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INF 4140: Models of Concurrency

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Topic: About Chap. 2& 3: synchronization, critical sections

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Exercises: 2.17, 2.18, 2.33, 3.1, 3.7, 3.8 from the textbook

Exercise 1 (2.17)

For which initial values does the program terminate (under weak scheduling). What are the corresponding final values. Explain the answer.

Exercise 2 (2.18)

```
co 

<a wait (x > 0) x := x-1;>
| |

<a wait (x < 0) x := x+2;>
| |

<a wait (x = 0) x := x-1;>
oc
```

For which initial values does the program terminate (under weak scheduling). What are the corresponding final values. Explain the answer.

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Exercise 3 (2.33)

```
int x := 10; c := true;
 1
 2
3
 4
     \mathbf{co}
           \langle \mathbf{await} \ \mathbf{x} = 0 \rangle; \ \mathbf{c} := \mathbf{false}
 5
 6
      7
             while (c) < x := x-1>
8
9
     \mathbf{oc}
10
```

- 1. Termination under weak fairness?
- 2. Termination under strong fairness?
- 3. Add the following statement as 3rd arm of the co-statement:

```
while (c) { if (x < 0) < x := 10 > ; }
```

Exercise 4 (Dekker's algo (3.1)) The code shows the initialization and process P_1 , a second P_2 is symmetric.

```
bool enter1 = false, enter2 = false;
   int turn = 1;
2
3
   process P1{
4
      while (true){
5
6
        enter1 := true
                                          ## entry protocol
7
        while (enter2) {
8
9
           if(turn = 2){
             enter1 := false;
10
             \mathbf{while}(\text{turn} = 2) \text{ skip};
11
             enter1 := true;
12
13
        }
14
15
        CS;
16
17
        enter1 := false;
                                            ## exit protocol
18
        turn := 2;
19
        non-CS;
20
21
22
```

- 1. mutex?
- 2. deadlock
- 3. unnecessary delay
- 4. eventual entry

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Also: how many times can one process that wants to enter its critical section be bypassed by the other before the first gets in?

Exercise 5 (3.7) Consider the following code snippet (due to Lamport [?])

```
int lock = 0;
   process CS[i = 1 \text{ to } n]
2
      while (true) {
3
        <await (lock = 0)>;
4
       lock := i;
5
       Delay
6
           \mathbf{while}(lock != i){
7
             <await (lock = 0)>; lock := i; Delay;
8
9
10
       ĆS;
11
       lock := 0;
12
       non-CS;
13
```

- 1. Suppose the delay code is deleted.
 - (a) mutex?
 - (b) deadlock?
 - (c) unnecessary delay?
 - (d) eventual entry
- $2. \,$ Suppose the Delay code is added and long enough. Reconsider your answers under that circumstances.

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Exercise 6 (3.8) Consider the following code. Not that the flip-operation is assumed to be atomic (for instance, representing a HW operation). Then consider the sketched code intended to solve the CS problem.

```
flip (lock)
1
                                            \# flip the lock
      < lock = (lock + 1) \% 2;
2
      return (lock);>
                                            # return the new value
3
4
   int lock = 0;
                                            # shared variable
5
6
   process CS[i = 1 \text{ to } 2]
7
      while (true) {
8
       while (flip (lock) != 1)
9
          \{ \mathbf{while} ( lock != 0) \ skip; \}
10
       CS;
11
       lock := 0;
12
       non-CS;
13
14
15
```

- 1. Spot the defect in the code, violating the basic safety assumption, i.e., "mutual exclusion".
- 2. What happens if the calculation is done modulo 3, instead of modulo 2 as now?