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# INF5410 Array signal processing. Chapter 2.4 Refraction and diffraction

Sverre Holm



# Deviations from simple media

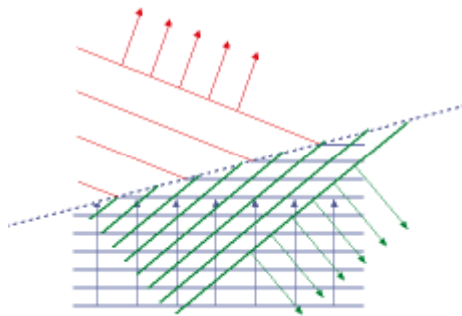
1. Dispersion:  $c = c(\omega)$ 
  - Group and phase velocity, dispersion equation:  $\omega = f(k) \neq c \cdot k$
  - Evanescent (= non-propagating) waves: purely imaginary  $k$
2. Attenuation:  $c = c_{\Re} + jc_{\Im}$ 
  - Wavenumber is no longer real, imaginary part gives attenuation.
  - Waveform changes with distance
3. Non-linearity:  $c = c(s(t))$ 
  - Generation of harmonics, shock waves
4. Refraction:  $c=c(x,y,z)$ 
  - Snell's law



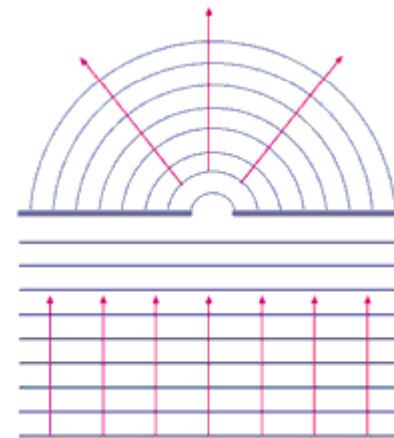
# Reflection, refraction, diffraction

- Click

<http://lectureonline.cl.msu.edu/~mmp/kap13/cd372.htm>



When a wave meets the interface, it is either refracted or reflected.



A wave is diffracted by an aperture.



## 4. Refraction - avbøyning

- Unchanged phase on interface:

$$\vec{k}_i \cdot \vec{x} = \vec{k}_r \cdot \vec{x} = \vec{k}_t \cdot \vec{x}$$

- Fig 2.10:

$$|\vec{k}_i| \cdot \sin \theta_i = |\vec{k}_r| \cdot \sin \theta_r = |\vec{k}_t| \cdot \sin \theta_t$$

- Reflected (same  $c$ ) :  
 $k = \omega/c \Rightarrow \theta_r = \theta_i$
- Refracted, Snell's law:  
 $\sin \theta_i / c_i = \sin \theta_t / c_t$
- Willebrand Snell von Royen,  
NL 1591-1626

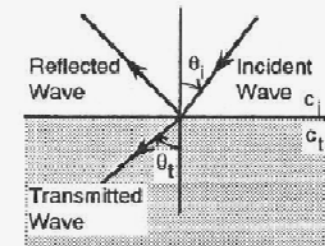


Figure 2.10 An incident wave striking a discontinuity in the medium results in a reflected wave and a transmitted wave. The angle of reflection equals the angle of incidence, and the angle of refraction of the transmitted wave obeys Snell's Law. In this example, the propagation speed in the lower medium is greater than in the upper.

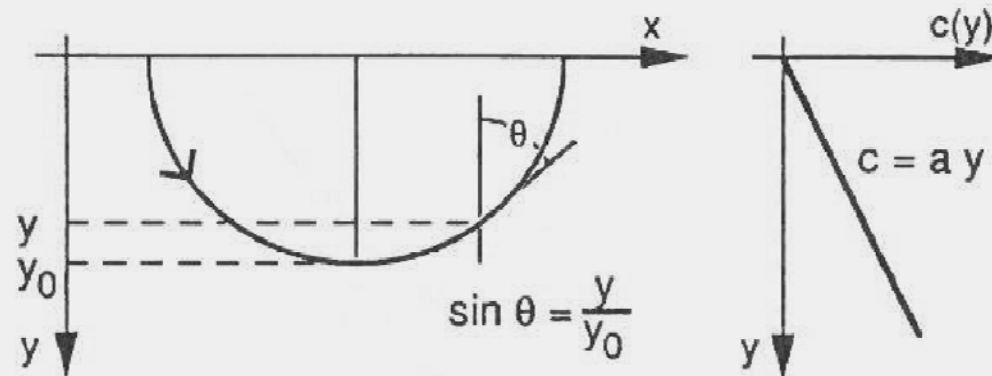


# Critical Angle – total reflection

- $\sin\theta_i/c_i = \sin\theta_t/c_t$
- Total reflection for all  $\theta_i$  which result in  $\theta_t > 90^\circ$
- Critical angle  $\sin\theta_i = c_i/c_t$
- Ex: steel  $c_t = 5800$  m/s, water  $c_i = 1490$  m/s,  
 $\theta_i < 16.5^\circ$
- Important for containing 100% of transmitted energy inside optical fibers



# Simple model for the sea



**Figure 2.11** A linear change in the speed of sound with depth results in circular rays. The linear sound profile is shown in the right panel.

Problem 2.8. More general:  $c=c_0(1+ay)$



# Snell's law on differential form

- Snell's law: 
$$\frac{\sin \theta(y)}{c(y)} = \frac{\sin \theta(y - \delta y)}{c(y - \delta y)}$$

- Multiply by  $c(y - \delta y)$  and subtract  $\sin \theta(y)$

$$\sin \theta(y - \delta y) - \sin \theta(y) = \frac{\sin \theta(y)}{c(y)} \cdot [c(y - \delta y) - c(y)]$$

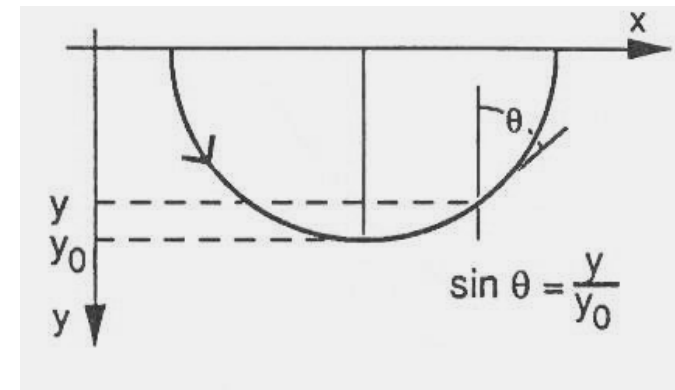
- In the limit:

$$\frac{1}{\sin \theta(y)} \frac{d \sin \theta}{dy} = \frac{1}{c(y)} \frac{dc}{dy}$$

- Solution:

$$\ln(\sin \theta) = \ln(c) + C_0$$

$$\sin \theta(y) = C_1 c(y)$$





# Linear variation of $c$ with depth

$$\sin \theta(y) = C_1 c(y)$$

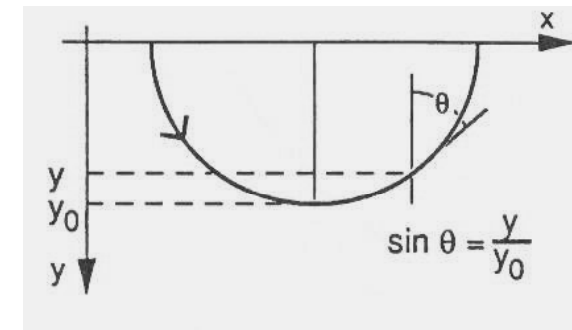
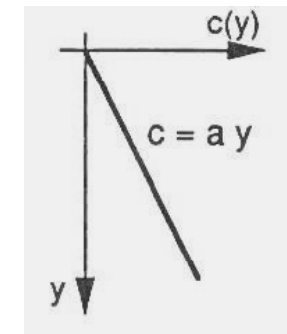
- Linear variation of  $c$  with depth. Find  $\theta(y)$  when wave is horizontal at depth  $y_0$

- Linear variation:  $c(y)=ay$
- Boundary condition:  $\sin\theta(y_0)=1 \Rightarrow C_1=1/ay_0$

- Solution:

$$\sin \theta = C_1 c(y) = ay/ay_0 = y/y_0$$

- A circle with radius  $y_0$

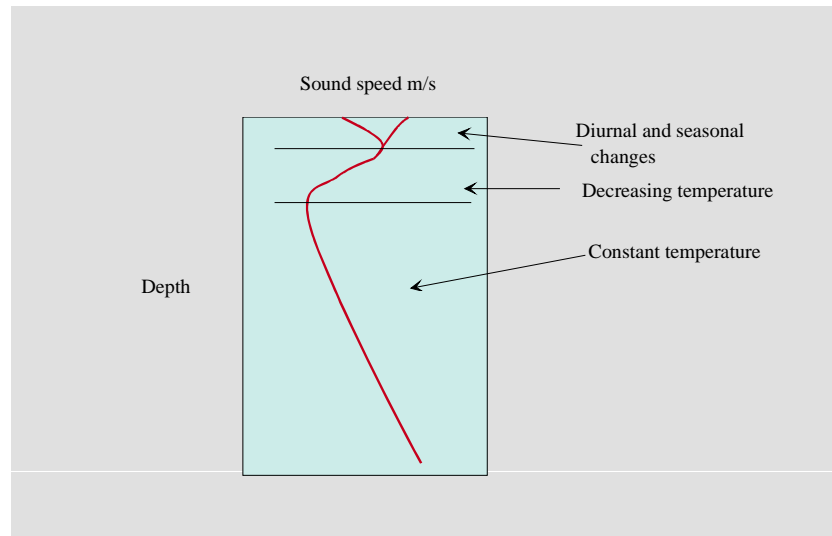






# Underwater acoustics: Sound speed profiles

$$c = 1448.6 + 4.618T - 0.0523T^2 + 1.25(S - 35) + 0.017D \quad .$$



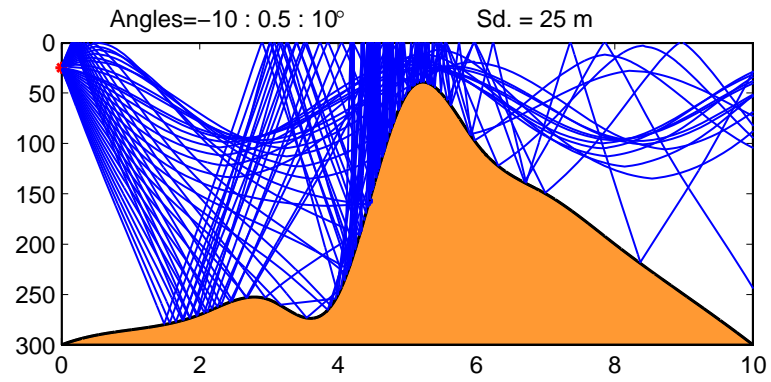
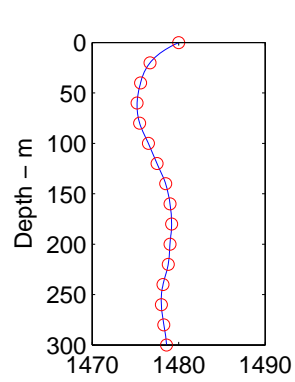
Empirical law:

- $c$  = velocity of sound (m/s),
- $T$  = temperature (°C),
- $S$  = salinity (per thousand, promille),
- $D$  = depth (m).

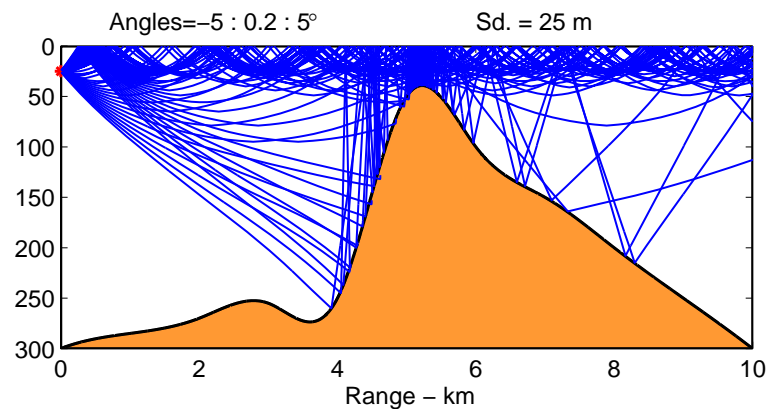
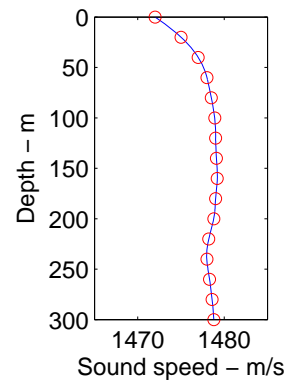
Fra: J Hovem, TTT4175  
Marin akustikk, NTNU



# Sound propagation: underwater peak



Summer



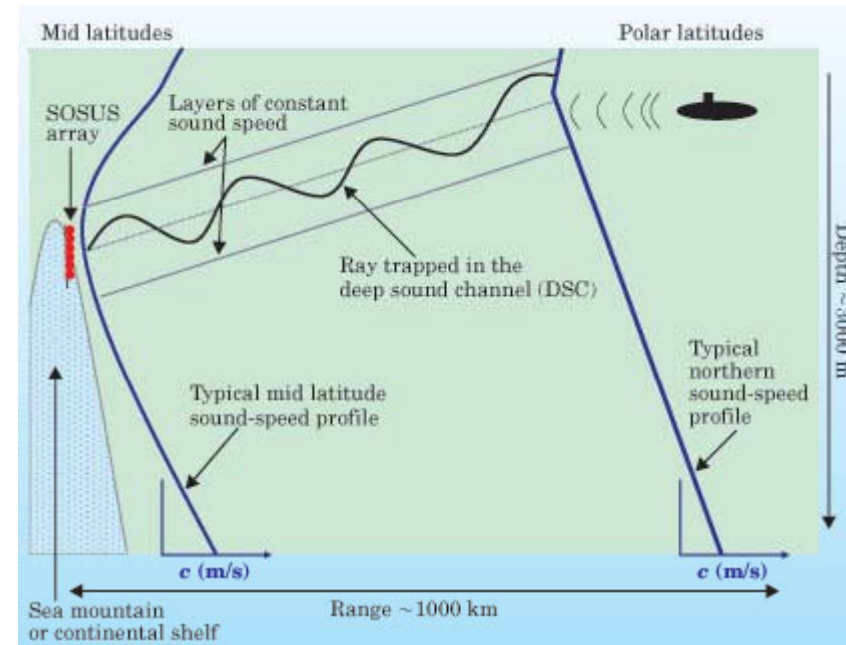
Winter

From: J Hovem, TTT4175  
Marin akustikk, NTNU



# Deep sound channel

- $c$  decreases as the water cools but increases with depth.
- Deep sound channel (DSC)
- From the cold surface at the poles to  $\sim 1300$  m at the equator
- Sound can propagate thousands of kilometers
- 1950s: US Navy SOSUS (Sound Ocean Surveillance System) network to monitor Soviet submarines.
- Kuperman and Lynch, "Shallow-water acoustics", Physics Today, 2004



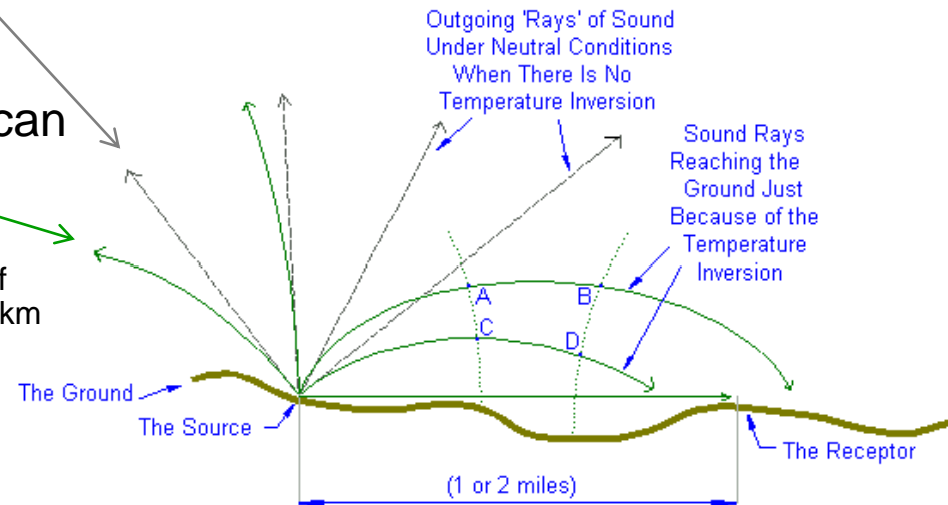


# Bending of sound in air

- $c \approx 331.4 + 0.6 \cdot T$   
around room temperature
- Ex:  $T=20\text{ C} \Rightarrow c=343,4\text{ m/s}$
- Usually  $T$  falls with height
  - Sound is bent out into space.
- Inversion: opposite  $\Rightarrow$  Sound can be heard over much longer distances
  - Elephants at sunrise and dawn: range of infrasound increases from 1-2 km to 10 km
  - Inversion layer also makes polluted air visible



<http://www.aftenposten.no/nyheter/iriks/article4223421.ece>





# Sound refraction in wind

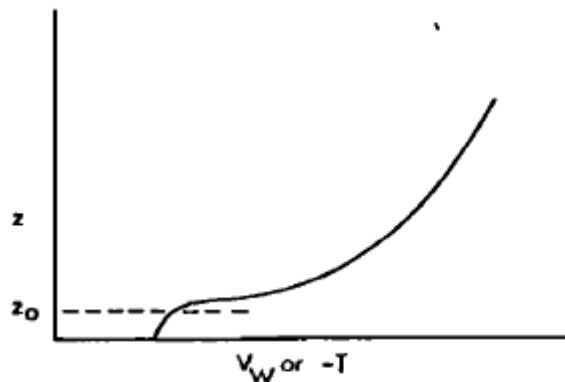


FIG. 12. Variation of wind velocity and temperature in the vicinity of a flat ground surface ( $z < \sim 10$  m).

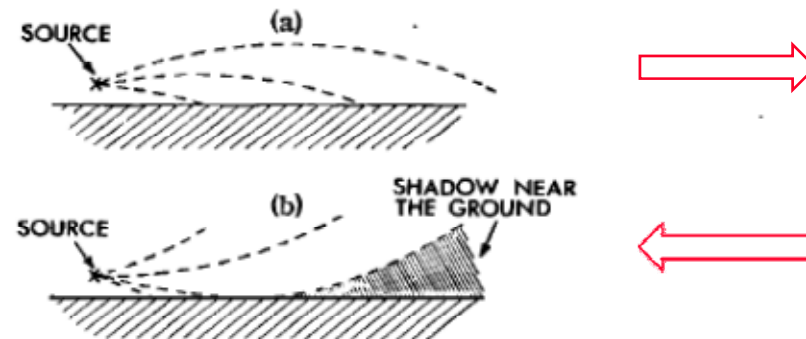
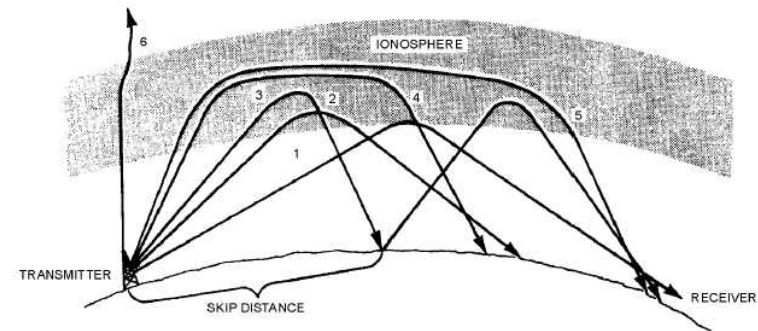
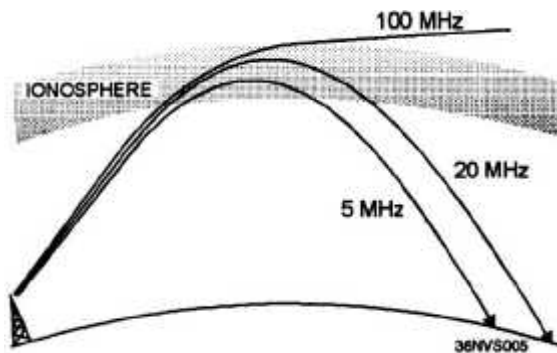


FIG. 14. (a) Refraction downward—inversion or downwind propagation. (b) Refraction upwards—lapse or upwind propagation.

- Effective  $c = c_0 + v_{\text{wind}}(z)$ 
  - Downwind, tailwind (medvind): higher  $c$  for higher height,  $z$ : refraction towards ground: louder traffic noise from highway (like inversion)
  - Upwind, headwind (motvind): lower  $c$  for higher height,  $z$ : refraction away from ground: weaker noise
  - Piercy et al., Review of noise propagation in the atmosphere, JASA, 1977



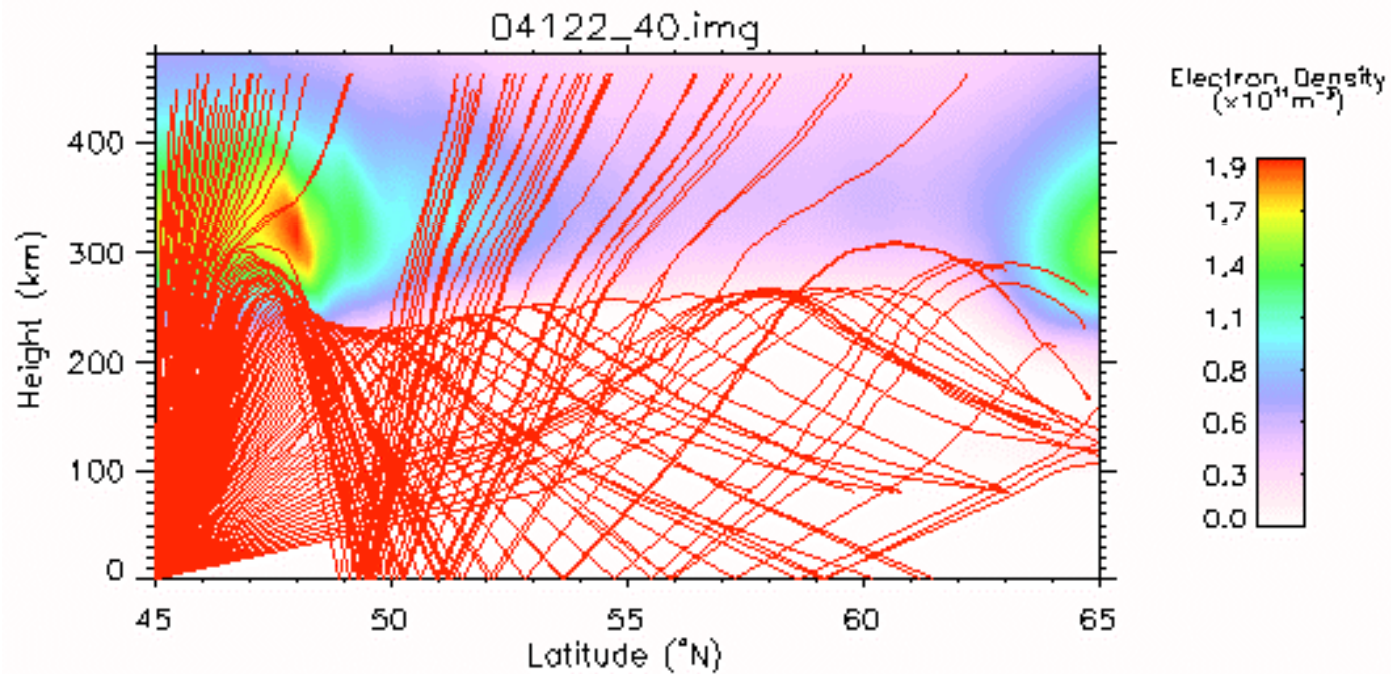
# Radio waves – bending in ionosphere



- Refraction and dispersion
- Index of refraction:  $n=c/v_p < 1$ , i.e.  $v_p > c$  ( $v_p \cdot v_g = c^2$ )



# Ray tracing - ionosphere



<http://www.cpar.qinetiq.com/raytrace.html>



## 2.4.2 Ray Theory

- Method for finding ray path based on geometry alone = high frequency approximation
- Read the details in the book if you need to understand better underwater acoustics or modeling of the ionosphere!





# Periodic media

250-mm-long steel cylinder rods  
lattice constant  $a=2.5\text{ mm}$   
radius of cylinders:  $R=1.0\text{ mm}$   
 $C_{\text{steel}}=6100\text{ m/s}$ ,  $c_{\text{air}}=334.5\text{ m/s}$   
 $f = 41.2\text{ to }48.0\text{ kHz}$

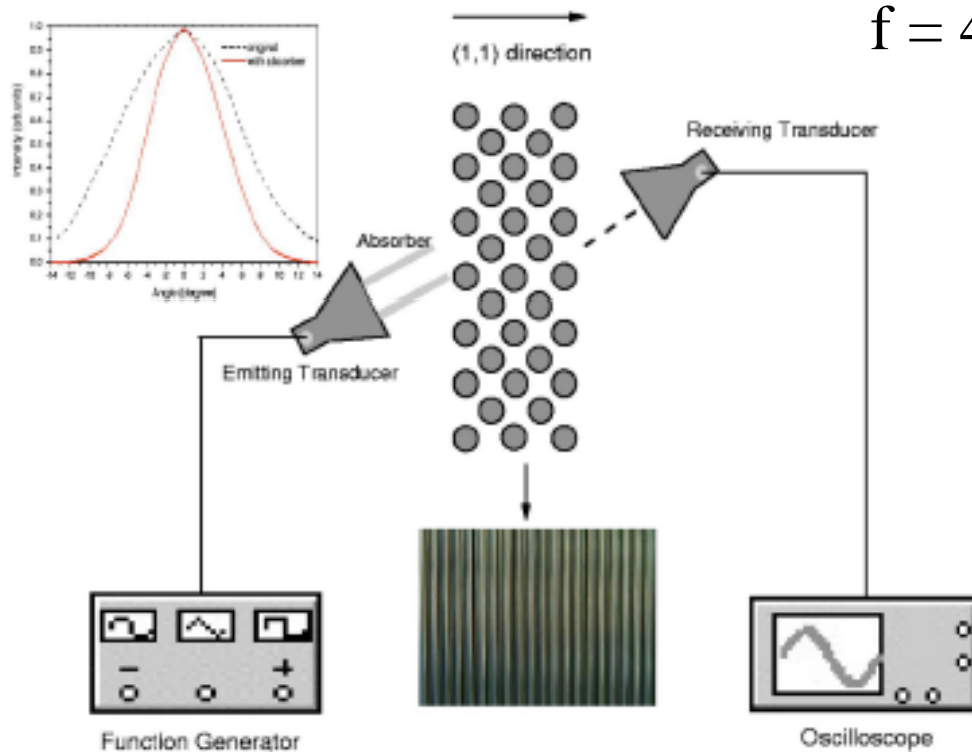
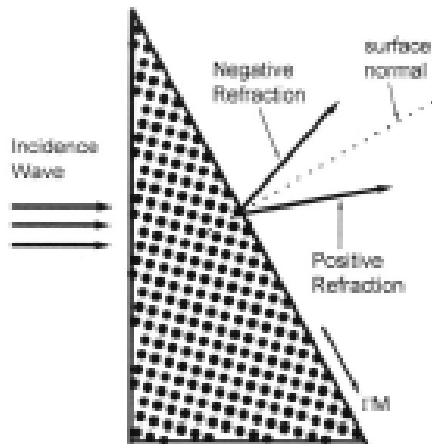


FIG. 2. (Color online) Schematic of the experimental setup used to measure the transmission of ultrasonic wave in a SC, consisting of two transducers, a flat rectangular slab of steel cylinders, a function generator, and an oscilloscope. The SC, the rectangular slab of steel cylinders shown as the middle-bottom inset, is placed between two transducers and the left-top inset shows measurements of the amplitude comparisons with the absorber (solid) to without the absorber (dashed).

Feng, Liu, Chen, Huang, Mao, Chen, Li, Zhu, Negative refraction of acoustic waves in two-dimensional **sonic crystals**, Physical Review B, 2005



# Periodic media



- Zhanga, Liu: Negative refraction of acoustic waves in two-dimensional **phononic crystals**, Applied Physics Letters, 2004.

- **Acoustic metamaterials** can manipulate sound waves in surprising ways, which include collimation, focusing, cloaking, sonic screening and extraordinary transmission.
- Recent theories suggested that imaging below the diffraction limit using passive elements can be realized by acoustic superlenses or magnifying hyperlenses. These could markedly enhance the capabilities in underwater sonar sensing, medical ultrasound imaging and non-destructive materials testing.
- Li et al, Experimental demonstration of an acoustic magnifying hyperlens, Nature 2009



# Array Processing Implications

- Spatial inhomogeneities must be taken into account by array processing algorithms
  - The essence of matched field processing
- Waves propagating in an inhomogeneous medium rarely travel in a straight line
  - Makes array processing/beamforming much harder
- Refraction can lead to multipath
  - Can be modeled as a low-pass filter, e.g. loss of high frequencies



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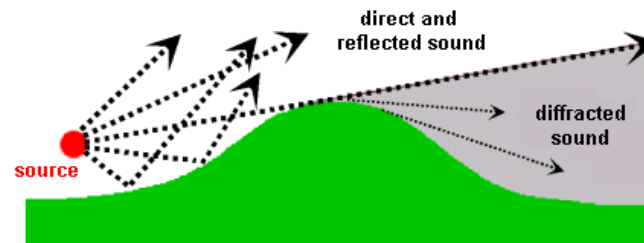
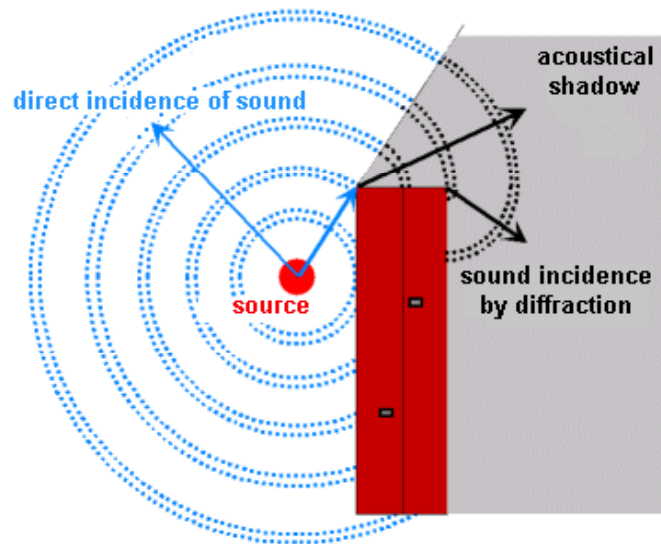


# Diffraction

- Ray theory: Geometrical model of optics
- High-frequency – small wavelength model
- Diffraction:
  - Wavelength comparable to structure size
  - Edges of shadows are not perfectly sharp
  - Can hear around corners
- In this course: mainly consequences of diffraction

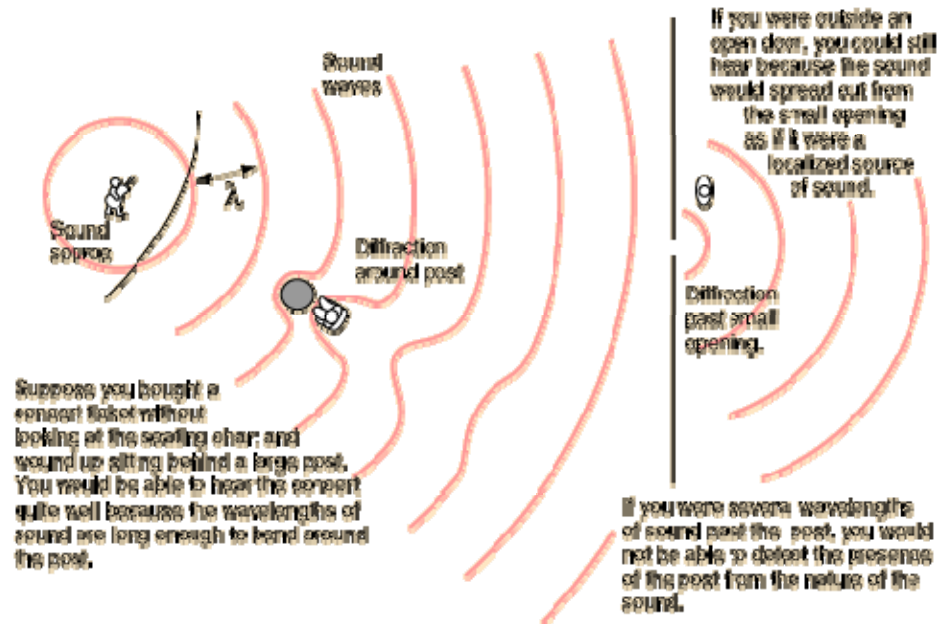


# Diffraction – (spredning)





# Diffraction

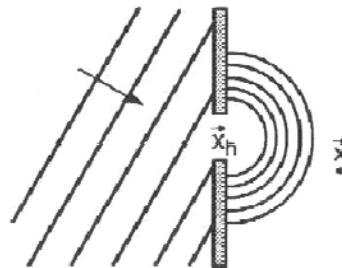


- Geometric acoustic is OK for dimensions  $> 1$  wavelength



# Huygens' principle

- Christian Huygens, NL, 1629-1695
- Each point on a travelling wavefront can be considered as a secondary source of spherical radiation
- Also a model for an oscillating piston = acoustic source



**Figure 2.13** A wave is shown impinging on a hole in a planar screen. The Rayleigh-Sommerfeld diffraction formula tells us what the wavefield at the point  $\vec{x}$  is in terms of the wavefield at the aperture.





## Mathematical formulation of diffraction

- Augustin Jean Fresnel (F) 1788 – 1827
- Gustav Robert Kirchhoff (D) 1824 – 1887
- Lord Rayleigh, John William Strutt (GB) 1842 – 1919, Nobel prize physics, 1904.
- Arnold Johannes Wilhelm Sommerfeld (D) 1868 – 1951
- Joseph von Fraunhofer (D) 1787 - 1826

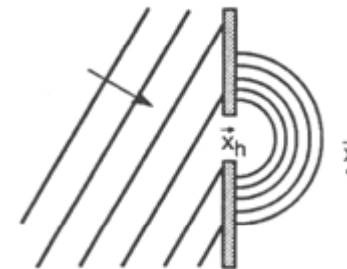


## Diffraction: deviation from geometrical model

- Rayleigh-Sommerfeld diffraction formula from a hole with aperture  $A$ :

$$s(\vec{x}) = \frac{1}{j\lambda} \int \int_A s(\vec{x}_h) \frac{\exp\{jkr\}}{r} \cos\theta dA$$

- Wave at  $x$  is a superposition of fields from the hole, due to linearity of wave equation
- Weighted by a spherical spreading function  $\exp\{jkr\}/r$
- Also weighted by  $1/\lambda$
- Obliquity factor  $\cos\theta$
- Phase shift of  $\pi/2$  due to  $1/j$



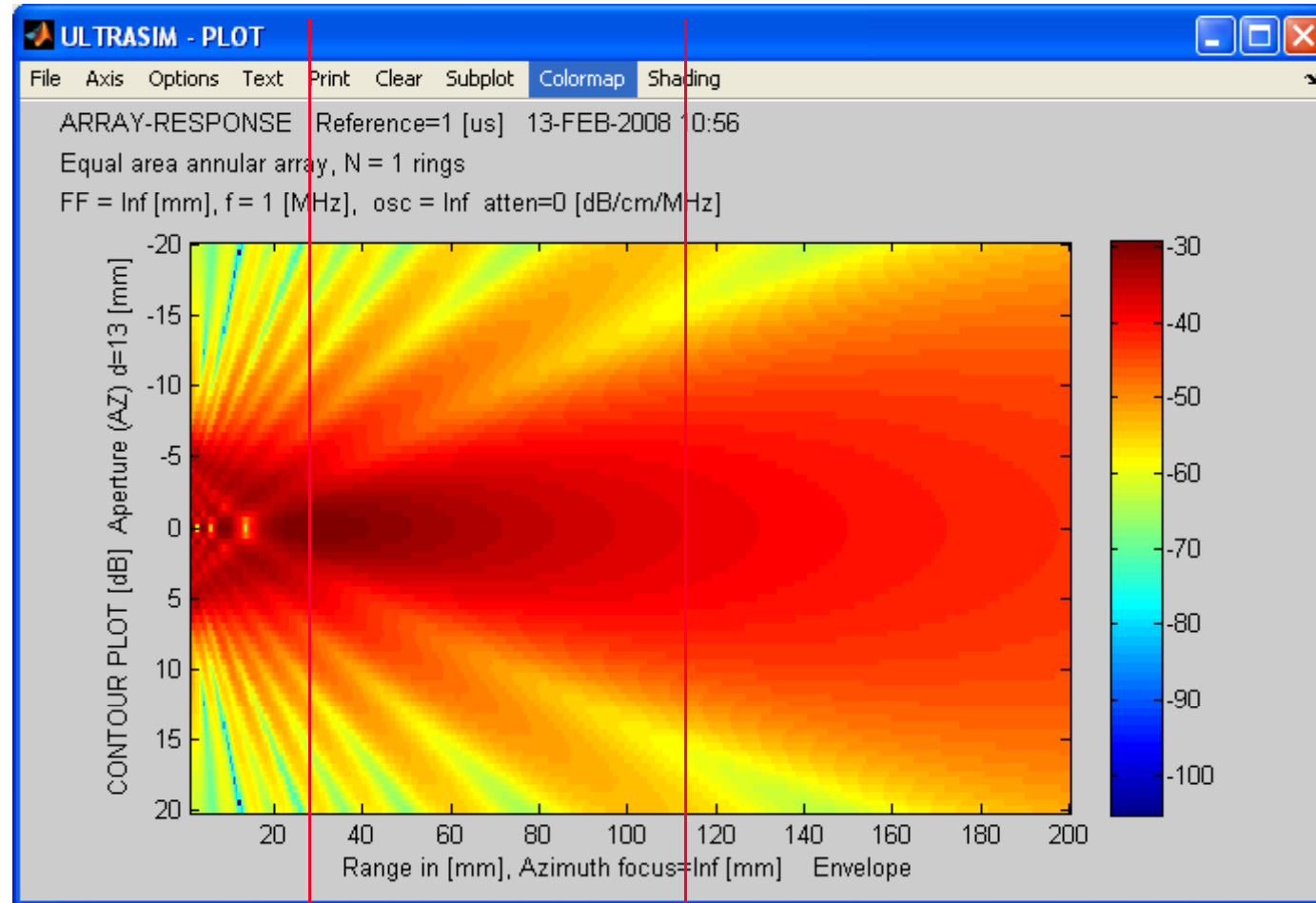


# Two approximations

- Fresnel, nearfield, (but not quite near)
- Fraunhofer, farfield
- Leads to
  - important estimates for nearfield – farfield transition distance
  - Fourier relationship between aperture excitation and field



# 1 MHz 13 mm, unfocused xdcr



$$D^2/4\lambda$$

$$D^2/\lambda=113 \text{ mm}$$



Olympus-Panametrics  
A303S  
(in our lab)

Simulation:

[http://www.ifi.uio.no/  
~ultrasim](http://www.ifi.uio.no/~ultrasim)



# Fresnel approximation

$$s(\vec{x}) = \frac{1}{j\lambda} \iint_A s(\vec{x}_h) \frac{\exp\{jkr\}}{r} \cos \theta dA$$

- $\cos \theta \approx 1$ ,  $r \approx d$  for amplitude
- Phase:
  - spherical surfaces  $\approx$  quadratic
  - parabolic approximation



# Fresnel derivation

- Point in the hole  $(\tilde{x}, \tilde{y}, 0)$ , in observation plane  $(\mathbf{x}, \mathbf{y}, \mathbf{z}=\mathbf{d})$

- Distance:  $r = [(x - \tilde{x})^2 + (y - \tilde{y})^2 + d^2]^{1/2}$

$$r = d \left[ 1 + \frac{(x - \tilde{x})^2 + (y - \tilde{y})^2}{d^2} \right]^{1/2}$$

- Approximate  $(1+x)^{1/2} \approx 1+x/2$ , i.e. small  $x/D \Leftrightarrow$  small angles

$$r \approx d + \frac{(x - \tilde{x})^2 + (y - \tilde{y})^2}{2d}$$

- Use the above expression for the phase and  $r \approx d$  for the amplitude in Rayleigh-Sommerfeld integral



# Fresnel approximation

$$s(x, y) = \frac{\exp\{jkd\}}{j\lambda d} \iint_A s(\tilde{x}, \tilde{y}) \exp\left\{\frac{jk[(x - \tilde{x})^2 + (y - \tilde{y})^2]}{2d}\right\} d\tilde{x}d\tilde{y}$$

- Nearfield approximation & within  $\approx 15^\circ$  of z-axis
- Also called paraxial approximation
- 2D convolution between field in hole and  $h(x,y)$ :

$$h(x, y) = \frac{\exp\{jkd\}}{j\lambda d} \exp\left\{\frac{jk(x^2 + y^2)}{2d}\right\}$$

- This is a quadratic phase function = the phase shift that a secondary wave encounters during propagation



# Fraunhofer approximation

- Expand phase term of Fresnel approximation

$$s(x, y) = \frac{\exp\{jkd\}}{j\lambda d} \int \int_A s(\tilde{x}, \tilde{y}) \exp\left\{\frac{jk[(x - \tilde{x})^2 + (y - \tilde{y})^2]}{2d}\right\} d\tilde{x}d\tilde{y}$$

- and neglect quadratic phase term variation over hole

$$(x - \tilde{x})^2 + (y - \tilde{y})^2 = x^2 + y^2 - 2x\tilde{x} - 2y\tilde{y} + \tilde{x}^2 + \tilde{y}^2 \approx x^2 + y^2 - 2x\tilde{x} - 2y\tilde{y}$$

- If  $D = \max$  linear dimension of hole, this is equivalent to assuming ( $d = \text{dist. from source}$ ):

$$\frac{\tilde{x}^2}{2d} \leq \frac{(D/2)^2}{2d} \ll \lambda/2 \Rightarrow d \gg \frac{D^2}{4\lambda} \quad \leftarrow \text{Fresnel limit}$$





# Fraunhofer approximation

$$s(x, y) = \frac{\exp\{jkd\}}{j\lambda d} \exp\left\{\frac{jk(x^2 + y^2)}{2d}\right\} \iint_A s(\tilde{x}, \tilde{y}) \exp\left\{\frac{jk(x\tilde{x} + y\tilde{y})}{d}\right\} d\tilde{x}d\tilde{y}$$

- Far-field approximation: valid far away from hole
- $s(x,y)$  = 2D Fourier transform of field in hole



# Fourier transform relationship

- Very important result
- *Link* between the physics and the signal processing!
- Basis for simplified expressions like angular resolution  $\approx \lambda/D$  etc
- Small hole leads to wide beam and vice versa just like a short time-function has a wide spectrum



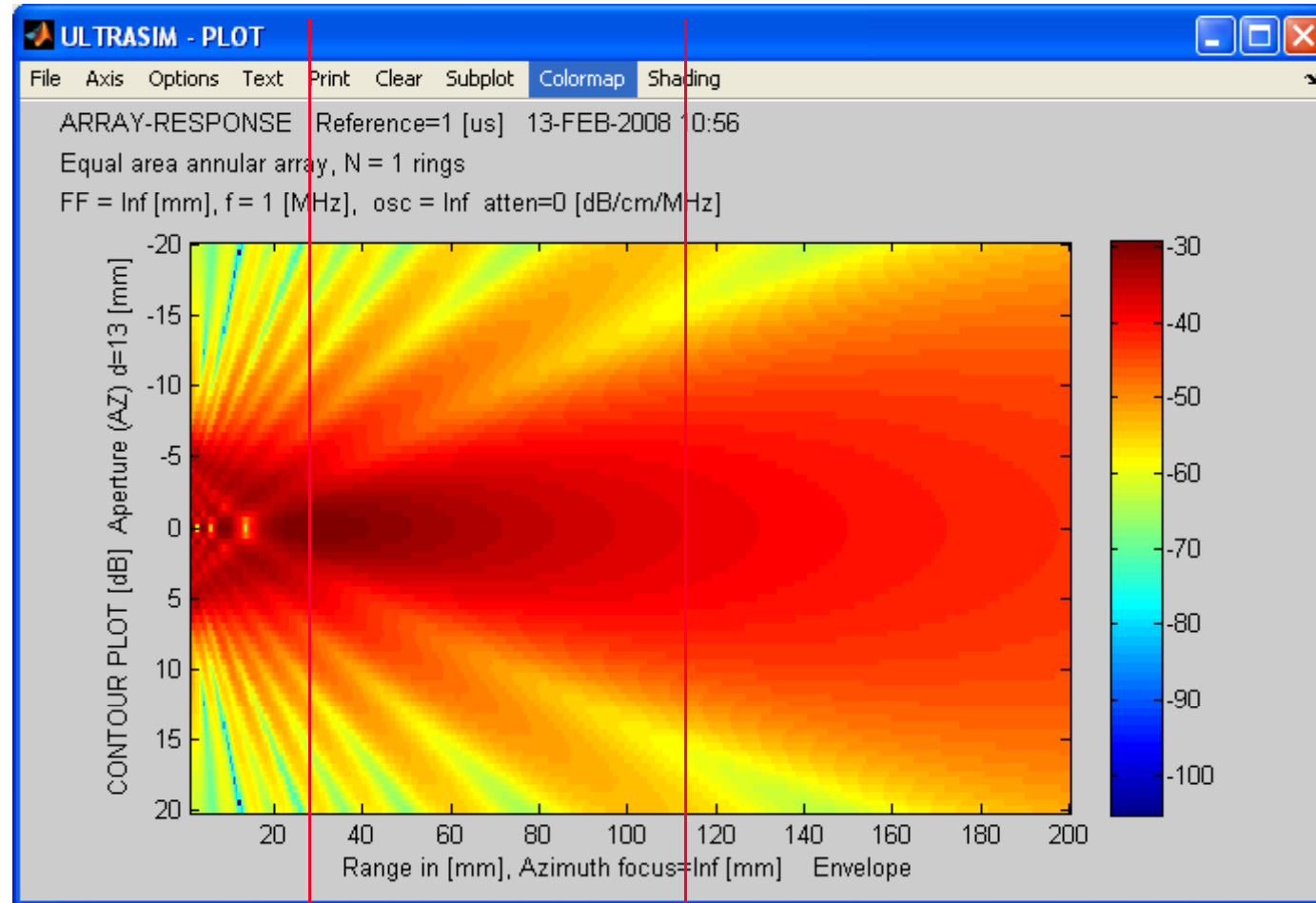
# Nearfield-farfield limit

Not a clear transition, several limits are used, in increasing size:

- $d_F = D^2/4\lambda$  : Fresnel limit
- $d = \pi r^2/\lambda = \pi/4 \cdot D^2/\lambda$  : Diffraction limit
- $d = D^2/\lambda$  : max path length difference  $\lambda/8$
- $d_R = 2D^2/\lambda$  : Rayleigh dist:  $\Delta \text{ path} = \lambda/16$
  
- Proportional to  $D^2/\lambda$ , multiplied by 0.25, 0.79, 1, or 2



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$$D^2/4\lambda$$

$$D^2/\lambda=113 \text{ mm}$$



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# Array Processing Implications

- Diffraction means that opaque objects located between the source and the array can induce complicated wavefields
  - Scattering theory:
    - » Acoustics: Schools of fish
    - » Electromagnetics: rain drops
    - » Complicated, but important to understand



# Norsk terminologi

- Bølgeligningen
- Planbølger, sfæriske bølger
- Propagerende bølger, bølgetall
- Sinking/sakking:  $\vec{\alpha}$
- Dispersjon
- Attenuasjon eller demping
- Refraksjon
- Ikke-linearitet
- Diffraksjon; nærfelt, fjernfelt
- Gruppeantenne (= array)

Kilde: Bl.a. J. M. Hovem: ``Marin akustikk'', NTNU, 1999