

Exercise 1

Question 1

a) "An agent is a computer system that is situated in some environment, and that is capable of autonomous action in this environment in order to meet its designated objectives" [W4], 95}

- 1, Objective/goal to affect the environment
- 2, Autonomy is the only general requirement
- 3, On behalf of someone
- 4, The intelligent agent is also proactive (as well as reactive), goal directed on its own

↳ "Multiagent systems are systems composed of multiple interacting computing elements, known as agents" [V&A, 15]

- 1) Agents engage in social activities like cooperation, coordination and negotiations
- 2) Research goal is to connect micro scale behaviour with macro scale (often emergent) properties/effects, and vice versa.

Question 2

a) This is a DM problem since it does not involve multiple agents, one user and static environment.

Definition of expected utility

$$u(A_s, E_{wr}) = \sum_{r \in R(A_s, E_{wr})} P(r | A_s, E_{wr}) \cdot u(r)$$

where

$$\sum_{r \in R(A_s, E_{wr})} P(r | A_s, E_{wr}) = 1$$

we have two stakeholders/strategies, A_1 and A_2
 and their corresponding available states,
 with outcome and probability of outcome

where $E_w = (E, e_0, \uparrow)$ is environment

$e = \{e_0, e_1, e_2, e_3\}$ set of possible states,

e_0 is initial state

$\uparrow(e_0 \rightarrow e_1) = \{e_1\}$ state transition for α_0

$\uparrow(e_1 \rightarrow e_2) = \{e_2, e_3\}$ state transition for α_1

- we have two agents
 $A_{S_1}(e_0) = \alpha_0$ use action 0
 $A_{S_2}(e_0) = \alpha_1$ use action 1
- We also have the probability of ending up in another state

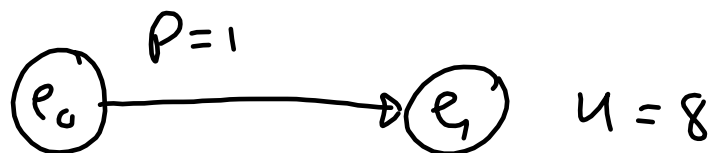
$P(e_0 \rightarrow e_1 | A_{S_1}, E_{hr}) = 1$
 meaning that the probability of ending up in state e_1 given agent A_{S_1} in environment using action α_0 is 1

- The utility of ending up in e_1
 $u(e_0 \rightarrow e_1) = 8$
- Let's check if $\sum p(r) = 1$ as required

$$\left. \begin{array}{l} P(e_0 \rightarrow e_1 | A_{S_2}, E_{nr}) = 0,7 \\ P(e_0 \rightarrow e_3 | A_{S_2}, E_{nr}) = 0,8 \end{array} \right\} = 1 \text{ for agent } A_{S_2}$$

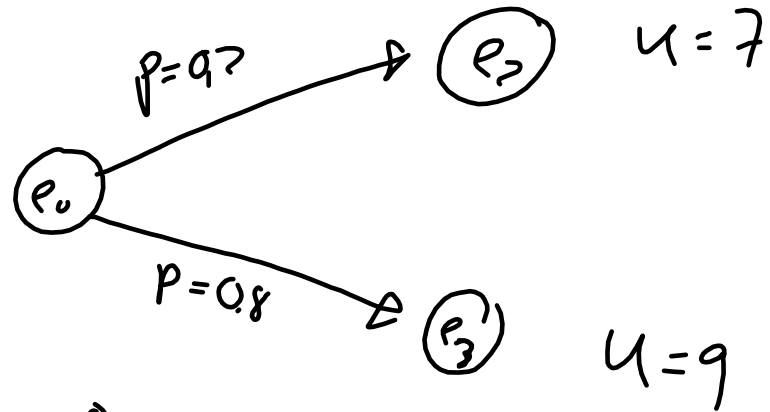
b) Calculate expected utility of LHM agents

A_{j_1}
 x_c



$$\hat{u}_1 = 1 \cdot 8 = \underline{\underline{8}}$$

$A_2 ? :$
 α_1



$$\hat{u}_2 = 0.7 \cdot 7 + 0.8 \cdot 9 = 1.4 + 7.2 = \underline{\underline{8.6}}$$

$\Rightarrow A_2$ is optimal in this environment using
 α_0 and α_1 $\hat{u}_1 < \hat{u}_2$

Question 3

- 9) "Endow" agents with mental states;
Desires & Beliefs
- 1) Desires modelled by max exp utility
 - 2) Beliefs from information processes
 - 3) Inspired from biology & sociology, social sciences which do manage complexity somehow
 - 4) key component of agent-based systems.

- b) Agents share common goals to
- 1) improve on overall goal
 - 2) simplify the design task
 - 3) in contrast to self-interested agents of different goals

- () Communication = the process of sharing
data / information / meaning
- 1, Communicating data "bit and bytes"
 - 2, Ontologies for meaning

d) Result starting (es in robot MA's)

1, Confidence

Multiple observations (assumed independent)
Strengthens statistical overall conclusion

2, Completeness

Broader or larger are to sample

3, Precision

Closeness to observation objects

4, Timeliness

Faster sampling of large area.