

# P and NP

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V18

## Recap

We measure complexity of a DTM as a function of input size  $n$ . This complexity is a function  $t_M(n)$ , the maximum number of steps the DTM needs on the input of size  $n$ .

We compare running times by asymptotic behaviour.

$g \in O(f)$  if there exist  $n_0$  and  $c$  such that for *every*  $n \geq n_0$  we have  $g(n) \leq c \cdot f(n)$ .

$\text{TIME}(f)$  is the set of languages decidable by some DTM with running time  $O(f)$ .

# Polynomial time

The class P, polynomial time, is

$$P = \bigcup_{k \in \mathbb{N}} \text{TIME}(n^k)$$

To prove that a language is in P, we can exhibit a DTM and prove that it runs in time  $O(n^k)$  for some  $k$ .

This can be done directly or by reduction.

## Abstracting away from DTMs

Let's consider algorithms working on relevant data structures.

Need to make sure that we have a reasonable encoding of input. For now, reasonable = polynomial-time encodable/decodable.

If we have such an encoding, can assume input is already decoded.

For example, a graph  $(V, E)$  as input can be reasoned about in terms of  $|V|$ , since  $|E| \leq |V|^2$

## Some problems in P

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Algorithm:

1. Mark  $s$
2. While new nodes are marked, repeat:
  - 2.1. For each marked node  $v$  and edge  $(v, w)$ , mark  $w$
3. If  $t$  is marked, accept; if not, reject.

## Another graph problem

### Problem (Shortest path)

*Given an edge-weighted undirected graph  $(V, E, w)$ , nodes  $s, t \in V$ , and a bound  $k \in \mathbb{N}$ , is the shortest path from  $s$  to  $t$  of weight  $\leq k$ ?*

Odd formulation. How can we use this to find the size of this shortest path?

Solvable by similar algorithm (BFS).

[https://en.wikipedia.org/wiki/Dijkstra%27s\\_algorithm](https://en.wikipedia.org/wiki/Dijkstra%27s_algorithm)

## Some important properties of $P$

$P$  is closed under union, intersection, complement, and concatenation.

Additionally, *polynomials* are closed under addition and multiplication.

Closure under multiplication allows for powerful reductions!



## Membership in $P$ by reduction

Given a decision problem  $L$ , I can prove that  $L \in P$  by reducing  $L$  to a problem I already know is in  $P$  — if my reduction takes polynomial time.

Recall that a reduction  $f$  transforms each  $w$  to  $f(w)$  such that  $w \in L_1 \leftrightarrow f(w) \in L_2$ .

Let  $L_1 \in P$ , and let  $M_{L_1}$  be the DTM deciding  $L_1$  in polynomial time  $p$ .

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The machine  $M_{L_1}(f(w))$  therefore runs in time  $O(p(p_f(n)))$ , which is a polynomial.  $(n^k)^l = n^{kl}$ .

# The class NP

Recall that  $\text{NTIME}(f(n))$  is the class of problems decidable by an NTM in time  $O(f(n))$ .

NTIME also has a polynomial-based class. 
$$\text{NP} = \bigcup_{k \in \mathbb{N}} \text{NTIME}(n^k)$$

Unfortunately, NTMs are annoying to work with. Let's define NP using DTMs.

# Verifiers

## Definition (7.18, reworded)

A verifier  $V$  for a language  $L$  is a DTM such that  $w \in L$  if and only if there exists a *certificate*  $c$  such that  $V(w, c)$  accepts.

We measure the running time of verifiers only with respect to  $w$ .

It follows that if the running time of  $V$  is polynomial,  $c$  is polynomial in the size of  $w$ .

## NTMs and verifiers

### Theorem

*NP is the class of languages that have polynomial-time verifiers.*

Need to prove both directions: NTMs to verifiers and back.

Given a verifier, easy to construct NTM: Just try all certificates of appropriate length.

A given verifier runs in time  $O(n^k)$  for some specific  $k$ .

The resulting NTM has an exponential-size transition table, but runs in polynomial time.

## NTMs to verifiers

Given an NTM, we can build a verifier as follows: Let the certificate be a sequence of choices of transitions.

If there is an accepting branch, there is a sequence of such choices of polynomial size.

Otherwise all branches reject, and so does our verifier.

## Abstracting away TMs

NP is the class of languages with polynomial-size membership proofs.

$P \subseteq NP$  still holds: If I can decide membership in polynomial time, I do not need a certificate.

NP is closed under union, intersection, and concatenation; but is *not known* to be closed under complement.

## Some problems in NP

This class has all the classic useful problems.

The most famous problem in NP is perhaps SAT: Given a propositional logic formula, is it satisfiable?

Propositional formulas are build up from variables  $x_i$  using conjunction ( $\wedge$ ), disjunction ( $\vee$ ), and negation  $\neg$ .

$x_1 \vee (x_2 \wedge \neg x_3)$  is an example. An assignment assigns true or false to each variable, and it is satisfying if the formula evaluates to true.



## SAT is in NP

If I write down an assignment, we can check that it is satisfying in linear time.

However, consider the problem UNSAT: The complement of SAT, i.e. those formulas that have *no satisfying assignment*.

Seems similar, but what certificate can we use?

## SAT is in NP

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This is why NP is not known to be closed under complement.

## 3-colourability

### Problem (3COL)

*Given an undirected graph  $(V, E)$ , is it possible to colour  $V$  using 3 colours such that no edge  $(v, w)$  connects the same colour?*

Again, easy certificate (a colouring).

We can also, like for P, use reductions rather than explicit algorithms.

Let's reduce 3COL to SAT.

# Propositional logic programming

We will need this for the Cook-Levin theorem.

How do we go from graphs to true and false?

Well, we need to know what colour a vertex is. And we need constraints to ensure that

- Each vertex is exactly one colour
- No two neighbours are the same colour

# Gadgetry

A piece of a problem to simulate another piece of another problem is called a gadget.

We need a gadget for each vertex, and one for each edge.

Variables:  $\chi(v_i, R), \chi(v_i, G), \chi(v_i, B)$  (true means that vertex  $v_i$  is coloured Red, Green, Blue respectively)

# Gadgets

Each vertex must have a colour:  $\bigwedge_{v_i \in V} x(v_i, R) \vee x(v_i, G) \vee x(v_i, B)$

Each vertex must not have two colours:

$\bigwedge_{v_i \in V} \neg[x(v_i, R) \wedge x(v_i, G)] \wedge \neg[x(v_i, R) \wedge x(v_i, B)] \wedge \neg[x(v_i, G) \wedge x(v_i, B)]$

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No edge monochromatic:

$\bigwedge_{(v_i, v_j) \in E, C \in \{R, G, B\}} \neg[x(v_i, C) \wedge x(v_j, C)]$

## Analyzing the reduction

Correctness and polynomial time bound.

A satisfying assignment satisfies all my conjunctions of constraints.

If it exists, then exactly one of each  $x(v_i, C)$  will be true. Also, no edge  $(v, w)$  will have  $x(v, C)$  and  $x(w, C)$ .

The true variables give me a colouring.



## 3COL to SAT, time

How much time did we spend?

The “exactly one colour” formulas used  $3|V| + 3|V|$  variables.

The edge formulas used  $3|E|$  variables. Total  $6|V| + 3|E|$ .

## Many-one reductions

### Definition (Polynomial-time many-one reducibility)

A language  $A$  is polynomial-time many-one reducible to another language  $B$  ( $A \leq_P B$ ) if there exists a polynomial-time computable function  $f$  such that for all  $w$ ,  $w \in A \leftrightarrow f(w) \in B$ .

If  $A \leq_P B$ , then  $B$  is “more expressive” — it can simulate all problems in  $A$  with a polynomial overhead.

We would expect that  $B$  has the more difficult decision problem.

# Hardness

So far, we have talked about membership in a class.

But even though some NP problems seem harder,  $P \subseteq NP$ .

Absent a proof that  $P \neq NP$ , we can still talk about the hardest problems in a class using reductions (if  $A \leq_P B$ , then B is at least as hard as A).

# Completeness

Given a type of reduction  $\leq_X$ , consider the following definition.

## Definition ( $\leq_X$ -completeness)

A language  $A$  is  $\leq_X$ -hard for a class  $C$  if and only if  $B \leq_X A$  for every  $B \in C$ . If  $A$  is also in  $C$ , it is  $\leq_X$ -complete.

Choice of  $\leq_X$  vital. Idea for NP: Polynomial-time reductions, since P is a lower class.

If I choose too powerful a reduction, everything becomes complete.

Take exponential time reductions: I can then reduce SAT to PATH!

# NP-completeness

A language  $A \in \text{NP}$  is NP-complete iff  $A$  is  $\leq_P$ -hard for NP.

Not obvious that any such problem exists.

Not at all obvious how to prove this property, that *all* other languages reduce to one.

# Completeness, properties

The problem is getting the first NP-complete language. If  $A$  is NP-complete and  $A \leq_P B \in \text{NP}$ , then  $B$  is also NP-complete.

Reductions can be composed, after all.