

RTOS: Mailbox example



Mailbox example for uC/OS-II

```
#include <stdio.h>
#include "includes.h"
/* Definition of Task Stacks */
#define TASK_STACKSIZE
                              2048
OS_STK task1_stk[TASK_STACKSIZE];
OS_STK task2_stk[TASK_STACKSIZE];
OS_STK task3_stk[TASK_STACKSIZE];
/* Definition of Task Priorities */
#define TASK1_PRIORITY
                           6
#define TASK2_PRIORITY
#define TASK3_PRIORITY
//Semaphore to protect jtag uart
OS_EVENT *shared_jtag_sem;
//Message mailbox OS_EVENT structure
OS_EVENT *MSG_box;
```

```
int main(void)
  printf("======\n");
 printf(" Starting mailbox example\n");
 printf("=====\n");
 //Create semaphore to protect jtag uart
 shared_jtag_sem = OSSemCreate(1);
 //Create an empty mailbox
 msg_box = OSMboxCreate((void*)NULL);
 //Create the various tasks
 OSTaskCreateExt(task1,
             NULL,
             &task1_stk[TASK_STACKSIZE-1],
             TASK1 PRIORITY,
             TASK1 PRIORITY,
             &task1_stk[0],
             TASK_STACKSIZE,
             NULL,
             OS_TASK_OPT_STK_CHK | OS_TASK_OPT_STK_CLR
 OSTaskCreateExt(task2,
             NULL,
             &task2_stk[TASK_STACKSIZE-1],
             TASK2_PRIORITY,
             TASK2_PRIORITY,
             &task2_stk[0],
             TASK_STACKSIZE,
             NULL.
             OS_TASK_OPT_STK_CHK | OS_TASK_OPT_STK_CLR
 OSTaskCreateExt(task3,
             NULL,
             &task3_stk[TASK_STACKSIZE-1],
             TASK3_PRIORITY,
             TASK3_PRIORITY,
             &task3 stk[0],
             TASK STACKSIZE,
             NULL,
             OS_TASK_OPT_STK_CHK | OS_TASK_OPT_STK_CLR
 //Start multitasking under ucosii
 OSStart();
  return 0:
```

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```
void task1(void* pdata)
{
    INT8U error_code = OS_NO_ERR;
    int t1;

while (1)
{
     t1 = OSTimeGet();
     OSSemPend(shared_jtag_sem,0,&error_code);
     printf("Task1 sending message: %d ms\n",t1);
     OSSemPost(shared_jtag_sem);
     //Post the message with broadcast to all pending tasks
     error_code = OSMboxPostOpt(MSG_box,(void *)&t1,OS_POST_OPT_BROADCAST);
     OSTimeDlyHMSM(0, 0, 1, 0);
}
```

Running application with broadcast

```
Task1 sending message: 1071 ms
Task2 received message: 1071 ms (at 1076 ms)
Task3 received message: 1071 ms (at 1079 ms)
Task1 sending message: 2076 ms
Task2 received message: 2076 ms (at 2081 ms)
Task3 received message: 2076 ms (at 2083 ms)
```

```
void task2(void* pdata)
{
    INT8U error_code = OS_NO_ERR;
    int t1;
    int *msg_rx;

while (1)
{
    //Pend messages sent from task1
    msg_rx = (int*)OSMboxPend(MSG_box,0,&error_code);
    t1 = OSTimeGet();

    OSSemPend(shared_jtag_sem,0,&error_code);
    printf("Task2 received message: %d ms (at %d ms)\n",*msg_rx ,t1);
    OSSemPost(shared_jtag_sem);
}
```

Running application w/o broadcast

```
Task1 sending message: 1097 ms

Task2 received message: 1097 ms (at 1100 ms)

Task1 sending message: 2100 ms

Task2 received message: 2100 ms (at 2104 ms)

error_code = OSMboxPost(MSG_box,(void *)&t1);
```

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- OSMboxPend returns a pointer to the message sent through the mailbox
- If that messages is updated before the receiving task has processed the message, the data will be overwritten
- Solution: create a local copy of the received message

```
Task1 sending message: 171 ms
Task2 received message: 171 ms (at 174 ms)
Task1 sending message: 274 ms
Task2 received message: 274 ms (at 277 ms)
Task3 received message: 274 ms (at 176 ms)
```

```
void task3(void* pdata)
  INT8U error_code = OS_NO_ERR;
 int t1:
 int *msg_rx;
                                                              Task1 sending message: 170 ms
 int msq_local;
                                                              Task2 received message: 170 ms (at 173 ms)
 while (1)
                                                              Task1 sending message: 273 ms
   msg_rx = (int*)OSMboxPend(MSG_box,0,&error_code);
                                                              Task2 received message: 273 ms (at 276 ms)
   msg_local = *msg_rx;
                                                              Task3 received message: 170 ms (at 175 ms)
   t1 = OSTimeGet():
   usleep(110000);
   OSSemPend(shared_jtag_sem,0,&error_code);
    printf("Task3 received message: %d ms (at %d ms)\n",msq_local ,t1);
    OSSemPost(shared_jtag_sem);
```