## Description Logic 2: Reasoning

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- As we saw last time, description logics allows us to model knowledge in a natural way.
- Today we will see why we make the restrictions, and what makes exactly these restrictions important.

### Contents

Assumptions

Reasoning problems

Tableau algorithm for  $\mathcal{ALCN}$ 

Soundness, Completeness and Termination

Removing the assumptions

Complexity

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- We only allow acyclic TBoxes, so e.g. no  $A \equiv \exists R.D$ , where D is defined in terms of A.
- We only allow ABox axioms on the form A(c) for atomic concepts A (and R(a, b) as usual). (Not really a restriction, as D(c) for complex D can be expressed as  $A_D \equiv D$  and  $A_D(c)$  for some fresh concept name  $A_D$ )

## Example ontology in $\mathcal{ALCN}$

TBox:

 $\begin{array}{l} \textit{Animal} \equiv \leq 2 \textit{ hasParent } \sqcap \geq 2 \textit{ hasParent} \\ \textit{Donkey} \equiv \textit{Animal} \sqcap \textit{Stubborn} \\ \textit{Horse} \equiv \textit{Animal} \sqcap \neg \textit{Stubborn} \\ \textit{Mule} \equiv \textit{Animal} \sqcap \exists \textit{hasParent}.\textit{Horse} \sqcap \exists \textit{hasParent}.\textit{Donkey} \end{array}$ 

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ABox:

Horse(mary) Mule(peter) Horse(hannah)

hasParent(peter, mary) hasParent(peter, carl) hasParent(sven, hannah) hasParent(sven, carl)

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For concepts C and D:

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- Instance checking (whether for some concept C and individual a,  $\mathcal{K} \vDash C(a)$ ).

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- Instance checking (whether for some concept C and individual a,  $\mathcal{K} \vDash C(a)$ ).
- **ABox consistency** (whether  $\mathcal{A}$  is consistent w.r.t.  $\mathcal{T}$ ).

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(iii) C and D are disjoint  $\Leftrightarrow$  C  $\sqcap$  D is unsatisfiable.

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– Then we replace every assertion A(a) with D'(a) in  $\mathcal{A}$ , if  $A \equiv D'$  is in  $\mathcal{T}'$ . E.g.:

 $Donkey(peter) \rightsquigarrow$ ( $\leq 2 hasParent \sqcap \geq 2 hasParent \sqcap Stubborn)(peter)$ 

### Important results

#### Theorem

Assume  $C \equiv D$  is replaced by  $C \equiv D'$  in an expansion of  $\langle \mathcal{A}, \mathcal{T} \rangle$  to  $\langle \mathcal{A}', \emptyset \rangle$ . Then: (i) C is satisfiable w.r.t.  $\mathcal{T} \Leftrightarrow \{D'(x)\}$  is consistent.

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(iii)  $\langle \mathcal{A}, \mathcal{T} \rangle \vDash C(a) \Leftrightarrow \mathcal{A}' \cup \{\neg D'(a)\}$  is inconsistent.

## Negated Normal Form

For our reasoning algorithm, we need our concepts in Negated Normal Form (NFF):

$$\neg (C \sqcap D) \rightsquigarrow \neg C \sqcup \neg D$$
  

$$\neg (C \sqcup D) \rightsquigarrow \neg C \sqcap \neg D$$
  

$$\neg \exists R.C \rightsquigarrow \forall R.\neg C$$
  

$$\neg \forall R.C \rightsquigarrow \exists R.\neg C$$
  

$$\neg \leq nR \rightsquigarrow \geq (n+1)R$$
  

$$\neg \geq nR \rightsquigarrow \leq (n-1)R$$

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is satisfiable. (We write  $\mathcal{A}_n^k$  for the k-th set in  $\mathcal{A}_n$ )

Now no more rules apply.

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$$\begin{array}{rcl} \mathcal{A}_0 & = & \{\{(\leq 1 \; R \; \sqcap \geq 2 \; R)(x_0)\}\}\\ \mathcal{A}_1 & = & \{\mathcal{A}_0^1 \cup \{(\leq 1 \; R)(x_0), (\geq 2 \; R)(x_0)\}\} & \text{ by } \sqcap \text{-rule}\\ \mathcal{A}_2 & = & \{\mathcal{A}_1^1 \cup \{R(x_0, y_1), R(x_0, y_2), y_1 \neq y_2\}\} & \text{ by } \geq \text{-rule} \end{array}$$

We want to check whether the concept

 $\leq 1 \ R \sqcap \exists R.C \sqcap \exists R.D$ 

We want to check whether the concept

 $\leq 1 \ R \sqcap \exists R.C \sqcap \exists R.D$ 

is satisfiable.

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#### Contents

Assumptions

Reasoning problems

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Soundness, Completeness and Termination

Removing the assumptions

Complexity

#### Definitions

#### Definition

- (i) The algorithm terminates on one ABox A when no rules are applicable. Such an ABox is then called *complete*.
- (ii) A *clash* is an obvious contradiction, that is,  $\mathcal{A}$  contains a clash if either:

$$\begin{array}{l} - \ \bot(x) \in \mathcal{A}, \text{ or} \\ - \ \{C(x), \neg C(x)\} \subseteq \mathcal{A}, \text{ or} \\ - \ \{(\leq n R)(x)\} \cup \\ \{R(x, y_i) \mid 1 \leq i \leq n+1\} \cup \\ \{y_i \neq y_j \mid (1 \leq i < j \leq n+1)\} \subseteq \mathcal{A}. \end{array}$$

#### Soundness and completeness

Let  $\hat{S}$  be the set of complete ABoxes resulting from applying the tableau algorithm to  $\{\mathcal{A}\}$ .

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#### Theorem (Soundness)

If  $\mathcal{A}$  has a model, then at least one of the ABoxes of  $\hat{\mathcal{S}}$  has a model.

#### Proof.

Done by induction on the proofs, showing that each rule preserves consistency.

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Done by induction on the proofs, showing that each rule preserves consistency.

#### Theorem (Completeness)

If at least one of the ABoxes,  $\hat{A}$  of  $\hat{S}$  is clash free, then at A has a model.

#### Proof.

Done by constructing a model for  $\mathcal{A}$  from  $\hat{\mathcal{A}}$ .

### Assumptions

- We only allow equivalence axioms,  $A \equiv D$ , where A is atomic and D is not atomic. Each atomic concept should only occur once on a left-hand side.
- We only allow acyclic TBoxes, so e.g. no  $A \equiv \exists R.D$ , where D is defined in terms of A.
- We only allow ABox axioms on the form A(c) for atomic concepts A (and R(a, b) as usual). (Not really a restriction, as D(c) for complex D can be expressed as  $A_D \equiv D$  and  $A_D(c)$  for some fresh concept name  $A_D$ )

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- New: We only allow ABoxes on the form  $\{C(x_0)\}$  as input to the tableau algorithm.

#### Terminaton on single concept

#### Theorem (Termination)

If  $C_0$  is an ALCN-concept, then the tableau algorithm terminates on  $\{\{C_0(x_0)\}\}$ , that is, there cannot be an infinite sequence of rule applications

$$\{\{C_0(x_0)\}\} \rightarrow S_1 \rightarrow S_2 \rightarrow \ldots$$

To prove termination, we do the following:

- We first define a function f mapping each state S in the proof (each set of ABoxes) to a set Q for which there is a strict well-ordering <.

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- We first define a function f mapping each state S in the proof (each set of ABoxes) to a set Q for which there is a strict well-ordering <.
- Then, we prove that if S' is the result of applying a rule to a state S, then f(S') < f(S).
- The result then follows from the fact that any strictly decreasing sequence in a well-ordered set is finite.

#### Proof-sketch of termination

#### Lemma

Let  $\mathcal{A}$  be an ABox contained in  $\mathcal{S}_i$  for some  $i \geq 1$ .

- For every individual  $x \neq x_0$  occuring in  $\mathcal{A}$ , there is a unique sequence  $R_1, \ldots, R_l$  $(l \geq 1)$  of role names and a unique sequence  $x_1, \ldots, x_{l-1}$  of individual names such that  $\{R_1(x_0, x_1), R_2(x_1, x_2), \ldots, R_l(x_{l-1}, x)\} \subseteq \mathcal{A}$ . In this case, we say that x occurs on level l in  $\mathcal{A}$ .

### Proof-sketch of termination

#### Lemma

Let A be an ABox contained in  $S_i$  for some  $i \geq 1$ .

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- If  $C(x) \in A$  for an individual x on level I, then the maximal role depth of C (i.e. the maximal nesting of constructors involving roles) is bounded by the maximal role depth of  $C_0$  minus I. Consequently, the level of any individual in A is bounded by the maximal role depth of  $C_0$ .

### Lemma (Cont.)

- If  $C(x) \in A$  then C is a subdescription of  $C_0$ . Consequently, the number of different concept assertions on x is bounded by the size of  $C_0$ .
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- If  $C(x) \in A$  then C is a subdescription of  $C_0$ . Consequently, the number of different concept assertions on x is bounded by the size of  $C_0$ .
- The number of different role successors of x in A (i.e. individuals y such that  $R(x, y) \in A$  for a role name R) is bounded by the sum of of the numbers occuring in the at-least restrictions in  $C_0$  pluss the number of different existential restrictions in  $C_0$ .

The facts stated in this lemma imply the following:

 The canonical interpretation constructed by the tableaux algorithm has the shape of a finite tree;

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- The canonical interpretation constructed by the tableaux algorithm has the shape of a finite tree;
- the depth of the tree is linearly bounded by the size of  $C_0$ ;
- the branching factor of the tree is bounded by the sum of the numbers occuring in the at-least restrictions pluss the number of different existential restrictions in  $C_0$ .
- This means that ALCN enjoys the *finite tree model property*, that is, any satisfiable concept  $C_0$  is satisfiable in a finite interpretation that has the shape of a tree whose root belongs to  $C_0$ .

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Assumptions

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What happens if we apply the algorithm to a general extended  $\mathcal{ALCN}$ -ABox?

$$\mathcal{A}_0 \hspace{0.1in} = \hspace{0.1in} \{R(a,a), (\leq 1 \, R)(a), (orall R.A)(a)\}$$

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What happens if we apply the algorithm to a general extended  $\mathcal{ALCN}\text{-}\mathsf{ABox}?$  It might not terminate:

}

$$\begin{array}{rcl} \mathcal{A}_{0} & = \; \{R(a,a), (\leq 1\,R)(a), (\forall R.\exists R.A)(a) \\ \mathcal{A}_{1} & = \; \mathcal{A}_{0} \cup \{(\exists R.A)(a)\} \\ \mathcal{A}_{2} & = \; \mathcal{A}_{1} \cup \{R(a,x_{0}), \mathcal{A}(x_{0})\} \\ \mathcal{A}_{3} & = \; \mathcal{A}_{2} \cup \{(\exists R.A)(x_{0})\} \\ \mathcal{A}_{4} & = \; \mathcal{A}_{3} \cup \{R(x_{0},x_{1}), \mathcal{A}(x_{1})\} \\ \mathcal{A}_{4} & = \; \mathcal{A}_{1} \cup \{\mathcal{A}(a), R(a,x_{1}), \mathcal{A}(x_{1})\} \\ \vdots \\ \mathcal{A}_{i} & = \; \mathcal{A}_{1} \cup \{\mathcal{A}(a), R(a,x_{j}), \mathcal{A}(x_{j})\} \end{array}$$

What happens if we apply the algorithm to a general extended  $\mathcal{ALCN}$ -ABox? It might not terminate:

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However, if we restrict the  $\exists$ -rule and the  $\geq$ -rule to only be applicable when no other rules are, then we can guarantee termination also for general  $\mathcal{ALCN}$ -ABoxes.

Atomic Inclusions

- If we allow (acyclic) Aboxes with inclusions of the form  $A \sqsubseteq C$  where A is a base name, then we can just make a fresh concept  $A_{new}$  and extend the inclusion to a definition, by replacing it with  $A \equiv C \sqcap A_{new}$ .

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E.g.

$$Donkey \sqsubseteq Animal \sqcap Stubborn$$

$$\downarrow$$

$$Donkey \equiv Animal \sqcap Stubborn \sqcap Donkey_{new}$$

**General Inclusions** 

- If we allow TBoxes with general inclusions of the form  $C \sqsubseteq D$  for complex concepts C and D, then it is enough to only handle the inclusion

 $\top \sqsubseteq (\neg C_1 \sqcup D_1) \sqcap (\neg C_2 \sqcup D_2) \sqcap \cdots \sqcap (\neg C_n \sqcup D_n)$ 

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- However, we now lose termination, for instance for the knowledge base with ABox  $\{\top(x_0)\}$  and TBox  $\{\top \sqsubseteq \exists R. \top\}$ .
- This can be fixed with *blocking*.

Inclusions: Blocking

#### Definition

We will say that a variable y is an *ancestor* of a variable x if there exists some R where either R(y, x), or there exists some variable z where z is an ancestor of x and R(y, z).

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We say that an application of a  $\exists$ -rule or a  $\geq$ -rule to a variable x is *directly blocked* by a variable y if

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#### Contents

Assumptions

Reasoning problems

Tableau algorithm for  $\mathcal{ALCN}$ 

Soundness, Completeness and Termination

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## Proof (Sketch).

In  $\ensuremath{\operatorname{PSPACE}}$  : If we alter the algorithm accordingly:

(i) Apply  $\forall$ -,  $\sqcap$ - and  $\sqcup$ -rules as long as possible, and look for clashes of the form  $\bot(x)$  and  $A(x), \neg A(x)$ .

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Generated successors can be treated sepparately, so we only need to store one path of the tree. Furthermore, we do not need to generate all *n* individuals for every  $(\ge nR)(x)$ . PSPACE-*hard:* Can be reduced to validity of Quantified Boolean Formula.

# More complexity results

DL	Combined complexity	Data complexity
$\mathcal{ALC}$	EXPTIME-COMPLETE	NP-complete
$\mathcal{ALCN}$	EXPTIME-COMPLETE	NP-complete
SHIQ	ExpTime-complete	NP-complete
$\mathcal{SHOIN}(D)$	NEXPTIME-COMPLETE	NP-hard
SROIQ	N2ExpTime-complete	NP-hard
$\mathcal{EL}$	P-complete	P-complete
$\mathcal{RL}$	P-complete	P-complete
$DL_{Lite}$	In P	In LOGSPACE

### More info

For more info see:

- F. Baader and W. Nutt's chapter *Basic Description Logics* from *The Description Logic Handbook*.
- P. Hitzler, M. Krötzsch, and S. Rudolph's book *Foundations of Semantic Web Technologies*.

Thanks for listening!