# INF5490 RF MEMS

#### L16: Wireless systems using RF MEMS

S2008, Oddvar Søråsen Department of Informatics, UoO

## INF5490: topics

- "RF MEMS"
  - $\rightarrow$  2 parts: **RF** and **MEMS**
  - Description and modeling of MEMS components in focus
- This lecture:

- MEMS components used in RF systems

# Today's lecture

- Wireless communication
- Different principles for RF transmission
- Technology and components used today
- Transceiver with RF MEMS

   "RF receiver front-end" architecture
   Transmitter architecture
- Relevant research topics

## **RF-systems**

- RF is essential for wireless communication
  - Radio waves used for transmitting/receiving
    - Electromagnetic waves (Maxwell's equations)
- Radio "transceiver" is a basic component
  - Transmitter + Receiver
- RF systems must
  - Transfer **power** at a specific **frequency**
  - Use a limited bandwidth
- Filtering needed to separate channels

#### General communication system



Bit streams are modulated (coded) onto a carrier

Radio channel introduces noise, interference, disturbances

Receiver shapes the signal for demodulation

## Different coding principles

- Many different modulation schemes exist
  - F.ex. BFSK, Binary Frequency Shift Keying
  - Transfering digital data
  - Coding bits to 2 different frequencies (Tb is bitduration)



#### **Demodulation BFSK**

Coherent demodulator

logic 0: 
$$s_0(t) = \int_0^{T_b} (A \cos \omega_0 t) (A \cos \omega_0 t - A \cos \omega_1 t) dt = \frac{A^2 T_b}{2};$$
 (1.1)  
logic 1:  $s_1(t) = \int_0^{T_b} (A \cos \omega_1 t) (A \cos \omega_0 t - A \cos \omega_1 t) dt = -\frac{A^2 T_b}{2}.$  (1.2)



## BPSK

- Binary Phase-Shift Keying
- Modulate phase onto carrier
  - Phase changes 180 degrees from 0 to 1 (+  $\pi$ )



#### **Demodulation BPSK**

logic 1: 
$$s_1(t) = \int_0^{T_b} (-A\cos\omega_0 t)(A\cos\omega_0 t) dt = -\frac{A^2 T_b}{2};$$
  
logic 0:  $s_0(t) = \int_0^{T_b} (A\cos\omega_0 t)(A\cos\omega_0 t) dt = \frac{A^2 T_b}{2}.$ 



# QPSK

- Quadrature Phase-Shift Keying
- Having more than 2 representations of input data
  - Input is combined into bitgroups 00,01,10,11

- Half bit rate in each channel
- Demultiplexer sends every second bit up or down
- I and Q-channels are 90 degrees out of phase
  - In-phase component and quadrature component



# QPSK, contd.

- QPSK demodulation
  - Sin and cos-signals are orthogonal
  - Each channel is demodulated independently as for BPSK



- QPSK is an ex. of quadrature modulation where the bit flow is split into pairs of bits (dibits)
  - Each dibit is mapped into four levels before modulation

# Offset QPSK: modulator

- Each transmitting channel is non-ideal, having finite bandwidth:
  - → Offset QPSK can be used
  - Time delay Tb introduced in Q-channel
    - Offset = half the symbol period (2 Tb = period)
    - Hinders simultaneous signal transitions at A and B
    - Smaller phase shift. Lower requirements to channel bandwidth



# Minimum Shift Keying

- Avoid large phase shifts at the end of each symbol!
  - Large, fast changes in phase mean large symbol bandwidth
  - Solution: Multiply channel signals with half sine pulses instead of rectangular pulses
- This is an example of MSK, Minimum Shift Keying
  - Continuous phase shift: not abrupt change of phase and no fast signal change
- MSK has a larger decrease in its spectrum than QPSK
  - Lower sidelobe signal influence

#### **Receiver architecture**

#### • Input filter, BPF1

- Band selection filter
- Narrow band RF filtering
- Reduces Gauss noise and interference
- Compromise, otherwise impractical. Good RF filtering is costly



#### Receiver, contd.

- LNA, RF amplifier (Low Noise Amplifier)
  - Requires high gain due to low SNR
  - LNA amplifies also interference/noise  $\rightarrow$  Saturation can result
  - High gain means high BPF1 requirements
    - "Compromise": the BPF1 must be practical
  - LNA is non-linear, adds also internal noise
    - Generates intermodulation products from interference
    - These may have the same frequency as the signal and be destroying



# LNA – Low Noise Amplifier

- Amplifier is typical non-linear
  - Output may be a 3rd order polynomial of the input signal

$$y(t) = \alpha_1 s(t) + \alpha_2 s^2(t) + \alpha_3 s^3(t)$$

For a single frequency input signal, double and triple frequencies are generated

$$y(t) = \alpha_1 A \cos \omega_0 t + \alpha_2 A^2 \cos^2 \omega_0 t + \alpha_3 A^3 \cos^3 \omega_0 t$$
  
=  $\frac{\alpha_2 A^2}{2} + \left(\alpha_1 A + \frac{3\alpha_3 A^3}{4}\right) \cos \omega_0 t + \frac{\alpha_2 A^2}{2} \cos 2\omega_0 t + \frac{\alpha_3 A^3}{4} \cos 3\omega_0 t$ 

Harmonics are generated

$$HD_3 = \frac{1}{4} \frac{\alpha_3}{\alpha_1} A^2 \quad (3. \text{ harmonic})$$

### Architecture, contd.

- Anti-image filter used before mixing, BPF2
- Mixing
  - Frequency transformed to Intermediate Frequency, IF
  - Variable or fixed local oscillator (LO) -frequency



# Mixing

- Mixing is mathematically equivalent to multiplication
- Multiplication of 2 frequencies,  $\omega_{rf}$ 
  - Intermediate frequency generated  $\omega_{if}$  v difference between  $\omega_{rf}$  and  $\omega_{lo}$

which is the

 $\omega_{lo}$ 

$$V_{\rm if}(t) = A \cos \omega_{\rm rf} t \times A \cos \omega_{\rm lo} t$$

$$V_{if}(t) = \frac{1}{2}A^{2}(\cos(\omega_{rf} + \omega_{lo})t + \cos(\omega_{rf} - \omega_{lo})t)$$
$$= \frac{1}{2}A^{2}(\cos(\omega_{rf} + \omega_{lo})t + \cos\omega_{if}t)$$

Suppose a frequency

$$- \omega_{image} = \omega_{rf} - 2 \times \omega_{if}$$

- The frequency is below the oscillator frequency
- Calculations show that this is mixed to the same IF  $\rightarrow$



Mixing of image frequency with local oscillator frequency

$$\cos(\omega_{image} - \omega_{lo})t$$

$$= \cos(\omega_{rf} - 2\omega_{if} - \omega_{lo})$$

$$= \cos(\omega_{rf} - \omega_{lo} - 2\omega_{if})$$

$$= \cos(\omega_{if} - 2\omega_{if})$$

$$= \cos(-\omega_{if})$$

$$= \cos\omega_{if}$$

#### → Same intermediate frequency generated!

# **BPF2** Image rejection filter

- Must remove image frequency using a filter, BPF2
  - For low IF, the difference is small, interference may come from neighboring channels within the transmission standard
  - For high IF, the difference is large, interference may come from signals following other standards

- "Trade-offs" between the various filters
  - Must select correct channel
  - On the same time remove
    - Image-frequency
    - Other interfering frequencies



#### Superheterodyne receiver (cont'd)



#### Architecture, contd.

- Following band-pass filter, BPF3
  - Operates at intermediate frequency, IF
  - Not so high Q-factor requirement, more practical to implement
- Amplifier at IF



# Transition to RF results in

- Increased frequency:
  - $\rightarrow$  Shorter wavelength
    - in vacuum:

$$\lambda \cdot f = c$$

- $\rightarrow$  Signals vary over short distances
  - voltage V, current I
- $\rightarrow$  Smaller component dimensions required
  - High precision fabrication required
  - → micro machining

## Present technology

- Technology and components used today
  - **Discrete**, **passive** components with good properties
    - R, C, L
    - Ex. crystals, inductors
  - Such components needed due to high performance and precision requirements
  - Off-chip solutions are the result
    - PCB assembly
    - Systems take a lot of space
    - Integrated solutions not possible
  - Active components
    - Amplifiers, switches
    - GaAs, bipolar Si, CMOS Si, PIN-diodes

#### Present RF technology has limitations

- The discrete components have **limited performance** 
  - Conventional PIN-diodes are inefficient for high frequencies
  - RF filters are especially difficult to implement
    - high Q-factor is difficult to achieve
    - costly
- Systems may not be fully integrated
  - PCB implementations
  - Efficient integration is import for cost, volume and reliability

# Transceivers using RF MEMS

- How micromechanical circuits can be used in communication systems
- Ex.: "RF receiver front-end"-architecture
  - A. Direct substitution of off-chip passive components
  - B. Special RF MEMS blocks
  - C. RF front-end with only mechanical components
- Architectures are somewhat "speculative"
  - We are not there yet
  - Give motivation for further progress!

#### Miniaturization of Transceivers







# A. Direct substitution

- Different types of MEMS-based components
  - Inductors with medium Q-value
  - Tunable capacitors
    - Used in VCO and matching networks
  - Low loss MEMS switches (~0.1 dB)
    - Increases flexibility of antenna
  - Resonators
- Used for
  - RF-filters (ceramic)
    - "preselect filter", "image-reject filter"
  - IF-filter (SAW)
    - "channel-select filter"
  - Crystal reference oscillator



# Benefits of MEMS substitutes

- Reduction of dimensions
- Possible integration
  - Multi-chip
  - Monolithic
- Power reduction
- More flexibility for impedance matching of MEMS filters

- Termination impedance matched to the following LNA (Low Noise Amplifier)
  - "Higher" (than 50 Ω) LNA input impedance can be used → power reduction and reduced noise



# B. Special RF MEMS blocks

- Figure shows 3 basic blocks that are substituted by RF MEMS
  - B1. Switchable RF channel-select filter bank
  - **B2.** Switchable micromechanical frequency synthesizer
  - B3. Micromechanical mixer-filter block



Figure 12.21. System block diagram for an RF channel-select receiver architecture utilizing large numbers of micromechanical resonators in banks to trade Q for power consumption. (On-chip µmechanics are shaded.)

#### B1. Switchable RF channel-select filter bank

- Idea
  - Use many, simple, nontunable filters with high Q
  - One for each channel, switched on command
  - A communication standard needs 100 1000 of filters
- Block diagram
  - Common input and output
  - Controlled by Vp from decoder
    - With no Vp the outputs are effectively "open-circuited"



#### Use of RF filter bank

- Narrow RF channel can be selected directly
  - A succeeding electronic block can be simplified!
  - Signal will not be influenced by adjacent channels
- LNA can be simplified
  - Dynamic range can be reduced, meaning reduced power consumption
  - Less stringent requirements to IIP3 gives an order of magnitude reduction in LNA power consumption:
    - Ex. CDMA cell phone, test results:
    - Single tone signal 900 kHz outside of centre frequency
    - LNA IIP3 > + 7.6 dBm by conventional implementation (intermodulation!)
    - By using a filter bank the tone is damped 40 dB  $\rightarrow$  IIP3 < -29.3 dBm
  - Requirements of LNA linearity is reduced
    - Then LNA gain can be increased  $\rightarrow$  improving SNR for the following blocks
  - Reduced phase noise requirements for LO
    - $\rightarrow$  also power reduction
    - On-chip realization of LO might be possible

#### **B2.** Switchable MEMS frequency synthesizer

- Implementing VCO with MEMS resonators
  - Oscillator can be implemented using a switchable resonator bank
  - Resonators oscillate with the frequencies needed for the given standard
  - Resonators must have high Q and should be thermally stabilized (mechanically or by electronic compensation)
    - Might allow the VCO to operate without crystal reference
    - → significant power reduction, f.ex. 90 nW versus 1-4 mW



#### B3. Micromechanical mixer-filter

- Use of a micro-machined mixer-filter eliminates the DC power consumption compared to what present commercial mixers need
- Two input ports used in the mixer-filter: one for RF, one for LO
  - RF-input port can be made capacitive
  - Output port can be tailored to a specific impedance
  - $\rightarrow$  LNA can be simplified and does not need a separate impedance matching



#### C. RF front-end with RF MEMS only

- Do we need LNA for RF?
  - Use of relatively broadbanded "image-reject" MEMS RF filter followed by a narrowband IF-mixer-filter
    - The only active RF-component are then the LO
    - $\rightarrow$  This gives low power consumption



Figure 12.23. System block diagram for an all-MEMS RF front-end receiver architecture. (On-chip µmechanics are shaded.)

# Benefits of using RF MEMS only

- System is power efficient
  - Power consumption of LNA and mixer eliminated
  - Can increase standby-time for cell phones significantly!
- Some of the actual components have already been demonstrated
  - Filter and mixer circuits
  - Ex. an image-reject filter at UHF with 3 dB insertion loss has been demonstrated
- A promising implementation technology is to use high Q f-f- beams
  - Higher frequencies than c-c beam

## **RF MEMS transmitter architecture**

- Little done in using RF MEMS in transmitters
  - Due to lack of high power capability
    - Transmitting power is a significant parameter
- Active research on this matter



Figure 12.24. RF channel-select transmitter architecture, possible only if high-power µmechanical resonators can be achieved. Here, on-chip µmechanical blocks are shaded, and the PA is not necessarily implemented on-chip.

# **RF MEMS transmitter architecture**

- RF MEMS channel selector can be placed after PA ("power amplifier")
  - Use MEMS filter bank
  - MEMS resonators should sustain high power, have high Q and low "insertion loss" (<1 dB)</li>
  - "Pure signals" are sent out
  - + PA requirements may be reduced, since all spectral noise due to nonlinearity is filtered out after the PA!
- Architecture may give significant reduction of power consumption
- "Up-converter" can be realized using MEMS mixer-filter structure



## Relevant research topics

- The architectures shown are to some extent based on resonators with performance not yet achieved
- Research topics
  - 1. Obtain required high Q at UHF
  - 2. Set specific impedance levels
  - 3. Good enough linearity and capability to sustain power
  - 4. Efficient integration methods

# 1. Frequency and Q-value

#### Frequency

- What frequency range can be covered?
- Structures/ geometry are critical issues
  - Research shows that 10 MHz 2.5 GHz can be achieved by using realistic element dimensions
  - Today components exist that have Q  $\sim$  1000 at 3 GHz
- Absolute value and tolerances in resonance frequency
  - Depends on fabrication, trimming and tuning
- Stability of resonator frequency
  - Wrt. temperature variations and aging
- Competing resonator types for high frequency and Q
  - "Thin-film bulk acoustic resonators"
    - High frequencies (UHF and over), Q > 1000
  - Use of piezolectric materials

# Frequency and Q-value, contd.

#### Q-factor

- Energy loss in material influences Q value
  - Q-factor depends on material type
- Q-factor dependence of fabrication
  - Surface cleanness
  - Doping: diffusion and implantation give different properties
- Loss via anchors reduce Q
  - "anchor-less" structures: f-f beam are beneficial
  - Balanced tuning fork structure
  - Circular resonator

#### 2. Custom set impedance level

- Serial "motional resistance"  $R_Q$  is often high
- Value of resistance should be matched directly to other transceiver components

   Components before and after resonator
- Should be ~ minimized
  - Realistic requirements: some hundred  $\Omega$ 's
  - Value depends on how small the gap, d, can be made

#### **Resonator** impedance

- "Motional" impedance and gap for 2-resonator structures
  - − Ex. By reducing gap (ca. 140  $\rightarrow$  70 Å) the resonance impedance will be **reduced** from 5000 Ω  $\rightarrow$  300 Ω (870 MHz)
  - BUT this will also degrade linearity
  - → important to balance linearity requirements to impedance requirements

TABLE 12.3. Two-Resonator µMechanical Filter Electrode-to-Resonator Gap Spacing Design<sup>a</sup>

Frequency	Gap Spacing, $d$ , for $R_Q$ of:				
	300 Ω	500 Ω	1000 Ω	2000 Ω	5000 Ω
70 MHz <sup>b</sup> 870 MHz <sup>c</sup>	160 Å 68 Å	178 Å 77 Å	207 Å 92 Å	243 Å 109 Å	301 Å 137 Å

<sup>*a*</sup> Determined with Q = 10,000,  $W_e = 0.54$ ,  $V_P = 10$  V, using Timoshenko methods and ignoring beam topography.

<sup>b</sup> CCBeam, polysilicon,  $L_r = 14.92 \ \mu\text{m}$ ,  $W_r = 8 \ \mu\text{m}$ ,  $h = 2 \ \mu\text{m}$ , BW = 200 kHz

<sup>c</sup> CCBeam, diamond,  $L_r = 5.97 \mu m$ ,  $W_r = 8 \mu m$ ,  $h = 2 \mu m$ , BW = 1.25 MHz.

#### Itoh et al

## Example of compromise

- If impedance matching means that a smaller gap has to be used than linearity requirements allow:
  - Eg. d\_min for desired impedance matching < d\_min for desired linearity</li>

#### • Solution: use several micromachined parallel filters

- With identical frequency response
- F.ex. 10 filters in parallel with R\_Q = 2000  $\Omega$  give R\_Q\_total = 2000  $\Omega$  /10 = 200  $\Omega$
- Parallel filters also increase power capability! →
  - 10 filters in parallel with 10 mW each, give totally 100 mW

# 3. Linearity and power capability

- Linearity and power capability are reduced when dimensions get smaller
  - Present ceramic or SAW filters have very high linearity
- MEMS structures based on c-c beams have OK linearity
  - Good enough, except for some standards allowing simultaneous transmit and receive
    - Ex. CDMA needs transmit-reject filter in front of the receiver filter bank
- Increased power capability
  - Use alternative geometries
  - Use alternative transduction
    - Piezoelectric
    - Magnetostrictive
  - Parallel units

# 4. Efficient integration methods

- Critical research topics
  - Combination of MEMS with transistors on-chip
    - Monolithic integration!
  - Jmfr. Lecture on integration and packaging
    - L15

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