2nd November 2022

- Binary heaps
- Leftist heaps
- Binomial heaps
- Fibonacci heaps

Priority queues are important in, among other things, operating systems (process control in multitasking systems), search algorithms $(A, A^*, D^*, etc.),$ and simulation.

Priority queues are data structures that hold elements with some kind of priority (*key*) in a queue-like structure, implementing the following operations:

- **insert()** Inserting an element into the queue.
- **deleteMin()** Removing the element with the highest priority.

And maybe also:

- **buildHeap ()** Build a queue from a set (>1) of elements.
- **increaseKey()/DecreaseKey()** Change priority.
- delete() Removing an element from the queue.
- $\text{merge}()$ Merge two queues.

An unsorted linked list can be used. **insert()** inserts an element at the head of the list (*O*(1)), and **deleteMin()** searches the list for the element with the highest priority and removes it (*O*(*n*)).

A sorted list can also be used (reversed running times).

– Not very efficient implementations.

To make an efficient priority queue, it is enough to keeps the elements "almost sorted".

A *binary heap* is organized as a complete binary tree. (All levels are full, except possibly the last.)

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insert(14)

Binary Heaps (16) **insert(14)**

 (21)

 $\begin{pmatrix} 19 \end{pmatrix}$ (68)

"**percolateUp()**"

deleteMin()

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deleteMin()

"**percolateDown()**"

buildHeap() *O*(*N*)

(Insert elements into the array unsorted, and run **percolateDown()** on each root in the resulting heap (the tree), bottom up)

(The sum of the heights of a binary tree with *N* nodes is O(*N*).)

merge() *O*(*N*)

(*N* = number of elements)

- To implement an efficient **merge()**, we move away from arrays, and implement so-called *leftist heaps* as pure trees.
- The idea behind leftist heaps is to make the heap (the tree) as skewed as possible, and do all the work on a short (right) branch, leaving the long (left) branch untouched.
- A *leftist heap* is still a binary tree with the heap structure (key in root is lower
than key in children), but with an extra skewness requirement.
- For all nodes *X* in our tree, we define the *null-path-length*(*X*) as the distance from *X* to a descendant with less than two children (*i.e.* 0 or 1).
- **The skewness requirement is that for every node the null path length of its left child be at least as large as the null path length of the right child.**
- For the empty tree we define the *null-path-length* to be -1, as a special case.

merge() *O*(log *N*)

Worst Case

insert() *O*(log *N*) **deleteMin()** *O*(log *N*)

buildHeap() *O*(*N*)

(*N* = number of elements)

In a leftist heap with *N* nodes, the right path is at most $\lfloor \log (N+1) \rfloor$ long.

Leftist heaps:

merge(), **insert()** and **deleteMin()** in *O*(log *N*) time w.c.

Binary heaps:

insert() in *O*(1) time on average.

Binomial heaps

merge(), **insert()** og **deleteMin()** in *O*(log *N*) time w.c. **insert()** *O*(1) time on average

Binomial heaps are collections of trees (sometimes called a forest), each tree a heap.

 \bigcirc B_0

 \bigcap B_0 B_1

Maximum one tree of each size:

6 elements: 6 binary = 011 (0+2+4) $\cancel{B_0}$ B₁ B₂

(Doubly linked, circular list.)

The trees (the root list) is kept sorted on height.

buildHeap() *O*(*N*) *O*(*N*) (Run *N* **insert()** on an initially empty heap.)

(*N* = number of elements)

Binomial Heaps – implementation

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- Very elegant, and in theory efficient, way to implement heaps: Most operations have *O*(1) amortized running time. (Fredman & Tarjan '87)
- **insert()**, **decreaseKey()** and **merge()** *O*(1) amortized time
-

• **deleteMin()** *O*(log *N*) amortized time

- Combines elements from leftist heaps and binomial heaps.
- A bit complicated to implement, and certain hidden constants are a bit high.
- Best suited when there are few **deleteMin ()** compared to the other operations. The data structure was developed for a shortest path algorithm (with many **decreaseKey ()** operations), also used in spanning tree algorithms.

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- The second time a node gets a child node removed, it is cut off, and becomes the root of a separate tree

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The problem with our **decreaseKey()**-method and *lazy merging* is that we have to clean up afterwards. This is done in by the **deleteMin()**-method, which then becomes expensive (*O*(log *N*) amortized time):

- All trees are examined, we start with the smallest, and merge two and two, so that we get at most one tree of each size.
- Each root has a number of children this is used as the size of the tree. (Recall how we construct binomial trees, and that they may be partial as a result of **decreaseKey()** operations)
- The trees are put in lists, one per size, and we begin merging, starting with the smallest. (As for Binomial heaps.)

buildHeap() *O*(*N*) (Run *N* **insert()** on an initially empty heap.)

(*N* = number of elements)