

IN3070/4070 – Logic – Autumn 2020

Lecture 11: Modal Logics

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INFORMATICS



UNIVERSITY OF
OSLO

Today's Plan

- ▶ Motivation
- ▶ Modal Logic
- ▶ Satisfiability & Validity
- ▶ Different Modal Logics
- ▶ A Modal Sequent Calculus

Outline

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- ▶ Modal Logic
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- ▶ Turns out: many of the reasoning patterns from the previous slide can be turned into **decidable logics**.

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- ▶ $\Diamond \Box$ is not a formula.

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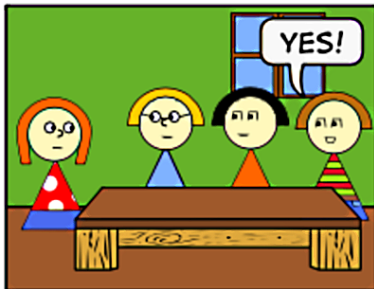
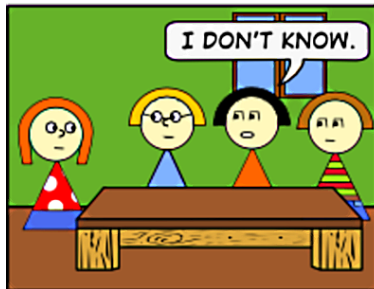
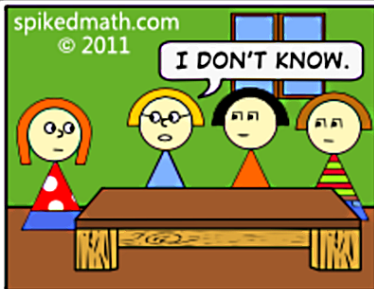
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- ▶ For epistemic logic, we want:

$$\{p \rightarrow \Box p, \Diamond \neg p\} \models \neg p$$

THREE LOGICIANS WALK INTO A BAR...



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- ▶ for temporal logic, we want:

$$\{p, \Box(p \rightarrow \Diamond q), \Box(q \rightarrow \Diamond p)\} \models \Box\Diamond(q \wedge \Diamond p)$$

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Definition 2.4 (Modal Interpretation).

A *modal interpretation (Kripke model)* $\mathcal{I}_M := (F, \{\mathcal{I}(w)\}_{w \in W})$ consists of

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A *propositional interpretation* is a function $\mathcal{I} : \mathcal{P} \rightarrow \{T, F\}$ that assigns a truth value to every propositional variable.

Definition 2.4 (Modal Interpretation).

A *modal interpretation (Kripke model)* $\mathcal{I}_M := (F, \{\mathcal{I}(w)\}_{w \in W})$ consists of

- ▶ a *Kripke frame* $F = (W, R)$

Kripke Semantics

Definition 2.2 (Kripke Frame).

A *(Kripke) frame* $F = (W, R)$ consists of

- ▶ a non-empty set of *worlds* W
- ▶ a binary *accessibility relation* $R \subseteq W \times W$ on the worlds in W

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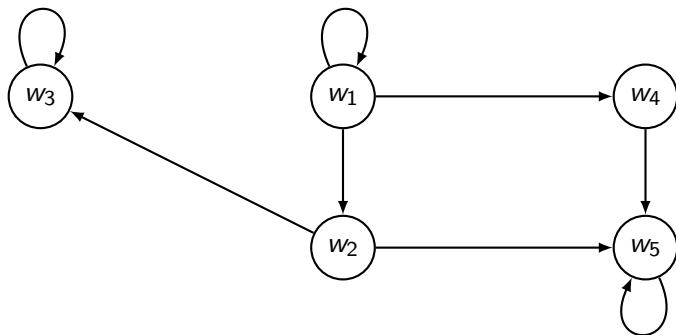
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Kripke Frame – Example

Example: $F = (W, R)$ with $W = \{w_1, w_2, w_3, w_4, w_5\}$ and

$$R = \{(w_1, w_1), (w_3, w_3), (w_5, w_5), \\ (w_1, w_2), (w_2, w_3), (w_1, w_4), (w_4, w_5), (w_2, w_5)\}$$



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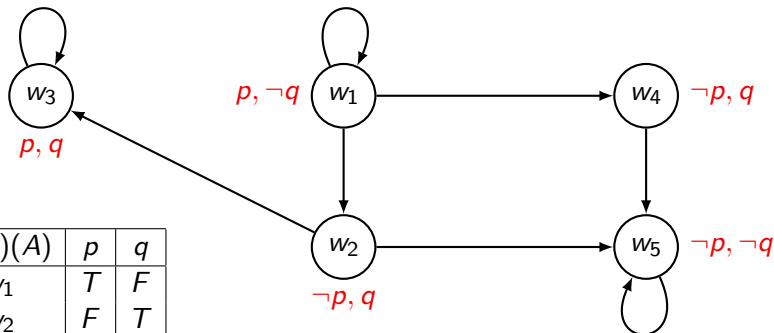
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- ▶ Temporal logic:
 - ▶ Worlds: states at different points in time
 - ▶ $w_1 R w_2$: w_1 is earlier than w_2 .

Kripke Model – Example

Example: $F = (W, R)$ as before



$\mathcal{I}(w)(A)$	p	q
w_1	T	F
w_2	F	T
w_3	T	T
w_4	F	T
w_5	F	F

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Definition 2.5 (Modal Truth Value).

Let $\mathcal{I}_M = ((W, R), \{\mathcal{I}(w)\}_{w \in W})$ be a Kripke model. The *modal truth value* $v_{\mathcal{I}_M}(w, A)$ of a formula A in the world w in the model \mathcal{I}_M is *T* (*true*) if “ w forces A under \mathcal{I}_M ”, denoted $w \Vdash A$, and *F* (*false*), otherwise.

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- ▶ $w \Vdash A \wedge B$ iff $w \Vdash A$ and $w \Vdash B$
- ▶ $w \Vdash A \vee B$ iff $w \Vdash A$ or $w \Vdash B$
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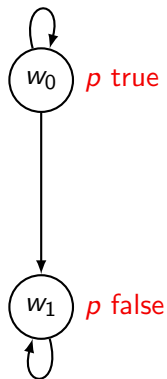
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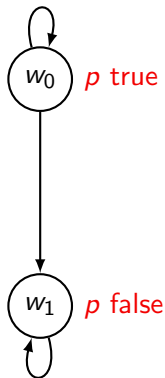


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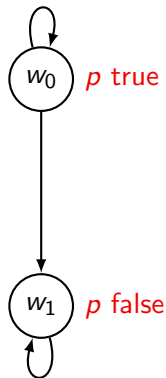
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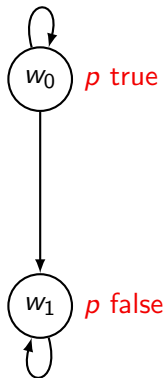
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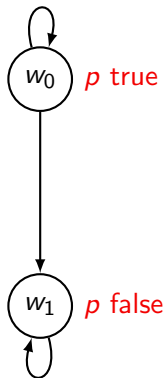
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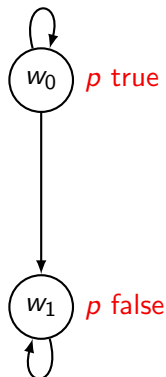
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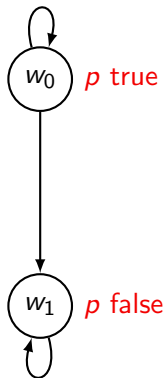
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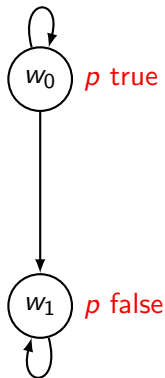
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Checking the weather

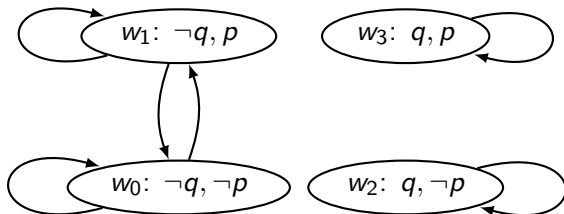
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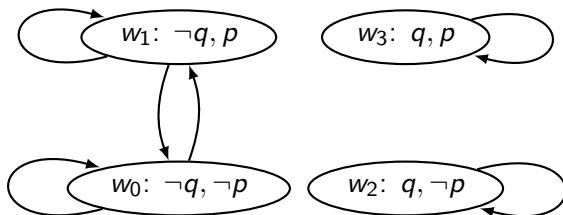
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- ▶ If we look out of the window, we know whether it rains:

$$\mathcal{I} \models q \rightarrow ((p \rightarrow \Box p) \wedge (\neg p \rightarrow \Box \neg p))$$

Outline

- ▶ Motivation
- ▶ Modal Logic
- ▶ Satisfiability & Validity
- ▶ Different Modal Logics
- ▶ A Modal Sequent Calculus

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Example: K

Proposition 3.1.

$$K := \Box(p \rightarrow q) \rightarrow (\Box p \rightarrow \Box q)$$

is a valid formula of modal logic.

Proof.

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Logical Consequence: Local and Global

There are two ways of defining logical consequence in modal logic.

Definition 3.2 (Global Logical Consequence).

Let U be a set of formulae and A be a formula. A is a *global consequence* of U , denote $U \models^G A$, iff for every modal interpretation \mathcal{I}_M the following holds: if $w \Vdash F$ for all $F \in U$ and all worlds $w \in W$ then $w \Vdash A$ for all worlds $w \in W$.

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Let U be a set of formulae and A be a formula. A is a *global consequence* of U , denote $U \models^G A$, iff for every modal interpretation \mathcal{I}_M the following holds: if $w \Vdash F$ for all $F \in U$ and all worlds $w \in W$ then $w \Vdash A$ for all worlds $w \in W$.

Definition 3.3 (Local Logical Consequence).

Let U be a set of formulae and A be a formula. A is a *local consequence* of U , denote $U \models^L A$, iff for every modal interpretation \mathcal{I}_M the following holds: for all world $w \in W$ if $w \Vdash F$ for all $F \in U$ then $w \Vdash A$.

- ▶ the deduction theorem does not hold for the global consequence
- ▶ if $U \models^L A$ then $U \models^G A$; the opposite direction does not hold

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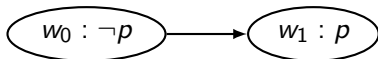
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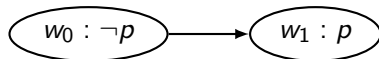
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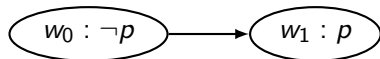
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A frame (W, R) is **reflexive**
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- ▶ Reminder: (W, R) is reflexive if wRw for all $w \in W$.

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modal logic	condition on R	axioms
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D	serial	$\Box A \rightarrow \Diamond A$
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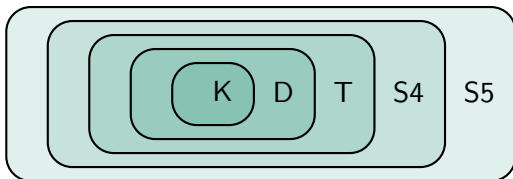
Lemma: if a relation is reflexive and euclidean, it is also symmetric and transitive, i.e. an equivalence relation.

Validity Relation for Different Modal Logics

The **validity relationship** between different modal logics and domain conditions is depicted in the following figure:

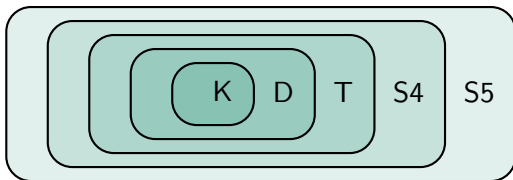
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E.g. a formula that is valid in D is also valid in T, S4, etc.

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- ▶ Axioms require same labels: $u : A, \Gamma \Rightarrow u : A, \Gamma$

Rules for the Succedent

- ▶ The \Box -right rule creates a new label:

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Proof Example

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$$\frac{1 : \Box p \wedge \Diamond q \Rightarrow 1 : \Diamond(p \wedge q)}{\Rightarrow 1 : (\Box p \wedge \Diamond q) \rightarrow \Diamond(p \wedge q)} \rightarrow\text{-right}$$

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$$\frac{
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 }{\diamond\text{-right}}$$

Proof Example

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 \dots, 2 : p, 2 : q, 1R2 \Rightarrow 2 : p, \dots \quad \dots, 2 : p, 2 : q, 1R2 \Rightarrow 2 : q, \dots \\
 \hline
 \dots, 2 : p, 2 : q, 1R2 \Rightarrow 2 : p \wedge q, 1 : \diamond(p \wedge q) \quad \wedge\text{-left} \\
 \hline
 1 : \Box p, 2 : p, 2 : q, 1R2 \Rightarrow 1 : \diamond(p \wedge q) \quad \diamond\text{-right} \\
 \hline
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 - ▶ More about that next week!