

Lecture 23. 10. April 2018

5.5 Bianchi's 2nd identity

Exterior differentiation of (5.56) \Rightarrow

$$\begin{aligned} d \underline{R}^\mu_\nu &= \underline{R}^\mu_\lambda \wedge \underline{\Omega}^\lambda_\nu - \underline{\Omega}^\mu_\rho \wedge \underline{\Omega}^\rho_\lambda \wedge \underline{\Omega}^\lambda_\nu - \underline{\Omega}^\mu_\lambda \wedge \underline{R}^\lambda_\nu + \underline{\Omega}^\mu_\lambda \wedge \underline{\Omega}^\lambda_\rho \wedge \underline{\Omega}^\rho_\nu \\ &= \underline{R}^\mu_\lambda \wedge \underline{\Omega}^\lambda_\nu - \underline{\Omega}^\mu_\lambda \wedge \underline{R}^\lambda_\nu \end{aligned} \quad (5.64)$$

We now have **Bianchi's 2nd identity** as a form equation:

$$\boxed{d \underline{R}^\mu_\nu + \underline{\Omega}^\mu_\lambda \wedge \underline{R}^\lambda_\nu - \underline{R}^\mu_\lambda \wedge \underline{\Omega}^\lambda_\nu = 0} \quad (5.65)$$

As a component equation Bianchi's 2nd identity is given by

$$R^\mu_{\nu[\alpha\beta;\gamma]} = 0 \quad (5.66)$$

Definition 5.5.1 (Contraction)

'Contraction' is a tensor operation defined by

$$R_{\nu\beta} \equiv R^\mu_{\nu\mu\beta} \quad (5.67)$$

We must here have summation over μ . What we do, then, is constructing a new tensor from another given tensor, with a rank 2 lower than the given one.

The tensor with components $R_{\nu\beta}$ is called **the Ricci curvature tensor**.

Another contraction gives **the Ricci curvature scalar**, $R = R^\mu_\mu$.

Riemann curvature tensor has four symmetries. The definition of the Riemann tensor implies that $R^\mu_{\nu\alpha\beta} = -R^\mu_{\nu\beta\alpha}$

Bianchi's 1st identity: $R^\mu_{[\nu\alpha\beta]} = 0$

From Cartan's 2nd structure equation follows

$$\begin{aligned} \underline{R}_{\mu\nu} &= d\underline{\Omega}_{\mu\nu} + \underline{\Omega}_{\mu\lambda} \wedge \underline{\Omega}^\lambda_\nu \\ \Rightarrow R_{\mu\nu\alpha\beta} &= -R_{\nu\mu\alpha\beta} \end{aligned} \quad (5.68)$$

By choosing a locally Cartesian coordinate system in an inertial frame we get the following expression for the components of the Riemann curvature tensor:

$$R_{\mu\nu\alpha\beta} = \frac{1}{2}(g_{\mu\beta,\nu\alpha} - g_{\mu\alpha,\nu\beta} + g_{\nu\alpha,\mu\beta} - g_{\nu\beta,\mu\alpha}) \quad (5.69)$$

from which it follows that $R_{\mu\nu\alpha\beta} = R_{\alpha\beta\mu\nu}$. Contraction of μ and α leads to:

$$\begin{aligned} R^\alpha_{\nu\alpha\beta} &= R^\alpha_{\beta\alpha\nu} \\ \Rightarrow R_{\nu\beta} &= R_{\beta\nu} \end{aligned} \quad (5.70)$$

i.e. the Ricci tensor is symmetric. In 4-D the Ricci tensor has 10 independent components.

In 4-dimensional spacetime the four symmetries of the Riemann curvature tensor reduce the number of independent components from 256 to 20.

6.1 Energy-momentum conservation

6.1.1 Newtonian fluid

Energy-momentum conservation for a Newtonian fluid in terms of the divergence of the energy momentum tensor can be shown as follows. The total derivative of a velocity field is

$$\frac{D\vec{v}}{Dt} \equiv \frac{\partial\vec{v}}{\partial t} + (\vec{v} \cdot \vec{\nabla})\vec{v} \quad (6.1)$$

$\frac{\partial\vec{v}}{\partial t}$ is the local derivative which gives the change in \vec{v} as a function of time at a given point in space. $(\vec{v} \cdot \vec{\nabla})\vec{v}$ is called the **convective** derivative of \vec{v} . It represents the change of \vec{v} for a moving fluid particle due to the inhomogeneity of the fluid velocity field. In component notation the above become

$$\frac{Dv^i}{Dt} \equiv \frac{\partial v^i}{\partial t} + v^j \frac{\partial v^i}{\partial x^j} \quad (6.2)$$

The continuity equation

$$\frac{\partial\rho}{\partial t} + \nabla \cdot (\rho\vec{v}) = 0 \quad \text{or} \quad \frac{\partial\rho}{\partial t} + \frac{\partial(\rho v^i)}{\partial x^i} = 0 \quad (6.3)$$

Euler's equation of motion (ignoring gravity)

$$\rho \frac{D\vec{v}}{Dt} = -\vec{\nabla}p \quad \text{or} \quad \rho \left(\frac{\partial v^i}{\partial t} + v^j \frac{\partial v^i}{\partial x^j} \right) = -\frac{\partial p}{\partial x^i} \quad (6.4)$$

The **energy momentum tensor** is a symmetric tensor of rank 2 that describes material characteristics.

$$T^{\mu\nu} = \begin{pmatrix} T^{00} & T^{01} & T^{02} & T^{03} \\ T^{10} & T^{11} & T^{12} & T^{13} \\ T^{20} & T^{21} & T^{22} & T^{23} \\ T^{30} & T^{31} & T^{32} & T^{33} \end{pmatrix} \quad (6.5)$$

$c \equiv 1$

T^{00} represents energy density.

T^{i0} represents momentum density.

T^{ii} represents pressure ($T^{ii} > 0$).

T^{ii} represents stress ($T^{ii} < 0$).

T^{ij} represents shear forces ($i \neq j$).

Example 6.1.1 (Energy momentum tensor for a Newtonian fluid)

$$\begin{aligned} T^{00} &= \rho & T^{i0} &= \rho v^i \\ T^{ij} &= \rho v^i v^j + p \delta^{ij} \end{aligned} \quad (6.6)$$

where p is pressure, assumed isotropic here. We choose a locally Cartesian coordinate system in an inertial frame such that the covariant derivatives are reduced to partial derivatives. The divergence of the momentum energy tensor, $T^{\mu\nu}_{;\nu}$ has 4 components, one for each value of μ .

The zeroth component is

$$\begin{aligned} T^{0\nu}_{;\nu} &= T^{0\nu}_{,\nu} = T^{00}_{,0} + T^{0i}_{,i} \\ &= \frac{\partial \rho}{\partial t} + \frac{\partial(\rho v^i)}{\partial x^i} \end{aligned} \quad (6.7)$$

which by comparison to Newtonian hydrodynamics implies that $T^{0\nu}_{;\nu} = 0$ is the continuity equation. This equation represents the conservation of energy.

The i th component of the divergence is

$$\begin{aligned} T^{i\nu}_{;\nu} &= T^{i0}_{,0} + T^{ij}_{,j} \\ &= \frac{\partial(\rho v^i)}{\partial t} + \frac{\partial(\rho v^i v^j + p \delta^{ij})}{\partial x^j} \\ &= \rho \frac{\partial v^i}{\partial t} + v^i \frac{\partial \rho}{\partial t} + v^i \frac{\partial \rho v^j}{\partial x^j} + \rho v^j \frac{\partial v^i}{\partial x^j} + \frac{\partial p}{\partial x^i} \end{aligned} \quad (6.8)$$

now, according to the continuity equation

$$\begin{aligned} \frac{\partial(\rho v^i)}{\partial x^i} &= -\frac{\partial \rho}{\partial t} \\ \Rightarrow T^{i\nu}_{;\nu} &= \rho \frac{\partial v^i}{\partial t} + v^i \frac{\partial \rho}{\partial t} - v^i \frac{\partial \rho}{\partial t} + \rho v^j \frac{\partial v^i}{\partial x^j} + \frac{\partial p}{\partial x^i} \\ &= \rho \frac{Dv^i}{Dt} + \frac{\partial p}{\partial x^i} \\ \therefore T^{i\nu}_{;\nu} = 0 &\Rightarrow \rho \frac{Dv^i}{Dt} = -\frac{\partial p}{\partial x^i} \end{aligned} \quad (6.9)$$

which is Euler's equation of motion. It expresses the conservation of momentum.

The equations $T^{\mu\nu}_{;\nu} = 0$ are general expressions for energy and momentum conservation.

6.1.2 Perfect fluids

A perfect fluid is a fluid with no viscosity and is given by the energy-momentum tensor

$$T_{\mu\nu} = \left(\rho + \frac{p}{c^2}\right)u_\mu u_\nu + pg_{\mu\nu} \quad (6.10)$$

where ρ and p are the mass density and the stress, respectively, measured in the fluid's rest frame, u_μ are the components of the 4-velocity of the fluid.

In a comoving orthonormal basis the components of the 4-velocity are $u^{\hat{\mu}} = (c, 0, 0, 0)$. Then the energy-momentum tensor is given by

$$T_{\hat{\mu}\hat{\nu}} = \begin{pmatrix} \rho c^2 & 0 & 0 & 0 \\ 0 & p & 0 & 0 \\ 0 & 0 & p & 0 \\ 0 & 0 & 0 & p \end{pmatrix} \quad (6.11)$$

where $p > 0$ is pressure and $p < 0$ is tension.

There are three different types of perfect fluids that are useful.

1. **dust** or non-relativistic gas is given by $p = 0$ and the energy-momentum tensor $T_{\mu\nu} = \rho u_\mu u_\nu$.
2. **radiation** or ultra-relativistic gas is given by a traceless energy-momentum tensor, i.e. $T^\mu{}_\mu = 0$. It follows that $p = \frac{1}{3}\rho c^2$.
3. **vacuum energy**: If we assume that no velocity can be measured relatively to vacuum, then all the components of the energy-momentum tensor must be Lorentz-invariant. It follows that $T_{\mu\nu} \propto g_{\mu\nu}$. If vacuum is defined as a perfect fluid we get $p = -\rho c^2$ so that $T_{\mu\nu} = pg_{\mu\nu} = -\rho c^2 g_{\mu\nu}$.