Modelling IV

State Machines

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Based on slides prepared by Prof. Øystein Haugen, HiØ & SINTEF



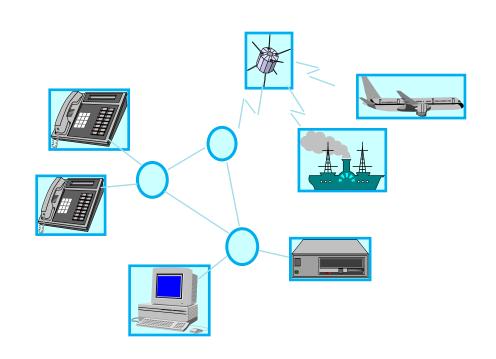
Overview of lecture

- State machines
- Consistency
- One versus several control states
- Robustness



Suitability of UML state machines

- reactive
- concurrent
- real-time
- distributed
- heterogeneous





Main notions

Finite

a finite number of control states

Control state

- a stable situation where the process awaits stimuli
- represents the control pointer within program execution

Machine

- only stimulus in the form of a message triggers behavior
- the behavior consists of executing transitions
- may also have local variables (not to be confused with control states)



Our example today



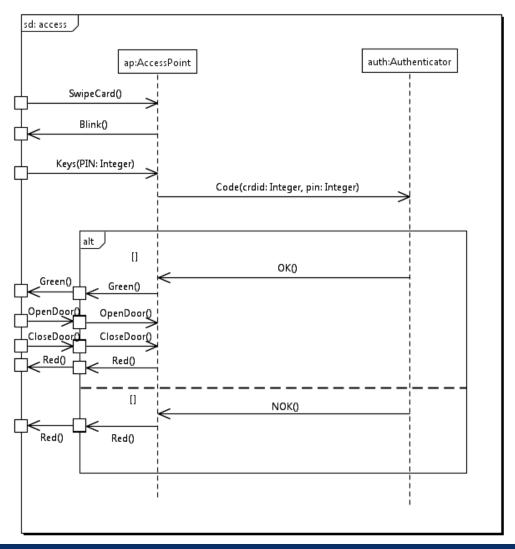


Access control system

- A set of Access Points are established to control the access to an area
- The Access Points controls the locking of a door
 - in a more abstract sense, access control systems may control bank accounts or any other asset that one wants to protect
- The Access Point access is granted when two pieces of correct identification is presented
 - a card
 - a PIN (Personal Identification Number)
- The access rights are awarded by a central Authentication service



Happy Day Scenario

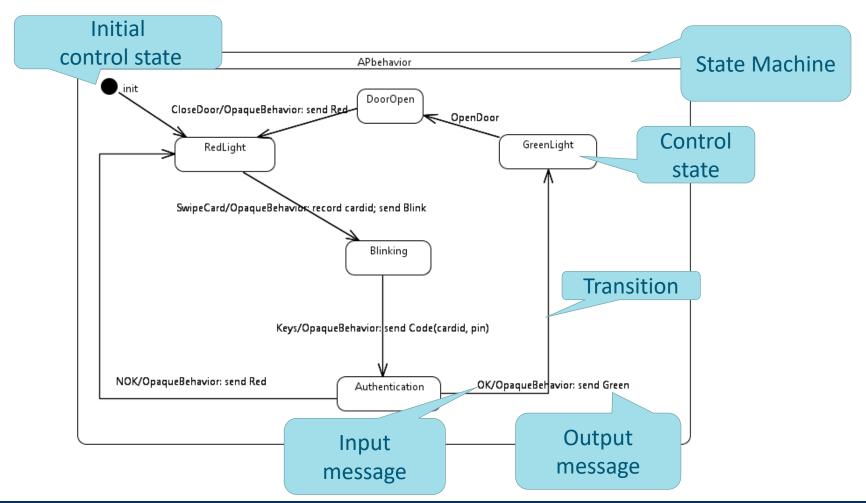




OpaqueBehavior is a UML behavior defined in another language

In this course we are flexible wrt how behaviors are expressed Hence, using the OpaqueBehavior construct is not important

The behaviour of the AccessPoint

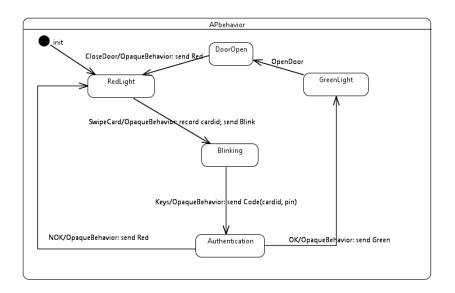


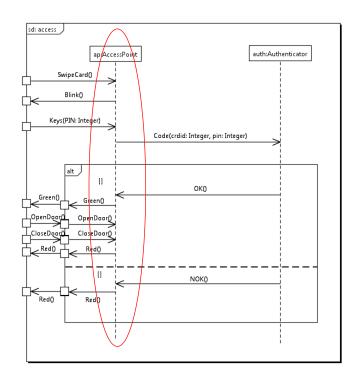


Consistency



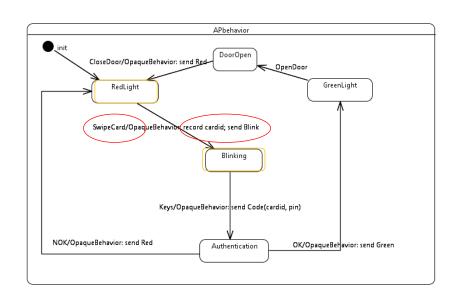
Runtime consistency check

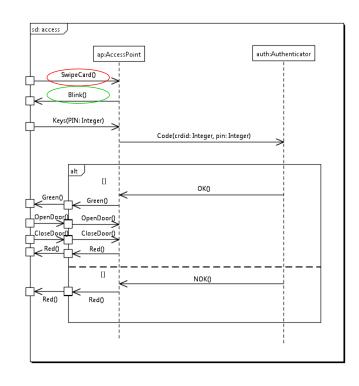




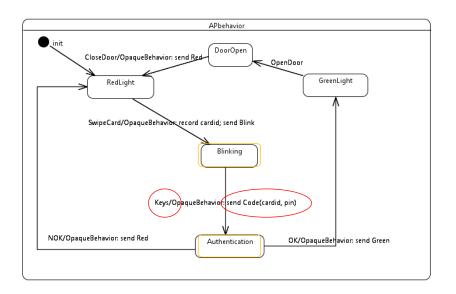


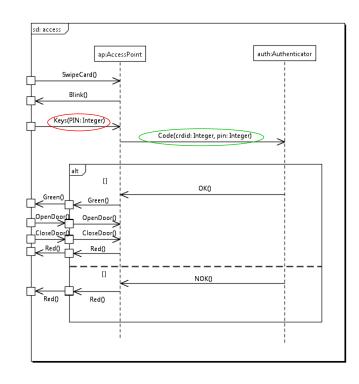
Let's execute the state machine according to the sequence diagram





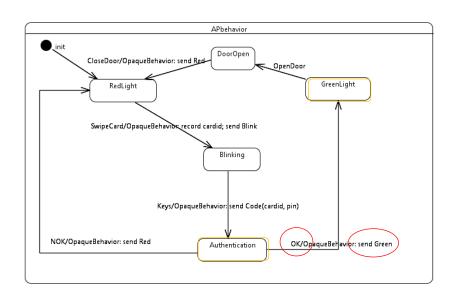
Play it again Sam

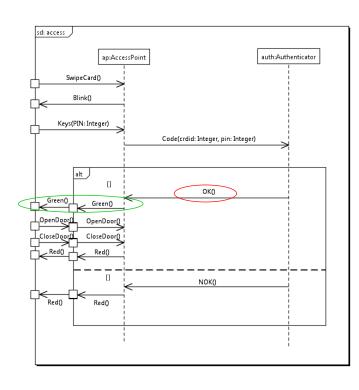




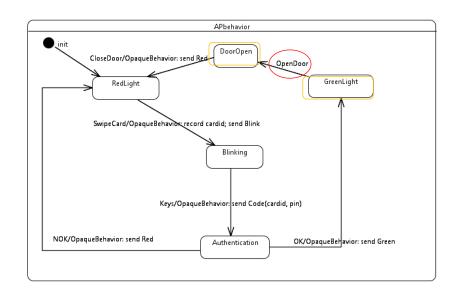


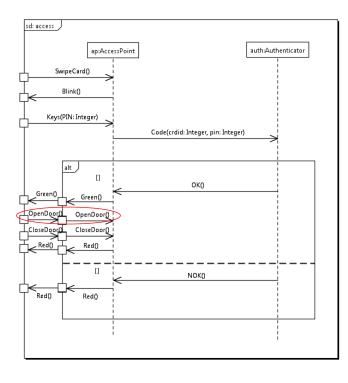
Access granted (one out of two alternatives)





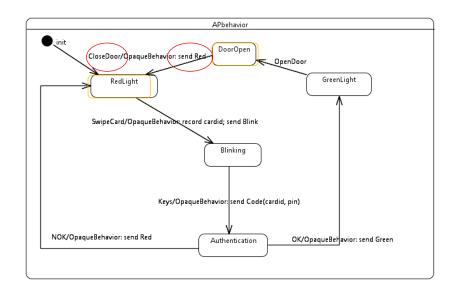
User opens the door

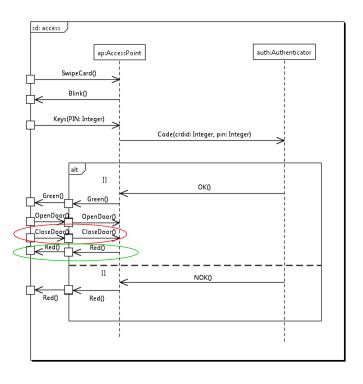






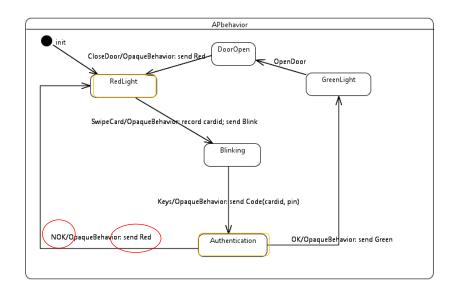
User closes the door again

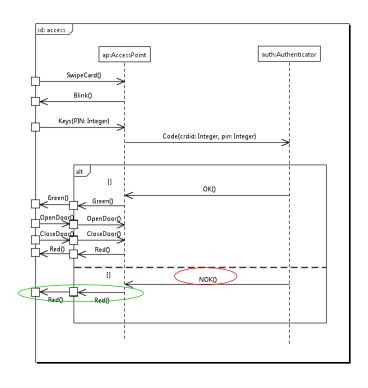






Access not granted (second of two alternatives)







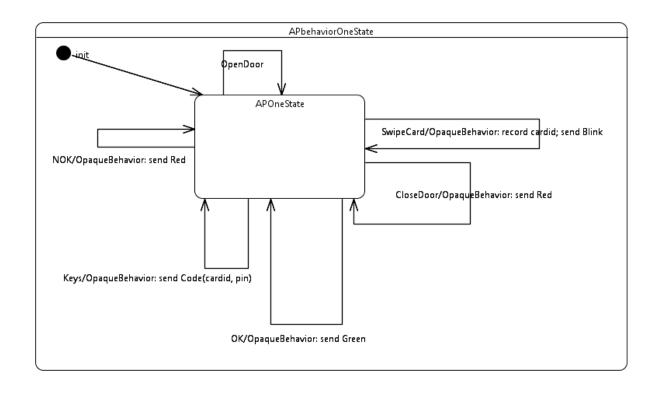
Concluding the runtime consistency check

The state machine APbehavior allows all traces of the sequence diagram Access

All traces of the sequence diagram are consistent with the state machine

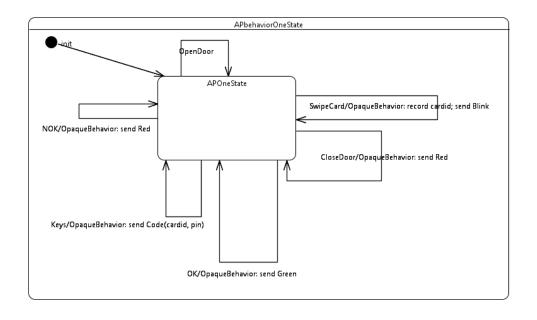


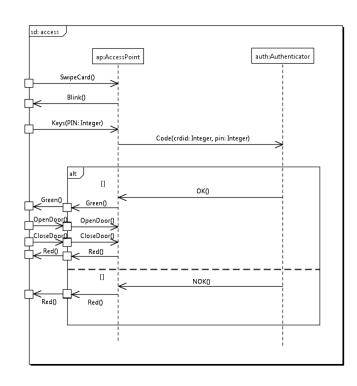
Another attempt to define the state machine





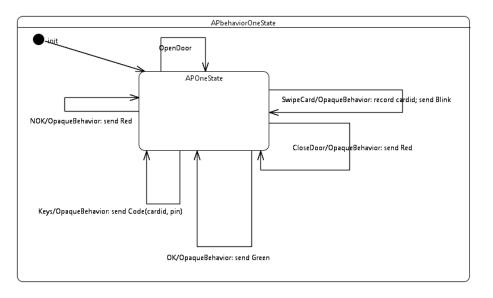
Do we still have consistency?

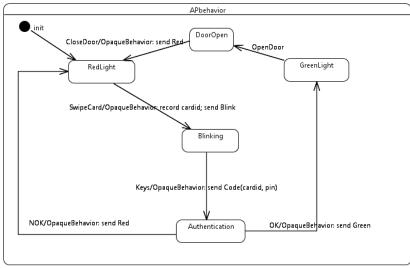




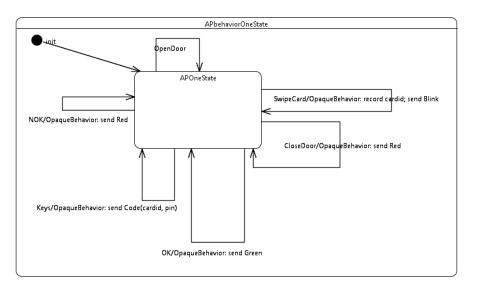


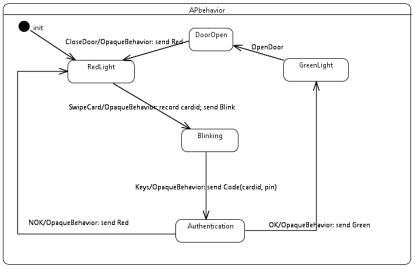
Which state machine is the better description?





What if the user started keying the PIN at once?





APbehavior may spot the problem APbehaviorOneState will go on in error



Why use several control states?

- Different control states distinguishes between different situations
- In different situations, different reactions may be desirable to the same trigger



Guidelines and Reminders

- Even though the one control state machine was consistent with the sequence diagram, the state machine was flawed
 - sequence diagrams are only partial descriptions
 - state machines are complete descriptions
- Use several control states if you can
 - each control state represents a recognizable situation
- We should supplement our state machine with all possible transitions
 - this helps us consider and handle most error situations

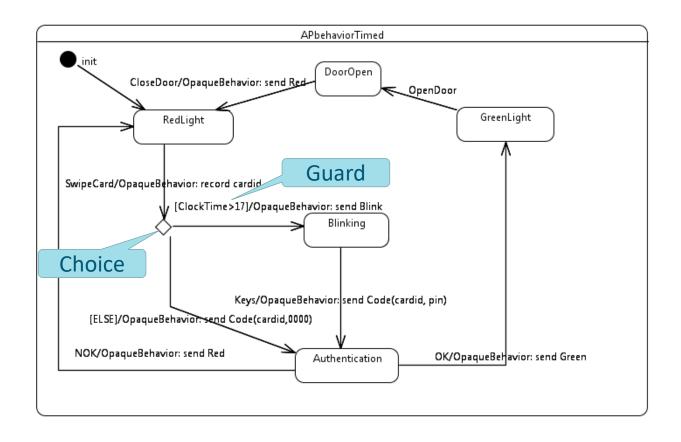


What if we need to modify a state machine?

- Our access control system should possibly be acting differently during working hours than at other times
- How well do state machines cope with modifications?



Enhancing the state machine





Summary

- State machines describe behaviour of independently acting components
- Reactive systems are suitable for state machines
- Consistency checks between sequence diagrams and state machines are very useful
 - but not sufficient
- State machines are robust in as much as additional functionality can often be included without ripple effects on other parts of the behaviour