

# Examples of MPI programming

# A 1D example

The computational problem:

- A uniform mesh in  $x$ -direction with  $M + 2$  points:
  - $x_0$  is left boundary point,  $x_{M+1}$  is right boundary point
  - $x_1, x_2, \dots, x_M$  are interior points
- The main computation is a time-stepping procedure. That is, for  $\ell = 1, 2, \dots$  we compute
  -

$$u_i^{\ell+1} = 2u_i^\ell - u_i^{\ell-1} + C_2 (u_{i-1}^\ell - 2u_i^\ell + u_{i+1}^\ell) \quad i = 1, 2, \dots, M$$

- $u_i^\ell$  denotes a value at spatial point  $x_i$  and time level  $\ell$
- $C_2$  is a constant
- $u_0^\ell$  and  $u_{M+1}^\ell$  are given as boundary conditions (for all time levels)
- The above computation may arise from solving a 1D wave equation, but we don't need to know the mathematical/numerical details

# Observations

- To compute the  $u^{\ell+1}$  values on time level  $\ell + 1$ , we need two preceding time levels:  $\ell$  and  $\ell - 1$ 
  - We assume that the  $u^0$  and  $u^1$  values (for all subscript  $i$  indices) are given as initial conditions
  - The main computation is a time stepping iteration
- The value of  $u_i^{\ell+1}$  does not depend on the value of  $u_j^{\ell+1}$ 
  - The  $u^{\ell+1}$  values can be computed **independently**, in any order!!!

# Serial implementation

- Three 1D arrays are needed:
  - $u^{\ell+1}$ : double \*up= (double\*) malloc( (M+2) \* sizeof(double)) ;
  - $u^\ell$ : double \*u= (double\*) malloc( (M+2) \* sizeof(double)) ;
  - $u^{\ell-1}$ : double \*um= (double\*) malloc( (M+2) \* sizeof(double)) ;
- Preparation work for prescribing the  $u^0$  (um array) and  $u^1$  values (u array)
- Main computation: A while-loop for doing the time steps
  - At each time step, a for-loop for updating the interior points

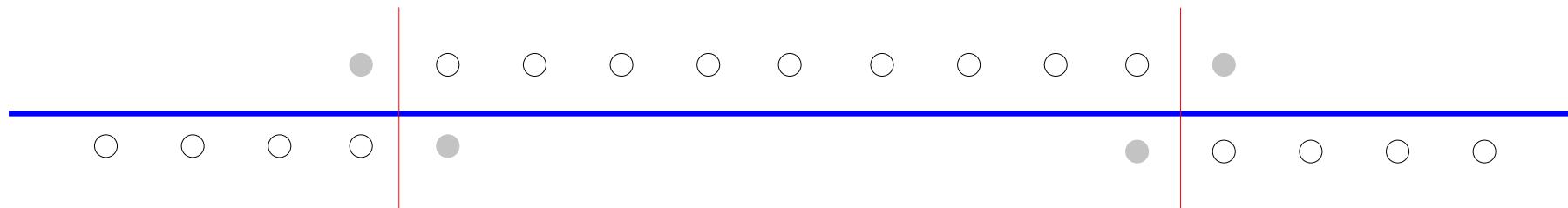
# Time stepping

```
t = dt;  
while (t<T) {  
    t += dt;  
    for (i=1; i<=M; i++)  
        up[i] = 2*u[i]-um[i]+C2*(u[i-1]-2*u[i]+u[i+1]);  
    up[0] = value_of_left_BC(t); // left boundary condition  
    up[M+1] = value_of_right_BC(t); // right boundary condition  
  
    /* preparation for next time step: shuffle the three arrays */  
    tmp = um;  
    um = u;  
    u = up;  
    up = tmp;  
}
```

# Parallelization

Parallelization starts with dividing the work

- The global domain is decomposed into  $P$  segments (subdomains)
  - actually, the  $M$  interior points are divided



# MPI programming

- Each subdomain is assigned with a portion of the interior points

```
int P, my_rank, my_start, my_stop, M_local;  
MPI_Comm_size (MPI_COMM_WORLD, &P);  
MPI_Comm_rank (MPI_COMM_WORLD, &my_rank);  
my_start = (my_rank*M)/P+1;  
my_stop = ((my_rank+1)*M)/P;  
M_local = my_stop - my_start + 1;
```

- In addition, each subdomain is expanded with two “ghost points”
  - if there is a neighbor subdomain over the boundary, the value of the ghost point is to be provided by the neighbor
  - if there is no neighbor subdomain over the boundary, the ghost point is actually a physical boundary point ( $x_0$  or  $x_{M+1}$ )
- Data allocation per MPI process:

```
double *up_local=(double*) malloc( (M_local+2) * sizeof(double));  
double *u_local = (double*) malloc( (M_local+2) * sizeof(double));  
double *um_local= (double*) malloc( (M_local+2) * sizeof(double));
```

# Computation per MPI process

```
t = dt;
while (t<T) {
    t += dt;
    for (i=1; i<=M_local; i++)
        up_local[i] = 2*u_local[i]-um_local[i]
                    +C2*(u_local[i-1]-2*u_local[i]+u_local[i+1]);
    if (my_rank==0)
        up_local[0] = value_of_left_BC(t); // left boundary condition
    if (my_rank==P-1)
        up_local[M_lcoal+1] = value_of_right_BC(t); // right boundary condition
    communicate1D (up_local, M_local, my_rank, P);
/* preparation for next time step: shuffle the three arrays */
    tmp = um_lcoal;
    um_local = u_local;
    u_local = up_local;
    up_local = tmp;
}
```

# Communication

```
void communicate1D (double *up_local, int M_local, int my_rank, int P)
{
    MPI_Status status;

    if (my_rank%2) { // odd-number proc exchanges with left neighbor
        if (my_rank>1) {
            MPI_Send (&(up_local[1]),1,MPI_DOUBLE,my_rank-1,1,MPI_COMM_WORLD);
            MPI_Recv (&(up_local[0]),1,MPI_DOUBLE,my_rank-1,2,MPI_COMM_WORLD, &status);
        }
    }
    else { // even-number proc exchanges with right neighbor
        if (my_rank<(P-1)) {
            MPI_Recv (&(up_local[M_local+1]),1,MPI_DOUBLE,my_rank+1,1,MPI_COMM_WORLD);
            MPI_Send (&(up_local[M_local]),1,MPI_DOUBLE,my_rank+1,2,MPI_COMM_WORLD);
        }
    }
}
```

# Communication (continued)

```
if (my_rank%2) { // odd-number proc exchanges with right neighbor
    if (my_rank<(P-1) {
        MPI_Send (&(up_local[M_local]),1,MPI_DOUBLE,my_rank+1,3,MPI_COMM_WORLD)
        MPI_Recv (&(up_local[M_local+1]),1,MPI_DOUBLE,my_rank+1,4,MPI_COMM_WORLD)
    }
}
else { // even-number proc exchanges with left neighbor
    if (my_rank>1) {
        MPI_Recv (&(up_local[1]),1,MPI_DOUBLE,my_rank-1,3,MPI_COMM_WORLD,&stat)
        MPI_Send (&(up_local[0]),1,MPI_DOUBLE,my_rank-1,4,MPI_COMM_WORLD);
    }
}
```

# Alternative communication

An equivalent implementation that uses MPI\_Sendrecv:

```
void communicate1D (double *up_local, int M_local, int my_rank, int P)
{
    MPI_Status status;

    int left_neigh = (my_rank>1) ? my_rank-1 : MPI_PROC_NULL;
    int right_neigh = (my_rank<(P-1)) ? my_rank+1 : MPI_PROC_NULL;

    // send to left neighbor, receive from right neighbor
    MPI_Sendrecv (&(up_local[1]),1,MPI_DOUBLE, left_neigh,5,
                  &(up_local[M_local+1]),1,MPI_DOUBLE, right_neigh,5,
                  MPI_COMM_WORLD, &status);

    // send to right neighbor, receive from left neighbor
    MPI_Sendrecv (&(up_local[M_local]),1,MPI_DOUBLE, right_neigh,6,
                  &(up_local[0]),1,MPI_DOUBLE, left_neigh,6,
                  MPI_COMM_WORLD, &status);
}
```

# A 2D example

2D uniform grid:

$x_0, x_1, \dots, x_M, x_{M+1}$  in the  $x$  direction

$y_0, y_1, \dots, y_N, y_{N+1}$  in the  $y$  direction

$$\begin{aligned} u_{i,j}^{\ell+1} = & 2u_{i,j}^\ell - u_{i,j}^{\ell-1} \\ & + C_{2x} (u_{i-1,j}^\ell - 2u_{i,j}^\ell + u_{i+1,j}^\ell) \\ & + C_{2y} (u_{i,j-1}^\ell - 2u_{i,j}^\ell + u_{i,j+1}^\ell) \\ & i = 1, 2, \dots, M, \quad j = 1, 2, \dots, N \end{aligned}$$

# Serial implementation

```
double **up, **u, **um; // three 2D arrays
// ...
while (t<T) {
    t += dt;
    for (j=1; j<=N; j++)
        for (i=1; i<=M; i++)
            up[j][i] = 2*u[j][i]-u[j][i]
                        +C2x*(u[j][i-1]-2*u[j][i]+u[j][i+1])
                        +C2y*(u[j-1][i]-2*u[j][i]+u[j+1][i]);
    enforce_left_BC (up,M,N,t);
    enforce_right_BC (up,M,N,t);
    enforce_lower_BC (up,M,N,t);
    enforce_upper_BC (up,M,N,t);

    /* preparation for next time step: shuffle the three arrays */
    tmp = um;
    um = u;
    u = up;
    up = tmp;
}
```

# Parallelization approach 1

- Divide the 2D domain into horizontal blocks
  - The  $N$  interior points in the  $y$  direction is divided evenly among  $P$  processes
- Each MPI process is responsible for a subdomain of  $M \times N_{\text{local}}$  interior points
- Each subdomain is extended with a surrounding layer of ghost points

# MPI implementation (array allocation)

```
double **up_local, **u_local, **um_local;
int P, my_rank, my_start, my_stop, N_local;
MPI_Comm_size (MPI_COMM_WORLD, &P);
MPI_Comm_rank (MPI_COMM_WORLD, &my_rank);
my_start = (my_rank*N)/P+1;
my_stop = ((my_rank+1)*N)/P;
N_local = my_stop - my_start + 1;

up_local=(double**)malloc((N_local+2)*sizeof(double*));
up_local[0]=(double*)malloc((N_local+2)*(M+2)*sizeof(double));
for (j=1; j<=N_local+1; j++)
    up_local[j] = &(up_local[0][j*(M+2)]);

// similarly for allocating arrays u_local and um_local
```

# MPI implementation (main computation)

```
while (t<T) {  
    t += dt;  
    for (j=1; j<=N_local; j++)  
        for (i=1; i<=M; i++)  
            up_local[j][i] = 2*u_local[j][i]-u_local[j][i]  
                +C2x*(u_local[j][i-1]-2*u_local[j][i]+u_local[j][i+1])  
                +C2y*(u_local[j-1][i]-2*u_local[j][i]+u_local[j+1][i]);  
  
    enforce_left_BC (up_local,M,N_local,t);  
    enforce_right_BC (up_local,M,N_local,t);  
    if (my_rank==0)  
        enforce_lower_BC (up_local,M,N_local,t);  
    if (my_rank==P-1)  
        enforce_upper_BC (up_local,M,N_local,t);  
  
    communicate2D_vertical (up_local, M, N_local, my_rank, P);  
  
    // pointer swap for arrays up_local, u_local um_local  
}
```

# Communication in the vertical direction

```
void communicate2D_vertical(double **up_local, int M, int N_local,
                           int my_rank, int P)
{
    MPI_Status status;
    int lower_neigh = (my_rank>1) ? my_rank-1 : MPI_PROC_NULL;
    int upper_neigh = (my_rank<(P-1)) ? my_rank+1 : MPI_PROC_NULL;

    // send to lower neighbor, receive from upper neighbor
    MPI_Sendrecv (&(up_local[1][1]),M,MPI_DOUBLE, lower_neigh,5,
                  &(up_local[N_local+1][1]),M,MPI_DOUBLE, upper_neigh,5,
                  MPI_COMM_WORLD, &status);

    // send to upper neighbor, receive from lower neighbor
    MPI_Sendrecv (&(up_local[N_local][1]),M,MPI_DOUBLE, upper_neigh,6,
                  &(up_local[0][1]),M,MPI_DOUBLE, lower_neigh,6,
                  MPI_COMM_WORLD, &status);
}
```

# Parallelization approach 2

- 2D domain partitioning
  - Number of subdomains is  $P = Q \times R$
  - The  $M$  interior points in the  $x$  direction are divided into  $Q$  pieces
  - The  $N$  interior points in the  $y$  direction are divided into  $R$  pieces
  - Each subdomain is responsible for  $M_{\text{local}} \times N_{\text{local}}$  interior points
- Communication is now needed in both horizontal ( $x$ ) and vertical ( $y$ ) directions
  - Each MPI process needs a double index `my_rank_x`, `my_rank_y`
  - Vertical communication is as simple as in Parallelization approach 1
  - Horizontal communication requires intermediate buffers for outgoing and incoming messages, because the data points of array `up_local` that constitute the horizontal messages are not contiguous in memory
- MPI programming details are omitted