

Guide to Clawpack

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FYS-GEO 4500

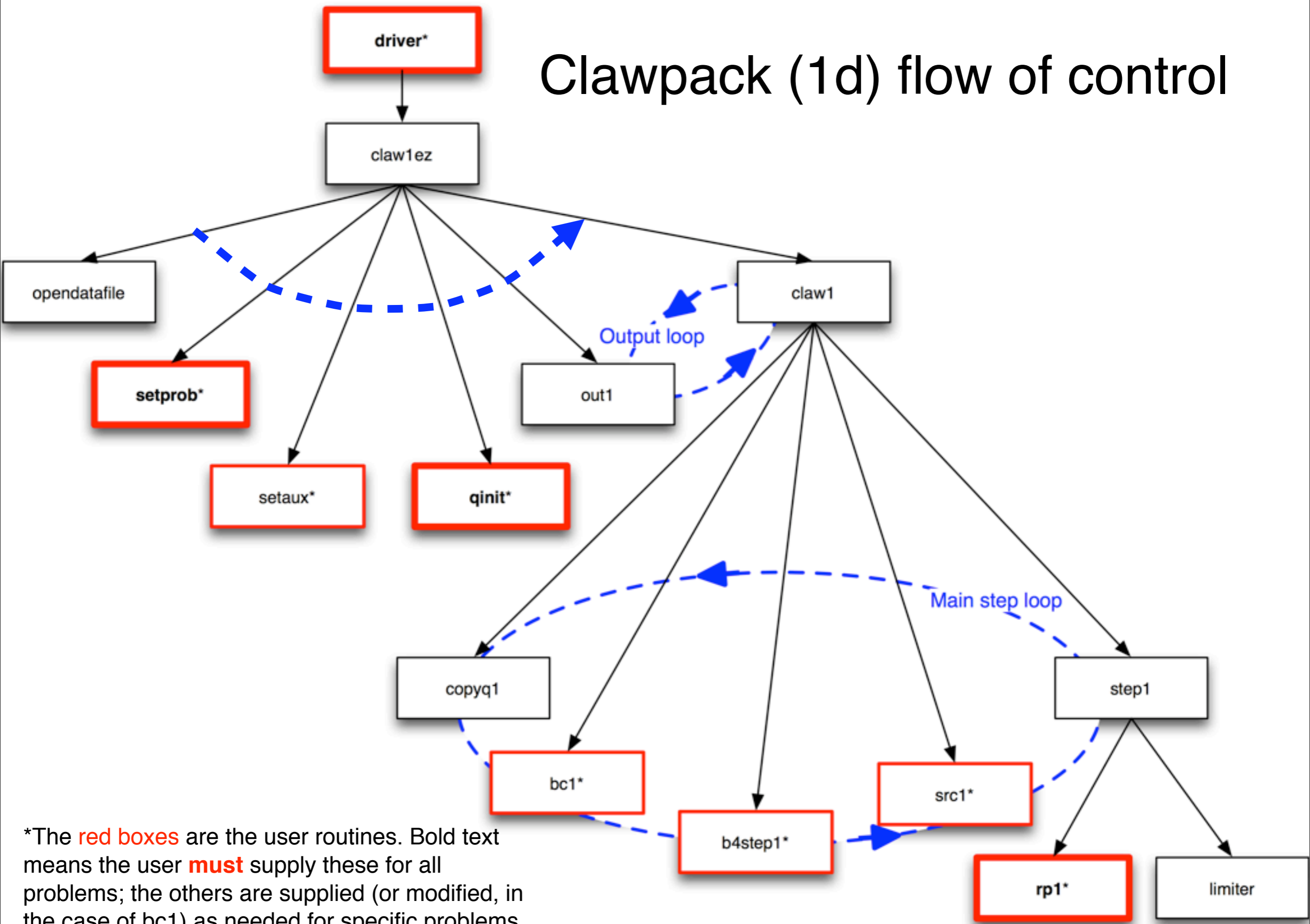
Program flow -1d - Fortran version

driver

```
call claw1ez
  call opendatafile
  call setprob*
  call setaux*
  call qinit*
  call out1
  loop on output steps
    call claw1
      loop on single steps
        call copyq1 (if variable time step)
        call bc1*
        call b4step1*
        call src1* (if using Strang splitting)
        call step1
          call rp1*
          call limiter
          call src1* (if needed)
          call copyq1 (if needed)
        end loop on single steps
      call out1
    end loop on output steps
  end
end
```

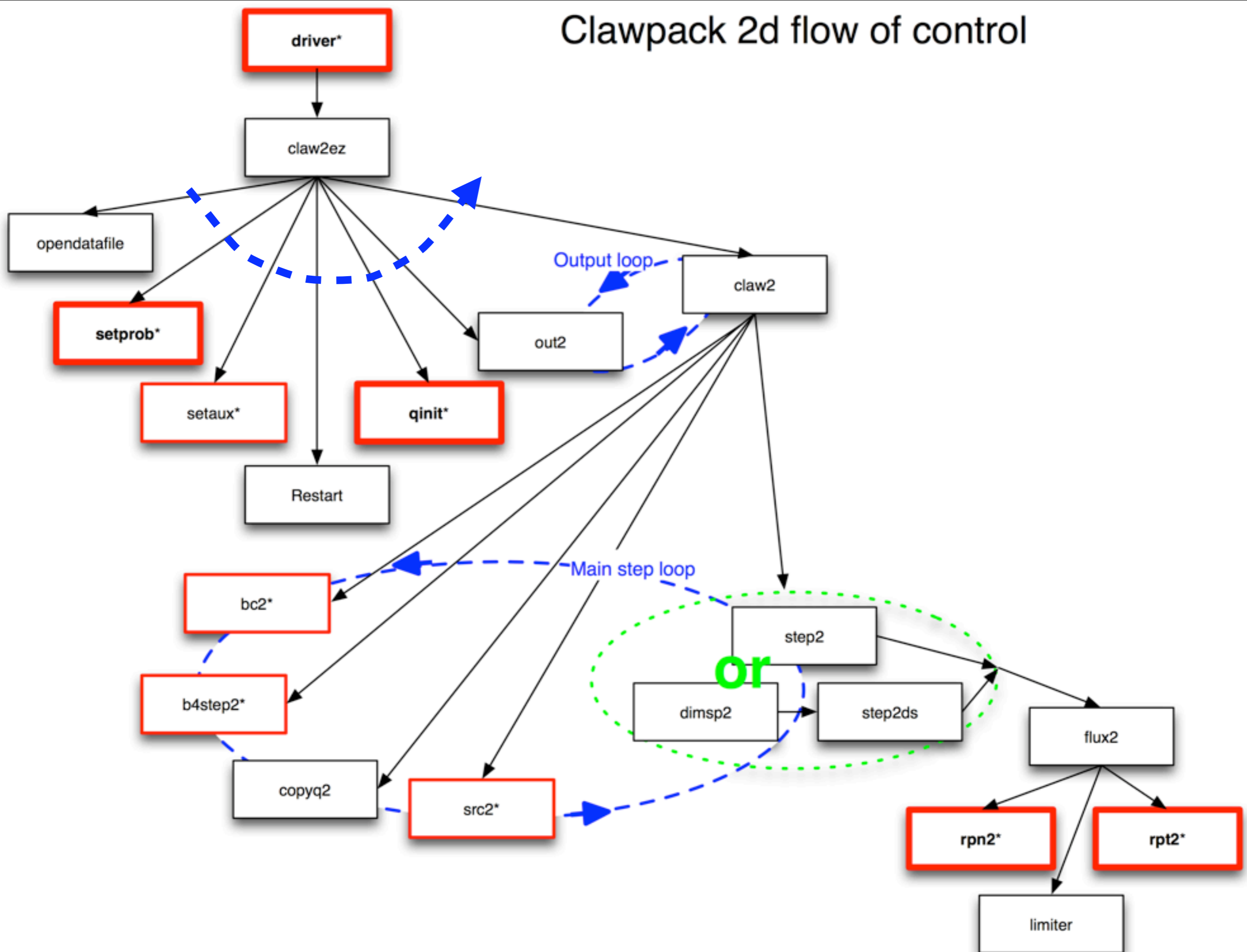
*The **red names** are the user routines. **Bold text** means the user must supply these for all problems, others are supplied (or modified, in the case of bc1) as needed for specific problems.

Clawpack (1d) flow of control

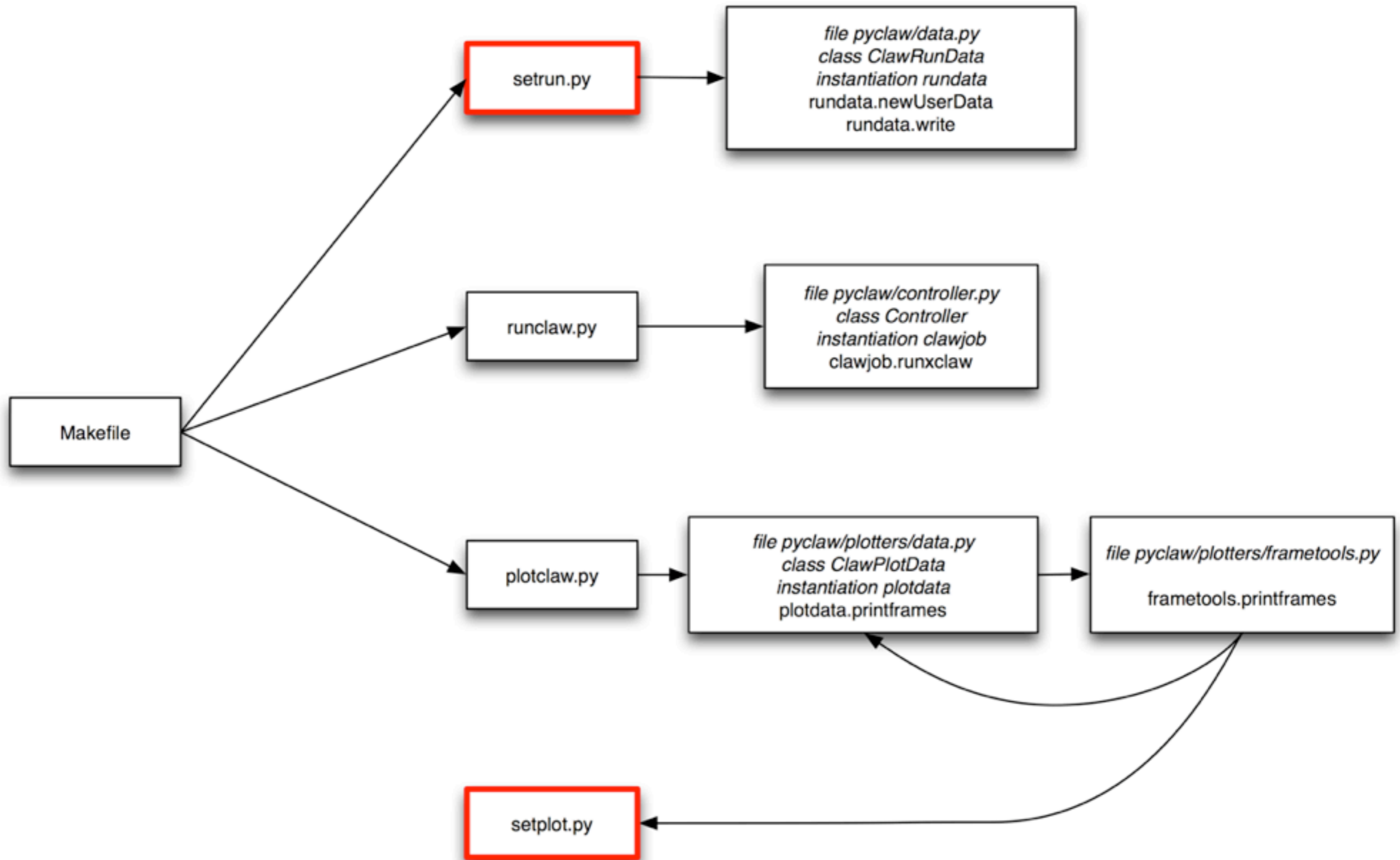


*The **red boxes** are the user routines. Bold text means the user **must** supply these for all problems; the others are supplied (or modified, in the case of **bc1**) as needed for specific problems.

Clawpack 2d flow of control



What Makefile does



Your Makefile must point to the appropriate source code files

```
#  
# List of sources for this program:
```

```
#  
CLAW_SOURCES = \  
driver.f \  
qinit.f \  
rpn2.f \  
rpt2.f \  
setprob.f
```

These are the files you write (or change) yourself. Include other files like bc2.f, b4step2.f, src2.f, and so on as needed. These should be in your run directory under \$CLAW/myclaw (as this Makefile is).

```
# Clawpack library to be used:  
CLAW_LIB = $(CLAW)/clawpack/2d/lib
```

```
CLAW_LIBSOURCES = \  
$(CLAW_LIB)/claw2ez.f \  
$(CLAW_LIB)/bc2.f \  
$(CLAW_LIB)/setaux.f \  
$(CLAW_LIB)/b4step2.f \  
$(CLAW_LIB)/claw2.f \  
$(CLAW_LIB)/step2.f \  
$(CLAW_LIB)/step2ds.f \  
$(CLAW_LIB)/dimsp2.f \  
$(CLAW_LIB)/flux2.f \  
$(CLAW_LIB)/copyq2.f \  
$(CLAW_LIB)/limiter.f \  
$(CLAW_LIB)/philim.f \  
$(CLAW_LIB)/src2.f\  
$(CLAW_LIB)/out2.f\  
$(CLAW_LIB)/restart2.f\  
$(CLAW_LIB)/opendatafile.f
```

These are the files you use from the Clawpack library referenced in the line above (2d or 1d are available now; 3d will come later).

If you want to make changes to any of these, make a copy first and move the copy to your run directory under \$CLAW/myclaw. You may change it there, but to use it you must add its name to the list above and remove it from this list.

What Makefile does

In `$CLAW/util/Makefile.common` (which should be invoked by every Clawpack Makefile):

```
#      Makefile for the clawpack code:
#
#      For this help summary, type:                make .help
#
#      To make all object files, type:             make .objs
#
#      To compile a single file.f:                 make file.o
#
#      To make the executable, type:               make .exe
#
#      To make data files by running
#      setrun.py:                                make .data      setrun.py
#
#      To make and run code putting results
#      in subdirectory named output:               make .output
#
#      To make and run code and then plot
#      results from subdirectory output
#      into subdirectory named plots:          make .plots     setplot.py
#
#      To create html files from the program
#      and data files using clawcode2html:         make .htmls
#
#      To clean up files created by make:           make clean
#      Deletes *.o, x*, .htmls
#
#      To clean up output and graphics files:      make clobber
#
```

What Makefile does

In `CLAW/util/Makefile.common`:

```
# Executable:
.objs: $(CLAW_OBJECTS) $(CLAW_LIBOBJECTS)
$(CLAW_EXE): $(CLAW_OBJECTS) $(CLAW_LIBOBJECTS)
    $(LINK) $(LFLAGS) $(CLAW_OBJECTS) $(CLAW_LIBOBJECTS) -o $(CLAW_EXE)
.exe: $(CLAW_EXE) ;
```

```
# Make data files needed by Fortran code:
.data: $(CLAW_setrun_file) ;
    python $(CLAW_setrun_file) $(CLAW_PKG)
    touch .data
```

```
# Run the code and put fort.* files into subdirectory named output:
# runclaw will execute setrun.py to create data files and determine
# what executable to run, e.g. xclaw or xamr.
.output: $(CLAW_EXE) .data;
    python $(CLAW)/python/pyclaw/runclaw.py $(CLAW_EXE) $(CLAW_OUTDIR)
    @echo $(CLAW_OUTDIR) > .output
```

```
# Rule to make the plots into subdirectory specified by CLAW_PLOTDIR,
# using data in subdirectory specified by CLAW_OUTDIR and the plotting
# commands specified in CLAW_setplot_file.
.plots: .output $(CLAW_setplot_file) ;
    $(PLOT_CMD) $(CLAW_OUTDIR) $(CLAW_PLOTDIR) $(CLAW_setplot_file)
    @echo $(CLAW_PLOTDIR) > .plots
```

```
CLAW_PKG = Classic                # Clawpack package to use
CLAW_EXE = xclaw                  # Executable to create
CLAW_setrun_file = setrun.py      # File containing function to make data
CLAW_OUTDIR = _output             # Directory for output
CLAW_setplot_file = setplot.py    # File containing function to set plots
CLAW_PLOTDIR = _plots            # Directory for plots
PLOT_CMD := python $(CLAW)/python/pyclaw/plotters/plotclaw.py
```


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    $(LINK) $(LFLAGS) $(CLAW_OBJECTS) $(CLAW_LIBOBJECTS) -o $(CLAW_EXE)
.exe: $(CLAW_EXE) ;
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# Make data files needed by Fortran code:
.data: $(CLAW_setrun_file) ;
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# what executable to run, e.g. xclaw or xamr.
.output: $(CLAW_EXE) .data;
    python $(CLAW)/python/pyclaw/runclaw.py $(CLAW_EXE) $(CLAW_OUTDIR)
    @echo $(CLAW_OUTDIR) > .output
```

```
# Rule to make the plots into subdirectory specified by CLAW_PLOTDIR,
# using data in subdirectory specified by CLAW_OUTDIR and the plotting
# commands specified in CLAW_setplot_file.
.plots: .output $(CLAW_setplot_file) ;
    $(PLOT_CMD) $(CLAW_OUTDIR) $(CLAW_PLOTDIR) $(CLAW_setplot_file)
    @echo $(CLAW_PLOTDIR) > .plots
```

```
CLAW_PKG = Classic                # Clawpack package to use
CLAW_EXE = xclaw                  # Executable to create
CLAW_setrun_file = setrun.py      # File containing function to make data
CLAW_OUTDIR = _output             # Directory for output
CLAW_setplot_file = setplot.py   # File containing function to set plots
CLAW_PLOTDIR = _plots             # Directory for plots
PLOT_CMD := python $(CLAW)/python/pyclaw/plotters/plotclaw.py
```

Rule

Target

Requirements

What Makefile does

In \$CLAW/util/Makefile.common:

```
# Executable:
objs: $(CLAW_OBJECTS) $(CLAW_LIBOBJECTS)
$(CLAW_EXE): $(CLAW_OBJECTS) $(CLAW_LIBOBJECTS)
$(LINK) $(LFLAGS) $(CLAW_OBJECTS) $(CLAW_LIBOBJECTS) -o $(CLAW_EXE)
.exe: $(CLAW_EXE) ;
```

```
# Make data files needed by Fortran code:
.data: $(CLAW_setrun_file) ;
python $(CLAW_setrun_file) $(CLAW_PKG)
touch .data
```

```
# Run the code and put fort.* files into subdirectory named output:
# runclaw will execute setrun.py to create data files and determine
# what executable to run, e.g. xclaw or xamr.
.output: $(CLAW_EXE) .data;
python $(CLAW)/python/pyclaw/runclaw.py $(CLAW_EXE) $(CLAW_OUTDIR)
@echo $(CLAW_OUTDIR) > .output
```

```
# Rule to make the plots into subdirectory specified by CLAW_PLOTDIR,
# using data in subdirectory specified by CLAW_OUTDIR and the plotting
# commands specified in CLAW_setplot_file.
.plots: .output $(CLAW_setplot_file) ;
$(PLOT_CMD) $(CLAW_OUTDIR) $(CLAW_PLOTDIR) $(CLAW_setplot_file)
@echo $(CLAW_PLOTDIR) > .plots
```

```
CLAW_PKG = Classic # Clawpack package to use
CLAW_EXE = xclaw # Executable to create
CLAW_setrun_file = setrun.py # File containing function to make data
CLAW_OUTDIR = _output # Directory for output
CLAW_setplot_file = setplot.py # File containing function to set plots
CLAW_PLOTDIR = _plots # Directory for plots
PLOT_CMD := python $(CLAW)/python/pyclaw/plotters/plotclaw.py
```

Rule

What Makefile does

In \$CLAW/util/Makefile.common:

```
# Executable:
.objs: $(CLAW_OBJECTS) $(CLAW_LIBOBJECTS)
$(CLAW_EXE): $(CLAW_OBJECTS) $(CLAW_LIBOBJECTS)
    $(LINK) $(LFLAGS) $(CLAW_OBJECTS) $(CLAW_LIBOBJECTS) -o $(CLAW_EXE)
.exe: $(CLAW_EXE) ;
```

```
# Make data files needed by Fortran code:
```

```
.data: $(CLAW_setrun_file) ;
    python $(CLAW_setrun_file) $(CLAW_PKG)
    touch .data
```

Command

```
# Run the code and put fort.* files into subdirectory named output:
# runclaw will execute setrun.py to create data files and determine
# what executable to run, e.g. xclaw or xamr.
```

```
.output: $(CLAW_EXE) .data;
    python $(CLAW)/python/pyclaw/runclaw.py $(CLAW_EXE) $(CLAW_OUTDIR)
    @echo $(CLAW_OUTDIR) > .output
```

Rule

```
# Rule to make the plots into subdirectory specified by CLAW_PLOTDIR,
# using data in subdirectory specified by CLAW_OUTDIR and the plotting
# commands specified in CLAW_setplot_file.
```

```
.plots: .output $(CLAW_setplot_file) ;
    $(PLOT_CMD) $(CLAW_OUTDIR) $(CLAW_PLOTDIR) $(CLAW_setplot_file)
    @echo $(CLAW_PLOTDIR) > .plots
```

```
CLAW_PKG = Classic          # Clawpack package to use
CLAW_EXE = xclaw           # Executable to create
CLAW_setrun_file = setrun.py # File containing function to make data
CLAW_OUTDIR = _output      # Directory for output
CLAW_setplot_file = setplot.py # File containing function to set plots
CLAW_PLOTDIR = _plots      # Directory for plots
PLOT_CMD := python $(CLAW)/python/pyclaw/plotters/plotclaw.py
```

What Makefile does

In `CLAW/util/Makefile.common`:

```
# Executable:
.objs: $(CLAW_OBJECTS) $(CLAW_LIBOBJECTS)
$(CLAW_EXE): $(CLAW_OBJECTS) $(CLAW_LIBOBJECTS)
    $(LINK) $(LFLAGS) $(CLAW_OBJECTS) $(CLAW_LIBOBJECTS) -o $(CLAW_EXE)
.exe: $(CLAW_EXE) ;
```

```
# Make data files needed by Fortran code:
.data: $(CLAW_setrun_file) ;
    python setrun.py Classic
    touch .data
```

```
# Run the code and put fort.* files into subdirectory named output:
# runclaw will execute setrun.py to create data files and determine
# what executable to run, e.g. xclaw or xamr.
.output: $(CLAW_EXE) .data;
    python CLAW/python/pyclaw/runclaw.py xclaw _output
    @echo $(CLAW_OUTDIR) > .output
```

```
# Rule to make the plots into subdirectory specified by CLAW_PLOTDIR,
# using data in subdirectory specified by CLAW_OUTDIR and the plotting
# commands specified in CLAW_setplot_file.
.plots: .output $(CLAW_setplot_file) ;
    python CLAW/python/pyclaw/plotters/plotclaw.py _output _plots setplot.py
    @echo $(CLAW_PLOTDIR) > .plots
```

```
CLAW_PKG = Classic                # Clawpack package to use
CLAW_EXE = xclaw                  # Executable to create
CLAW_setrun_file = setrun.py      # File containing function to make data
CLAW_OUTDIR = _output             # Directory for output
CLAW_setplot_file = setplot.py    # File containing function to set plots
CLAW_PLOTDIR = _plots             # Directory for plots
PLOT_CMD := python $(CLAW)/python/pyclaw/plotters/plotclaw.py
```

What Makefile does

In `$CLAW/util/Makefile.common`:

`setrun.py` and `setplot.py` should be defined in the run directory and can be changed by you

`runclaw.py` and `plotclaw.py` are defined in `$CLAW/python/pyclaw` and should not be changed

```
# Make data files needed by Fortran code:
```

```
.data: $(CLAW_setrun_file) ;  
    python setrun.py    Classic  
    touch .data
```

```
# Run the code and put fort.* files into subdirectory named output:
```

```
# runclaw will execute setrun.py to create data files and determine  
# what executable to run, e.g. xclaw or xamr.  
.output: $(CLAW_EXE) .data;  
    python $CLAW/python/pyclaw/runclaw.py    xclaw    _output  
    @echo $(CLAW_OUTDIR) > .output
```

```
# Rule to make the plots into subdirectory specified by CLAW_PLOTDIR,
```

```
# using data in subdirectory specified by CLAW_OUTDIR and the plotting
```

```
# commands specified in CLAW_setplot_file.
```

```
.plots: .output $(CLAW_setplot_file) ;  
    python $CLAW/python/pyclaw/plotters/plotclaw.py    _output    _plots    setplot.py  
    @echo $(CLAW_PLOTDIR) > .plots
```

```
CLAW_PKG = Classic                # Clawpack package to use  
CLAW_EXE = xclaw                  # Executable to create  
CLAW_setrun_file = setrun.py      # File containing function to make data  
CLAW_OUTDIR = _output             # Directory for output  
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CLAW_PLOTDIR = _plots             # Directory for plots  
PLOTCMD := python $(CLAW)/python/pyclaw/plotters/plotclaw.py
```

What about Python?

Directory structure of \$CLAW/python/pyclaw:

Makefile
README.txt

__init__.py
controller.py
data.py
runclaw.py
solution.py
util.py



controllers, etc., for Fortran **or** Python version of clawpack

evolve

__init__.py
clawpack.py
limiters.py
solver.py
rp



Python version of clawpack

__init__.py
rp_acoustics.py
rp_advection.py
rp_burgers.py
rp_euler.py
rp_shallow.py

io

__init__.py
ascii.py
hdf5.py
netcdf.py



input/output routines for Python version of clawpack

plotters

__init__.py
lplotclaw.py
colormaps.py
data.py
frametools.py
multiframetools.py
plotclaw.py
plotpages.py
TODO



plotting routines for Fortran **or** Python version of clawpack

More information about using Python with
Clawpack, especially the plotting stuff,
available from:

<http://kingkong.amath.washington.edu/claw4/www/users/>

<http://kingkong.amath.washington.edu/claw4/www/users/plotting.html#plotting>

<http://kingkong.amath.washington.edu/claw4/www/users/pyclaw/index.html#pyclaw>