



UiO : Department of Informatics  
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**INF3490 - Biologically inspired computing**

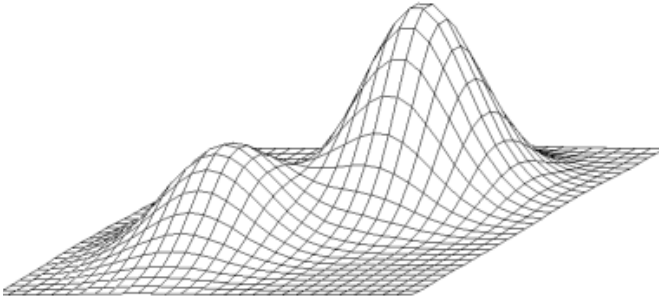
Lecture 1: Marsland chapter 9.1, 9.4-9.6

**Optimization and Search**  
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**Optimization and Search**



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**Optimization and Search Methods  
(selection)**

1. Exhaustive search
2. Greedy search and hill climbing
3. Gradient ascent
4. Simulated annealing

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**Optimization**

We need

- A numerical representation  $x$  for all possible solutions to the problem
- A function  $f(x)$  that tells us how good solution  $x$  is
- A way of finding
  - $\max_x f(x)$  if bigger  $f(x)$  is better (benefit)
  - $\min_x f(x)$  if smaller  $f(x)$  is better (cost)

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## Optimisation and Search

- **Continuous Optimization** is the mathematical discipline which is concerned with finding the maxima and minima of functions, possibly subject to constraints.
- **Discrete Optimization** is the activity of looking thoroughly in order to find an item with specified properties among a collection of items.



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## Discrete optimization

- **Chip design**
  - Routing tracks during chip layout design
- **Timetabling**
  - E.g.: Find a course time table with the minimum number of clashes for registered students
- **Travelling salesman problem**
  - Optimization of travel routes and similar logistics problems



## Example: Travelling Salesman Problem (TSP)

- Given the coordinates of  $n$  cities, find the **shortest closed tour** which visits each **once and only once** (i.e. exactly once).
- Constraint :
  - all cities be visited, once and only once.



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## 1. Exhaustive search

- Test all possible solutions, pick the best
- Guaranteed to find the optimal solution



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## Exhaustive search

Only works for simple discrete problems, but can be approximated in continuous problems

- Sample the space at regular intervals (grid search)
- Sample the space randomly  $N$  times

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## 2. Greedy search

- Pick a solution as the current best
- Compare to all neighboring solutions
  - If no neighbor is better, then terminate
  - Otherwise, replace the current best with the best of the neighbors
  - Repeat

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## Hill climbing

- Pick a solution as the current best
- Compare to a random neighbor
  - If the neighbor is better, replace the current best
  - Repeat

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## Continuous optimization

- **Mechanics**
  - Optimized design of mechanical shapes etc.
- **Economics**
  - Portfolio selection, pricing options, risk management etc.
- **Control engineering**
  - Process engineering, robotics etc.



### 3. Gradient ascent / descent

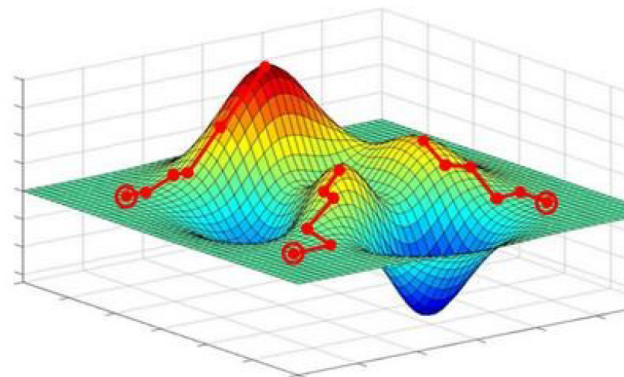
In continuous optimization we may be able to calculate the gradient of  $f(x)$ :

$$\nabla f(x) = \begin{bmatrix} \frac{\delta f(x)}{\delta x_0} \\ \frac{\delta f(x)}{\delta x_1} \\ \vdots \\ \frac{\delta f(x)}{\delta x_n} \end{bmatrix}$$

The gradient tells us in which direction  $f(x)$  increases the most

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### 3. Gradient ascent / descent



### Gradient ascent / descent

Starting from  $x^{(0)}$ , we can iteratively find higher  $f(x^{(k+1)})$  by adding a value proportional to the gradient to  $x^{(k)}$ :

$$x^{(k+1)} = x^{(k)} + \gamma \nabla f(x^{(k)})$$

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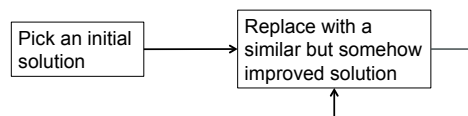
### Local optima

Algorithms like greedy search, hill climbing and gradient ascent/descent can only find local optima:

- They will only move through a strictly improving chain of neighbors
- Once they find a solution with no better neighbors they stop

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## Exploitation



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## Global optimization

- Most of the time, we must expect the problem to have many local optima
- Ideally, we want to find the best local optima: the global optimum

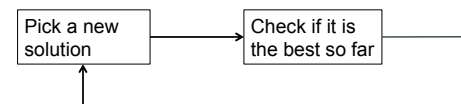
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## Exploitation and Exploration

- Search methods should combine:
  - Trying completely new solutions (like in exhaustive search) => **Exploration**
  - Trying to improve the current best solution by local search => **Exploitation**

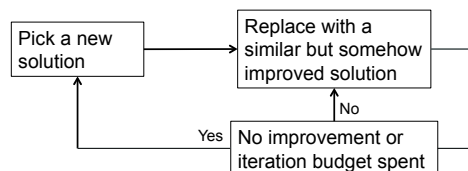
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## Exhaustive search – pure exploration



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## Mixed solution



Works better, but only if there are few local optima

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## Going the wrong way

What if we modified the hill climber to sometimes choose worse solutions?

- Goal: avoid getting stuck in a local optimum
- Always keep the new solution if it is better
- However, if it is worse, we'd still want to keep it sometimes, i.e. with some probability

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## Annealing

A thermal process for obtaining low energy states of a solid in a heat bath:

- Increase the temperature of the heat bath to a the point at which the solid melts
- Decrease the temperature slowly
- If done slowly enough, the particles arrange themselves in the minimum energy state

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## 4. Simulated annealing

- Set an initial temperature  $T$
- Pick an initial solution
- Repeat:
  - Pick a solution neighboring the current solution
  - If the new one is better, keep it
  - Otherwise, keep the new one with a probability  $P(\Delta f, T) = e^{-\Delta f/T}$
  - Decrease  $T$

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