

IN4080 exercises (autumn 2023)

Week 11: Speech processing, dialogue management, system design and evaluation

(The two first questions are extracted from exams of previous years)

You wish to develop a (phone-based) spoken dialogue system that will call random U.S. citizens in order to collect opinion poll data for the next US election, with two candidates on the ballot: Kamala Harris and Ivanka Trump.

This system is framed as a *Markov Decision Process* (MDP) formalised as such:

- We have five possible states:
 - s_1 is the starting state
 - s_2 if the callee indicated their intention to vote for Kamala Harris
 - s_3 if the callee indicated their intention to vote for Ivanka Trump
 - s_4 if the callee expressed something else (that was not understood)
- The set of actions that can be taken by the dialogue system are as follows:
 - a_1 : Say "Hi, I'm a automated bot developed to collect polling data. May I ask you for whom you plan to vote in the next election?"
 - a_2 : Say "Sorry I did not understand. Who do you wish to vote for?"
 - a_3 : Say "Ok, thank you for your help, and have a nice day!"
- The transition model is as follows:
 - In state s_1 , only action a_1 is possible, with three possible transitions:
 $P(s' = s_2 | s = s_1, a = a_1) = 0.48$, $P(s' = s_3 | s = s_1, a = a_1) = 0.40$, $P(s' = s_4 | s = s_1, a = a_1) = 0.12$
 - In states s_2 and s_3 , only a_3 is possible and terminates the dialogue.
 - In state s_4 , only a_2 is possible, with the following transitions:
 $P(s' = s_2 | s = s_4, a = a_2) = 0.36$, $P(s' = s_3 | s = s_4, a = a_2) = 0.32$, $P(s' = s_4 | s = s_4, a = a_2) = 0.32$
- Finally, the reward model is defined as such:
 - $R(s = s_2, a = a_3) = R(s = s_3, a = a_3) = 10$ (if the system manages to register the callee's political preference)
 - $R(s = s_4, a = a_2) = -1$ (to capture the annoyance of asking the callee to repeat)
 - Other actions have a reward of zero.

Based on this MDP model, calculate the expected cumulative reward of asking the callee to repeat when their answer was not properly understood, that is: $Q(s = s_4, a = a_2)$. You can assume a discount factor of 0.9.

Question 2

Assume you wish to develop a talking robot that can respond to various requests. When a human is perceived around the robot, the first first step is to engage the human, for instance with a greeting, accompanied or not by gestures. We wish to apply reinforcement learning to determine the best engagement strategy among two options: *SayHi* and *SayHiWithGestures*.

Formally speaking, we can frame this problem as an MDP with

- 2 states: *HumanNotEngaged* (which is the starting state) and *HumanEngaged* (which is a final state).
- 3 actions: *SayHi*, *SayHiWithGestures*, and *AskHowCanIHelpYou*. The first two actions (*SayHi* and *SayHiWithGestures*) are only available for the starting state *HumanNotEngaged*, while the action *AskHowCanIHelpYou* is only available for the final state *HumanEngaged*.

The transition model $P(s'|s, a)$ for this MDP is as follows:

- If the robot executes action *SayHi* in the state *HumanNotEngaged*, we have a probability 0.5 of reaching the state *HumanEngaged*, and a probability 0.5 of staying in the state *HumanNotEngaged*.
- If the robot executes action *SayHiWithGestures* in the state *HumanNotEngaged*, we have a probability 0.7 of reaching the state *HumanEngaged*, and a probability 0.3 of staying in the state *HumanNotEngaged*.

The reward function $R(s, a)$ of this MDP is as follows:

- The reward of executing action *SayHi* in the state *HumanNotEngaged* is -1
- The reward of executing action *SayHiWithGestures* in the state *HumanNotEngaged* is -2, since the physical gestures "cost" more to the agent in terms of energy and mechanical wear.
- Finally, the reward of executing action *AskHowCanIHelpYou* in the state *HumanEngaged* is +10. You can consider this action as the final one in this MDP, which means that the expected cumulative reward $Q(\text{HumanEngaged}, \text{AskHowCanIHelpYou}) = 10$.

Questions:

- 1) Compute the expected cumulative rewards $Q(\text{HumanNotEngaged}, \text{SayHi})$ and $Q(\text{HumanNotEngaged}, \text{SayHiWithGestures})$ based on the MDP described above. To compute those Q-values, you need to use Bellman's equation and refine your estimates through several iterations. You can stop after 5 iterations and use a discount factor $\gamma=0.9$. For the first iteration, you can initialize the Q-values to zero. (10 points)
- 2) Based on those Q-values, which engagement strategy should the robot chose? (2 points)

Tip: Bellman's equation is:

$$Q(s, a) = R(s, a) + \gamma \sum_{s' \in S} P(s'|s, a) \max_{a'} Q(s', a')$$

Question 3

The PARADISE framework for the evaluation of dialogue systems operates by:

1. Defining a set of objective measures that can be extracted automatically from any given dialogue. Those measures may include both indicators of tasks success as well efficiency/quality costs (total elapsed time, number of clarification requests, etc.)
2. Inferring the weight of each quality measure by fitting a regression model that predicts the user satisfaction from those measures. This is done using a small dataset of dialogues where the user is asked to provide a rating for the dialogue that has just taken place.

Download the dataset at the following address:

https://home.nr.no/~plison/data/paradise_example.tsv

The file contains a tab-separated list of measures for 500 dialogues. For each dialogue, we provide:

- The total elapsed time (in seconds)
- The number of times the system had to ask the user to clarify their intent
- The number of times the system had to ask the user to repeat
- The total number of dialogue turns
- Whether the task was successfully completed at the end of the dialogue
- Whether the user uttered "thank you" at the end of the dialogue
- Finally, a rating provided by the user at the end of the dialogue, on a scale from 1 to 5 (where 1 means least satisfied and 5 most satisfied)

Based on the data above:

- 1) Train a linear regression model (using e.g. `sklearn.linear_model.LinearRegression`) to fit a model that predicts the user rating from the objective measure.
- 2) Which objective measure is most predictive of the user rating, according to your fitted regression model?
- 3) Assume you record a new dialogue lasting 2 minutes, including 8 clarification requests and 2 repetition requests, for a total of 33 dialogue turns, and that ended up with a successfully completed task, and a user uttering "Thank you" at the end. What would be the predicted user rating according to your model?