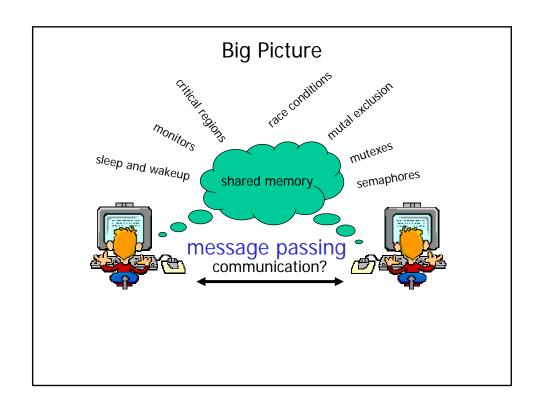
Inter-Process Communication: Message Passing

Thomas Plagemann

With slides from Pål Halvorsen, Kai Li, and Andrew S. Tanenbaum



Message Passing API

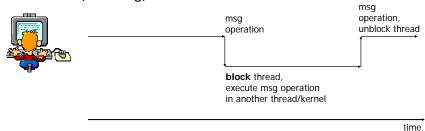
- Generic API
 - send(dest, &msg)
 recv(src, &msg)
- What should the "dest" and "src" be?
 - pid
 - file: e.g. a (named) pipe
 - port: network address, pid, etc
 - no src: receive any message
 - src combines both specific and any
- What should "msg" be?
 - Need both buffer and size for a variable sized message

Issues

- Asynchronous vs. synchronous
- Direct vs. indirect
- · How are links established?
- Can a link be associated with more than two processes?
- How many links can there be between any pair?
- What is the capacity of a link?
- What is the size of a message?
- · Is a link unidirectional or bidirectional?

Asynchronous vs. Synchronous

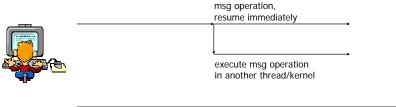
• Synchronous (blocking):



- thread is blocked until message primitive has been performed
- may be blocked for a very long time

Asynchronous vs. Synchronous

• Asynchronous (non-blocking):



time

- thread gets control back immediately
- thread can run in parallel other activities
- thread cannot reuse buffer for message before message is received
- how to know when to start if blocked on full/empty buffer?
 - poll
 - · interrupts/signals
 - ..

Asynchronous vs. Synchronous

- Send semantic:
 - Synchronous
 - Will not return until data is out of its source memory
 - · Block on full buffer
 - Asynchronous
 - Return as soon as initiating its hardware
 - Completion
 - Require application to check status
 - Notify or signal the application
 - · Block on full buffer

- Receive semantic:
 - Synchronous
 - Return data if there is a message
 - · Block on empty buffer

- Asynchronous

- Return data if there is a message
- Return null if there is no message

Buffering

- No buffering
 - synchronous
 - Sender must wait until the receiver receives the message
 - Rendezvous on each message
- Buffering
 - asynchronous or synchronous
 - Bounded buffer
 - Finite size
 - · Sender blocks when the buffer is full
 - · Use mesa-monitor to solve the problem?
 - Unbounded buffer
 - "Infinite" size
 - · Sender never blocks

Direct Communication





- Must explicitly name the sender/receiver ("dest" and "src") processes
- A buffer at the receiver
 - More than one process may send messages to the receiver
 - To receive from a specific sender, it requires searching through the whole buffer
- · A buffer at each sender
 - A sender may send messages to multiple receivers

Message Passing: Producer-Consumers Problem

```
void consumer(void)
{
   while (TRUE) {
      recv( producer, item );
      ...
      consume item;
      ...
   }
}
```

Message Passing: Producer-Consumers Problem with N messages

```
#define N 100
                                          /* number of slots in the buffer */
void producer(void)
     int item:
    message m;
                                          /* message buffer */
    while (TRUE) {
         item = produce_item();
                                          /* generate something to put in buffer */
         receive(consumer, &m);
                                          /* wait for an empty to arrive */
         build_message(&m, item);
                                          /* construct a message to send */
         send(consumer, &m);
                                          /* send item to consumer */
}
void consumer(void)
     int item, i;
    message m;
    for (i = 0; i < N; i++) send(producer, &m); /* send N empties */
    while (TRUE) {
         receive(producer, &m);
                                          /* get message containing item */
         item = extract_item(&m);
                                          /* extract item from message */
         send(producer, &m);
                                          /* send back empty reply */
         consume_item(item);
                                          /* do something with the item */
```

Indirect Communication



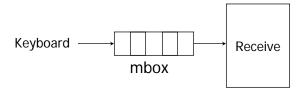




- "dest" and "src" are a shared (unique) mailbox
- Use a mailbox to allow many-to-many communication
 - Requires open/close a mailbox before using it
- Where should the buffer be?
 - A buffer and its mutex and conditions should be at the mailbox

Using Message-Passing

- · What is message-passing for?
 - Communication across address spaces
 - Communication across protection domains
 - Synchronization
- Use a mailbox to communicate between a process/thread and an interrupt handler: fake a sender



Process Termination

- P waits for a message from Q, but Q has terminated
 - Problem: P may be blocked forever
 - Solution:
 - · P checks once a while
 - · Catch the exception and informs P
 - · Send ack message
- P sends a message to Q, but Q has terminated
 - Problem: P has no buffer and will be blocked forever
 - Solution:
 - · Check Q's state and cleanup
 - · Catch the exception and informs P

Message Loss & Corruption

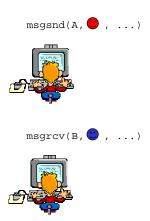
- Unreliable service
 - best effort, up to the user to
- Detection
 - Acknowledge each message sent
 - Timeout on the sender side
- Retransmission
 - Sequence number for each message
 - Retransmit a message on timeout
 - Retransmit a message on out-of-sequence acknowledgement
 - Remove duplication messages on the receiver side

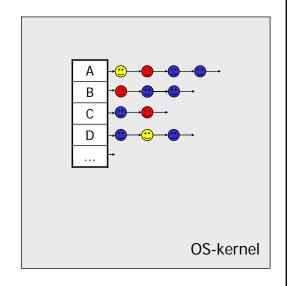
Linux Mailboxes

- Messages are stored as a sequence of bytes
- · System V IPC messages also have a type
- Mailboxes are implemented as message queues sorting messages according to FIFO
- Can be both blocking and non-blocking (IPC_NOWAIT)
- The next slides have some simplified (pseudo) code
 - Linux 2.4.18
 - several parts missing
 - the shown code may block holding the queue lock
 - waiting queues are more complex
 - ...

Linux Mailboxes

• Example:





Linux Mailboxes

• One msq_queue structure for each present queue:

```
struct msg_queue {
        struct kern_ipc_perm q_perm;
                                          /* access permissions */
                                          /* last msgsnd time */
        time_t q_stime;
                                         /* last msgrcv time */
/* last change time */
        time_t q_rtime;
        time_t q_ctime;
        unsigned long q_cbytes;
                                        /* current number of bytes on queue */
        unsigned long q_qnum;
                                         /* number of messages in queue */
        unsigned long q_qbytes;
                                          /* max number of bytes on queue */
                                          /* pid of last msgsnd */
/* last receive pid */
        pid_t q_lspid;
        pid_t q_lrpid;
        struct list_head q_messages;
        struct list_head q_receivers;
        struct list_head q_senders;
};
```

Messages are stored in the kernel using the msg_msg structure:

NOTE: the message is stored immediately after this structure - no pointer is necessary

Linux Mailboxes

• Create a message queue using the sys_msgget system call:

```
long sys_msgget (key_t key, int msgflg)
{
    ...
    create new message queue and set access permissions
    ...
}
```

• To manipulate a queue, one uses the sys_msgctl system call:

```
long sys_msgctl (int msqid, int cmd, struct msqid_ds *buf)
{
    ...
    switch (cmd) {
        case IPC_INFO:
            return info about the queue, e.g., length, etc.
        case IPC_SET:
            modify info about the queue, e.g., length, etc.
        case IPC_RMID:
            remove the queue
    }
    ...
}
```

Linux Mailboxes

• Send a message to the queue using the sys_msgsnd system call:

```
long sys_msgsnd (int msqid, struct msgbuf *msgp, size_t msgsz, int msgflg)
{
    msq = msg_lock(msqid);
    ...
    if ((msgsz + msq->q_cbytes) > msq->q_qbytes)
        insert message the tall of msq->q_messages *msgp, update msq
    else
        put sender in waiting senders queue (msq->q_senders)
    msg_unlock(msqid);
    ...
}
```

Linux Mailboxes

• Receive a message from the queue using the sys_msgrcv system call:

- the msgtyp parameter and msgflg flag determine which messages to retrieve:
 - = 0: return first message
 - > 0: first message in queue with msg_msg.m_type = msgtyp
 - > 0 & ${\tt MSG_EXCEPT}$: first message in queue with ${\tt msg_msg.m_type}$!= ${\tt msgtyp}$

Our Mailbox

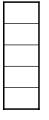
- · We make it simpler than Linux
 - Deliver messages in FIFO order
- Mailbox ⇒ buffer space
 - Finite space
- Main purpose:
 - Send
 - Receive
- · Maintenance:
 - Init
 - Open
 - Close
 - Statistics

Linux Pipes

- · Classic IPC method under UNIX:
 - > 1s -1 | more
 - shell runs two processes 1s and more which are linked via a pipe
 - the first process (ls) writes data (e.g., using write) to the pipe and the second (more) reads data (e.g., using read) from the pipe
- the system call pipe(fd[2]) creates one file descriptor for reading (fd[0]) and one for writing (fd[1])
 - allocates a temporary inode and a memory page to hold data

```
struct pipe_inode_info {
   wait_queue_head_t wait;
   char *base;
   unsigned int len;
   unsigned int start;
   unsigned int raders, writers;
   unsigned int waiting_readers, waiting_writers;
   unsigned int r_counter, w_counter;
}
```







Linux: Mailboxes vs. Pipes

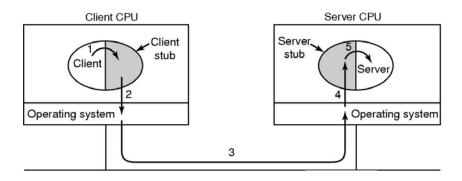
- · Are there any differences between a mailbox and a pipe?
 - Message types
 - · mailboxes may have messages of different types
 - · pipes do not have different types
 - Buffer
 - pipes one or more pages storing messages contiguously
 - mailboxes linked list of messages of different types
 - Termination
 - pipes exists only as long as some have open the file descriptors
 - · mailboxes must often be closed
 - More than two processes
 - a pipe often (not in Linux) implies one sender and one receiver
 - many can use a mailbox

Performance

- Performance is an important issue (at least when sender and receiver is on one machine), e.g.:
 - shared memory and using semaphores
 - mailboxes copying data from source to mailbox and from mailbox to receiver
- Can one somehow optimize the message passing?

Remote Procedure Call

- Message passing uses I/O
- Idea of RPC is to make function calls
- Small libraries (stubs) and OS take care of communication



Remote Procedure Call

Implementation Issues:

- Cannot pass pointers call by reference becomes copy-restore
- Marshaling packing parameters
- Weakly typed languages client stub cannot determine size
- Not always possible to determine parameter types
- Cannot use global variables may get moved to remote machine/protection domain

Summary

- Many ways to perform IPC on a machine
- Direct message passing or message passing using mailboxes

• Next: INF[34]160