

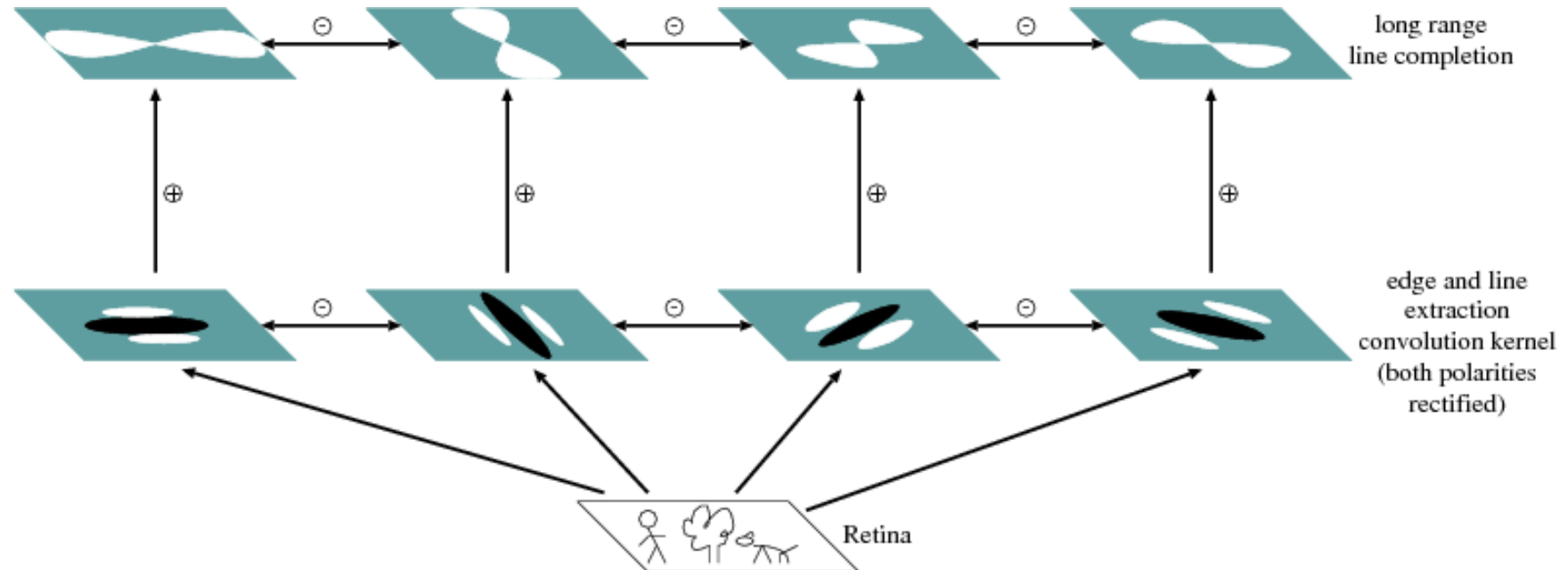


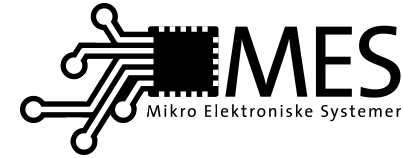
Neuromorphic Electronics

An Example of a Neuromorphic System

The CAVIAR demonstrator: the biggest AER system ever assembled

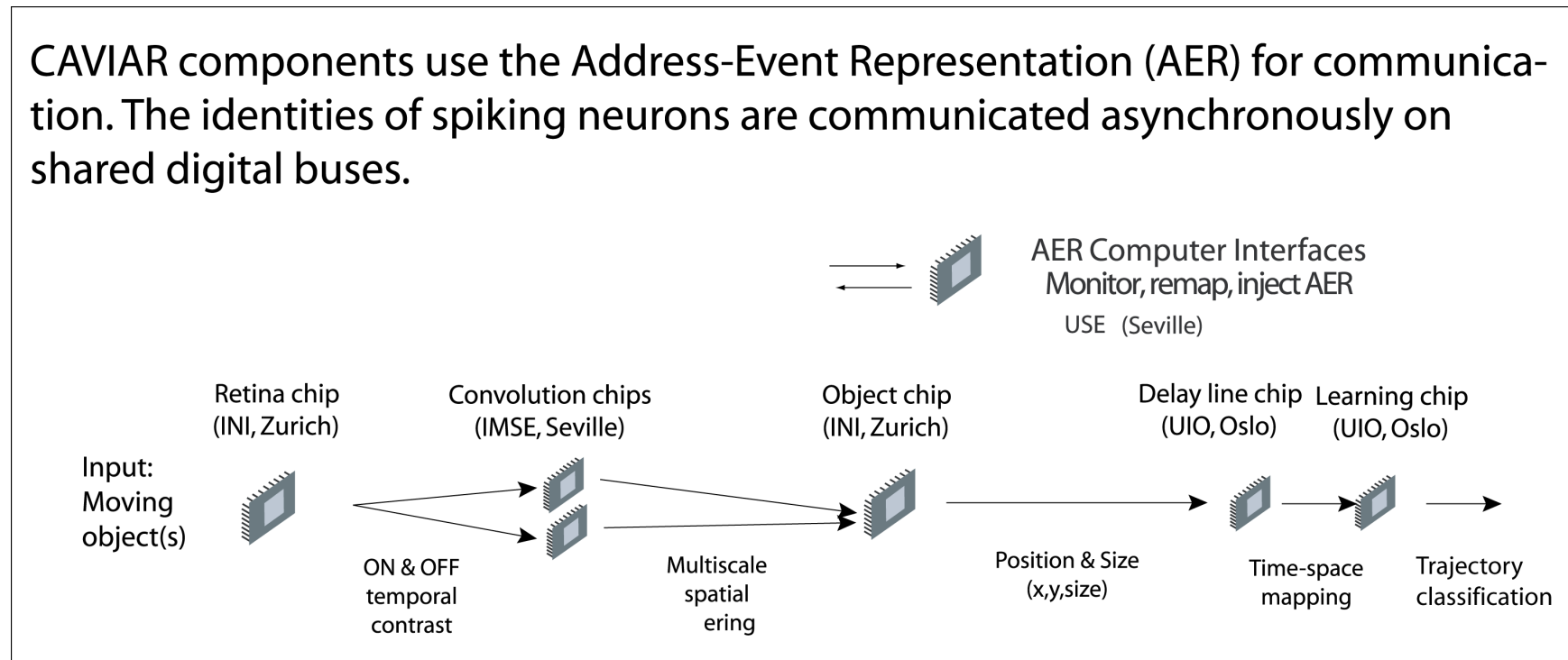
Inspiration: BCS (boundary contour system)



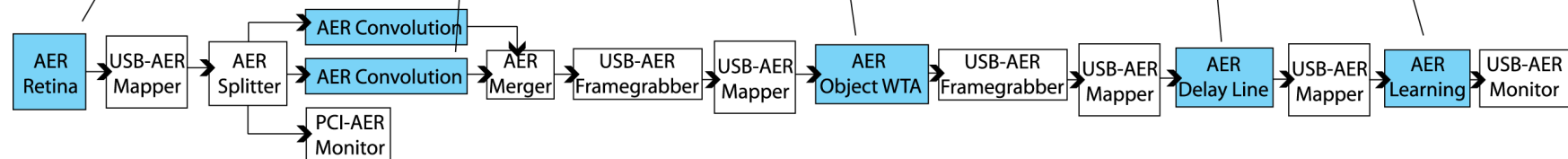
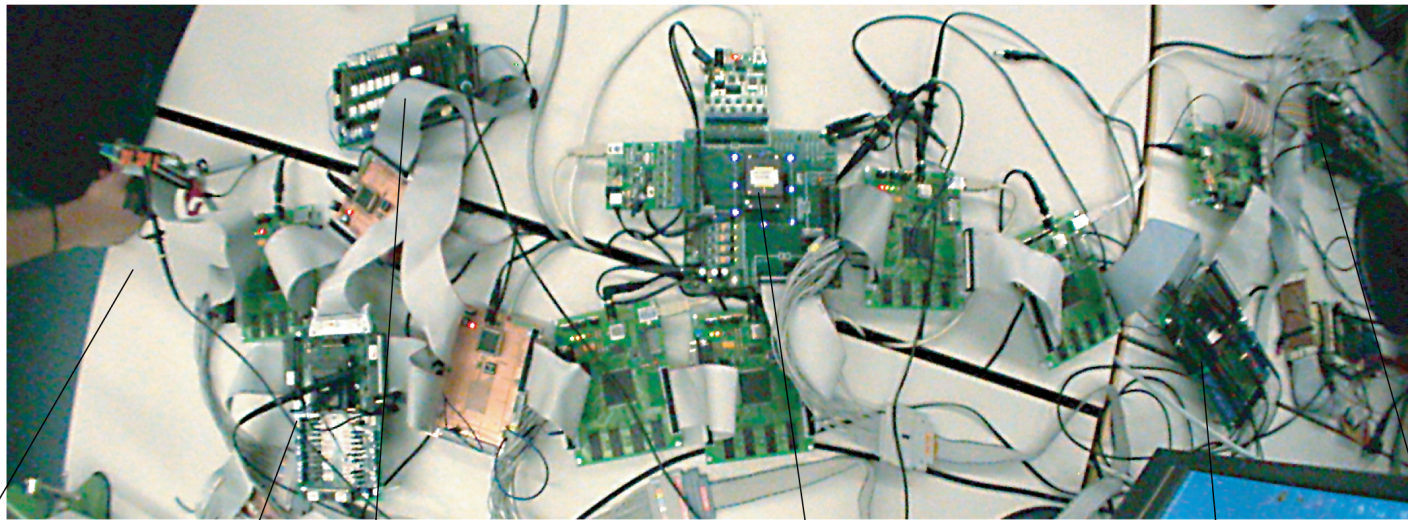


System Overview

CAVIAR components use the Address-Event Representation (AER) for communication. The identities of spiking neurons are communicated asynchronously on shared digital buses.

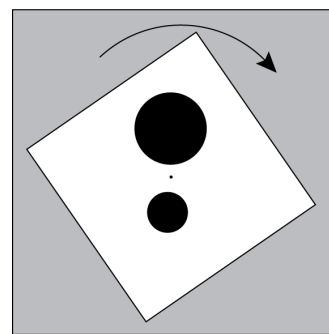


Physical System

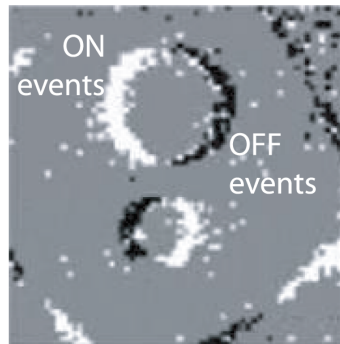




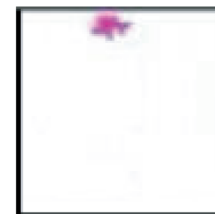
Retina, Convolution, and Object WTA Function



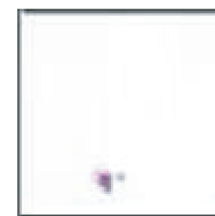
Input



Retina output

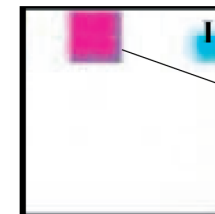


Large
scale

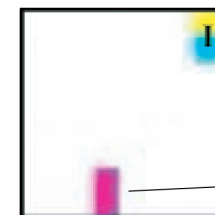


Small
scale

Convolution outputs



Large object



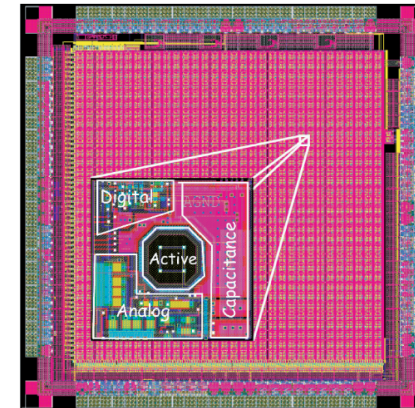
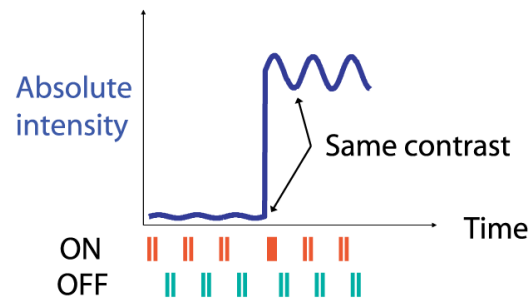
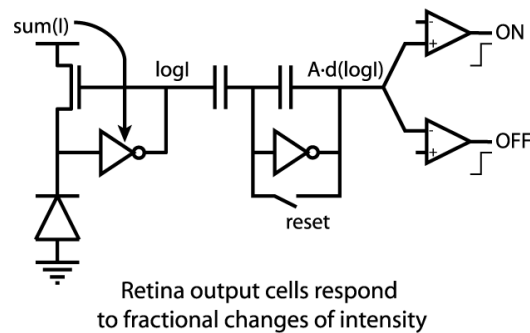
Winning scale



Small object

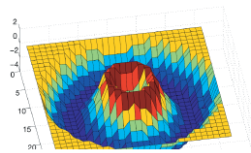
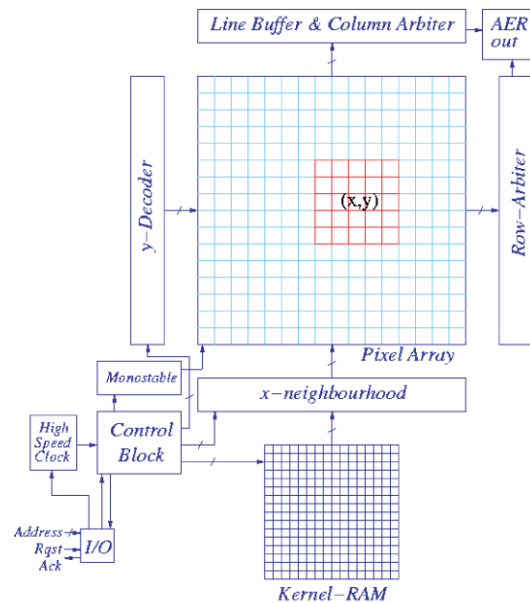
'Object' outputs

Diff Log Retina

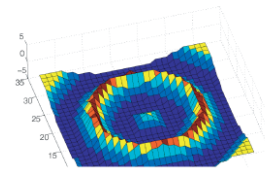


64x64
Pixel size $(40\mu)^2$, Fill factor 9%, Dark level, 1lux
1 Meps
2 mA chip, 20mA board

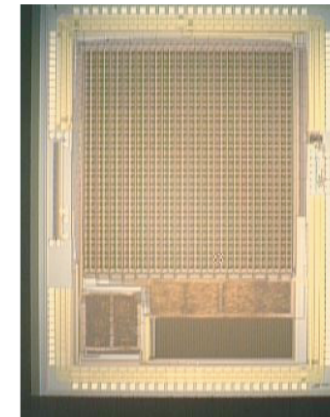
Convolution Chip



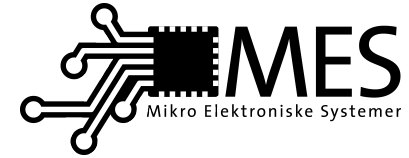
'small' kernal



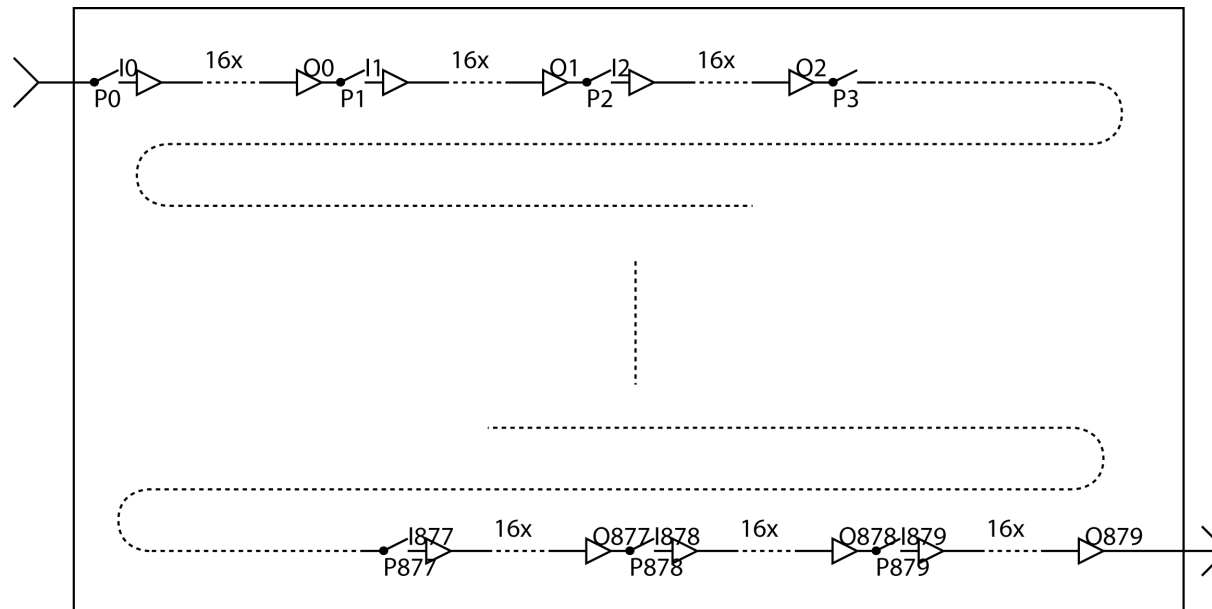
'large' kernal

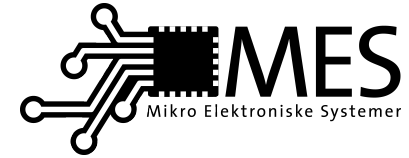


32x32
arbitrary kernal size with 3 bit weights
input 3-33 Meps, output 25Meps
"convolution throughput" $1-10^7$
20-45mA chip, +20mA board

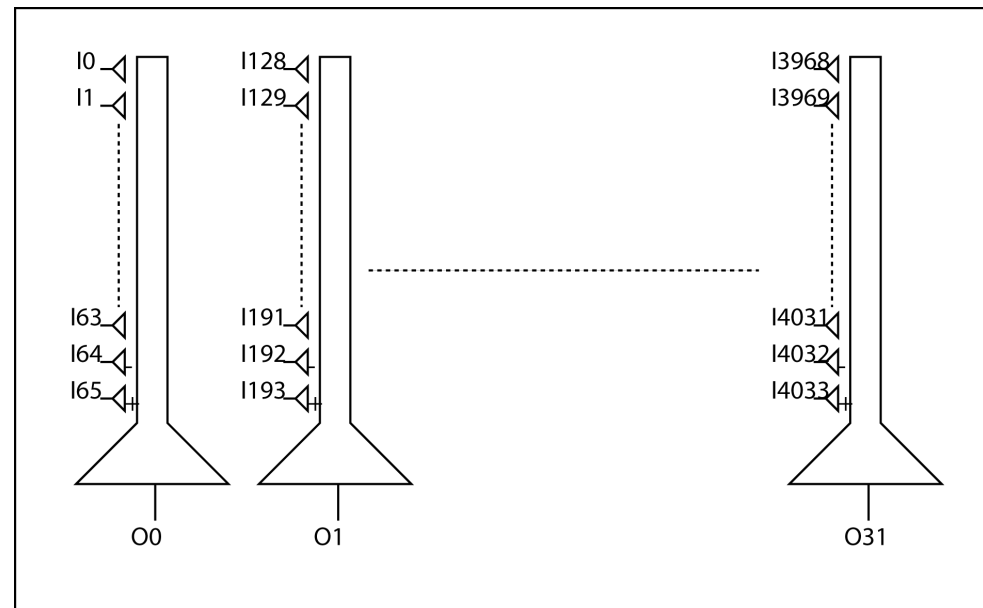


Spatio Temporal Classification (1/2)



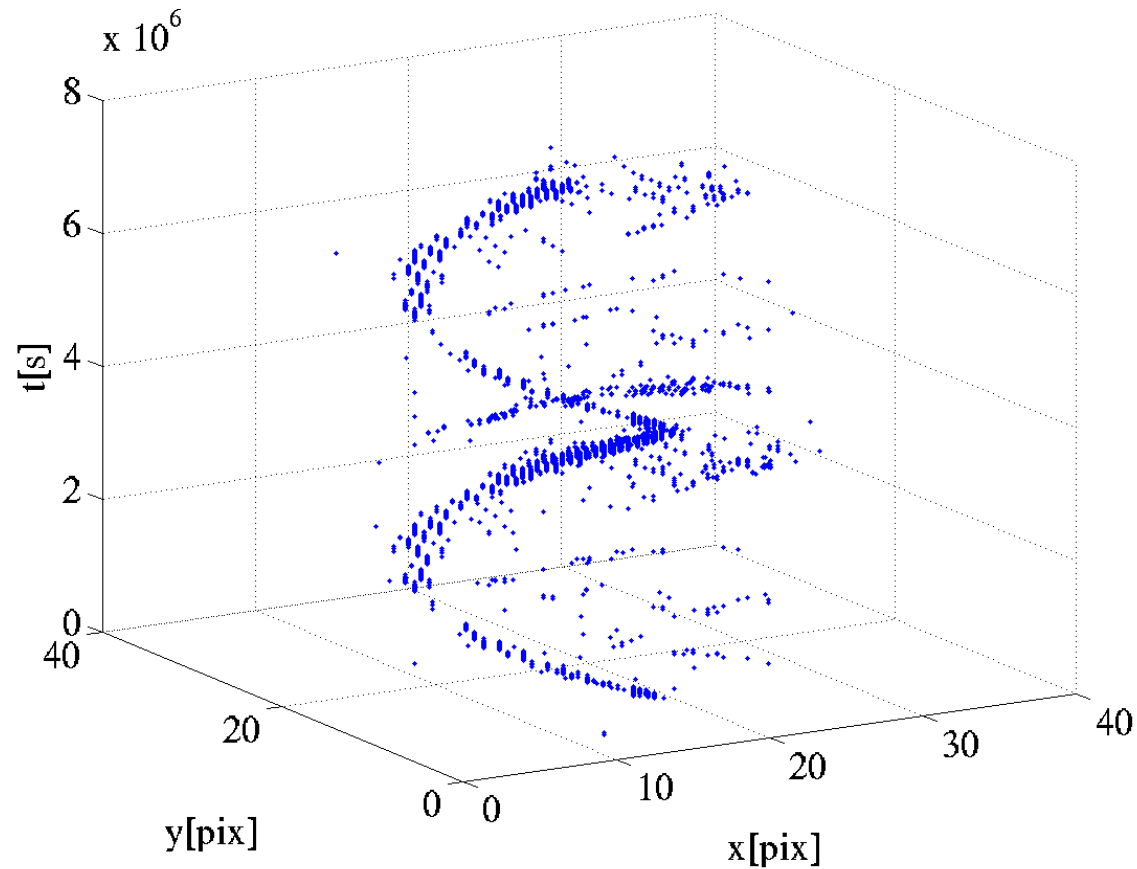


Spatio Temporal Classification (2/2)





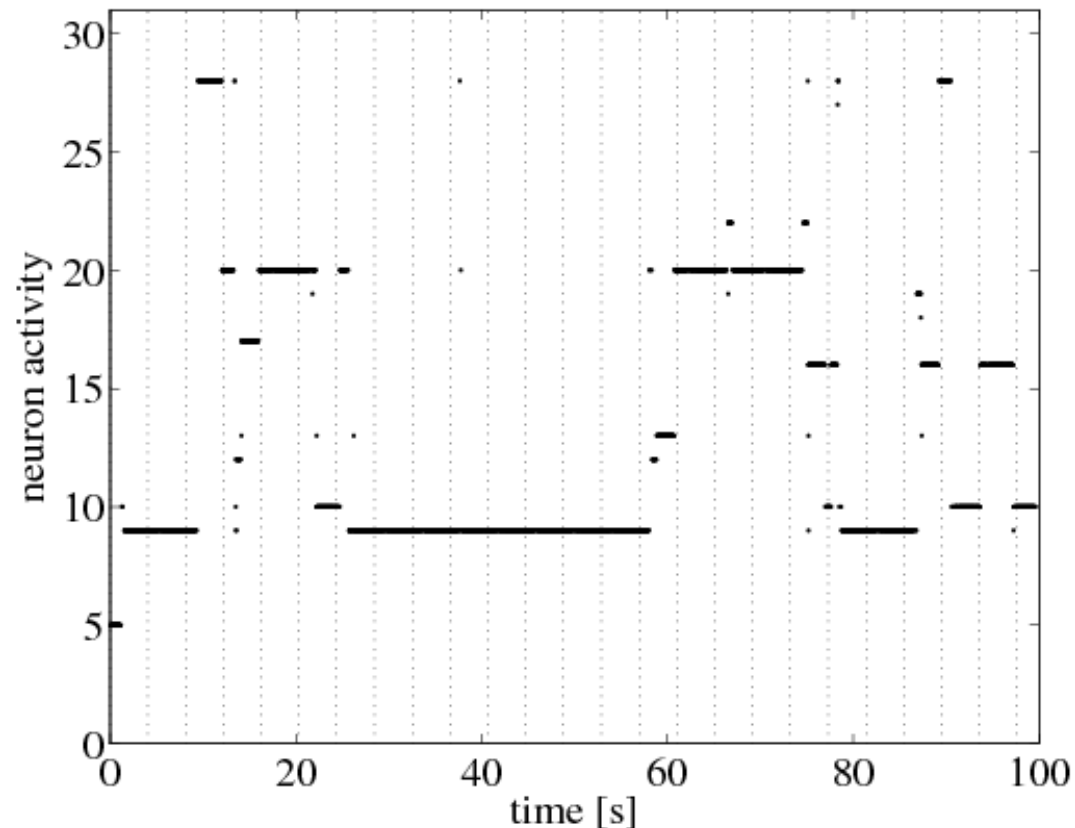
Expanding Time into Space





Classification of Phases in a Cyclic Motion Pattern (1/3)

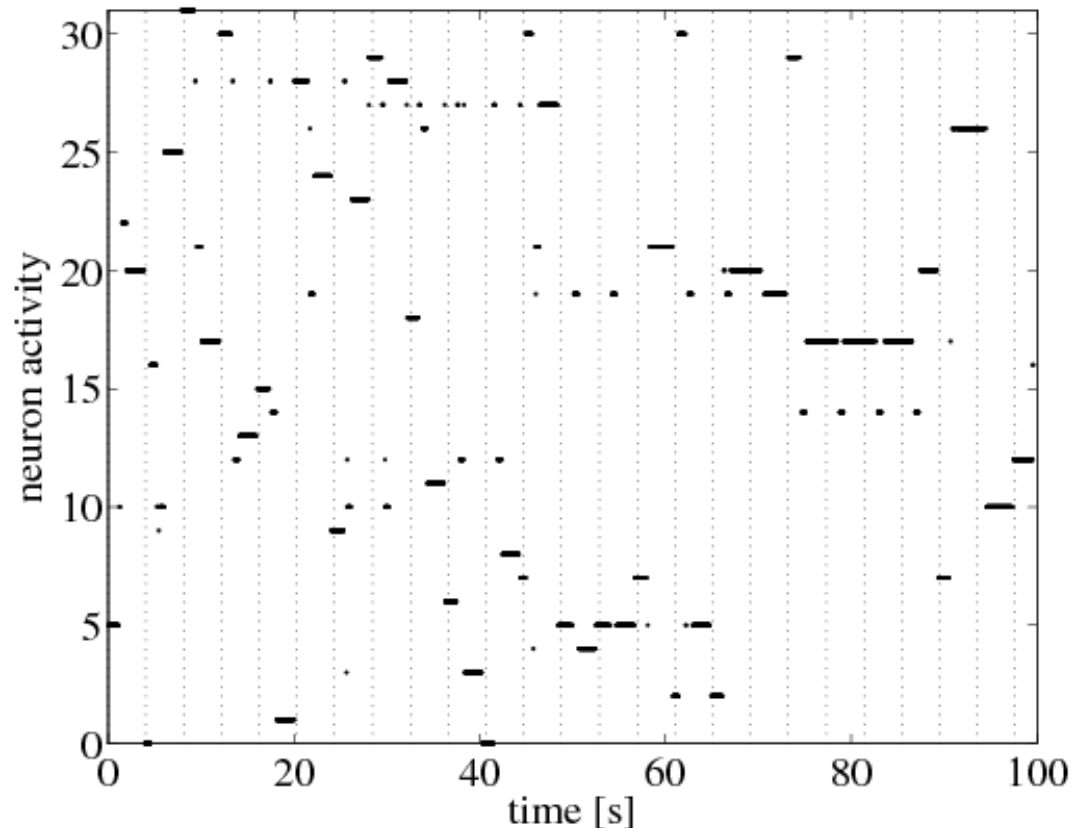
Random Weights





Classification of Phases in a Cyclic Motion Pattern (2/3)

During Learning





Classification of Phases in a Cyclic Motion Pattern (3/3)

After Learning

