Lecture spring 2024:
General Relativity
Problem sheet 6
$\rightsquigarrow$ These problems are scheduled for discussion on Thursday, 7 March 2024.
Legend

* If pressed for time, make sure to try solving the other problem(s) before attempting this one


## Problem 19

From your classes in 3D vector calculus, you are familiar with the expressions for the divergence $(\nabla \cdot \mathbf{A})$ and curl of a vector $(\nabla \times \mathbf{A})$ in spherical coordinates. Now re-derive these expressions by using the definition of the covariant derivative and the Christoffel symbols!
[Hint: first state these expressions in Euclidian orthonormal coordinates, in which they take a particularly simple form. Then determine the metric in spherical coordinates by an explicit coordinate transformation; use this to express the Christoffel symbols.]

## Problem 20

The metric for a three-sphere can be written as

$$
d s^{2}=\mathrm{d} \psi^{2}+\sin ^{2} \psi\left(\mathrm{~d} \theta^{2}+\sin ^{2} \theta \mathrm{~d} \phi^{2}\right)
$$

a) Calculate the Christoffel symbols $\Gamma_{\mu \nu}^{\rho}$ by varying the length of a time-like curve $\tau=\int d \tau$.
[Hint: follow the derivation of the geodesic equation - but instead of using the Euler-Lagrange equations, directly vary the integrand (note that you can use the 'trick' of considering the square of the integrand, because $u^{\mu} u_{\mu}=-1$, which simplifies the calculation). In the end, you can simply read off the Christoffel symbols as the coefficients in front of the $u^{\mu} u^{\nu}$ terms.]
b) Calculate the Riemann tensor, the Ricci tensor and the Ricci scalar.

## Problem 21*

Show that the vanishing of the Riemann tensor is a sufficient (and necessary) condition for the spacetime to be Minkowskian everywhere on the manifold, i.e. a (single, global) coordinate transformation will bring $g_{\mu \nu}$ into the form $\eta_{\mu \nu}$. Discuss: does this imply that spacetime is a globally trivial Minkowski space?

## Problem 22*

Consider a vector $V \in T_{x_{0}}$ that is parallel-transported from some point $x_{0}$ on the manifold to a point $x_{0}+\Delta x$, and from there to a point $y=x_{0}+\Delta x+\delta x$. Here, both $\Delta x$ and $\delta x$ denote small displacements (for some coordinate choice $x^{\mu}$ ). ${ }^{1}$ Denote the resulting vector as $V_{a} \in T_{y}$. Now parallel-transport instead the vector $V$ from $x_{0}$ $x_{0}+\delta x$ and from there to $y$, and denote the resulting vector as $V_{b} \in T_{y}$. Show that

$$
V_{b}-V_{a}=R_{\tau \sigma \nu}^{\mu} V^{\sigma}(\Delta x)^{\nu}(\delta x)^{\tau}
$$

Discuss the result.

[^0]
[^0]:    ${ }^{1}$ Technically, you could consider a curve $x^{\mu}(\lambda)$, where $\lambda$ is not necessarily an affine parameter, and define the above-mentioned points e.g. as $x_{0}^{\mu} \equiv x^{\mu}(\lambda=0),\left(x_{0}+\Delta x\right)^{\mu} \equiv x^{\mu}(\lambda=1)$ and $\left(x_{0}+\Delta x+\delta x\right)^{\mu} \equiv x^{\mu}(\lambda=2)$. Then, $(\Delta x)^{\mu}=\delta \lambda\left(d x^{\mu} / d \lambda\right)$ for the first displacement etc.

