

# INF3580 – Semantic Technologies – Spring 2010

## Lecture 8: OWL, the Web Ontology Language

Martin Giese

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DEPARTMENT OF  
INFORMATICS



UNIVERSITY OF  
OSLO

# Today's Plan

- 1 Reminder: RDFS
- 2 Description Logics
- 3 Introduction to OWL

# Outline

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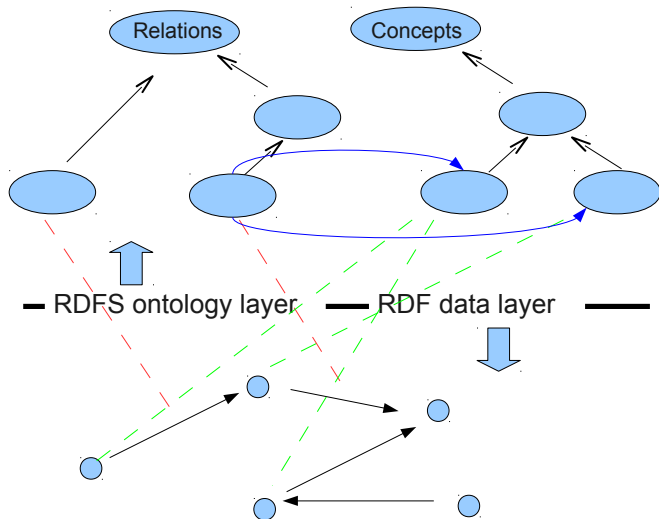
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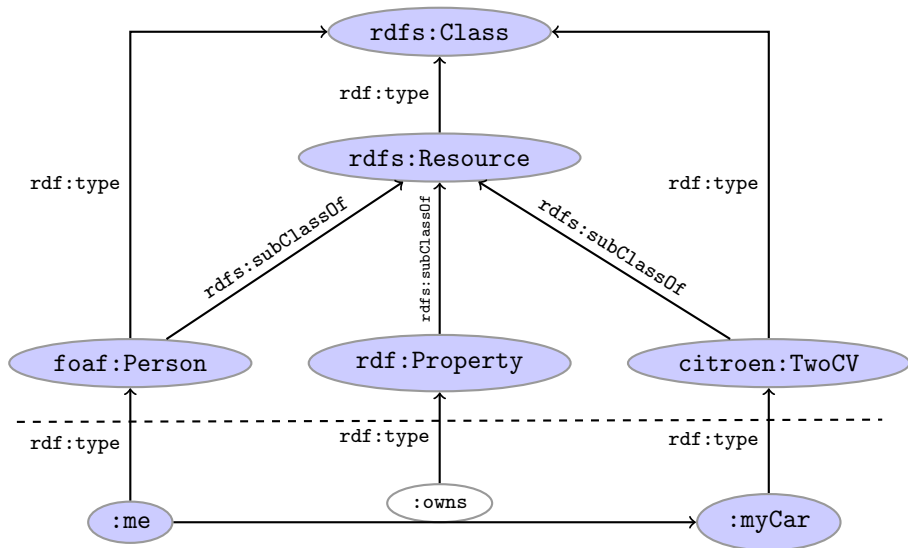
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- There are rules to reason about classes



## An RDFS knowledge base



## Example



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  - `rdfs:Class` not quite the same as a set

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- A setting well-studied as *Description Logics*

# Example: The $\mathcal{ALC}$ Description Logic

## Vocabulary

Fix a set of *atomic concepts*  $A$  and of *roles*  $R$

## $\mathcal{ALC}$ concept descriptions

$C, D \rightarrow$	$A$		(atomic concept)
	$\top$		(universal concept)
	$\perp$		(bottom concept)
	$\neg C$		(atomic negation)
	$C \sqcap D$		(intersection)
	$C \sqcup D$		(union)
	$\forall R.C$		(value restriction)
	$\exists R.C$		(existential restriction)

## Axioms

$C \sqsubseteq D$  and  $C \equiv D$  for concept descriptions  $D$  and  $C$ .

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  - A 4WD has at least one front drive axle and one rear drive axle



# ALC Semantics

## Interpretation

An interpretation  $\mathcal{I}$  fixes a set  $\Delta^{\mathcal{I}}$ , the *domain*,  $A^{\mathcal{I}} \subseteq \Delta^{\mathcal{I}}$  for each atomic concept  $A$ , and  $R^{\mathcal{I}} \subseteq \Delta^{\mathcal{I}} \times \Delta^{\mathcal{I}}$  for each role  $R$

## Interpretation of concept descriptions

$$\begin{aligned}
 \top^{\mathcal{I}} &= \Delta^{\mathcal{I}} \\
 \perp^{\mathcal{I}} &= \emptyset \\
 (\neg C)^{\mathcal{I}} &= \Delta^{\mathcal{I}} \setminus C^{\mathcal{I}} \\
 (C \sqcap D)^{\mathcal{I}} &= C^{\mathcal{I}} \cap D^{\mathcal{I}} \\
 (C \sqcup D)^{\mathcal{I}} &= C^{\mathcal{I}} \cup D^{\mathcal{I}} \\
 (\forall R.C)^{\mathcal{I}} &= \{a \in \Delta^{\mathcal{I}} \mid \forall b.(a, b) \in R^{\mathcal{I}} \rightarrow b \in C^{\mathcal{I}}\} \\
 (\exists R.C)^{\mathcal{I}} &= \{a \in \Delta^{\mathcal{I}} \mid \exists b.(a, b) \in R^{\mathcal{I}} \wedge b \in C^{\mathcal{I}}\}
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## Interpretation of Axioms

$C \sqsubseteq D$  holds in  $\mathcal{I}$  ( $\mathcal{I} \models C \sqsubseteq D$ ) if  $C^{\mathcal{I}} \subseteq D^{\mathcal{I}}$ .  $\mathcal{I} \models C \equiv D$  if  $C^{\mathcal{I}} = D^{\mathcal{I}}$

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- Therefore,  $TwoCV \sqsubseteq Car$  *doesn't* hold in this interpretation

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- i.e. the set of all things  $a$  that have a drive axle  $b$  which is a front axle.

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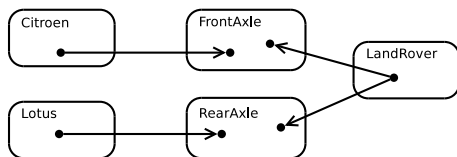
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# Universal and Existential Restrictions cont.

- Assume:

- All *Citroen* cars have one drive axle and that is the front axle
- All *Lotus* cars have one drive axle and that is the rear axle
- All *LandRover* cars have two drive axles, one front and one back



- In such a model:

- $Citroen \sqsubseteq \forall driveAxle. FrontAxle$
- $LandRover \sqsubseteq \exists driveAxle. FrontAxle \sqcap \exists driveAxle. RearAxle$
- $Lotus \sqsubseteq \forall driveAxle. RearAxle$

# Universal Restrictions and `rdfs:range`

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  - and role assertions  $R(b, c)$

# Example TBox and ABox

## TBox

$TwoCV \sqsubseteq Car$

$Car \sqsubseteq \exists driveAxle.\top$

$TwoCV \sqsubseteq \forall driveAxle.FrontAxle$

$FrontDrivenCar \equiv Car \sqcap \forall driveAxle.FrontAxle$

$FrontAxle \sqcap RearAxle \sqsubseteq \perp$

$FourWheelDrive \equiv \exists driveAxle.FrontAxle \sqcap \exists driveAxle.RearAxle$

## ABox

$TwoCV(myCar)$

$owns(me, myCar)$

$driveAxle(myCar, ax)$

$(FrontAxle \sqcup RearAxle)(ax)$

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# Outline

- 1 Reminder: RDFS
- 2 Description Logics
- 3 Introduction to OWL**

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- Extends RDFS with boolean operations, universal/existential restrictions, etc.



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    - Designed for compatibility with rule-based inference tools.



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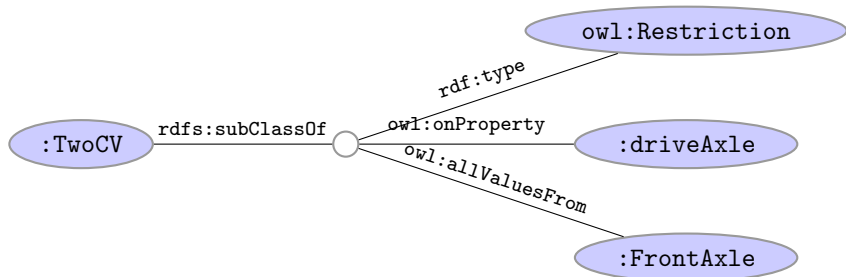
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## Example: Universal Restrictions in OWL/RDF

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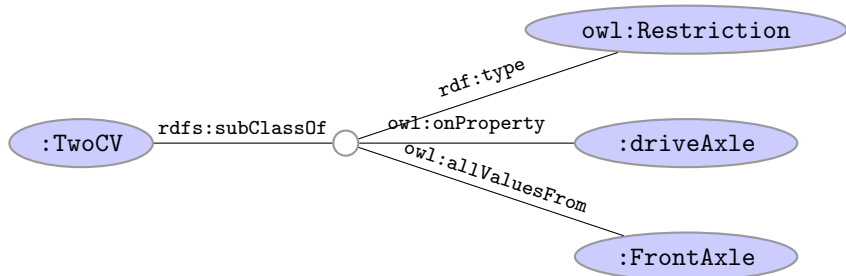
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- In Turtle syntax:  

```
:TwoCV rdfs:subClassOf [ rdf:type owl:Restriction ;
                           owl:onProperty :driveAxle ;
                           owl:allValuesFrom :FrontAxle
                           ] .
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- In OWL Functional syntax:

```
SubClassOf(CV ObjectAllValuesFrom(driveAxle FrontAxle))
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$\neg C$	not $C$
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- Examples:

DL	Manchester
$FrontAxle \sqcup RearAxle$	FrontAxle or RearAxle
$\forall driveAxle.FrontAxle$	driveAxle only FrontAxle
$\exists driveAxle.RearAxle$	driveAxle some RearAxle

# Demo: Using Protégé

- Create a Car class
- Create an Axle class
- Create FrontAxle and RearAxle as subclasses
- Make the axle classes disjoint
- Add a driveAxle object property
- Add domain Car and range Axle
- Add 2CV, subclass of Car
- Add superclass driveAxle only FrontAxle
- Add Lotus, subclass of Car
- Add superclass driveAxle only RearAxle
- Add LandRover, subclass of Car
- Add superclass driveAxle some FrontAxle
- Add superclass driveAxle some RearAxle
- Add 4WD as subclass of Thing
- Make equivalent to driveAxle some RearAxle and driveAxle some FrontAxle
- Classify.
- Show inferred class hierarchy: Car  $\sqsupseteq$  4WD  $\sqsupseteq$  LandRover
- Tell story of 2CV Sahara, which is a 2CV with two motors, one front, one back
- Add Sahara as subclass of 2CV
- Add 4WD as superclass of 2CV
- Classify.
- Show that Sahara is equivalent to bottom.
- Explain why. In particular, disjointness of front and rear axles

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- Reasoning (e.g. Classification) maps everything to DL first

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OntClass car = model.createClass(CARS+"Car");
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  - See class `OntModelSpec`

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- Works on the level of concept descriptions and axioms
- Can parse and write all mentioned OWL formats, and then some

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  - transitive, inverse, symmetric, functional properties