Exercises from lecture 5 (Swarm robotics 2) TEK5010 Multiagent systems 2020

Question 1

In this exercise we will explore consensus modelling in swarm systems.

- a) Could you explain the voter model and characterize its performance?
- b) Could you also describe and characterize the majority rule?
- c) Given a network of 5 agents, each located at position x, y and of 2 possible states s describe by the tuple $(x, y, s = \{0,1\})$

$$(0,0,s=0)$$
, $(5,0,s=1)$, $(4,7,s=1)$, $(2,5,s=0)$ and $(0,4,s=1)$

Could you track one iteration of the consensus process for this population using both models?

d) Optional: Simulate the general case when there are N agents of O opinions. How does the two models compare?