

Modeling and simulation of multicellular and multiscale systems using the cellular Potts model

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Plan for week 45

Monday 2 Nov (Zoom only)

10:15 - 12:00, Lecture: Modelling multicellular systems using the cellular Potts model.

Tuesday 3 Nov (FV414 + Zoom)

12:00 - 13:20, Hands-on 1: Getting started with the software Morpheus.

13:40 - 15:00, Hands-on 2: Simulation and analysis of simple models.

Pre-assignments

Reading



+ Jupyter **Notebooks**

II.1 Magnetization to Morphogenesis: A Brief

Abstract. This chapter discusses the history and development of what we propose to rename the Glazier-Graner-Hogeweg model (GGH model), start-ing with its ancestors, simple models of magnetism, and concluding with its current state as a powerful, cell-oriented method for simulating biological de-velopment and tissue physiology. We will discuss some of the choices and accidents of this development and some of the positive and negative conse-quences of the model's pedigree.

Modeling multicellular systems using the cellular Potts model

Systems biology

Tissue

Bulk or single-cell data





Intracellular interactions Intracellular simulation





Multicellular systems biology



Tissue

Bulk or single-cell data

2 5 26 87

Intracellular interactions



Intracellular simulation



Tissue



Multicellular systems biology







Intracellular interactions Intracellular simulation





Tissue





Drost et al, Nature 2015

Multicellular systems biology





Tissue







Drost et al, Nature 2015

Intracellular interactions





Intercellular interactions





Multicellular Systems biology









Intracellular interactions

Intracellular simulation





Tissue



Image data



Drost et al, Nature 2015



Intercellular network





Buske et al., FEBS J 2012

Approaches for tissue and multicellular modeling

Tissue modeling: continuous approach

Drosophila segmentation



Hans Meinhardt, Models of Biological Pattern Formation 1982 The Algorithmic Beauty of Sea Shells 1998

Limb morphogenesis



Sheth et al., Science 2012

Vascular patterning



Manoussaki et al., Acta biotheoretica 1996

Cardiac physiology



Fenton et al., Scholarpedia 2008

Tissue modeling: discrete / cell-based approach

Lateral inhibition



Liver regeneration



Hoehme et al., PNAS 2010







Buske et al., 2011

Vascular Patterning



Köhn-Luque et al., 2013



Tissue modeling: discrete approach

- Tissue organization at cellular level
 - ▶ spatial structure
 - dynamic changes
- Cellular behavior
 - ▶ cell motility
 - cell division
 - cell adhesion
 - ▶ cell shape
 - ▶ etc.
- Multi-scale coupling
 - intracellular processes
 - extracellular gradients

Cell-based modeling

- Tissue organization at cellular level
 - ▶ spatial structure
 - dynamic changes
- Cellular behavior
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Multi-scale cell-based modeling

- Tissue organization at cellular level
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Multi-scale cell-based modeling

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Mathematical and Computational Models for cell-based modeling

Different cell-based modeling approaches



Different cell-based modeling approaches





Different cell-based modeling approaches





Cellular Potts model



vascular patterning

п г



Stem cells in the intestinal crypt



Social life of Dictoystelium Discoideum

CPM: From Magnetization to Morphogenesis

Ising Model	Potts Model Cellular Potts Model
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$
2 states	q states q states (unique per domain)
$\mathcal{H}_{ ext{lsing}} = -rac{J}{2} \sum_{(ec{i},ec{j}) ext{ neighbors}} \sigma(ec{i}) \sigma(ec{j})$	$ \mathcal{H}_{\text{Potts}} = J \sum_{\substack{(\vec{i},\vec{j}) \text{ neighbors} \\ \sigma}} (1 - \delta(\sigma(\vec{i}), \sigma(\vec{j}))) \\ + \lambda \sum_{\sigma} (v(\sigma) - V_t(\sigma))^2 \\ \mathcal{H}_{\text{CPM}} = \sum_{\substack{(\vec{i},\vec{j}) \text{ neighbors} \\ \sigma}} J(\tau(\sigma(\vec{i})), \tau(\sigma(\vec{j})))(1 - \delta(\sigma(\vec{i}), \sigma(\vec{j}))) \\ + \sum_{\sigma} \lambda_{\text{Vol}}(\tau)(v(\sigma) - V_t(\sigma)))^2 \\ \mathcal{H}_{\text{CPM}} = \sum_{\substack{(\vec{i},\vec{j}) \text{ neighbors} \\ \sigma}} J(\tau(\sigma(\vec{i})), \tau(\sigma(\vec{j})))(1 - \delta(\sigma(\vec{i}), \sigma(\vec{j}))) \\ + \sum_{\sigma} \lambda_{\text{Vol}}(\tau)(v(\sigma) - V_t(\sigma)))^2 \\ \mathcal{H}_{\text{CPM}} = \sum_{\substack{(\vec{i},\vec{j}) \text{ neighbors} \\ \sigma}} J(\tau(\sigma(\vec{i})), \tau(\sigma(\vec{j})))(1 - \delta(\sigma(\vec{i}), \sigma(\vec{j}))) \\ \mathcal{H}_{\text{CPM}} = \sum_{\substack{(\vec{i},\vec{j}) \text{ neighbors} \\ \sigma}} J(\tau(\sigma(\vec{i})), \tau(\sigma(\vec{j})))(1 - \delta(\sigma(\vec{i}), \sigma(\vec{j}))) \\ \mathcal{H}_{\text{CPM}} = \sum_{\substack{(\vec{i},\vec{j}) \text{ neighbors} \\ \sigma}} J(\tau(\sigma(\vec{i})), \tau(\sigma(\vec{j})))(1 - \delta(\sigma(\vec{i}), \sigma(\vec{j}))) \\ \mathcal{H}_{\text{CPM}} = \sum_{\substack{(\vec{i},\vec{j}) \text{ neighbors} \\ \sigma}} J(\tau(\sigma(\vec{i})), \tau(\sigma(\vec{j})))(1 - \delta(\sigma(\vec{i}), \sigma(\vec{j}))) \\ \mathcal{H}_{\text{CPM}} = \sum_{\substack{(\vec{i},\vec{j}) \text{ neighbors} \\ \sigma}} J(\tau(\sigma(\vec{i})), \tau(\sigma(\vec{j})))(1 - \delta(\sigma(\vec{i}), \sigma(\vec{j}))) \\ \mathcal{H}_{\text{CPM}} = \sum_{\substack{(\vec{i},\vec{j}) \text{ neighbors} \\ \sigma}} J(\tau(\sigma(\vec{i})), \tau(\sigma(\vec{j})))(1 - \delta(\sigma(\vec{i}), \sigma(\vec{j}))) \\ \mathcal{H}_{\text{CPM}} = \sum_{\substack{(\vec{i},\vec{j}) \text{ neighbors} \\ \sigma}} J(\tau(\sigma(\vec{i})), \tau(\sigma(\vec{j})))(1 - \delta(\sigma(\vec{i}), \sigma(\vec{j}))) \\ \mathcal{H}_{\text{CPM}} = \sum_{\substack{(\vec{i},\vec{j}) \text{ neighbors} \\ \sigma} J(\tau(\sigma(\vec{i})), \tau(\sigma(\vec{j})))(1 - \delta(\sigma(\vec{i}), \sigma(\vec{j}))) \\ \mathcal{H}_{\text{CPM}} = \sum_{\substack{(\vec{i},\vec{j}) \text{ neighbors} \\ \sigma} J(\tau(\sigma(\vec{i})), \tau(\sigma(\vec{j})))(1 - \delta(\sigma(\vec{i}), \sigma(\vec{j}))) \\ \mathcal{H}_{\text{CPM}} = \sum_{\substack{(\vec{i},\vec{j}) \text{ neighbors} \\ \sigma} J(\tau(\sigma(\vec{i})), \tau(\sigma(\vec{j})))(1 - \delta(\sigma(\vec{i}), \sigma(\vec{j}))) \\ \mathcal{H}_{\text{CPM}} = \sum_{\substack{(\vec{i},\vec{j}) \text{ neighbors} \\ \sigma} J(\tau(\sigma(\vec{i})), \tau(\sigma(\vec{j})))(1 - \delta(\sigma(\vec{j}), \sigma(\vec{j}))) \\ \mathcal{H}_{\text{CPM}} = \sum_{\substack{(\vec{i},\vec{j}) \text{ neighbors} \\ \sigma} J(\tau(\sigma(\vec{j})))(1 - \delta(\sigma(\vec{j}), \sigma(\vec{j})))} $
static equilibrium statistics	static equilibrium statistics kinetics
random initial conditions	physically-motivated initial conditions and domain properties domain properties

Cellular Potts model - cell size

Cell represented as a lattice domain





Cellular Potts model - contact energy



Contact	Cell	Medium
Cell	Jcc	Јсм
Medium	J _{CM}	—



Cellular Potts model - energy function



Cellular Potts model - dynamics

Stochastic minimization of energy

Modified Metropolis algorithm:

- Pick a random node
- · Pick a second random node in neighborhood
- Compute energy difference ΔH is spin is copied:

$$\Delta H = H_{after} - H_{before}$$

• Probability to accept copy depends on ΔH :





Cellular Potts model - dynamics

Stochastic minimization of energy

Modified Metropolis algorithm:

- Pick a random node
- · Pick a second random node in neighborhood
- Compute energy difference ΔH is spin is copied:

$$\Delta H = H_{after} - H_{before}$$

Probability to accept copy depends on ΔH:



Cellular Potts model - cell sorting

Energy function (Hamiltonian):



Energy minimization:

$$P(\Delta H) = \begin{cases} 1 & \text{if } \Delta H \le 0\\ e^{-\frac{\Delta H}{T}} & \text{otherwise} \end{cases}$$



CPM: Modeling Cell Sorting



Multi-scale cell-based modeling using CPM



Proposed Mechanism of Vascular Patterning





A hybrid cellular Potts model for vascular patterning





A hybrid cellular Potts model for vascular patterning





Morpheus modeling environment for multicellular systems biology Walter de Back ContextVision AB



Jörn Starruß Center for High Performance Computing



Computational modeling Workflow



Computational modeling Without the need for programming



Modeling features

Differential equations Gene regulatory and signaling networks



Ordinary differential equations Euler, Heun, Runge-Kutta, adaptive time-step methods, stiff methods

Stochastic differential equations Heun-Maruyama

Delay differential equations with constant delays

Import models in SBML format e.g. from BioModels database

Reaction-diffusion systems Morphogen gradients and intercellular signaling



Finite volume method

Reaction-diffusion systems Operator-splitting method

Import domains from images



Brusch et al., Curr Top Dev Biol, 2014

Cell-based models

Cell shape, motility and surface mechanics



Multi-scale models Coupling model formalisms



Multi-scale models Cell cycle example

- Intracellular ODE model for cell cycle dynamics
- Cell-based Potts model cell surface mechanics and cell division



Multi-scale models

Cell cycle example



A hybrid cellular Potts model for vascular patterning



Multi-scale models

Vascular patterning example

Multi-scale models

Mapping between different spatial contexts

Multi-scale models Mapping data to cell membranes

MembraneProperties

- Scalar field on cell membrane
- Couple to biomechanical properties

Ouchi et al., 2006

Multi-scale models

Mapping data to cell membranes

MembraneProperties

- Scalar field on cell membrane
- + System
- Reaction-diffusion on membrane

Multi-scale models Mapping data to cell membranes

MembraneProperties

- Scalar field on cell membrane
- + System
- Reaction-diffusion on membrane

+ NeighborhoodReporter

 Modeling cell-cell signaling via membrane-bound ligands/receptors

Automation and model integration

Convert mathematical models into simulations

Convert mathematical models into simulations

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Cellular Potts model

Energy function (Hamiltonian):

Modified Metropolis algorithm for energy minimization:

$$P(\Delta H) = \begin{cases} 1 & \text{if } \Delta H \leq 0\\ e^{-\frac{\Delta H}{T}} & \text{otherwise} \end{cases}$$

Hands-on session 1: Getting started with Morpheus

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Goals for hands-on session 1

- 1. Check out the GUI and run example models
- 2. Understand and edit the main components of a model
- 3. Construct a simple ODE model, export and visualize the data
- 4. Build a simple CPM model and visualize cells
- 5. Combine these models to create a multi-scale model.

Hands-on session 2: Simulation and analysis of simple models

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Goals for hands-on session 2

- 1. Select parameters for a parameter sweep analysis
- 2. Specify parameter ranges
- 3. Run a parameter sweep
- 4. Visualize sets of simulation results from a parameter sweep
- 5. Use a python notebook for further analysis