

INF3490/INF4490 Exercises - Week 7

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ℙ marks the programming exercises, we strongly recommend using the python programming language for these. Exercises may be added/changed after publishing.

1 Policies

What policy would make on-policy and off-policy learning equivalent, specifically if we consider Q-learning and SARSA-learning? In other words, what policy used by an agent will make the learning based on Q-learning and SARSA-learning the same?

2 Reinforcement learning for chess

Imagine you were to design a reinforcement learning agent for playing chess. The state that the agent sees on its turn is the layout of the chess board. We can set the reward structure for the agent to be +1 for winning, -1 for losing, 0 for drawing, and 0 again for every move that does not lead to a win or loss. Such an agent will essentially learn to win. It will do so eventually after much exploration and a number of episodes, since it is always trying to maximize its expected return (cumulative rewards in the long run). What might happen if, in addition, we give a positive reward to the agent for taking its opponent's pieces as well?

3 Large state/action spaces

In most real world problems with large state/action spaces, quantizing the state/action space and using tables to store/update values, e.g. the Q table, is not feasible. Can you suggest a way for reinforcement learning algorithms to generalize to arbitrarily large real valued state/action spaces? Hint: The tables are approximating a value function, i.e. mapping a state-action pair to a value. What else could be used for function approximation?

Contact and Github

Corrections of grammar, language, notation or suggestions for improving this material are appreciated. E-mail me at olehelg@uio.no or use **GitHub** to submit an issue or create a pull request. The **GitHub repository** contains all source code for assignments, exercises, solutions, examples etc. As many people have been involved with writing and updating the course material, they are not all listed as authors here. For a more complete list of authors and contributors see the **README**.