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String Search

7th September 2022

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Searching is increasingly important

- Vast ammounts of information is available
 - Google and other search engines search for given strings (or sets of strings) on all registered web-pages
 - The amount of stored digital information grows steadily (rapidly – 61 % compound rate)
 - 3 zettabytes (10²¹ = 1 000 000 000 000 000 000 000 bytes) in 2012
 - 4.4 zettabytes in 2013
 - 59 zettabytes in 2020 (44 ZB estimated in 2019)
 - 175 zettabytes in 2025 (estimated)





Searching is increasingly important

- Search for a given pattern in DNA strings (about 3 «gigaletters» (10⁹) in human DNA – four letters in the alphabet: A, C, G, T)
- Searching for similar patterns is also relevant
 - The genetic sequences in organisms are changing over time because of mutations
 - We will look at searches for similar patterns that in connection with **Dynamic Programming**

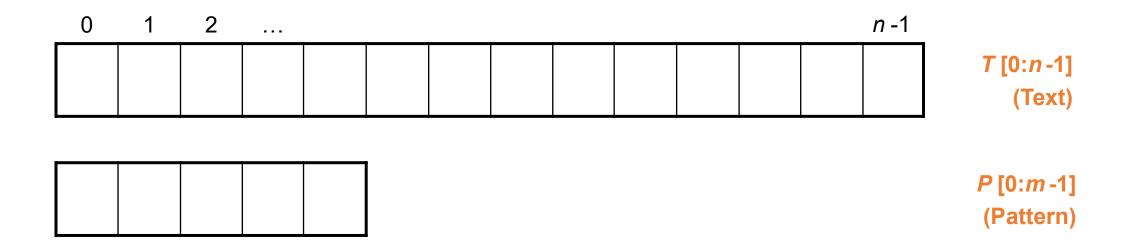


Definitions

- An **alphabet** is a finite set of «symbols» $A = \{a_1, a_2, ..., a_k\}$
- A string S = S [0: n-1] or S = < s₀ s₁... s_{n-1} > of length n is a sequence of n symbols from A

String Search:

Given two strings *T* (= Text) and *P* (= Pattern), *P* is usually much shorter than *T* Decide whether *P* occurs as a (continuous) substring in *T*, and if so, find where it occurs



Variants of String Search

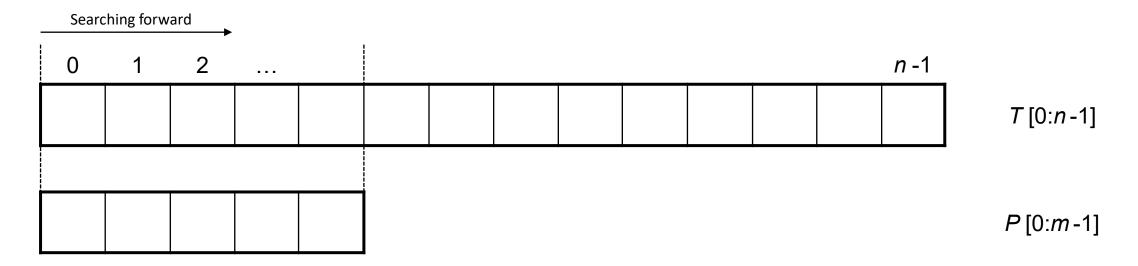
- Naive algorithm, no preprocessing of T or P
 - Assume that the length of *T* and *P* are *n* and *m* respectively
 - The naive algorithm is already a polynomial-time algorithm, with worst case execution time O(n*m), which is also O(n²)

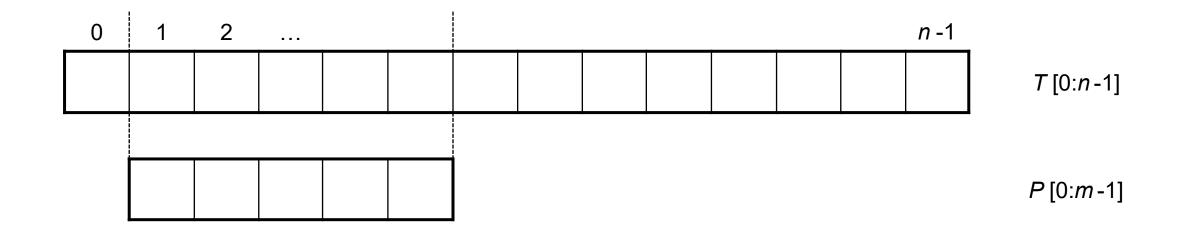
• Preprocessing of P (the pattern) for each new P

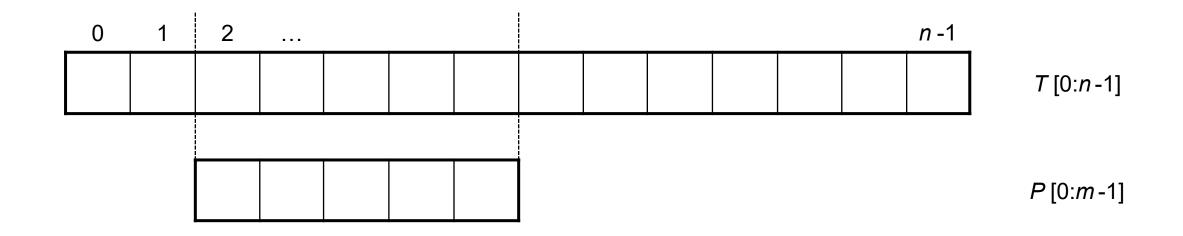
- Prefix-search: The Knuth-Morris-Pratt algorithm
- Suffix-search: The Boyer-Moore algorithm
- Hash-based: The Karp-Rabin algorithm
- Preprocessing of the text T (Used when we search the same text a lot of times (with different patterns), done to an extreme degree in search engines)
 - Suffix trees: Data structure that relies on a structure called a Trie

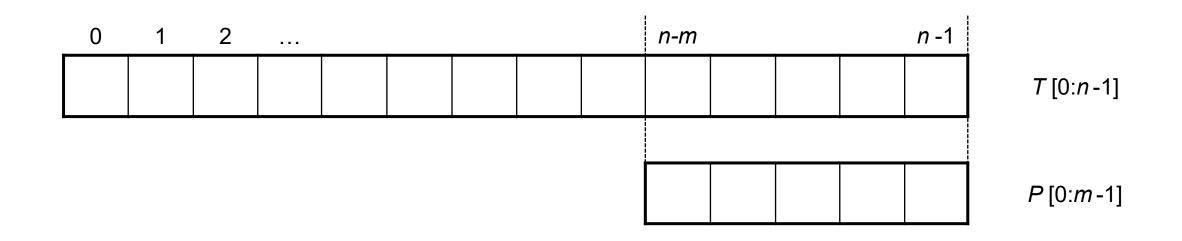
The naive algorithm (Prefix based)

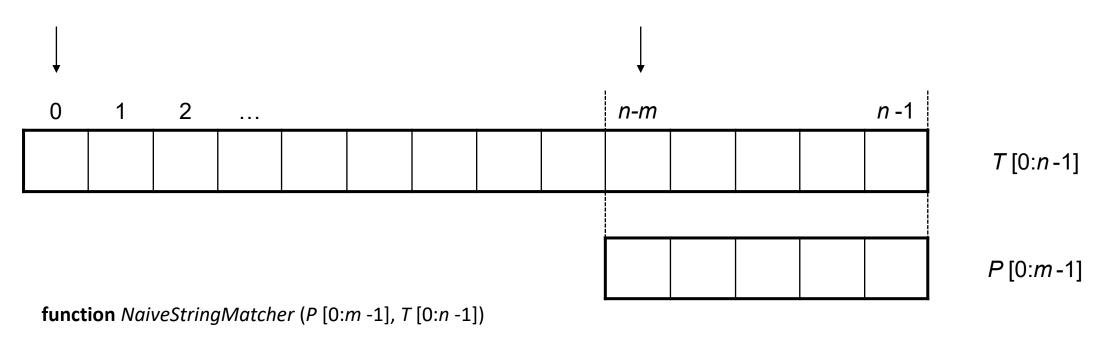
"Window"











for $s \leftarrow 0$ to n - m do

// loop through all window positions

if *T* [*s* :*s* + *m* - 1] = *P* **then** // is window = P?

return(s)

// if so, return start-index of window

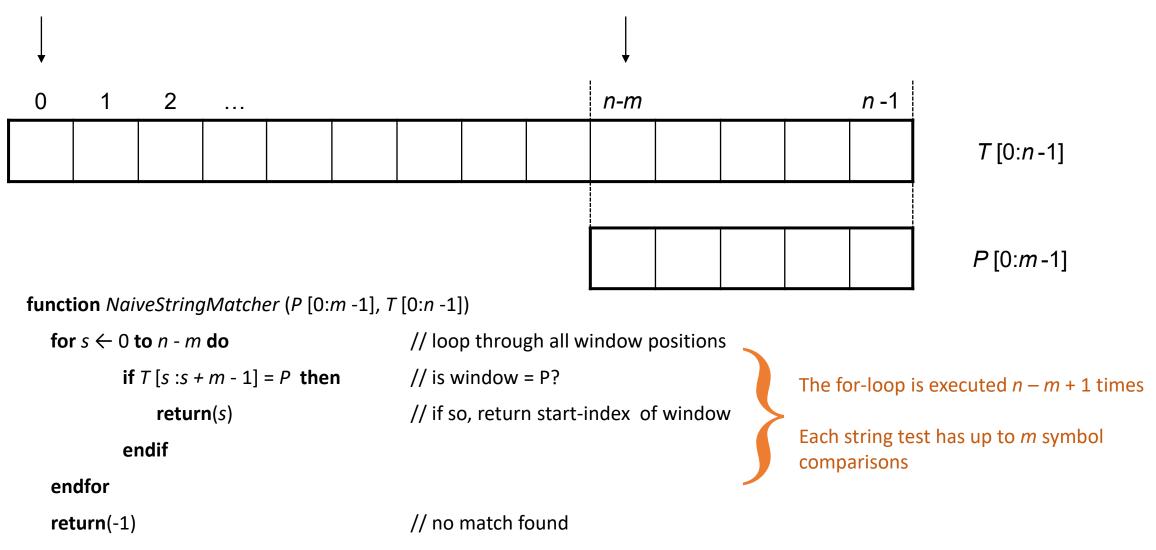
endif

endfor

return(-1)

// no match found

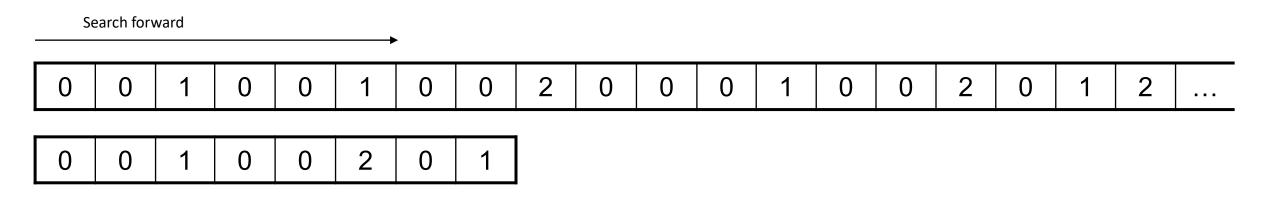
end NaiveStringMatcher



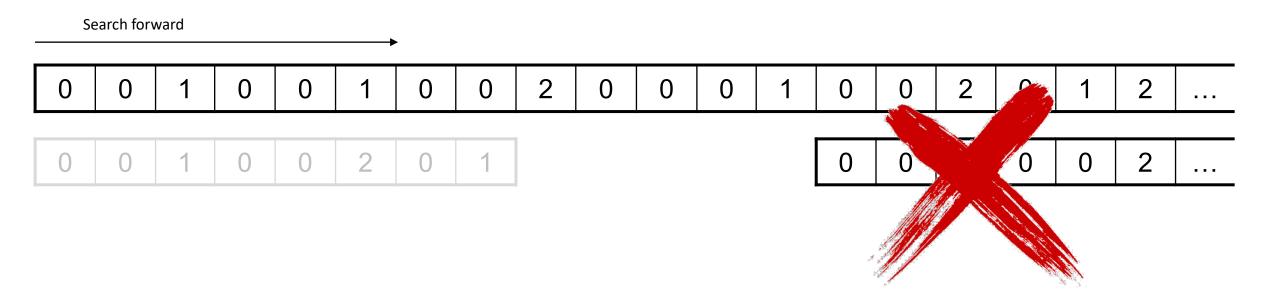
end NaiveStringMatcher

O(nm) execution time (worst case)

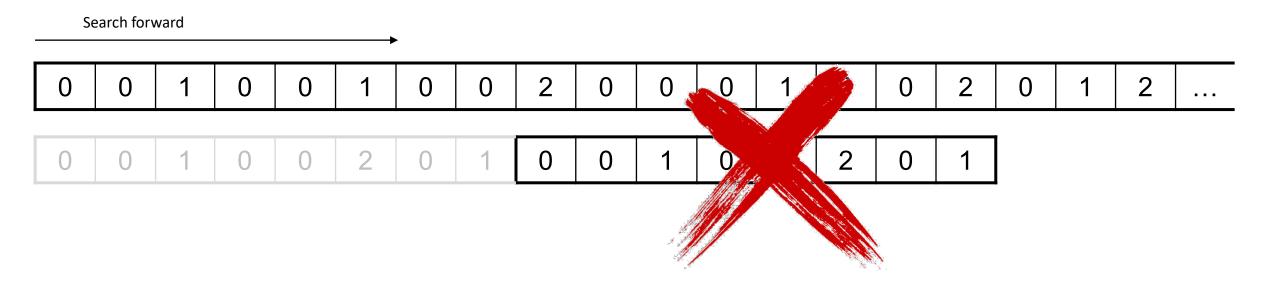
- There is room for improvement in the naive algorithm
 - The naive algorithm moves the window (pattern) only one character at a time
 - But we can move the window farther, based on what we know from earlier comparisons
 - USE WHAT WE KNOW, TO START FROM FIRST POSISTION WHERE A MATCH IS POSSIBLE
 - How far can we move it?



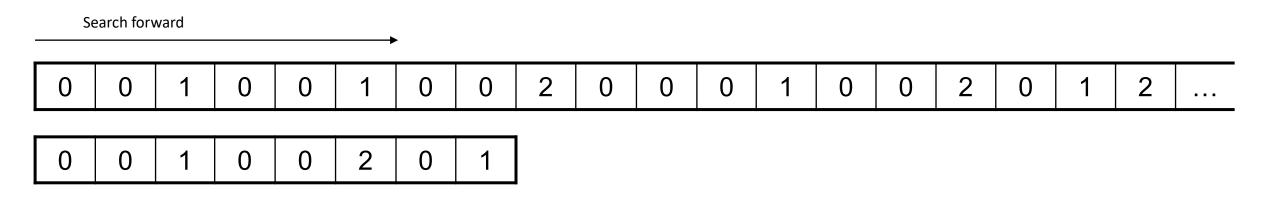
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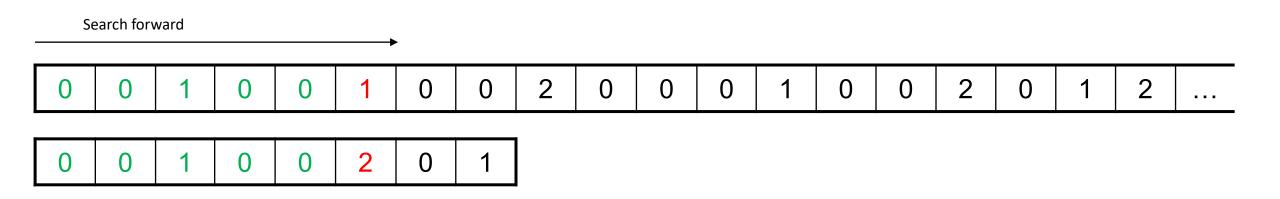
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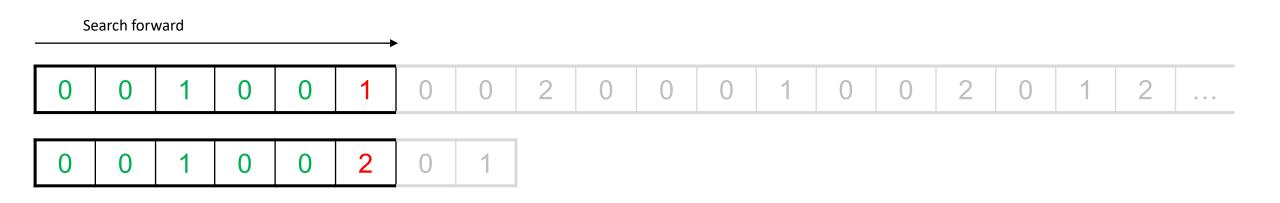
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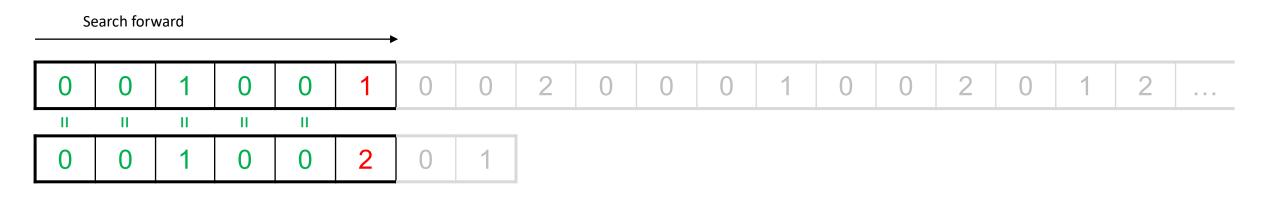
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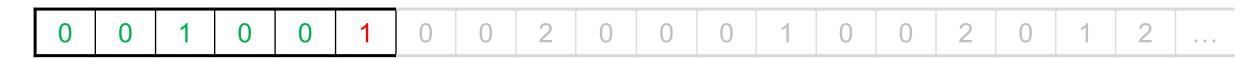
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0	0	1	0	0	2	0	1
---	---	---	---	---	---	---	---

We move the pattern one step: Mismatch (in the second symbol) (We have to move at least one step...)



0	0	1	0	0	2	0	1
---	---	---	---	---	---	---	---

We move the pattern two steps: Mismatch (in the first symbol)

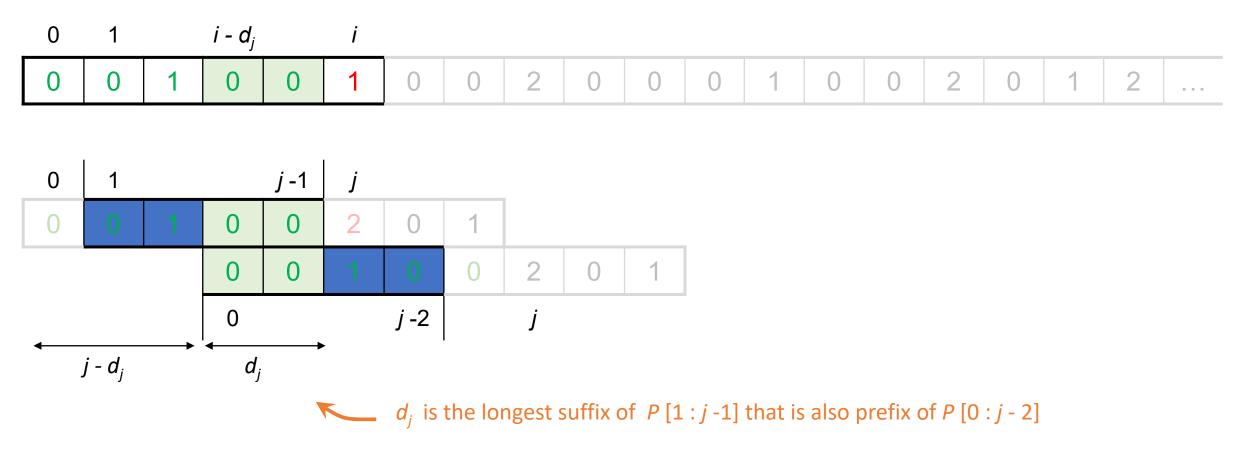


we had a match previously



We move the pattern three steps: Now, there is at least a match in the part of *T* where we had a match previously

- We can skip a number of tests and move the pattern more than one step before we start comparing characters again.
 (3 in the above situation.)
- The key is that we know what the characters of T and P are, up to the point where P and T got different.
 (T and P are equal up to this point.)
- For each possible index *j* in *P*, we assume that the first difference between *P* and *T* occurs at *j*, and from that compute how far we can move *P* before the next string-comparison. (We only need to look at P for this!)
- It may well be that we never get an overlap like the one above, and we can then move *P* all the way to the point in *T* where we found an inequality. This is the best case for the efficiency of the algorithm.



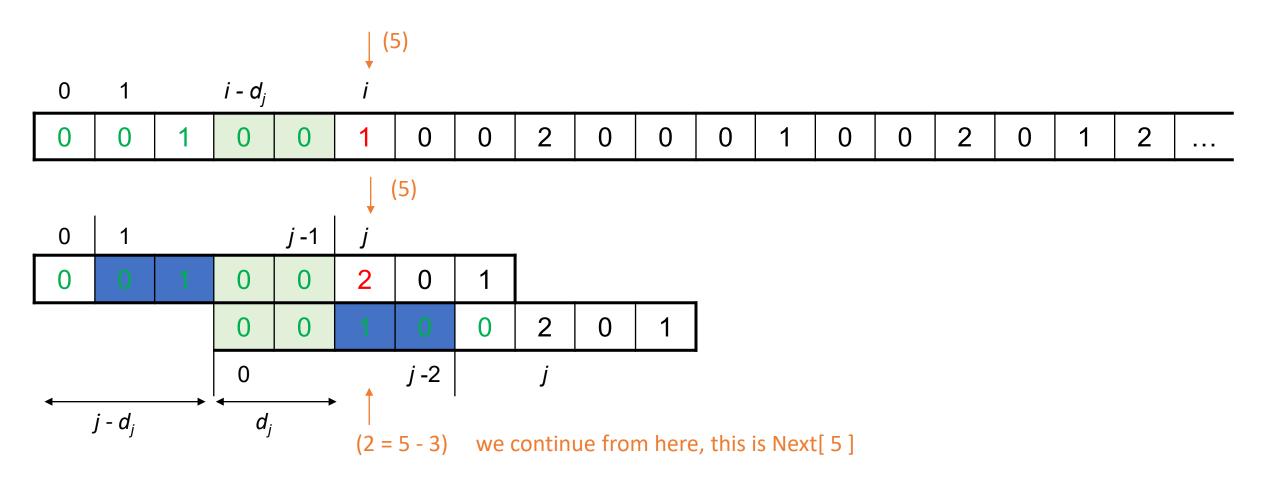
We know that if we move P less than $j - d_j$ steps, there can be no (full) match

And we know that, after this move, $P[0: d_j-1]$ will match the corresponding part of T

Thus we can start the comparison at d_i in P and compare P $[d_i:m-1]$ with the symbols from index i in T

Idea behind the Knuth-Morris-Pratt algorithm

- We will produce a table Next [0: m-1] that shows how far we can move P when we get a (first) mismatch at index j in P, j = 0,1,2, ..., m-1
- But the array Next will not give this number directly. Instead, Next [j] will contain the new (and smaller value) that j should have when we resume the search after a mismatch at j in P (see below)
 - That is: *Next* [*j*] = *j* <number of steps that *P* should be moved>
 - or: *Next* [*j*] *is the value that is named d_i* on the previous slide
- After P is moved, we know that the first d_j symbols of P are equal to the corresponding symbols in T (that's how we chose d_j)
- So, the search can continue from index *i* in *T* and *Next* [*j*] in *P*
- The array *Next*[] can be computed from *P* alone!



(From index 5, starting again from 2 is the same as moving the pattern 3 steps)

function *KMPStringMatcher* (*P* [0:*m* -1], *T* [0:*n* -1]) $i \leftarrow 0$ // indeks i T $i \leftarrow 0$ // indeks i P *CreateNext*(*P* [0:*m* -1], *Next* [*n* -1]) // preprocessing of the pattern P while i < n do // loop until we have a full match, or get to the end of T if P[i] = T[i] then // if the symbols match, we can continue looking for a full match if j = m - 1 then // check if match is full return(i - m + 1)// if so, return start-index of the (full) match endif // if match is not full, check next symbol $i \leftarrow i + 1$ $j \leftarrow j + 1$ else // if the symbols did not match, we must move the window $j \leftarrow Next[j]$ // move window by decreasing j – implicit shift according to the preprosessing **if** *j* = 0 **then** // if j then becomes 0 (it can not be decreased any more) **if** *T* [*i*] ≠ *P* [0] **then** // and symbols do not match $i \leftarrow i + 1$ // move window by increasing i – explicit shift endif endif

endif

endwhile

return(-1)

end KMPStringMatcher

// no match found

O(n)

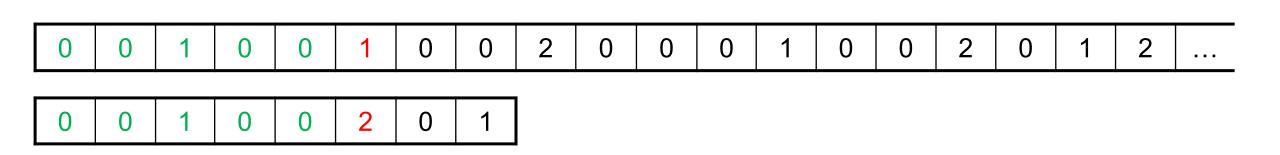
Calculating the array Next[] from P

function CreateNext (P [0:m -1], Next [0:m -1])

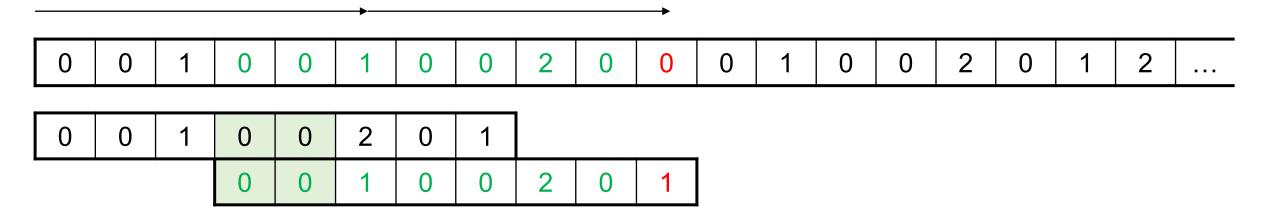
end CreateNext

. . .

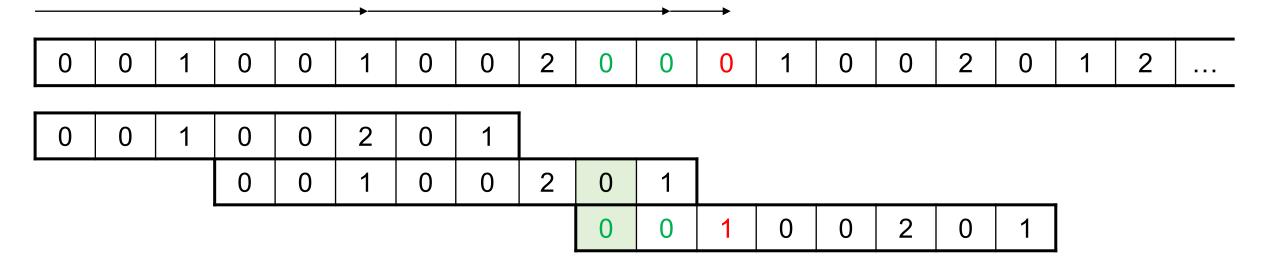
- This can be written straight-ahead with simple searches, and will then use time $O(m^2)$
- A more clever approach finds the array *Next* in time *O*(*m*)
- We will look at the procedure in an exercise next week



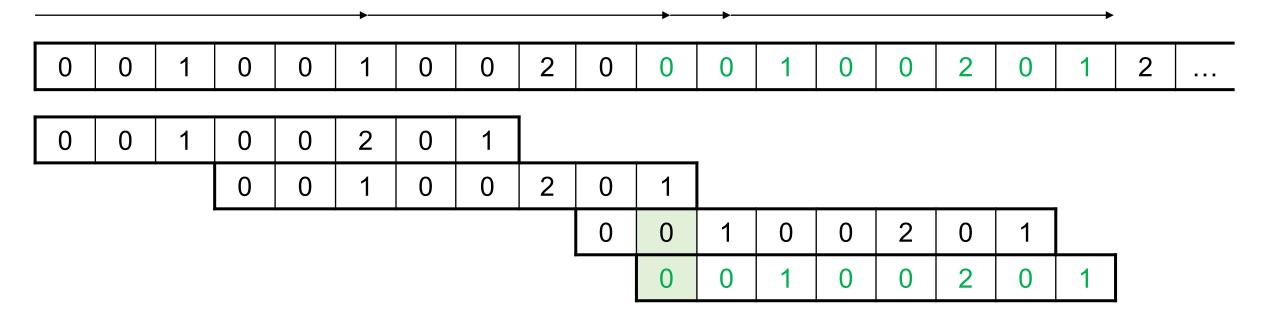
The array *Next* for the string *P* above:



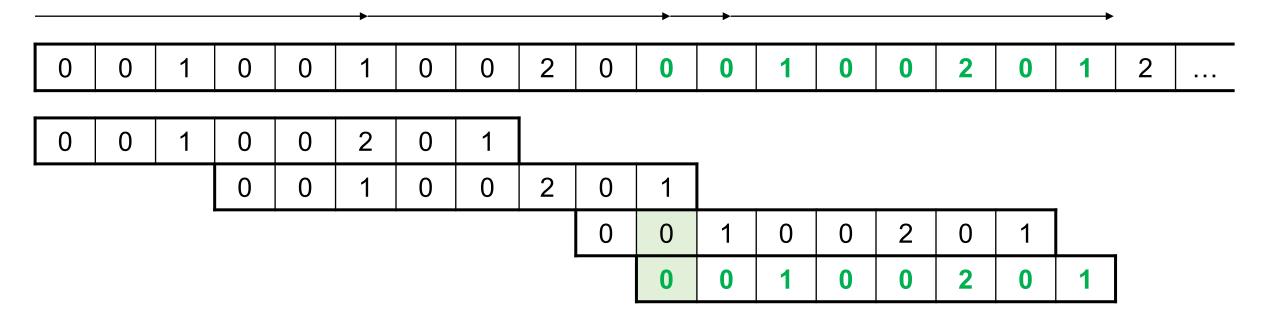
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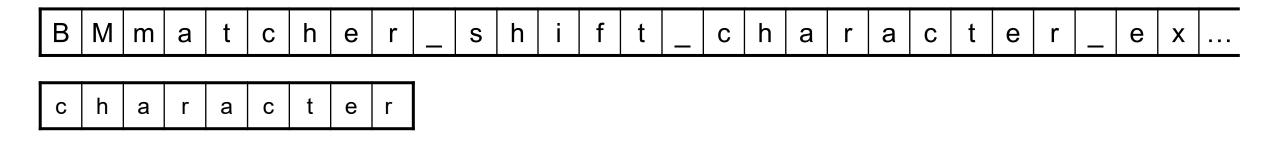
The array *Next* for the string *P* above:

j = 0 1 2 3 4 5 6 7 Next[j] = 0 0 1 1 1 2 0 1

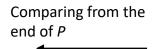
This is a linear algorithm: worst case runtime O(n)

The Boyer-Moore algorithm (Suffix based)

- The naive algorithm, and Knuth-Morris-Pratt is prefix-based (from left to right through *P*)
- The Boyer-Moore algorithm (and variants of it) is suffix-based (from right to left in *P*)
- Horspool proposed a simplification of Boyer-Moore, and we will look at the resulting algorithm here



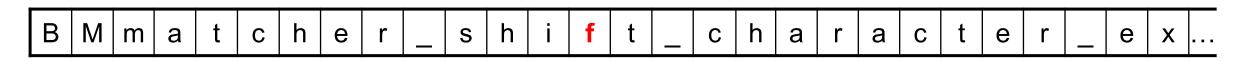
The Boyer-Moore algorithm (Horspool)





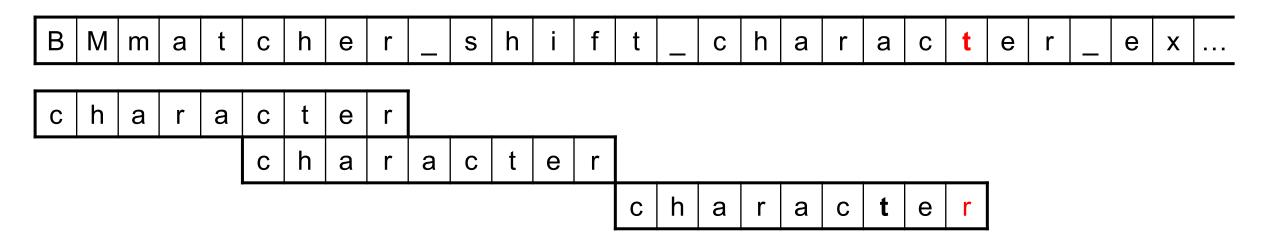
С	h	а	r	а	С	t	е	r
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The Boyer-Moore algorithm (Horspool)

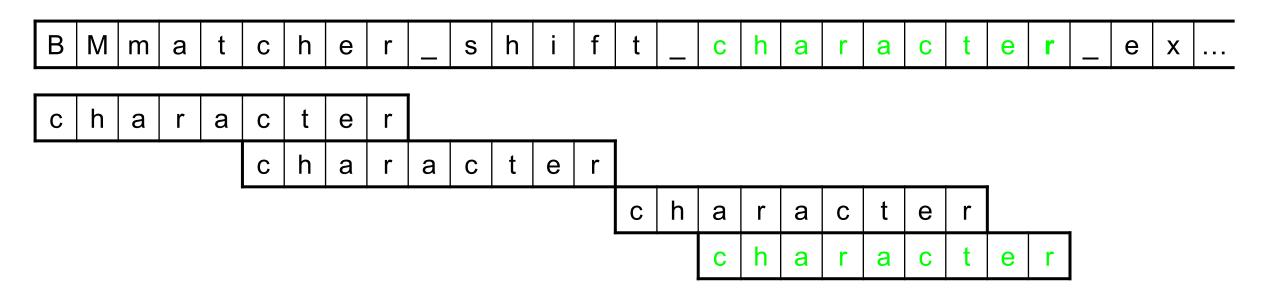


	С	h	а	r	а	С	t	е	r					
-						С	h	а	r	а	С	t	е	r

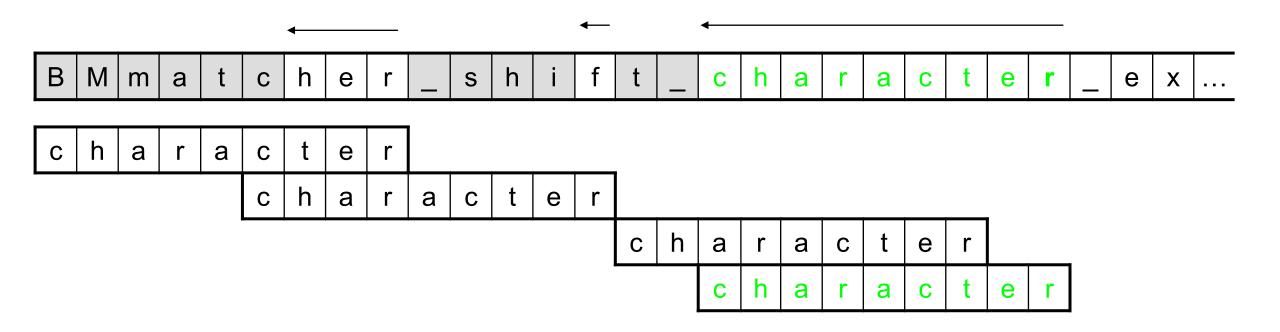
The Boyer-Moore algorithm (Horspool)



The Boyer-Moore algorithm (Horspool)



The Boyer-Moore algorithm (Horspool)



Worst case execution time O(mn), same as for the naive algorithm!

However: Sub-linear ($\leq n$), as the average execution time is $O(n (\log_{|A|} m) / m)$

```
function HorspoolStringMatcher (P [0:m -1], T [0:n -1])
  i \leftarrow 0
  CreateShift(P [0:m -1], Shift [0:|A| - 1])
  while i < n - m do
          i \leftarrow m - 1
          while j \ge 0 and T[i+j] = P[j] do
                    j \leftarrow j - 1
          endwhile
          if j = 0 then
                    return(i)
          endif
          i \leftarrow i + \text{Shift}[T[i + m - 1]]
          endwhile
  return(-1)
end HorspoolStringMatcher
```

// preprocessing of the pattern P
// loop through all window positions (from left)

// compare window and pattern (from right)

// if we have a full match,
// return start-index of window

// if not, move pattern to the right, and align
// according to the last symbol of the window

Calculating the array Shift[] from P

```
function CreateShift (P [0:m -1], Shift [0:|A| -1])
```



...

- We must preprocess *P* to find the array *Shift*
- The size of Shift[] is the number of symbols in the alphabet
- We search from the end of *P* (minus the last symbol), and calculate the distance from the end for every first occurrence of a symbol
- For the symbols not occuring in *P*, we know:

Shift [t] = <the length of P>

(*m*)

This will give a "full shift"

The Karp-Rabin algorithm (hash based)

- We assume that the alphabet for our strings is $A = \{0, 1, 2, ..., k 1\}$
- Each symbol in A can be seen as a digit in a number system with base k
- Thus each string in A* can be seen as number in this system (and we assume that the most significant digit comes first, as usual)

```
Example:
```

```
k = 10, and A = \{0, 1, 2, ..., 9\} we get the traditional decimal number system
The string "6832355" can then be seen as the number 6 832 355
```

Given a string P [0: m -1]. We can then calculate the corresponding number P' using m - 1 multiplications and m - 1 additions (Horners rule, computed from the innermost right expression and outwards):

P' = P[m - 1] + k(P[m - 2] + ... + k(P[1] + k(P[0])...))

Example (written as it computed from left to right): 1234 = (((1*10) + 2)*10 + 3)*10 + 4

- Given a string T [0: n -1], and an integer s (start-index), and a pattern of length m. We then refer to the substring T [s: s + m -1] as T_s, and its value is referred to as T'_s
- The algorithm:
 - We first compute the value *P*['] for the pattern *P*.
 - Based on Horners rule, we compute T_{0} , T_{1} , T_{2} , ..., and successively compare these numbers to P'
- This is very much like the naive algorithm
- However: Given T'_{s-1} and k^{m-1} , we can compute T'_s in constant time:

This constant time computation can be done as follows (where T'_{s-1} is defined as on the previous slide, and k^{m-1} is pre-computed):

$$T'_{s} = k * (T'_{s-1} - k^{m-1} * T[s]) + T[s+m]$$
 $s = 1, ..., n-m$

Example:

 $k = 10, A = \{0, 1, 2, ..., 9\}$ (the usual decimal number system) and m = 7. $T'_{s-1} = 7937245$ $T'_{s} = 9372458$

 $T'_{s} = 10 * (7937245 - (1000000 * 7)) + 8 = 9372458$

- We can compute T'_{s} in constant time when we know T'_{s-1} and k^{m-1}
- We can therefore compute
 - P' and
 - T'_{s} , s = 0, 1, ..., n m (n m + 1 numbers)
 - in time *O*(*n*)
- We can threfore "theoretically" implement the search algorithm in time O(n)
- However, the numbers T's and P' will be so large that storing and comparing them will take too long time (in fact O(m) time – back to the naive algorithm again)
- The Karp-Rabin trick is to instead use modular arithmetic:
 - We do all computations modulo a value *q*
- The value q should be chosen as a prime, so that kq just fits in a register (of e.g. 64 bits)
- A prime number is chosen as this will distribute the values well

• We compute $T^{\prime(q)}_{s}$ and $P^{\prime(q)}$, where

 $T^{\prime(q)}_{s} = T^{\prime}_{s} \mod q,$ $P^{\prime(q)} = P^{\prime} \mod q, \text{ (only once)}$

and compare

x mod y is the remainder when deviding x with y, this is always in the interval $\{0, 1, ..., y - 1\}$.

- We can get $T'^{(q)}_{s} = P'^{(q)}$ even if $T'_{s} \neq P'$. This is called a spurious match
- So, if we have $T^{(q)}_{s} = P^{(q)}$, we have to fully check whether $T_{s} = P$
- With large enough q, the probability for getting spurious matches is low (see next slides)

function KarpRabinStringMatcher (P [0:m -1], T [0:n -1], k, q) $c \leftarrow k^{m-1} \mod q$ $P^{'(q)} \leftarrow 0$

 $T'^{(q)}_{s} \leftarrow 0$

for $i \leftarrow 1$ to m do $P^{\prime(q)} \leftarrow (k * P^{\prime(q)} + P[i]) \mod q$ $T^{\prime(q)}_{0} \leftarrow (k * T^{\prime(q)}_{0} + T[i]) \mod q$

endfor

for $s \leftarrow 0$ to n - m do **if** *s* > 0 **then** $T'^{(q)} \leftarrow (k * (T'^{(q)} - T[s] * c) + T[s + m]) \mod q$ endif if $T'^{(q)} = P'^{(q)}$ then if $T_s = P$ then **return**(s) endif endif endfor return(-1) end KarpRabinStringMatcher

// initialize

// calculate value for P
// and first position of window

// loop through all positions for the window
// calculate value for the (new) window
// (based on previous window)

// if we have a match mod q,
// then we must check the actual strings
// and return the start-index

// no match found

The Karp-Rabin algorithm , time considerations

- The worst case running time occurs when the pattern *P* is found at the end of the string *T*
- If we assume that the strings are distributed uniformally, the probability that $T^{\prime(q)}_{s}$ is equal to $P^{\prime(q)}$ (which is in the interval $\{0, 1, ..., q-1\}$) is 1/q
- Thus $T^{(q)}_{s}$, for s = 0, 1, ..., n-m-1 will for each s lead to a spurious match with probability 1/q
- With the real match at the end of T, we will on average get (n m) / q spurious matches during the search
- Each of these will lead to *m* symbol comparisons. In addition, we have to check whether *T*^{'(q)}_{n-m} equals *P* when we finally find the correct match at the end
- Thus the number of comparisons of single symbols and computations of new values $T^{(q)}$, will be:

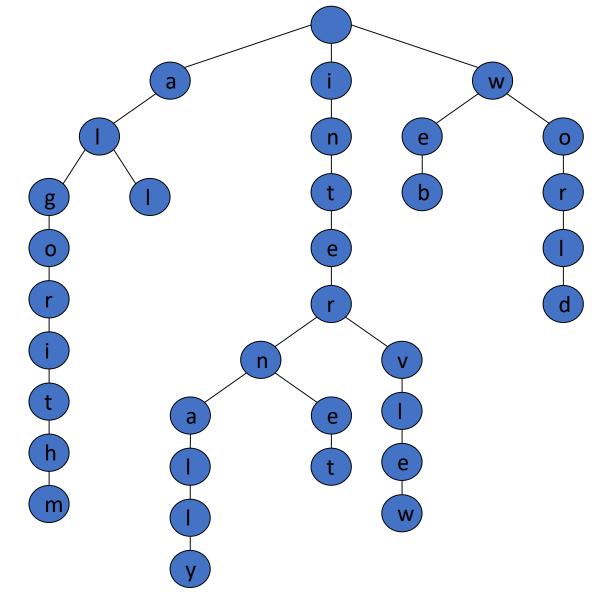
$$\left(\frac{n-m}{q}+1\right)m+(n-m+1)$$

• We can choose values so that q >> m. Thus the runing time will be O(n)

Multiple searches in a fixed string T (structure)

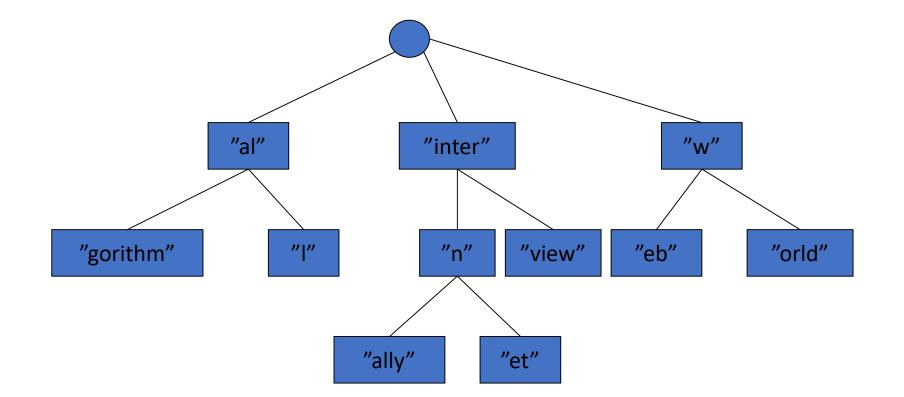
- It is then usually smart to *preprocess T*, so that later searches in *T* for different patterns *P* will be fast
 - Search engines (like Google or Bing) do this in a very clever way, so that searches in huge number of webpages can be done extremely fast
- We often refer to this as *indexing* the text (or data set), and this can be done in a number of ways. We will look at the following technique:
 - Suffix trees, which relies on "Tries" trees
 - So we first look at Tries
- T may also gradually change over time. We then have to update the index for each such change
 - The index of a search engine is updated when the crawler finds a new web page

Tries (word play on Tree/Retrieval)

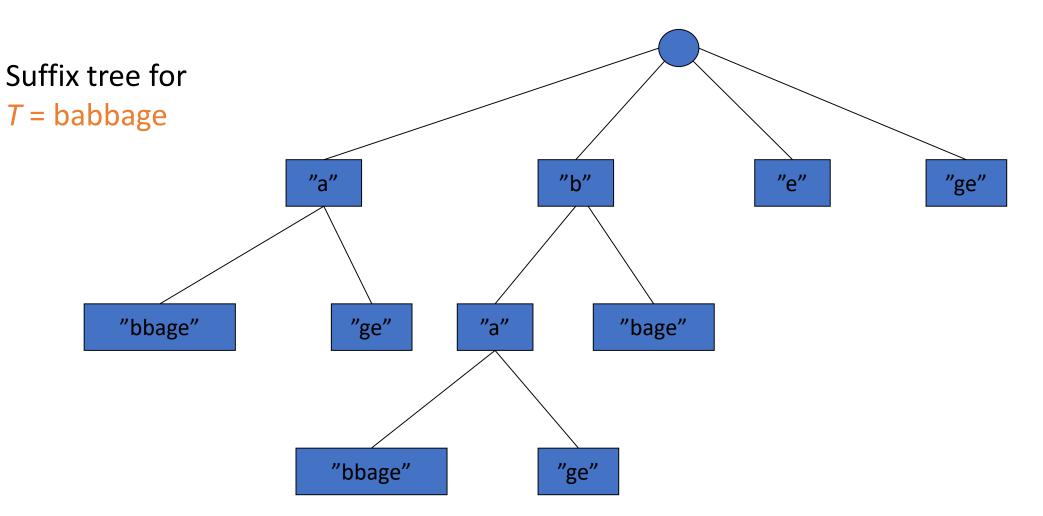


There is a small error in the textbook here

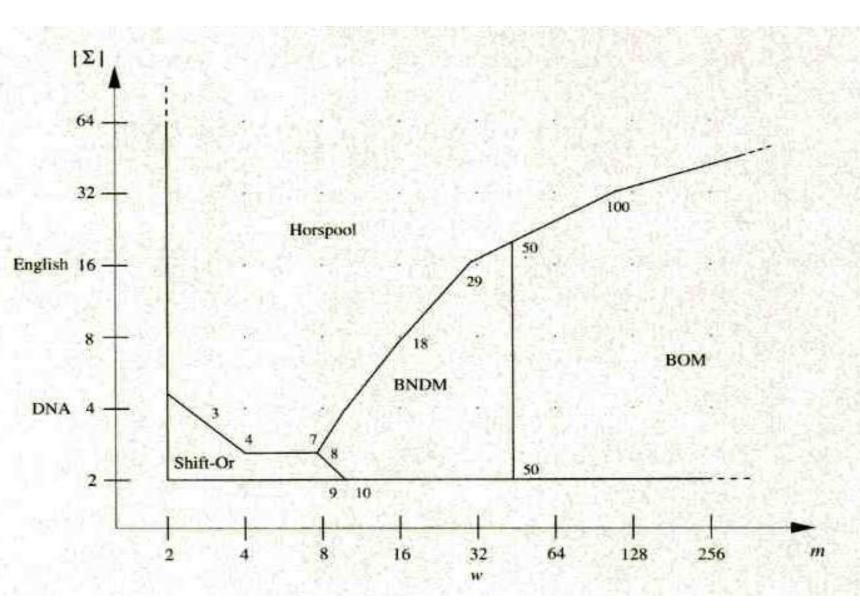
Compressed trie



Suffix trees (compressed)



 Looking for P in this trie will decide whether P occurs as a substring of T, all substrings have a path strting in the root



FLEXIBLE PATTERN MATCHINGTO IN STRINGS CAAGCAGAAT

Practical on-line search algorithms for texts and biological sequences

