## **Solutions to problem set 7**

## 7.1 The canonical commutation relations.

$$\hat{A}_{\mathbf{k}a} = \sqrt{\frac{\hbar}{2\omega_k\epsilon_0}} \left( \hat{a}_{\mathbf{k}a} + \hat{a}_{-\mathbf{k}\bar{a}}^{\dagger} \right), \quad \hat{E}_{\mathbf{k}a} = i\sqrt{\frac{\hbar\omega_k}{2\epsilon_0}} \left( \hat{a}_{\mathbf{k}a} - \hat{a}_{-\mathbf{k}\bar{a}}^{\dagger} \right)$$
$$\left[ \hat{A}_{\mathbf{k}a}, \hat{E}_{\mathbf{k}'a'}^{\dagger} \right] = -i\frac{\hbar}{\epsilon_0}\delta_{\mathbf{k}\mathbf{k}'}\delta_{aa'}$$

We need to express the ladder operators in terms of  $\hat{A}$  and  $\hat{E}^{\dagger}$ , by inspection, we see that:

$$\hat{a}_{\mathbf{k}a} = \frac{1}{2} \left( \sqrt{\frac{2\omega_k \epsilon_0}{\hbar}} \hat{A}_{\mathbf{k}a} - i \sqrt{\frac{2\epsilon_0}{\hbar\omega_k}} \hat{E}_{\mathbf{k}a} \right)$$

from which we calculate:

$$\hat{a}_{\mathbf{k}a}^{\dagger} = \frac{1}{2} \left( \sqrt{\frac{2\omega_k \epsilon_0}{\hbar}} \hat{A}_{\mathbf{k}a}^{\dagger} + i \sqrt{\frac{2\epsilon_0}{\hbar\omega_k}} \hat{E}_{\mathbf{k}a}^{\dagger} \right)$$

Then:

$$\begin{split} \left[ \hat{a}_{\mathbf{k}a}, \hat{a}_{\mathbf{k}'a'}^{\dagger} \right] &= \left[ \frac{1}{2} \left( \sqrt{\frac{2\omega_{k}\epsilon_{0}}{\hbar}} \hat{A}_{\mathbf{k}a} - i\sqrt{\frac{2\epsilon_{0}}{\hbar\omega_{k}}} \hat{E}_{\mathbf{k}a} \right), \frac{1}{2} \left( \sqrt{\frac{2\omega_{k'}\epsilon_{0}}{\hbar}} \hat{A}_{\mathbf{k}'a'}^{\dagger} + i\sqrt{\frac{2\epsilon_{0}}{\hbar\omega_{k'}}} \hat{E}_{\mathbf{k}'a'}^{\dagger} \right) \right] \\ &= \frac{1}{4} \left( \frac{2\epsilon_{0}\sqrt{\omega_{k}\omega_{k'}}}{\hbar} \underbrace{\left[ \hat{A}_{\mathbf{k}a}, \hat{A}_{\mathbf{k}'a'}^{\dagger} \right]}_{=0} + i\frac{2\epsilon_{0}}{\hbar}\sqrt{\frac{\omega_{k}}{\omega_{k'}}} \left[ \hat{A}_{\mathbf{k}a}, \hat{E}_{\mathbf{k}'a'}^{\dagger} \right] \right) \\ &+ \frac{1}{4} \left( -i\frac{2\epsilon_{0}}{\hbar}\sqrt{\frac{\omega_{k'}}{\omega_{k}}} \left[ \hat{E}_{\mathbf{k}a}, \hat{A}_{\mathbf{k}'a'}^{\dagger} \right] + \frac{2\epsilon_{0}}{\hbar\sqrt{\omega_{k}\omega_{k'}}} \underbrace{\left[ \hat{E}_{\mathbf{k}a}, \hat{E}_{\mathbf{k}'a'}^{\dagger} \right]}_{=0} \right) \\ &= i\frac{\epsilon_{0}}{2\hbar}\sqrt{\frac{\omega_{k}}{\omega_{k'}}} \underbrace{\left[ \hat{A}_{\mathbf{k}a}, \hat{E}_{\mathbf{k}'a'}^{\dagger} \right]}_{=-i\frac{\hbar}{\epsilon_{0}}\delta_{\mathbf{k}\mathbf{k}'}\delta_{aa'}} - i\frac{\epsilon_{0}}{2\hbar}\sqrt{\frac{\omega_{k'}}{\omega_{k}}} \underbrace{\left[ \hat{E}_{\mathbf{k}a}, \hat{A}_{\mathbf{k}'a'}^{\dagger} \right]}_{=0} \right) \end{split}$$

Looking at the last commutator:

$$\begin{bmatrix} \hat{E}_{\mathbf{k}a}, \hat{A}^{\dagger}_{\mathbf{k}'a'} \end{bmatrix} = \hat{E}_{\mathbf{k}a} \hat{A}^{\dagger}_{\mathbf{k}'a'} - \hat{A}^{\dagger}_{\mathbf{k}'a'} \hat{E}_{\mathbf{k}a} = \left( \hat{A}_{\mathbf{k}'a'} \hat{E}^{\dagger}_{\mathbf{k}a} \right)^{\dagger} - \left( \hat{E}^{\dagger}_{\mathbf{k}a} \hat{A}_{\mathbf{k}'a'} \right)^{\dagger} \\ = \left( \hat{A}_{\mathbf{k}'a'} \hat{E}^{\dagger}_{\mathbf{k}a} - \hat{E}^{\dagger}_{\mathbf{k}a} \hat{A}_{\mathbf{k}'a'} \right)^{\dagger} = \left[ \hat{A}_{\mathbf{k}'a'}, \hat{E}^{\dagger}_{\mathbf{k}a} \right]^{\dagger} \\ = \left( -i\frac{\hbar}{\epsilon_0} \delta_{\mathbf{k}'\mathbf{k}} \delta_{a'a} \right)^{\dagger} = i\frac{\hbar}{\epsilon_0} \delta_{\mathbf{k}'\mathbf{k}} \delta_{a'a}$$

So far, we have:

$$\begin{aligned} \left[ \hat{a}_{\mathbf{k}a}, \hat{a}_{\mathbf{k}'a'}^{\dagger} \right] &= i \frac{\epsilon_0}{2\hbar} \sqrt{\frac{\omega_k}{\omega_{k'}}} \left( -i \frac{\hbar}{\epsilon_0} \delta_{\mathbf{k}\mathbf{k}'} \delta_{aa'} \right) - i \frac{\epsilon_0}{2\hbar} \sqrt{\frac{\omega_{k'}}{\omega_k}} \left( i \frac{\hbar}{\epsilon_0} \delta_{\mathbf{k}'\mathbf{k}} \delta_{a'a} \right) \\ &= \frac{1}{2} \sqrt{\frac{\omega_k}{\omega_{k'}}} \delta_{\mathbf{k}\mathbf{k}'} \delta_{aa'} + \frac{1}{2} \sqrt{\frac{\omega_{k'}}{\omega_k}} \left( \delta_{\mathbf{k}'\mathbf{k}} \delta_{a'a} \right) \\ &= \frac{1}{2} \left( \sqrt{\frac{\omega_k}{\omega_{k'}}} + \sqrt{\frac{\omega_{k'}}{\omega_k}} \right) \delta_{\mathbf{k}\mathbf{k}'} \delta_{aa'} \end{aligned}$$

 $\delta_{\mathbf{k}\mathbf{k}'}$  will either return zero if  $\mathbf{k} \neq \mathbf{k}'$ , or 1 if  $\mathbf{k} = \mathbf{k}'$ , in the latter case,  $\sqrt{\frac{\omega_k}{\omega_{k'}}} + \sqrt{\frac{\omega_{k'}}{\omega_k}} = 2$ , and if not, the expression has no contribution, thus, we can neglect it and get the desired result:

$$\left[\hat{a}_{\mathbf{k}a}, \hat{a}_{\mathbf{k}'a'}^{\dagger}\right] = \delta_{\mathbf{k}\mathbf{k}'}\delta_{aa'}$$

## 7.2 Charged particle in a strong magnetic field (Midterm Exam 2005).

a) From Newtons second law:

$$m\frac{d\mathbf{v}}{dt} = e\left(\mathbf{v} \times \mathbf{B}\right) \tag{1}$$

for a particle moving in a magnetic field ( $\mathbf{E} = 0$ ). The velocity is restricted to the xy-plane, and the magnetic field is in the z-direction. Thus, by integration:

$$\frac{d\mathbf{v}}{dt} = \frac{eB}{m} (\mathbf{v} \times \mathbf{k})$$
$$\Rightarrow \mathbf{v} = \frac{eB}{m} (\mathbf{r} \times \mathbf{k}) + \mathbf{C}$$
$$= -\frac{eB}{m} \mathbf{k} \times \mathbf{r} + \mathbf{C}$$

We recognize this as the expression for angular velocity with  $\omega = -\frac{eB}{m}$  where **C** is a constant that can be determined from the initial conditions. We can parametrize **C** to a vector on the same form  $\mathbf{C} = -\omega \times \mathbf{r}_0$  where  $\mathbf{r}_0$  is a constant:

$$\mathbf{v} = \vec{\omega} \times \mathbf{r} - \vec{\omega} \times \mathbf{r}_0$$
  
$$\mathbf{v} = \vec{\omega} \times (\mathbf{r} - \mathbf{r}_0)$$
(2)

We see that this represents constant angular motion around the centre  $\mathbf{r}_0$  with angular frequency  $\omega = -\frac{eB}{m}$ .

To check if  $L_{mek} = m(xv_y - yv_x)$  is a constant of motion, we start by calculating:

$$m\frac{d\mathbf{v}}{dt} = e\mathbf{v} \times \mathbf{B}$$
$$= q \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ v_x & v_y & 0 \\ 0 & 0 & B \end{vmatrix}$$
$$= v_y B\mathbf{i} - v_x B\mathbf{j}$$

Then:

$$\frac{dL_{mek}}{dt} = m\left(\frac{dx}{dt}v_y + x\frac{dv_y}{dt} - \frac{dy}{dt}v_x - y\frac{dv_x}{dt}\right) \\
= m\frac{dx}{dt}v_y + xm\frac{dv_y}{dt} - m\frac{dy}{dt}v_x - ym\frac{dv_x}{dt} \\
= mv_xv_y - eBxv_x - mv_yv_x - eByv_y \\
= -eB\left(xv_x + yv_y\right) \\
= -eB\left(xv_x + yv_y\right) \\
= -eB\left(\mathbf{r} \cdot \mathbf{dr} \\
= -\frac{eB}{2}\left(\mathbf{r} \cdot \frac{d\mathbf{r}}{dt} + \frac{d\mathbf{r}}{dt} \cdot \mathbf{r}\right) \\
= -\frac{eB}{2}\frac{d}{dt}r^2$$

As we see,  $\frac{d}{dt}L_{mek} \neq 0$ , and thus not a constant of motion. Instead we have that  $L = L_{mek} + (eB/2)r^2$  is conserved as:

$$\frac{dL}{dt} = \frac{dL_{mek}}{dt} + \frac{eB}{2}\frac{d}{dt}r^2$$
$$= \frac{eB}{2}\frac{d}{dt}\left(-r^2 + r^2\right)$$
$$= 0$$

b) To check if **R** is a constant of motion, we take the derivative:

$$\begin{aligned} \frac{d\mathbf{R}}{dt} &= \frac{d\mathbf{r}}{dt} + \frac{1}{\omega} \frac{d}{dt} \left( \mathbf{k} \times \mathbf{v} \right) \\ &= \frac{d\mathbf{r}}{dt} + \frac{1}{\omega} \mathbf{k} \times \frac{d\mathbf{v}}{dt} \\ \stackrel{(1)}{=} &\mathbf{v} + \frac{e}{m\omega} \mathbf{k} \times (\mathbf{v} \times \mathbf{B}) \\ &= &\mathbf{v} + \frac{e}{m\omega} \left( \mathbf{v} \left( \mathbf{k} \cdot \mathbf{B} \right) - \mathbf{B} \left( \mathbf{k} \cdot \mathbf{v} \right) \right) \\ &= &\mathbf{v} + \frac{eB}{m\omega} \mathbf{v} \\ &= &\mathbf{v} + \frac{eB}{m\omega} \frac{m}{-eB} \mathbf{v} \\ &= &\mathbf{0} \end{aligned}$$

Which it is. Inserting (2) into the expression for  $\mathbf{R}$  we have:

$$\mathbf{R} = \mathbf{r} + \frac{1}{\omega} \mathbf{k} \times \mathbf{v}$$

$$= \mathbf{r} + \frac{1}{\omega} \mathbf{k} \times \vec{\omega} \times (\mathbf{r} - \mathbf{r}_0)$$

$$= \mathbf{r} + \frac{1}{\omega} \left( \vec{\omega} \cdot \left( \underbrace{\mathbf{k} \cdot (\mathbf{r} - \mathbf{r}_0)}_{=0} \right) - (\mathbf{r} - \mathbf{r}_0) \underbrace{(\mathbf{k} \cdot \vec{\omega})}_{=\omega} \right)$$

$$= \mathbf{r} - (\mathbf{r} - \mathbf{r}_0)$$

$$\mathbf{R} = \mathbf{r}_0$$
(3)

So **R** points to the centre of the circular orbit.  $\vec{\rho}$  is given by:

$$ec{
ho} = \mathbf{R} - \mathbf{r}$$
 $= \mathbf{r}_0 - \mathbf{r}$ 

So  $\rho$  points from the particle to the centre of orbit.

c) If we use (from the problem set):

$$\mathbf{v} = \frac{(\mathbf{p} - e\mathbf{A})}{m}$$
$$= \frac{1}{m} \left( \mathbf{p} + \frac{e}{2} \mathbf{r} \times \mathbf{B} \right)$$
$$= \frac{1}{m} \left( \mathbf{p} + \frac{eB}{2} \mathbf{r} \times \mathbf{k} \right)$$

where  $\mathbf{p}$  denotes the canonical momentum, we can express  $\mathbf{R}$  with  $\mathbf{p}$  and  $\mathbf{r}$  only :

$$\mathbf{R} = \mathbf{r} + \frac{1}{\omega} \mathbf{k} \times \mathbf{v}$$

$$= \mathbf{r} + \frac{1}{m\omega} \mathbf{k} \times \left( \mathbf{p} + \frac{eB}{2} \mathbf{r} \times \mathbf{k} \right)$$

$$= \mathbf{r} + \frac{1}{m\omega} \left( \mathbf{k} \times \mathbf{p} + \frac{eB}{2} \underbrace{\mathbf{k} \times [\mathbf{r} \times \mathbf{k}]}_{=\mathbf{r}} \right)$$

$$= \mathbf{r} + \frac{1}{m\omega} \underbrace{\mathbf{k} \times \mathbf{p}}_{=-p_y \hat{i} + p_x \hat{j}} + \underbrace{\frac{eB}{2m\omega}}_{=-\frac{1}{2}} \mathbf{r}$$

$$= \mathbf{r} \left( 1 - \frac{1}{2} \right) + \frac{1}{m\omega} \left( -p_y \hat{i} + p_x \hat{j} \right)$$

$$= \left( \frac{1}{2}x - \frac{1}{m\omega} p_y \right) \mathbf{i} + \left( \frac{1}{2}y + \frac{1}{m\omega} p_x \right) \mathbf{j}$$

$$\equiv X\mathbf{i} + Y\mathbf{j}$$

We can now express these as QM operators by replacing  $r\to \hat{r}$  and  $p\to \hat{p}$  with the commutation relations

$$[\hat{r}_j, \hat{p}_k] = i\hbar\delta_{jk}$$

This gives:

$$\hat{X} = \frac{1}{2}\hat{x} - \frac{1}{m\omega}\hat{p}_y$$
$$\hat{Y} = \frac{1}{2}\hat{y} - \frac{1}{m\omega}\hat{p}_x$$

These commute as:

$$\begin{bmatrix} \hat{X}, \hat{Y} \end{bmatrix} = \begin{bmatrix} \frac{1}{2}\hat{x} - \frac{1}{m\omega}\hat{p}_y, \frac{1}{2}\hat{y} + \frac{1}{m\omega}\hat{p}_x \end{bmatrix}$$
$$= \frac{1}{4}\underbrace{[\hat{x}, \hat{y}]}_{=0} + \frac{1}{2m\omega}\underbrace{[\hat{x}, \hat{p}_x]}_{=i\hbar} - \frac{1}{2m\omega}\underbrace{[\hat{p}_y, \hat{y}]}_{=-i\hbar} - \frac{1}{m^2\omega^2}\underbrace{[\hat{p}_y, \hat{p}_x]}_{=0}$$
$$= \frac{i\hbar}{m\omega}$$

For  $\rho = \mathbf{R} - \mathbf{r}$  we have the component operators:

$$\hat{\rho}_x = -\frac{1}{2}\hat{x} - \frac{1}{m\omega}\hat{p}_y$$
$$\hat{\rho}_y = -\frac{1}{2}\hat{y} + \frac{1}{m\omega}\hat{p}_x$$

That gives:

$$\begin{aligned} [\rho_x, \rho_y] &= \left[ -\frac{1}{2} \hat{x} - \frac{1}{m\omega} \hat{p}_y, -\frac{1}{2} \hat{y} + \frac{1}{m\omega} \hat{p}_x \right] \\ &= \frac{1}{4} \underbrace{[\hat{x}, \hat{y}]}_{=0} - \frac{1}{2m\omega} \underbrace{[\hat{x}, \hat{p}_x]}_{=i\hbar} + \frac{1}{2m\omega} \underbrace{[\hat{p}_y, \hat{y}]}_{=-i\hbar} - \frac{1}{m^2 \omega^2} \underbrace{[\hat{p}_y, \hat{p}_x]}_{=0} \\ &= -\frac{i\hbar}{m\omega} \end{aligned}$$

Here  $\hat{X}$  and  $\hat{Y}$  and  $\hat{\rho}_x$  and  $\hat{\rho}_y$  respectively commute as a phase space where we have replaced  $\hbar \to \hbar/m\omega$ . This means that there are unceartainty relations between the operators, and that they can not be known simultaniously. We now introduce  $l_B^2 = \hbar/m\omega$  such that

$$[\hat{X}, \hat{Y}] = [\hat{\rho}_y, \hat{\rho}_x] = il_B^2 \tag{4}$$

d)

$$\hat{a} = \frac{1}{\sqrt{2}l_B} \left( \hat{X} + i\hat{Y} \right) \quad \hat{b} = \frac{1}{\sqrt{2}l_B} \left( \hat{\rho}_x - i\hat{\rho}_y \right)$$

We know that  $\hat{X}$ ,  $\hat{Y}$  and  $\hat{\rho}_x$ ,  $\hat{\rho}_y$  are made up of hermitian operators, and thus:

$$\hat{a}^{\dagger} = \frac{1}{\sqrt{2}l_B} \left( \hat{X} - i\hat{Y} \right), \quad \hat{b}^{\dagger} = \frac{1}{\sqrt{2}l_B} \left( \hat{\rho}_x + i\hat{\rho}_y \right)$$

where 
$$l_B = \sqrt{\frac{\hbar}{\mid eB \mid}}$$
. Then:  

$$\begin{bmatrix} \hat{a}, \hat{a}^{\dagger} \end{bmatrix} = \frac{1}{2l_B^2} \begin{bmatrix} \hat{X} + i\hat{Y}, \hat{X} - i\hat{Y} \end{bmatrix}$$

$$= \frac{1}{2l_B^2} \left( \underbrace{\begin{bmatrix} \hat{X}, \hat{X} \end{bmatrix}}_{=0} + \underbrace{\begin{bmatrix} \hat{X}, -i\hat{Y} \end{bmatrix}}_{=-2i\left[\hat{X}, \hat{Y}\right]} + \underbrace{\begin{bmatrix} i\hat{Y}, -i\hat{Y} \end{bmatrix}}_{=0} \right)$$

$$= \frac{-2i^2 l_B^2}{2l_B^2}$$

$$= 1$$

$$\begin{bmatrix} \hat{b}, \hat{b}^{\dagger} \end{bmatrix} = \frac{1}{2l_B^2} [\hat{\rho}_x - i\hat{\rho}_y, \hat{\rho}_x + i\hat{\rho}_y]$$

$$= \frac{1}{2l_B^2} \left( \underbrace{\begin{bmatrix} \hat{\rho}_x, \hat{\rho}_x \end{bmatrix}}_{=0} + \underbrace{\begin{bmatrix} \hat{\rho}_x, i\hat{\rho}_y \end{bmatrix}}_{=2i\left[\hat{\rho}_x, \hat{\rho}_y \end{bmatrix}} + \underbrace{\begin{bmatrix} -i\hat{\rho}_y, i\hat{\rho}_y \end{bmatrix}}_{=0} \right)$$

$$= \frac{-2i^2 l_B^2}{2l_B^2}$$

$$= 1$$

$$\begin{bmatrix} \hat{a}, \hat{b}^{\dagger} \end{bmatrix} = \begin{bmatrix} \hat{X} + i\hat{Y}, \hat{\rho}_x + i\hat{\rho}_y \end{bmatrix}$$
  
= 
$$\begin{bmatrix} \hat{X}, \hat{\rho}_x \end{bmatrix} + i\begin{bmatrix} \hat{X}, \hat{\rho}_y \end{bmatrix} + i\begin{bmatrix} \hat{Y}, \hat{\rho}_x \end{bmatrix} - \begin{bmatrix} \hat{Y}, \hat{\rho}_y \end{bmatrix}$$

As  $[\hat{X}, \hat{\rho}_x] = \hat{Y}, \hat{\rho}_y]$  are trivially zero (they contain only operators that commute) we get:

$$-i\left[\hat{a},\hat{b}^{\dagger}\right] = \left[\hat{X},\hat{\rho}_{y}\right] + \left[\hat{Y},\hat{\rho}_{x}\right]$$
$$= \left[\hat{X},\hat{\rho}_{y}\right] + \left[\hat{Y},\hat{\rho}_{x}\right]$$

The relevant commutators are:

$$\begin{split} \left[ \hat{X}, \hat{\rho}_y \right] &= -\frac{1}{4} \left[ \hat{x}, \hat{y} \right] + \frac{1}{2m\omega} \left[ \hat{x}, \hat{p}_x \right] + \frac{1}{2m\omega} \left[ \hat{p}_y, \hat{y} \right] - \frac{1}{m^2 \omega^2} \left[ \hat{p}_x, \hat{p}_y \right] \\ &= \frac{1}{2m\omega} \left( \left[ \hat{x}, \hat{p}_x \right] - \left[ \hat{y}, \hat{p}_y \right] \right) \\ &= 0 \\ \left[ \hat{Y}, \hat{\rho}_x \right] &= \frac{1}{2m\omega} \left( \left[ \hat{y}, \hat{p}_y \right] - \left[ \hat{x}, \hat{p}_x \right] \right) \\ &= 0 \end{split}$$

such that

$$-i\left[\hat{a},\hat{b}^{\dagger}\right] \ = \ 0$$

And similarly  $\left[ \hat{a}, \hat{b} \right] = \left[ \hat{a}^{\dagger}, \hat{b}^{\dagger} \right] = 0.$ 

This means that the operators  $\hat{a}, \hat{a}^{\dagger}, \hat{b}, \hat{b}^{\dagger}$  follow the same algebra (and the same physics) as two independent harmonic oscillators.

e) The hamiltonian is:

$$H = \frac{1}{2m} \left( \mathbf{p} - a\mathbf{A} \right)^2 = \frac{1}{2}m\mathbf{v}^2$$

We found the velocity in (2), and by using the result (3), we see we get:

$$H = \frac{1}{2}m \left(\tilde{\omega} \times (\mathbf{r} - \mathbf{R})\right)^{2}$$
  
$$= \frac{1}{2}m \left(-\tilde{\omega} \times \tilde{\rho}\right)^{2}$$
  
$$\stackrel{\vec{\omega} \perp \vec{\rho}}{=} -\frac{1}{2}m\omega^{2}\rho^{2}$$
  
$$= -\frac{1}{2}m\omega^{2} \left(\rho_{x}^{2} + \rho_{y}^{2}\right)$$
(5)

Expressing these in terms of the ladder operators  $\hat{b}$  and  $\hat{b}^{\dagger}$  yields:

$$\hat{\rho}_x = \frac{l_B}{\sqrt{2}} \left( \hat{b} + \hat{b}^{\dagger} \right), \quad \hat{\rho}_y = -\frac{i l_B}{\sqrt{2}} \left( \hat{b} - \hat{b}^{\dagger} \right) \tag{6}$$

$$\hat{H} = \frac{1}{2}m\omega^{2}\frac{l_{B}^{2}}{2}\left(\left(\hat{b}+\hat{b}^{\dagger}\right)^{2}-\left(\hat{b}-\hat{b}^{\dagger}\right)^{2}\right) \\
= \frac{1}{4}m\omega^{2}l_{B}^{2}\left(2\hat{b}\hat{b}^{\dagger}+2\hat{b}^{\dagger}\hat{b}\right) \\
= \frac{1}{4}m\omega^{2}l_{B}^{2}\left(2\left[1+\hat{b}^{\dagger}\hat{b}\right]+2\hat{b}^{\dagger}\hat{b}\right) \\
= m\omega^{2}l_{B}^{2}\left(\hat{b}^{\dagger}\hat{b}+\frac{1}{2}\right) \\
= m\omega^{2}\frac{\hbar}{m\mid\omega\mid}\left(\hat{b}^{\dagger}\hat{b}+\frac{1}{2}\right) \\
= \hbar\omega\left(\hat{b}^{\dagger}\hat{b}+\frac{1}{2}\right)$$
(7)

This is the hamiltonian for the harmonic oscillator, and has the energy spectrum  $E_n = \hbar \omega \left(n + \frac{1}{2}\right)$  independent of m. This means that for each energy there are m degenrate states. The angular momentum operator is:

$$L = m\left(xv_y - yv_x\right) + \frac{eB}{2}r^2 = m\mathbf{r} \times \mathbf{v} + \frac{eB}{2}\mathbf{r}^2$$

From earlier, we had  $\mathbf{r} = \mathbf{R} - \vec{\rho}$ ,  $\mathbf{v} = -\vec{\omega} \times \vec{\rho}$ . Then:

$$\begin{split} L &= m \left( \mathbf{R} - \vec{\rho} \right) \times \left( -\vec{\omega} \times \vec{\rho} \right) + \frac{eB}{2} \left( \mathbf{R} - \vec{\rho} \right)^2 \\ &= m \left( -\vec{\omega} \left[ \left( \mathbf{R} - \vec{\rho} \right) \cdot \vec{\rho} \right] - \vec{\rho} \left[ \underbrace{\left( \mathbf{R} - \vec{\rho} \right) \cdot \left( -\vec{\omega} \right)}_{=0} \right] \right) + \frac{eB}{2} \left( \mathbf{R} - \vec{\rho} \right)^2 \\ &= -m\vec{\omega} \left( \vec{\rho} \cdot \mathbf{R} - \vec{\rho}^2 \right) + \frac{eB}{2} \left( \mathbf{R}^2 - 2\mathbf{R}\vec{\rho} + \vec{\rho}^2 \right) \\ &= m\vec{\omega} \left( \vec{\rho}^2 - \vec{\rho} \cdot \mathbf{R} \right) - m\omega \left( \frac{\mathbf{R}^2}{2} - \vec{\rho} \cdot \mathbf{R} + \frac{\vec{\rho}^2}{2} \right) \end{split}$$

Since L is zero except for the z component, we can drop the vector notation and have

$$L = \frac{1}{2}m\omega\left(\bar{\rho}^2 - \mathbf{R}^2\right)$$

Quantizing this, and remembering from (5) and (7), we have:

$$\begin{split} \vec{\rho}^2 &= \frac{l_B^2}{2} \left( \left( \hat{b} + \hat{b}^{\dagger} \right)^2 - \left( \hat{b} - \hat{b}^{\dagger} \right)^2 \right) \\ &= \frac{l_B^2}{2} \left( 2 \left[ 1 + \hat{b}^{\dagger} \hat{b} \right] + 2 \hat{b}^{\dagger} \hat{b} \right) \\ &= \frac{l_B^2}{2} \left( 4 \hat{b}^{\dagger} \hat{b} + 2 \right) \\ &= 2 l_B^2 \left( \hat{b}^{\dagger} \hat{b} + \frac{1}{2} \right) \end{split}$$

Then, for  $\mathbf{R}$ , we can write X and Y in terms of ladder operators as:

$$\hat{X} = \frac{l_B}{\sqrt{2}} \left( \hat{a} + \hat{a}^{\dagger} \right), \quad \hat{Y} = -\frac{i l_B}{\sqrt{2}} \left( \hat{a} - \hat{a}^{\dagger} \right)$$
(8)

Which will result in by the same calculation as above in:

$$\mathbf{R}^2 = 2l_B^2 \left( \hat{a}^\dagger \hat{a} + \frac{1}{2} \right)$$

Then:

$$\hat{L} = m\omega l_B^2 \left( \hat{b}^{\dagger} \hat{b} - \hat{a}^{\dagger} \hat{a} \right) = \hbar \left( \hat{b}^{\dagger} \hat{b} - \hat{a}^{\dagger} \hat{a} \right)$$

with eigenvalues:

$$l_{mn} = \hbar \left( n - m \right)$$

f) We want to calculate the expectation values  $\langle z | \hat{x} | z \rangle$  and  $\langle z | \hat{y} | z \rangle$  for the coherent degenerate groundstate  $|z\rangle$  that fulfills  $\hat{a} |z\rangle = z |z\rangle$  and  $\hat{b} |z\rangle = 0$ . From  $\hat{\mathbf{r}} = \hat{\mathbf{R}} - \hat{\rho}$ , we get:

$$\hat{x} = \hat{X} - \hat{\rho}_x, \quad \hat{y} = \hat{Y} - \hat{\rho}_y$$

Using the expressions in (6) and (8):

$$\begin{aligned} \langle z|\hat{x}|z\rangle &= \langle z|X|z\rangle - \langle z|\hat{\rho}_{x}|z\rangle \\ &= \langle z|\frac{l_{B}}{\sqrt{2}}\left(\hat{a}+\hat{a}^{\dagger}\right)|z\rangle - \langle z|\frac{l_{B}}{\sqrt{2}}\left(\hat{b}+\hat{b}^{\dagger}\right)|z\rangle \\ &= \frac{l_{B}}{\sqrt{2}}\left(\langle z|\hat{a}|z\rangle + \langle z|\hat{a}^{\dagger}|z\rangle - \langle z|\hat{b}|z\rangle + \langle z|\hat{b}^{\dagger}|z\rangle\right) \end{aligned}$$

The trick, is to let the let the hermitian conjugated operators act on the bras, and the regular operators on the kets such that  $\hat{a}|z\rangle = z|z\rangle$ ,  $\langle z|\hat{a}^{\dagger} = (\hat{a}|z\rangle)^{\dagger} = \langle z|z^{*}$  and  $\hat{b}|z\rangle = 0$ . We get:

$$\begin{aligned} \langle z|\hat{x}|z\rangle &= \frac{l_B}{\sqrt{2}} \left( \langle z|z|z\rangle + \langle z|z^*|z\rangle \right) \\ &= \frac{l_B}{\sqrt{2}} \left( z + z^* \right) \\ &= \sqrt{2} l_B \operatorname{Re}\left( z \right) \end{aligned}$$

Onto the next:

$$\begin{aligned} \langle z|\hat{y}|z\rangle &= \langle z|\hat{Y}|z\rangle - \langle z|\hat{\rho}_{y}|z\rangle \\ &= -\frac{il_{B}}{\sqrt{2}} \left( \langle z|\hat{a}|z\rangle - \langle z|\hat{a}^{\dagger}|z\rangle - \underbrace{\langle z|\hat{b}|z\rangle}_{=0} + \underbrace{\langle z|\hat{b}^{\dagger}|z\rangle}_{=0} \right) \\ &= -\frac{il_{B}}{\sqrt{2}} \left( z - z^{*} \right) \\ &= \sqrt{2}l_{B} \operatorname{Im}(z) \end{aligned}$$

Writing  $|z\rangle$  in the  $|m\rangle$  basis gives:

$$|z\rangle = \sum_{m} |m\rangle \langle m|z\rangle = e^{-\frac{1}{2}|z|^2} \sum_{m} \frac{z^m}{\sqrt{m!}} |m\rangle$$

This is gotten by use of equation 1.216 in the lecture notes. When considering how many states that fit in  $|z\rangle$  in the lowest landau level for a give z, we use :

$$\langle \hat{x} \rangle^2 + \langle \hat{y} \rangle^2 = \langle \hat{r} \rangle^2 = 2l_B^2 \left( \operatorname{Re}\left(z\right)^2 + \operatorname{Im}\left(z\right)^2 \right) = 2l_B^2 \mid z \mid^2$$

This corresponds to a circle in the complex plane with radius  $\sqrt{2}l_B \mid z \mid$  and an area

$$A = \pi \left( \sqrt{2}l_B \mid z \mid \right)^2$$
$$= 2\pi l_B^2 \mid z \mid^2$$

The state  $|z\rangle$ , corresponding to the edge of said circle, has an overlap with the  $|m\rangle$  state :

$$\begin{aligned} |\langle m|z\rangle|^{2} &= |e^{-\frac{1}{2}|z|^{2}} \sum_{m'} \frac{z^{m'}}{\sqrt{m'!}} \langle m|m'\rangle |^{2} \\ &= e^{-|z|^{2}} \frac{z^{2m}}{m!} \\ &= e^{-|z|^{2}} \frac{\left(|z|^{2}\right)^{m}}{m!} \end{aligned}$$
(9)

To find the m state with maximum overlap with  $|z\rangle$  we find:

$$\frac{d}{d \mid z \mid^2} \mid \langle m \mid z \rangle \mid^2 = \frac{d}{d \mid z \mid^2} \left( e^{-|z|^2} \frac{\left(\mid z \mid^2\right)^m}{m!} \right)$$
$$= -e^{-|z|^2} \frac{\left(\mid z \mid^2\right)^m}{m!} + e^{-|z|^2} \frac{m \left(\mid z \mid^2\right)^{m-1}}{m!}$$
$$= \frac{e^{-|z|^2} \left(\mid z \mid^2\right)^{m-1}}{m!} \left(-\mid z \mid^2 + m\right)$$

Then we get that  $m = |z|^2$ . Since the overlap falls exponentially, we can up to a good approximation take the state with -z— to be in the pure state m, which means that if we restrict the available space to a circle with radius  $r^2 = 2l_B^2|z|^2$  in the z plane we have that  $2l_B^2|z|^2 \le r^2$  and we can restrict m to  $2l_B^2m \le r^2$ . As the area is proportional to  $r^2$  we see that the number of states increases linearly with the available area in the complex plane. The density is

$$\rho = \frac{N}{A} = \frac{m}{2\pi l_B^2 m} = \frac{1}{2\pi l_B^2}$$

g) When introducing the electric field, we get an energy contribution:

$$H_E = -e\vec{E}\cdot\vec{r} = -eE\mathbf{x}$$

Quantizing this and using the relation  $\hat{x} = \hat{X} - \hat{\rho}_x$ , we get:

$$\hat{H}_E = -eE\left(\hat{X} - \hat{\rho}_x\right) = -\frac{l_B}{\sqrt{2}}eE\left(\hat{a} + \hat{a}^{\dagger} - \hat{b} - \hat{b}^{\dagger}\right)$$

Then the total hamiltonian is:

$$\hat{H} = \hat{H}_0 + \hat{H}_E = \hbar\omega \left( \hat{b}^{\dagger}\hat{b} + \frac{1}{2} \right) - \frac{l_B}{\sqrt{2}}eE\left( \hat{a} + \hat{a}^{\dagger} - \hat{b} - \hat{b}^{\dagger} \right)$$

In order to only consider the lowest landau level, i.e  $|m, 0\rangle \equiv |m\rangle$ , we need the "effective" hamiltonian for this level:

$$\hat{H}|m,0\rangle = \hbar\omega \left(\underbrace{\hat{b}^{\dagger}\hat{b}|m,0}_{=0} + \frac{1}{2}|m,0\rangle\right) - \frac{l_B}{\sqrt{2}}eE\left(\hat{a}|m,0\rangle + \hat{a}^{\dagger}|m,0\rangle - \underbrace{\hat{b}|m,0\rangle}_{=0} - \underbrace{\hat{b}^{\dagger}|m,0\rangle}_{=\sqrt{0+1}|m,1\rangle}\right)$$

We see that the last term isn't in the lowest Landau level, thus, we may neglect it. We're left with:

$$\hat{H}'|m,0\rangle = \frac{1}{2}\hbar\omega|m,0\rangle - \frac{l_B}{\sqrt{2}}eE\left(\hat{a} + \hat{a}^{\dagger}\right)|m,0\rangle$$

$$\hat{H}' = \frac{1}{2}\hbar\omega - \frac{l_B}{\sqrt{2}}eE\left(\hat{a} + \hat{a}^{\dagger}\right)$$

In the Heisenberg picture we can find the time evolution of  $\hat{a}$  and  $\hat{a}^{\dagger}$  and get:

$$\begin{aligned} \hat{a}(t)|z\rangle &= \hat{\mathcal{U}}(t,0)\hat{a}\hat{\mathcal{U}}(0,t)|z\rangle \\ &= \hat{\mathcal{U}}(t,0)\hat{a}|z(t)\rangle \\ &= \hat{\mathcal{U}}(t,0)z(t)|z(t)\rangle \\ &= z(t)|z\rangle \end{aligned}$$

So:

$$\begin{aligned} \hat{a}(t) &= \hat{\mathcal{U}}(t,0)\hat{a}\hat{\mathcal{U}}(0,t) \\ &= e^{-it\hat{H}'}\hat{a}e^{i\hbar\hat{H}'} \\ &= \hat{a} + \frac{it}{\hbar}\left[\hat{H}',\hat{a}\right] + \frac{1}{2!}\left(\frac{it}{\hbar}\right)^2\left[\hat{H}',\left[\hat{H}',\hat{a}\right]\right] + \cdots \end{aligned}$$

Calculating the commutator:

$$\begin{bmatrix} \hat{H}', \hat{a} \end{bmatrix} = \begin{bmatrix} \frac{1}{2}\hbar\omega - \frac{l_B}{\sqrt{2}}eE\left(\hat{a} + \hat{a}^{\dagger}\right), \hat{a} \end{bmatrix}$$
$$= -\frac{l_B}{\sqrt{2}}eE\left[\hat{a} + \hat{a}^{\dagger}, \hat{a}\right]$$
$$= -\frac{l_B}{\sqrt{2}}eE\left(\underbrace{[\hat{a}, \hat{a}]}_{=0} + \underbrace{[\hat{a}^{\dagger}, \hat{a}]}_{=-1}\right)$$
$$= \frac{l_B}{\sqrt{2}}eE$$

Since all operators commute with a scalar, and the "higher order" commutators vanish:

$$\hat{a}(t) = \hat{a} + \frac{itl_B}{\hbar\sqrt{2}}eE$$

Then:

$$\begin{aligned} \hat{a}(t)|z\rangle &= \left(z + \frac{itl_B}{\sqrt{2}}eE\right)|z\rangle \\ z(t) &= z + \frac{itl_B}{\sqrt{2}}eE \end{aligned}$$

which shows that  $|z\rangle$  gets a time dependence. In order to show that this corresponds to a drift in the y-direction, let's consider:

$$\hat{X}(t) = \frac{l_B}{\sqrt{2}} \left( \hat{a}(t) + \hat{a}^{\dagger}(t) \right), \text{ and } \hat{Y}(t) = -\frac{il_B}{\sqrt{2}} \left( \hat{a}(t) - \hat{a}^{\dagger}(t) \right)$$

Where  $\hat{a}^{\dagger}(t)$  is:

$$\begin{aligned} (\hat{a}(t))^{\dagger} &= (\hat{a} + \frac{itl_B}{\hbar\sqrt{2}}eE)^{\dagger} \\ \hat{a}^{\dagger}(t) &= \hat{a}^{\dagger} - \frac{itl_B}{\hbar\sqrt{2}}eE \end{aligned}$$

Then:

$$\hat{X}(t) = \frac{l_B}{\sqrt{2}} \left( \hat{a}(t) + \hat{a}^{\dagger}(t) \right) = \frac{l_B}{\sqrt{2}} \left( \hat{a} + \frac{itl_B}{\hbar\sqrt{2}} eE + \hat{a}^{\dagger} - \frac{itl_B}{\hbar\sqrt{2}} eE \right) = \hat{X}$$

No drift in the  $\hat{X}$  direction, onto  $\hat{Y}$ :

$$\begin{aligned} \hat{Y}(t) &= -\frac{il_B}{\sqrt{2}} \left( \hat{a} + \frac{itl_B}{\hbar\sqrt{2}} eE - \hat{a}^{\dagger} + \frac{itl_B}{\hbar\sqrt{2}} eE \right) \\ &= \hat{Y}(0) + \frac{l_B^2}{\hbar} eEt = \hat{Y}(0) + \frac{e}{|eB|} Et = \hat{Y}(0) - \frac{E}{|B|} t \end{aligned}$$

Then the velocity is:

$$v_{\text{drift}} = -\frac{E}{\mid B \mid}$$

in the y direction, as  $\hat{Y}(t)$  is the movement of the guiding center (center of orbit).