INF3380: Parallel Programming for Scientific Problems

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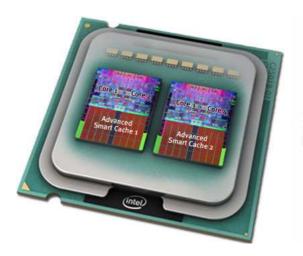
Course overview & recap of serial programming

Motivations

- Many problems in natural sciences can benefit from large-scale computations
 - more details
 - better accuracy
 - more advanced models
- Example of huge computations: Detailed weather analysis of the entire globe
 - surface area: $510,072,000 \text{ km}^2$
 - spatial resolution $1 \times 1 \text{km}^2 \rightarrow 5.1 \times 10^8$ small patches
 - spatial resolution $100 \times 100 \text{m}^2 \rightarrow 5.1 \times 10^{10}$ small patches
 - additional layers in the vertical direction
 - high resolution in the time direction
- Traditional single-CPU computers are limited in capacity
 - typical clock frequency $2 \sim 4$ GHz
 - typical memory size $4\sim16~\mathrm{GB}$

Motivations (cont'd)

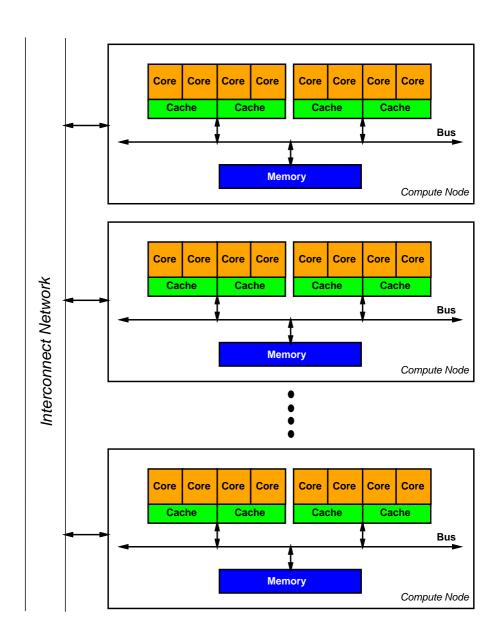
- Parallel computers are now everywhere!
 - CPUs nowadyas have more than one core on a chip
 - One computer may have several multicore chips
 - There are also accelerator-based parallel architectures GPGPU
 - Clusters of different kinds







An example of multicore-based cluster



Why learning parallel programming?

- Parallel computing a form of parallel processing by concurrently utilizing multiple computing units for one computational problem
 - shortening computing time
 - solving larger problems
- However . . .
 - modern multicore-based computers are good at multi-tasking, but not good at automatically computing one problem in parallel
 - automatic parallelization compilers have had little success
 - special parallel programming languages have had little success
 - serial computer programs have to be modified or rewritten to utilize parallel computers
- Learning parallel programming is thus important!

What will you learn in INF3380?

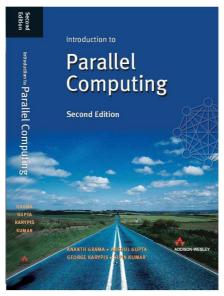
- An introduction to parallel programming
 - important concepts
 - basic parallel programming skills (MPI and OpenMP)
 - use of multicore PCs and PC clusters
 - a peek into GPU computing
- After finishing the course, you should be able to write simple parallel programs
- You should also be able to learn more about advanced parallel programming on your own later

Teaching approaches

- Focus on fundamental issues
 - parallel programming = serial programming + finding parallelism
 + enforcing work division and collaboration
- Use of examples relevant for natural sciences
 - mathematical details are not required
 - understanding basic numerical algorithms is needed
 - implementing basic numerical algorithms is essential
- Hands-on programming exercises and tutoring

Some important info

Textbook: Ananth Grama, George Karypis, Vipin Kumar and Anshul Gupta, Introduction to Parallel Computing, 2nd edition, Addison Wesley, 2003



- Lecture slides
- Two mandatory assignments
- Written exam with grades A–F

Recapitulation of serial programming

What is serial programming?

- Roughly, a computer program executes a sequence of operations applied to data structures
- A program is normally written in a programming language
- Data structures:
 - variables of primitive data types (char, int, float, double etc.)
 - variables of composite and abstract data types (struct in C, class in Java & Python)
 - array variables
- Operations:
 - statements and expressions
 - functions

Variables

In a dynamically typed programming language (e.g. Python) variables can be used without declaration beforehand

```
a = 1.0

b = 2.5

c = a + b
```

In statically typed languages (e.g. Java and C) declaration of variables must be done first

```
double a, b, c;
a = 1.0;
b = 2.5;
c = a + b;
```

Simple example

- Suppose we have temperature measurement for each hour during a day
- ullet t_1 is the temperature at 1:00 o'clock, t_2 is the temperature at 2:00 o'clock, and so on.
- How to find the average temperature of the day?
- We need to first add up all the 24 temperature measurements:

$$T = t_1 + t_2 + \ldots + t_{24} = \sum_{i=1}^{24} t_i$$

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Simple example (cont'd)

How to implement the calculations as a computer program?

- First, create an array of 24 floating-point numbers to store the 24 temperatures. That is, t[0] stores t_1 , t[1] stores t_2 and so on. Note that array index starts from 0!
- Sum up all the values in the array t
 - Same syntax for the computational loop in Java & C:

```
T = 0;
for (i=0; i<24; i++)
T = T + t[i];
```

Syntax for Python:

```
T = 0
for i in range(0,24):
T = T + t[i]
```

Finally, t_average = T/24;

Similarities and differences between languages

- For scientific applications, arrays of numerical values are the most important basic building blocks of data structures
- Extensive use of for-loops for doing computations
- Different syntax details
 - allocation and deallocation of arrays
 - Java: double[] v=new double[n];
 - C: double *v=malloc(n*sizeof(double));
 - Python: v=zeros(n,dtype=float64) (using NumPy)
 - definition of composite and abstract data types
 - I/O

C as the main choice of programming language

- C is one of the dominant programming languages in computational sciences
- Syntax of C inspired many newer languages (C++, Java, Python)
- Good computational efficiency
- C is ideal for using MPI and OpenMP (also GPU programming)
- We will thus choose C as the main programming language
- This lecture will give a crash course on scientific programming, with syntax details in C

Some words about pointers in C

- A variable in a program has a name and type, its value is stored somewhere in memory
- Type *p declares a pointer to a variable of datatype Type
- A pointer is actually a special type of variable, used to hold the memory address of a variable
- From a variable to its pointer: int a; int *p; p = &a;
- We can use a pointer to change the variable value *p = 2;
- A pointer can also be used to hold the memory address of the first entry of an array (such as returned by malloc)
- Array indexing: p[0], p[1]...
- Pointer arithmetic:

```
int *p = (int*)malloc(10*sizeof(int));
int *p2 = p + 3; /* p2 is now pointing to p[3] */
```

Allocating multi-dimensional arrays (1)

Let's allocate a 2D array for representing a $m \times n$ matrix

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$$

Java:

```
double[][] A = new double[m][n];
```

D C:

```
double **A = (double**)malloc(m*sizeof(double*));
for (i=0; i<m; i++)
   A[i] = (double*)malloc(n*sizeof(double));</pre>
```

Same syntax in Java and C for indexing and traversing a 2D array

```
for (i=0; i<m; i++)
  for (j=0; j<n; j++)
   A[i][j] = i+j;</pre>
```

Allocating multi-dimensional arrays (2)

Use of NumPy makes array allocation very simple in Python

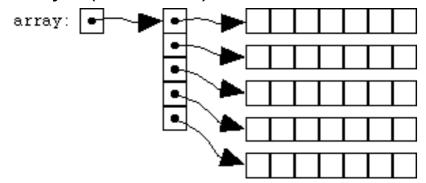
```
from numpy import *
A = zeros((m,n), dtype=float64)
```

Indexing and traversing a 2D array in Python

```
for i in range(0,m):
   for j in range(0,n):
   A[i,j] = i+j;
```

More about two-dimensional arrays in C (1)

C doesn't have true multi-dimensional arrays, a 2D array is actually an array of 1D arrays (like Java)



- A[i] is a pointer to row number i+1
- It is also possible to use static memory allocation of fix-sized 2D arrays, for example:

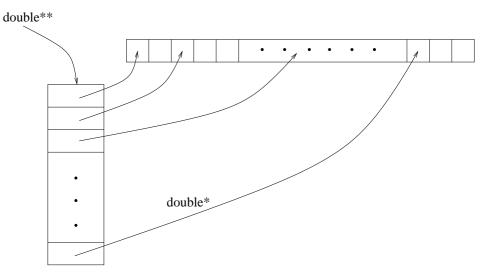
```
double A[10][8];
```

However, the size of the array is decided at compiler time (not runtime)

More about two-dimensional arrays in C (2)

- Dynamic memory allocation of 2D arrays through e.g. malloc
- Another way of dynamic allocation, to ensure contiguous underlying data storage (for good use of cache):

```
double *A_storage=(double*)malloc(n*n*sizeof(double));
double **A = (double**)malloc(n*sizeof(double*));
for (i=0; i<n; i++)
   A[i] = &(A_storage[i*n]);</pre>
```



Deallocation of arrays in C

- If an array is dynamically allocated, it is important to free the storage when the array is not used any more
- Example 1

```
int *p = (int*)malloc(n*sizeof(int));
/* ... */
free(p);
```

Example 2

```
double **A = (double**)malloc(m*sizeof(double*));
for (i=0; i<m; i++)
    A[i] = (double*)malloc(n*sizeof(double));
/* ... */
for (i=0; i<m; i++)
    free(A[i]);
free(A);</pre>
```

Be careful! Memory allocation and deallocation can easily lead to errors

The form of a C program

- A program in C is made up of functions
- A stand-alone C program must at least implement function main, which will be executed by the operating system
- Functions are made up of statements and declarations
- Variables must be declared before usage
- Possible to use functions and variables declared in libraries

Some syntax details in C

- Semicolon (;) terminates a statement
- Braces ({}) are used to group statements into a block
- Square brackets ([]) are used in connection with arrays
- Comments can be added between /* and */

Functions in C

- Function declaration specifies name, type of return value, and (optionally) a list of parameters
- Function definition consists of declaration and a block of code, which encapsulates some operation and/or computation

```
return_type function_name (parameter declarations)
{
  declarations of local variables
  statements
}
```

Function arguments

- All arguments to a C function are passed by value
- That is, a copy of each argument is passed to the function

```
void function test (int i) {
  i = 10;
}
```

The change of i inside test has no effect when the function returns

Passing pointers as function arguments can be used to get output

```
void function test (int *i) {
  *i = 10;
}
```

The change of i inside test now has effect

Function example 1: swapping two values

```
void swap (int *a, int *b)
{
  int tmp;
  tmp = *a;
  *a = *b;
  *b = tmp;
}
```

Function example 2: smoothing a vector

We want to smooth the values of a vector v by the following formula:

$$v_i^{\text{new}} = v_i + c(v_{i-1} - 2v_i + v_{i+1}), \quad 2 \le i \le n-1$$

where c is a constant

```
void smooth (double *v_new, double *v, int n, double c)
{
  int i;
  for (i=1; i<n-1; i++)
    v_new[i] = v[i] + c*(v[i-1]-2*v[i]+v[i+1]);
  v_new[0] = v[0];
  v_new[n-1] = v[n-1];
}</pre>
```

Similar computations occur frequently in numerical computations

Function example 3: matrix-vector multiplication

We want to compute y = Ax, where A is a $m \times n$ matrix, y is a vector of length m and x is a vector of length n:

$$y_{i} = A_{i1}x_{1} + A_{i2}x_{2} + \dots A_{in}x_{n} = \sum_{j=1}^{n} A_{ij}x_{j}, \quad 1 \leq i \leq m$$
 void mat_vec_prod (double **A, double *y, double *x, int m, int n)
$$\{ \\ \text{int i,j;} \\ \text{for (i=0; i$$

Example of a complete C program

```
#include <stdio.h> /* import standard I/O functions */
int myfunction(int x) /* define a function */
 int r;
 r = x * x + 2 * x + 3;
 return r;
int main (int nargs, char** args)
  int x,y;
 x = atoi(args[1]); /* read x from command line */
 y = myfunction(x); /* invoke myfunction */
 printf("x=%d, y=%d\n",x,y);
 return 0;
```

Compilation

- Suppose a file named first.c contains the C program
- Suppose we use GNU C compiler gcc
- Step 1: Creation of a file of object code:

```
gcc -c first.c
```

An object file named first.o will be produced.

Step 2: Creation of the executable:

```
qcc -o run first.o
```

The executable will have name run.

Alternatively (two steps in one),

Better to use the 2-step approach for complex examples

Some important compiler options

- During compilation:
 - Option -o turns on optimization flag of the compiler
 - Option -c produces an object file for each source file listed
 - Option -Ixxx suggests directory xxx for search of header files
- During linkage:
 - Option -lxxx links with a specified library with name libxxx.a or libxxx.so
 - Option -Lxxx suggests directory xxx for search of library files
 - Option -o specifies the name of the resulting executable