

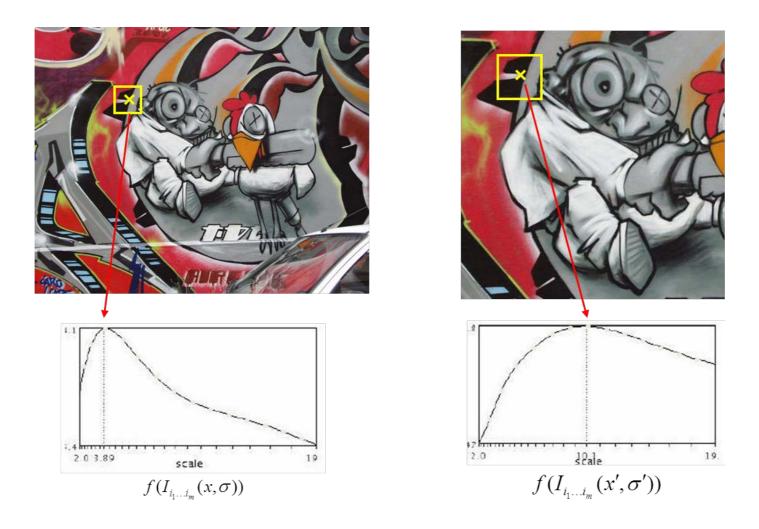
Lecture 3.2.2 Blob features

Trym Vegard Haavardsholm

Slides from Svetlana Lazebnik, Grauman&Leibe, S. Seitz, James Hays and Noah Snavely



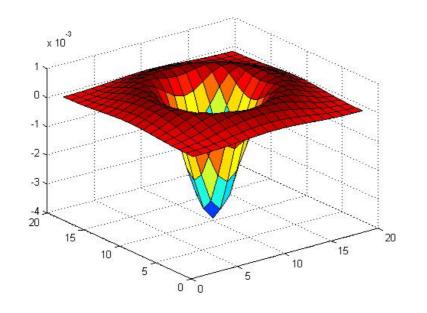
Automatic scale selection

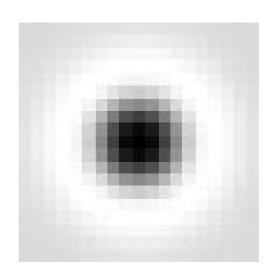




Another common definition of f

• The Laplacian of Gaussian (LoG)

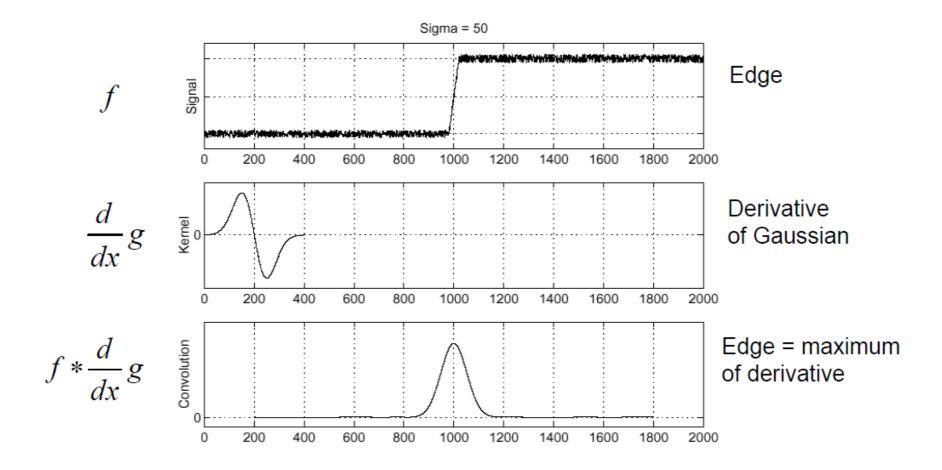




$$\nabla^2 g = \frac{\partial^2 g}{\partial x^2} + \frac{\partial^2 g}{\partial y^2}$$

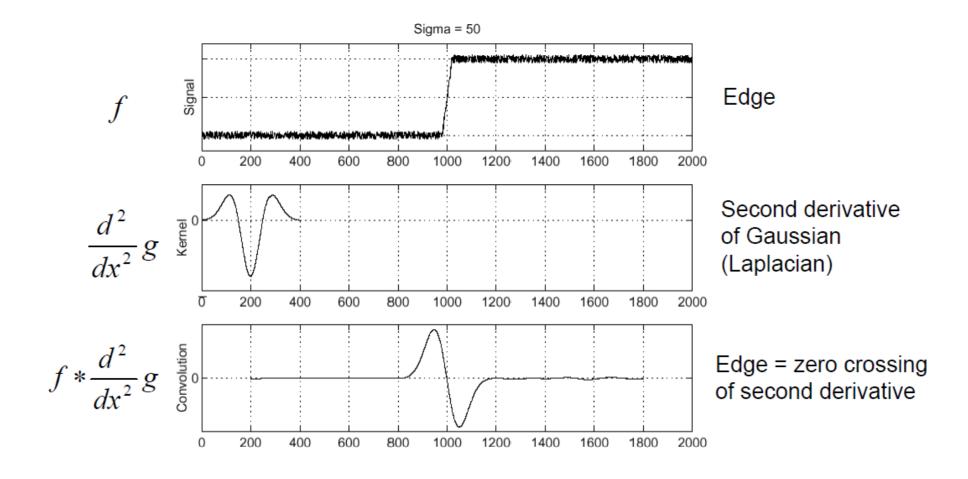


Edges and blobs





Edges and blobs

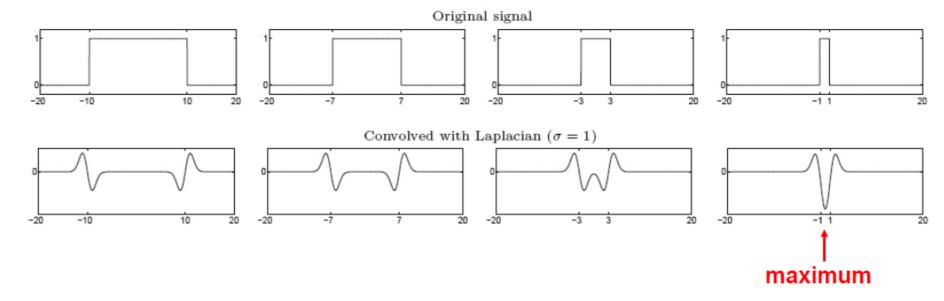




Edges and blobs

• Edge: Ripple

Blob: Superposition of two ripples

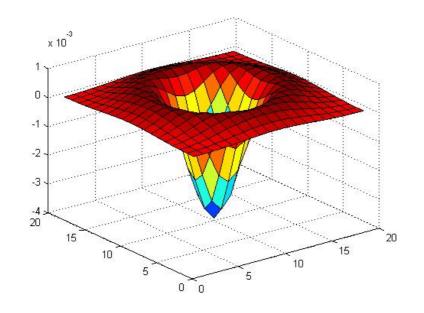


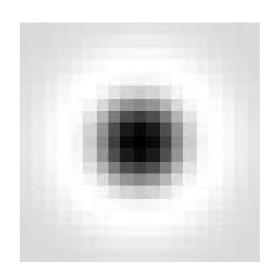
 The magnitude of the Laplacian response is maximum at the centre of the blob provided the scale of the Laplacian matches the scale of the blob



Laplacian of Gaussian

Normalize to make the response independant of scale



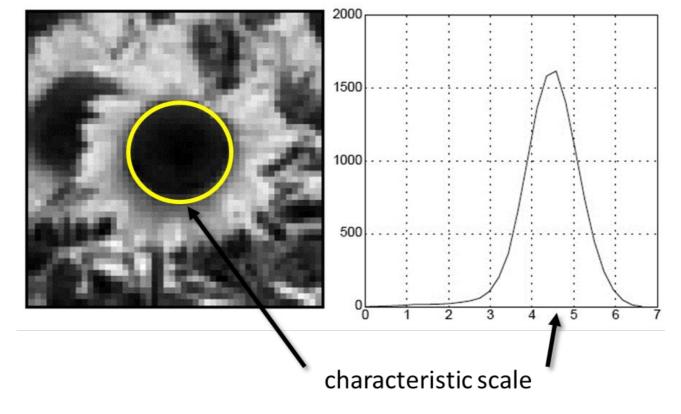


Scale-normalized:
$$\nabla_{\text{norm}}^2 g = \sigma^2 \left(\frac{\partial^2 g}{\partial x^2} + \frac{\partial^2 g}{\partial y^2} \right)$$



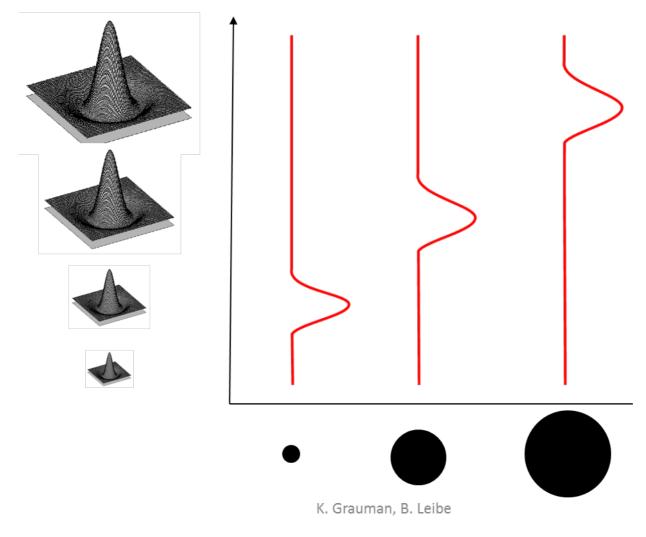
Characteristic scale

• We define the characteristic scale as the scale that produces peak of Laplacian response





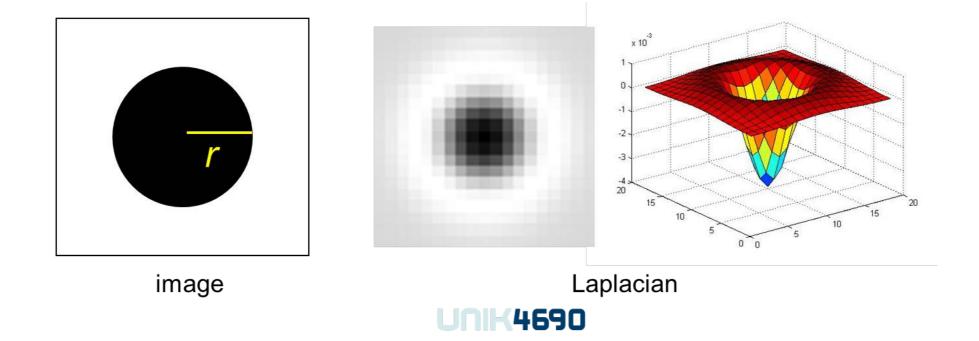
Characteristic scale





Scale selection

 At what scale does the Laplacian achieve a maximum response to a binary circle of radius r?

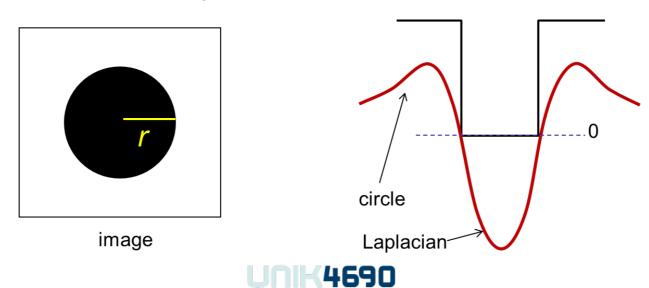


Scale selection

- To get maximum response, the zeros of the Laplacian have to be aligned with the circle
- The Laplacian is given by (up to scale):

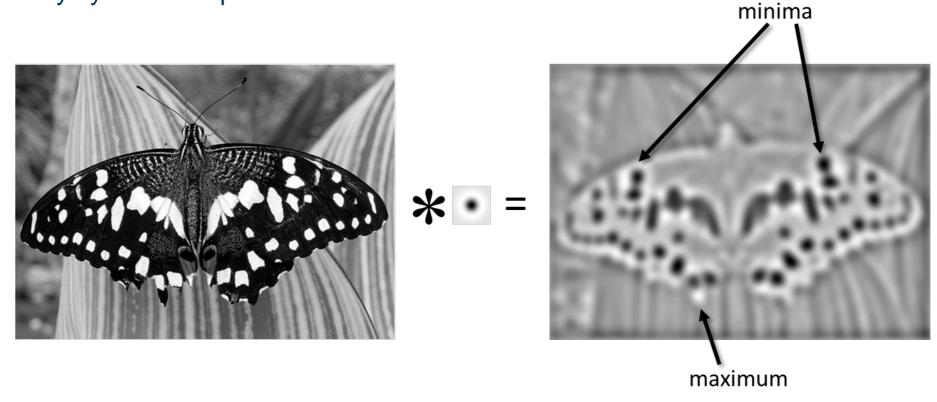
$$(x^2 + y^2 - 2\sigma^2) e^{-(x^2 + y^2)/2\sigma^2}$$

• Therefore, the maximum response occurs at $\sigma = r/\sqrt{2}$.



Laplacian of Gaussian

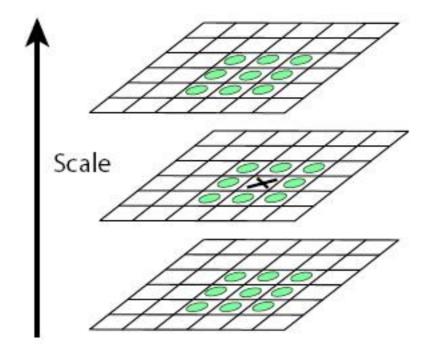
Circularly symmetric operator for blob detection in 2D



Find maxima and minima of LoG operator in space and scale



- Convolve the image with scale-normalized LoG at several scales
- Find maxima of squared LoG response in scale-space





Example







sigma = 2





sigma = 2.5018





sigma = 3.1296





sigma = 3.9149





sigma = 4.8972





sigma = 6.126





sigma = 7.6631





sigma = 9.5859





sigma = 11.9912

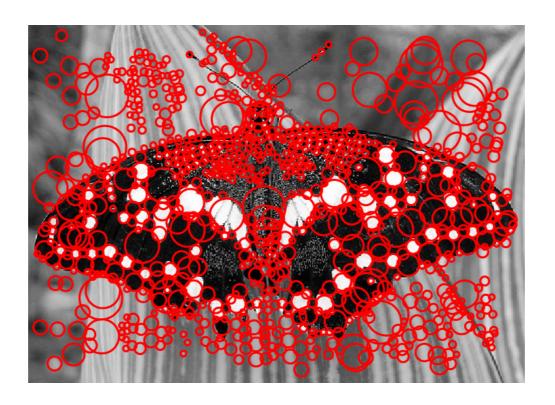




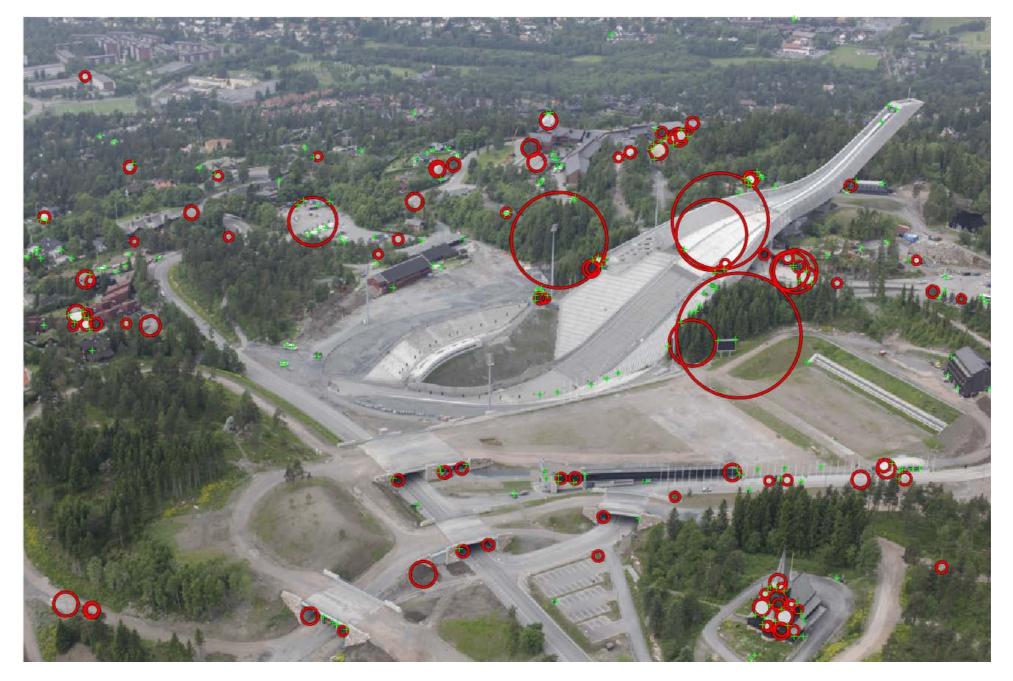
sigma = 15



Example: Detected blobs







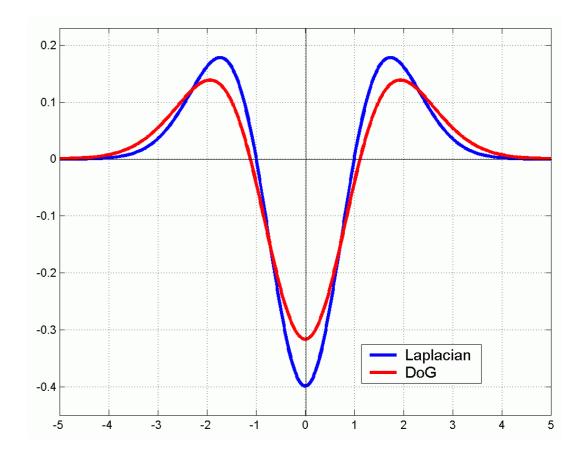
Efficient implementation

Approximating the Laplacian with a difference of Gaussians (DoG)

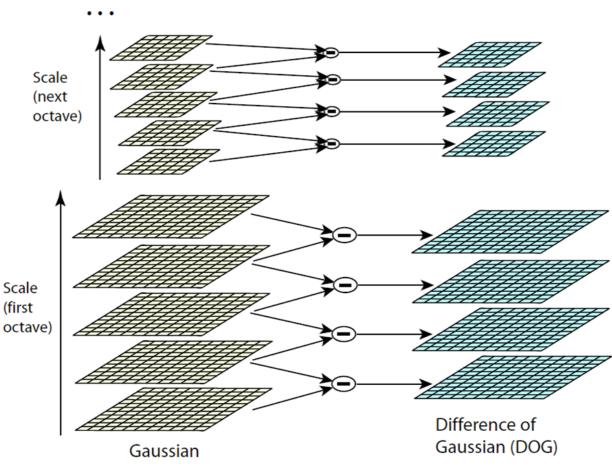
$$L = \sigma^2 \left(G_{xx}(x, y, \sigma) + G_{yy}(x, y, \sigma) \right)$$
 (Laplacian)

$$DoG = G(x, y, k\sigma) - G(x, y, \sigma)$$

(Difference of Gaussians)



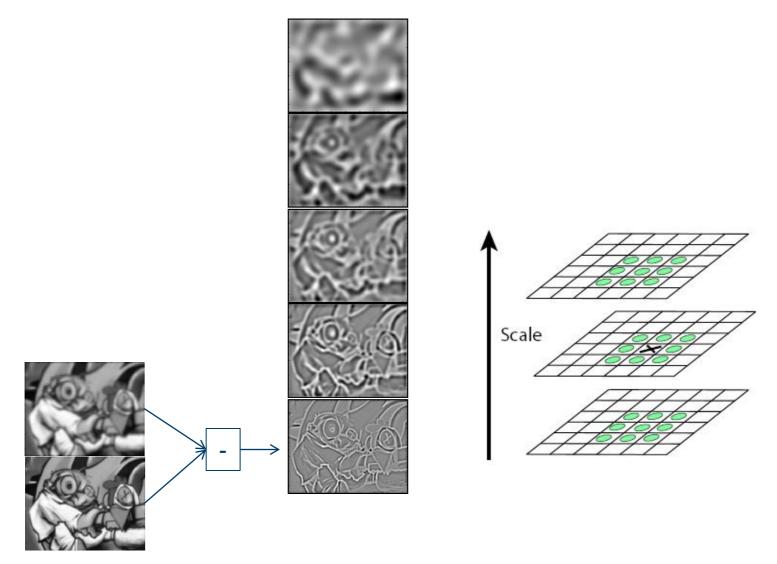
Efficient implementation



David G. Lowe. "Distinctive image features from scale-invariant keypoints." *IJCV* 60 (2), pp. 91-110, 2004.



Difference of Gaussians (DoG)





Summary

- Corner detectors
 - Stable in space
 - Min eigenvalue, Harris
- Blob detectors
 - Stable in scale and space
 - LoG, DoG
- Combine methods!
- Further reading
 - David G. Lowe, "Distinctive image features from scale-invariant keypoints"
 - T. Lindeberg, <u>"Feature detection with automatic scale selection"</u>
- Lab next week:
 - Implement and test feature detectors!

