1 \cos \theta + \psi_2 e^{-i\phi} \sin \theta &= \psi_1 \\ \psi_1 e^{i\phi} \sin \theta - \psi_2 \cos \theta &= \psi_2 \end{aligned}$$

We need to solve one of them, I'm choosing the second, where I get the relation:

$$\frac{e^{i\phi} \sin \theta}{1 + \cos \theta} \psi_1 = \psi_2$$

Then:

$$\frac{e^{i\phi} \sin \theta}{1 + \cos \theta} = \frac{e^{i\phi} 2 \sin \frac{\theta}{2} \cos \frac{\theta}{2}}{\cos^2 \frac{\theta}{2} + \sin^2 \frac{\theta}{2} + \cos^2 \frac{\theta}{2} - \sin^2 \frac{\theta}{2}} = \frac{e^{i\phi} \sin \frac{\theta}{2}}{\cos \frac{\theta}{2}}$$

This gives us the relation:

$$e^{i\phi} \sin \frac{\theta}{2} \psi_1 = \psi_2 \cos \frac{\theta}{2}$$

This is true for $\psi_1 = \cos \frac{\theta}{2}$ and $\psi_2 = e^{i\phi} \sin \frac{\theta}{2}$, which defines the eigenvectors for $\lambda = 1$:

$$\Psi_{\mathbf{n}} = \begin{pmatrix} \cos \frac{\theta}{2} \\ e^{i\phi} \sin \frac{\theta}{2} \end{pmatrix}$$

For $\Psi_{\mathbf{n}}^\dagger \sigma \Psi_{\mathbf{n}} = \mathbf{n}$, we get:

$$\Psi_{\mathbf{n}}^\dagger \sigma \Psi_{\mathbf{n}} = \left(\Psi_{\mathbf{n}}^\dagger \sigma_1 \Psi_{\mathbf{n}}, \Psi_{\mathbf{n}}^\dagger \sigma_2 \Psi_{\mathbf{n}}, \Psi_{\mathbf{n}}^\dagger \sigma_3 \Psi_{\mathbf{n}} \right)$$

$$\begin{aligned} \Psi_{\mathbf{n}}^\dagger \sigma_1 \Psi_{\mathbf{n}} &= \left(\cos \frac{\theta}{2}, e^{-i\phi} \sin \frac{\theta}{2} \right) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} \cos \frac{\theta}{2} \\ e^{i\phi} \sin \frac{\theta}{2} \end{pmatrix} \\ &= \left(\cos \frac{\theta}{2}, e^{-i\phi} \sin \frac{\theta}{2} \right) \begin{pmatrix} e^{i\phi} \sin \frac{\theta}{2} \\ \cos \frac{\theta}{2} \end{pmatrix} \\ &= e^{i\phi} \sin \frac{\theta}{2} \cos \frac{\theta}{2} + e^{-i\phi} \sin \frac{\theta}{2} \cos \frac{\theta}{2} \\ &= \frac{1}{2} \sin \theta \left(e^{i\phi} + e^{-i\phi} \right) \\ &= \cos \phi \sin \theta = n_1 \end{aligned}$$

$$\begin{aligned} \Psi_{\mathbf{n}}^\dagger \sigma_2 \Psi_{\mathbf{n}} &= \left(\cos \frac{\theta}{2}, e^{-i\phi} \sin \frac{\theta}{2} \right) \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} \cos \frac{\theta}{2} \\ e^{i\phi} \sin \frac{\theta}{2} \end{pmatrix} \\ &= \left(\cos \frac{\theta}{2}, e^{-i\phi} \sin \frac{\theta}{2} \right) \begin{pmatrix} -ie^{i\phi} \sin \frac{\theta}{2} \\ i \cos \frac{\theta}{2} \end{pmatrix} \\ &= i \left(-e^{i\phi} \sin \frac{\theta}{2} \cos \frac{\theta}{2} + e^{-i\phi} \sin \frac{\theta}{2} \cos \frac{\theta}{2} \right) \\ &= \frac{1}{2} i \sin \theta \left(e^{-i\phi} - e^{i\phi} \right) \\ &= -i^2 \sin \theta \sin \phi = n_2 \end{aligned}$$

$$\begin{aligned} \Psi_{\mathbf{n}}^\dagger \sigma_3 \Psi_{\mathbf{n}} &= \left(\cos \frac{\theta}{2}, e^{-i\phi} \sin \frac{\theta}{2} \right) \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} \cos \frac{\theta}{2} \\ e^{i\phi} \sin \frac{\theta}{2} \end{pmatrix} \\ &= \left(\cos \frac{\theta}{2}, e^{-i\phi} \sin \frac{\theta}{2} \right) \begin{pmatrix} \cos \frac{\theta}{2} \\ -e^{i\phi} \sin \frac{\theta}{2} \end{pmatrix} \\ &= \cos^2 \frac{\theta}{2} - e^{-i\phi} e^{i\phi} \sin^2 \frac{\theta}{2} \\ &= \cos \theta = n_3 \end{aligned}$$

Thus:

$$\Psi_{\mathbf{n}}^\dagger \sigma \Psi_{\mathbf{n}} = \left(\Psi_{\mathbf{n}}^\dagger \sigma_1 \Psi_{\mathbf{n}}, \Psi_{\mathbf{n}}^\dagger \sigma_2 \Psi_{\mathbf{n}}, \Psi_{\mathbf{n}}^\dagger \sigma_3 \Psi_{\mathbf{n}} \right) = (n_1, n_2, n_3) = \mathbf{n}$$

b)

$$e^{-\frac{i}{2}\alpha\sigma_z} \sigma_x e^{\frac{i}{2}\alpha\sigma_z}$$

From problem set 2, we have:

$$e^{\lambda \hat{A}} \hat{B} e^{-\lambda \hat{A}} = \hat{B} + \lambda [\hat{A}, \hat{B}] + \frac{\lambda^2}{2} [\hat{A}, [\hat{A}, \hat{B}]] + \dots \quad (2)$$

We choose $\hat{A} = -\frac{i}{2}\sigma_z$, we get our expression on the same form as in (2):

$$\begin{aligned} e^{-\frac{i}{2}\alpha\sigma_z} \sigma_x e^{\frac{i}{2}\alpha\sigma_z} &= \sigma_x + \alpha \left[-\frac{i}{2}\sigma_z, \sigma_x \right] + \frac{\alpha^2}{2} \left[-\frac{i}{2}\sigma_z, \left[-\frac{i}{2}\sigma_z, \sigma_x \right] \right] + \frac{\alpha^3}{6} \left[-\frac{i}{2}\sigma_z, \left[-\frac{i}{2}\sigma_z, \left[-\frac{i}{2}\sigma_z, \sigma_x \right] \right] \right] + \dots \\ &= \sigma_x + \alpha \left(-\frac{i}{2} \right) [\sigma_z, \sigma_x] + \frac{\alpha^2}{2} \left(-\frac{i}{2} \right)^2 [\sigma_z, [\sigma_z, \sigma_x]] + \frac{\alpha^3}{6} \left(-\frac{i}{2} \right)^3 [\sigma_z, [\sigma_z, [\sigma_z, \sigma_x]]] + \dots \end{aligned}$$

Then we know that the commutators are such that $[\sigma_x, \sigma_y] = 2i\epsilon_{xyz}\sigma_z$ where $\epsilon_{xyz} = 1$ and any odd number of permutations returns -1 , and any even number of permutations return 1 . Thus: $[\sigma_z, \sigma_x] = 2i\sigma_y$, $[\sigma_z, \sigma_y] = -2i\sigma_x$, and

$$\begin{aligned} e^{-\frac{i}{2}\alpha\sigma_z} \sigma_x e^{\frac{i}{2}\alpha\sigma_z} &= \sigma_x + \alpha \left(-\frac{i}{2} \right) 2i\sigma_y + \frac{\alpha^2}{2} \left(-\frac{i}{2} \right)^2 (2i) [\sigma_z, \sigma_y] \\ &\quad + \frac{\alpha^3}{6} \left(-\frac{i}{2} \right)^3 (2i) [\sigma_z, [\sigma_z, \sigma_y]] + \dots \end{aligned} \quad (3)$$

$$\begin{aligned} &= \sigma_x + \alpha \left(-\frac{i}{2} \right) 2i\sigma_y - \frac{\alpha^2}{2} \left(-\frac{i}{2} \right)^2 (2i)^2 \sigma_x - \frac{\alpha^3}{6} \left(-\frac{i}{2} \right)^3 (2i)^2 [\sigma_z, \sigma_x] + \dots \\ &= \sigma_x + \alpha\sigma_y - \frac{\alpha^2}{2}\sigma_x - \frac{\alpha^3}{6}\sigma_y + \dots \\ &= \left(1 - \frac{\alpha^2}{2} + \dots \right) \sigma_x + \left(\alpha - \frac{\alpha^3}{6} + \dots \right) \sigma_y \end{aligned} \quad (4)$$

The series continues in the familiar pattern of $\cos \alpha$ and $\sin \alpha$ due to the pattern in (3), which leaves us:

$$e^{-\frac{i}{2}\alpha\sigma_z} \sigma_x e^{\frac{i}{2}\alpha\sigma_z} = \cos \alpha \sigma_x + \sin \alpha \sigma_y \quad (5)$$

The unitary matrix $\hat{U} = e^{-\frac{i}{2}\alpha\sigma_{\mathbf{n}}}$, when transforming an operator/matrix, causes the transformations:

$$\sigma \rightarrow \hat{U} \sigma \hat{U}^\dagger = e^{-\frac{i}{2}\alpha\sigma_{\mathbf{n}}} \sigma e^{\frac{i}{2}\alpha\sigma_{\mathbf{n}}}$$

As we saw in (5), if $\mathbf{n} = (0, 0, 1) = z$, we got a rotation about the z axis. If we now imagine a different orthonormal coordinate system with unit vectors $\mathbf{n} = \mathbf{n}_z, \mathbf{n}_y, \mathbf{n}_x$, then the transformation $\hat{U} \sigma_{\mathbf{n}_x} \hat{U}^\dagger$ would look like:

$$\sigma_{\mathbf{n}_x} \rightarrow e^{-\frac{i}{2}\alpha\sigma_{\mathbf{n}}} \sigma_{\mathbf{n}_x} e^{\frac{i}{2}\alpha\sigma_{\mathbf{n}}} = \cos \alpha \sigma_{\mathbf{n}_x} + \sin \alpha \sigma_{\mathbf{n}_y}$$

and rotates the spin basis around the axis \mathbf{n} .

c)

$$e^{-\frac{i}{2}\alpha\sigma_{\mathbf{n}}} = \sum_{k=0}^{\infty} \frac{\left(-\frac{i}{2}\alpha\sigma_{\mathbf{n}} \right)^k}{k!}$$

Then we need to know what the different powers of $\sigma_{\mathbf{n}}$ are:

$$\begin{aligned} \sigma_{\mathbf{n}}^2 &= \begin{pmatrix} \cos \theta & e^{-i\phi} \sin \theta \\ e^{i\phi} \sin \theta & -\cos \theta \end{pmatrix}^2 = \begin{pmatrix} \cos^2 \theta + e^{-i\phi} e^{i\phi} \sin^2 \theta & \cos \theta e^{-i\phi} \sin \theta - \cos \theta e^{-i\phi} \sin \theta \\ e^{i\phi} \sin \theta \cos \theta - \cos \theta e^{i\phi} \sin \theta & e^{i\phi} \sin \theta e^{-i\phi} \sin \theta + \cos^2 \theta \end{pmatrix} \\ &= \begin{pmatrix} \cos^2 \theta + \sin^2 \theta & 0 \\ 0 & \cos^2 \theta + \sin^2 \theta \end{pmatrix} = \mathbb{1} \end{aligned}$$

Thus, we see that $\sigma_{\mathbf{n}}$ follows the standard Pauli matrix identities: $\sigma_{\mathbf{n}}^{2k} = \mathbb{1}$ and $\sigma_{\mathbf{n}}^{2k+1} = \sigma_{\mathbf{n}}$ for $k = 0, 1, \dots$. This let's us rewrite our series as:

$$e^{-\frac{i}{2}\alpha\sigma_{\mathbf{n}}} = \sum_{k=0}^{\infty} \frac{\left(-\frac{i}{2}\alpha\sigma_{\mathbf{n}}\right)^k}{k!} = \sum_{k=0}^{\infty} \frac{\left(-\frac{i}{2}\alpha\sigma_{\mathbf{n}}\right)^{2k}}{(2k)!} + \sum_{k=0}^{\infty} \frac{\left(-\frac{i}{2}\alpha\sigma_{\mathbf{n}}\right)^{2k+1}}{(2k+1)!}$$

Using that $(-i)^{2k} = (-1)^k$, $(-i)^{2k+1} = -i^{2k+1} = -i^{2k}i = (-1)^{k+1}i$, and the identities for the Pauli matrices, we get:

$$\begin{aligned} e^{-\frac{i}{2}\alpha\sigma_{\mathbf{n}}} &= \mathbb{1} \underbrace{\sum_{k=0}^{\infty} \frac{\left(\frac{\alpha}{2}\right)^{2k} (-1)^k}{(2k)!}}_{=\cos \frac{\alpha}{2}} + i\sigma_{\mathbf{n}} \underbrace{\sum_{k=0}^{\infty} \frac{\left(\frac{\alpha}{2}\right)^{2k+1} (-1)^{k+1}}{(2k+1)!}}_{=\sin \frac{\alpha}{2}} \\ e^{-\frac{i}{2}\alpha\sigma_{\mathbf{n}}} &= \cos \frac{\alpha}{2} \mathbb{1} + i \sin \frac{\alpha}{2} \sigma_{\mathbf{n}} \end{aligned}$$