

# Introduction to TEK5030 – Computer Vision

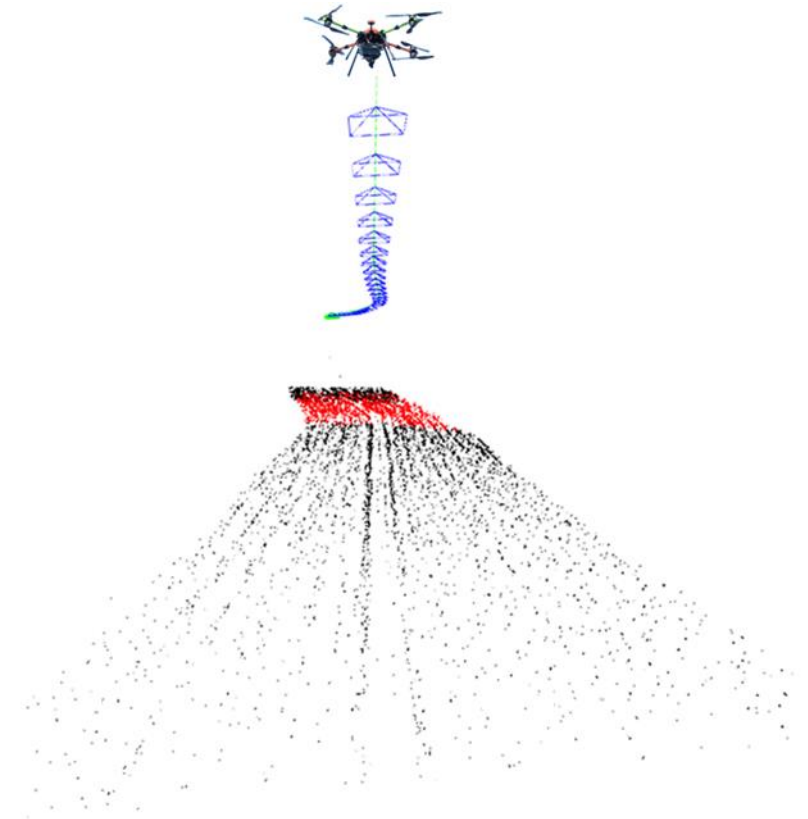
19.01.2024

Trym Vegard Haavardsholm ([trym.haavardsholm@its.uio.no](mailto:trym.haavardsholm@its.uio.no))

Idar Dyrdal ([idar.dyrdal@its.uio.no](mailto:idar.dyrdal@its.uio.no))

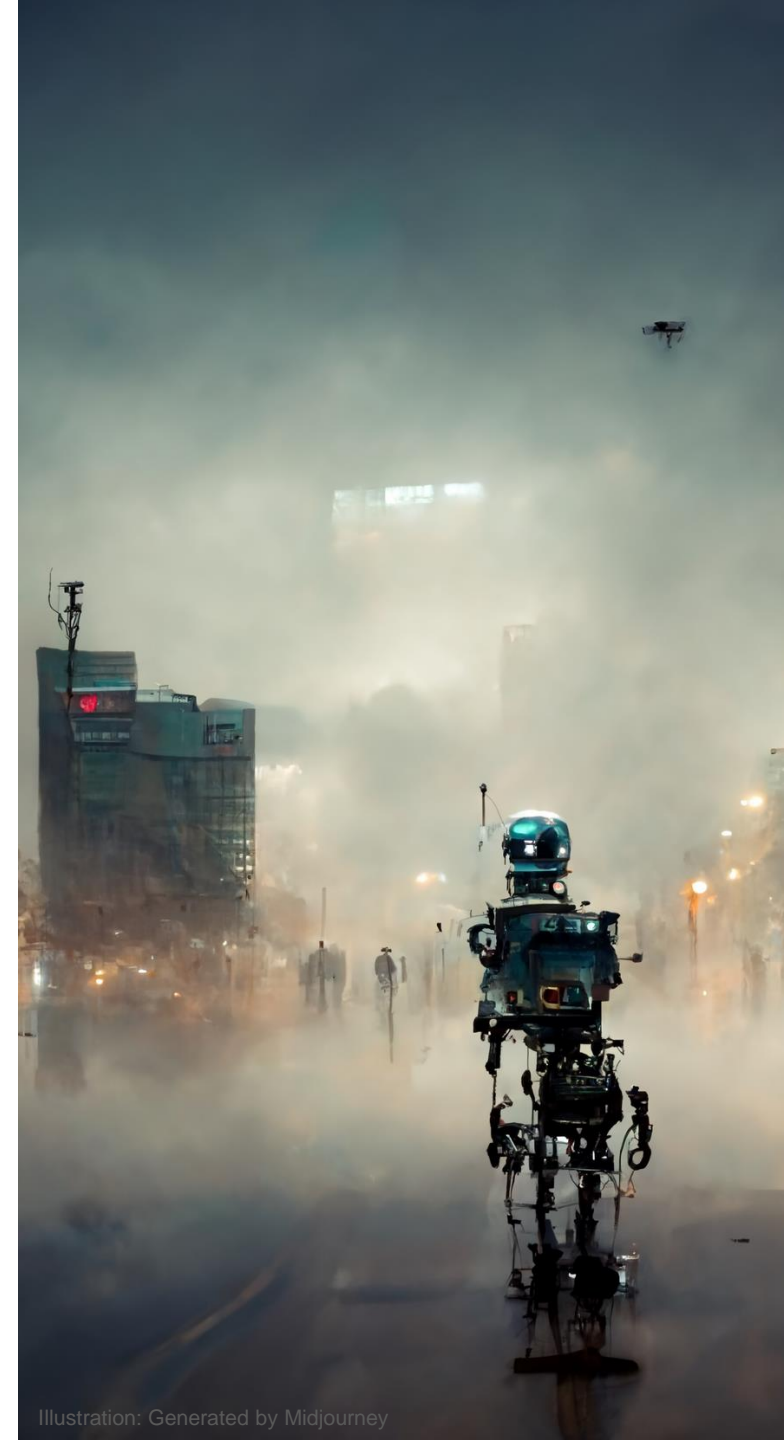
Thomas Opsahl ([thomasoo@its.uio.no](mailto:thomasoo@its.uio.no))

Ragnar Smestad ([ragnarsm@its.uio.no](mailto:ragnarsm@its.uio.no))



# Today

- A quick introduction to computer vision
- About the course
  
- Lab: An introduction to OpenCV
  - Processing live video streams with OpenCV!



«An image is worth more than a thousand words»



# «An image is worth more than a thousand words»

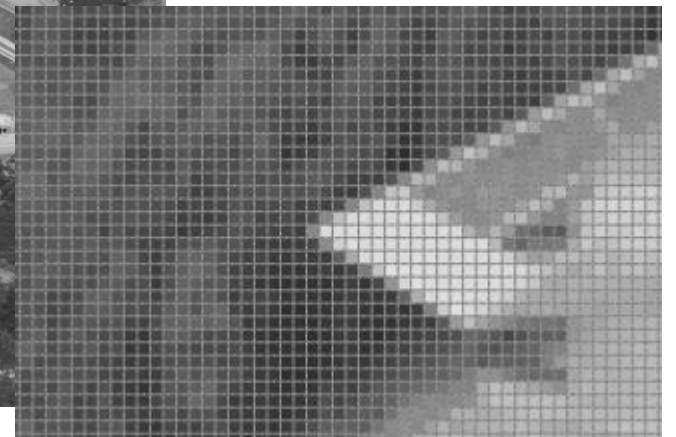
How can we extract  
this information?



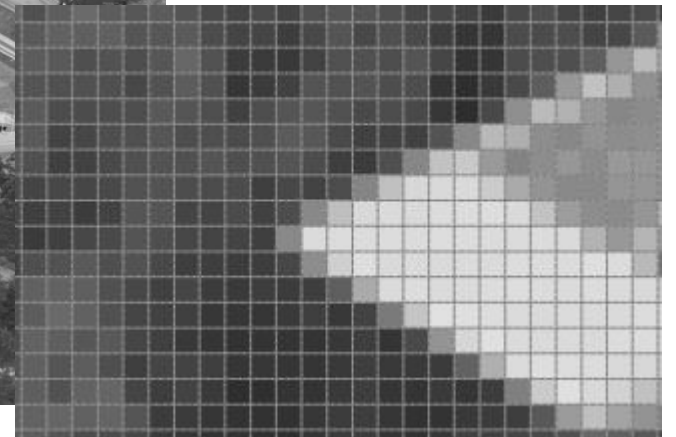
# Images and pixels



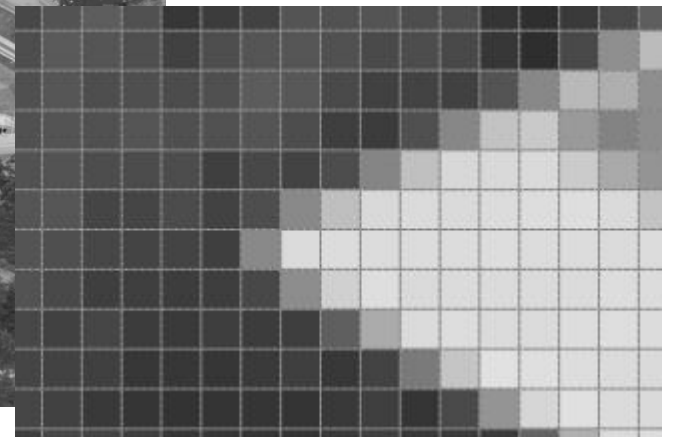
# Images and pixels



# Images and pixels



# Images and pixels





# Images and pixels



80	81	85	77	63	60	80	135	191
77	63	72	67	77	133	192	216	217
76	66	78	137	191	217	219	218	220
68	63	137	219	220	220	220	220	220
61	62	72	141	208	222	218	219	219
58	62	60	62	95	171	219	221	219

**It is easy to calculate with images!**



# It is easy to calculate with images!



=



**How fast can a machine  
crunch pixel values?**



Illustration: Generated by Midjourney

# Floating point operations (FP32) per second (FLOPS)



Photo: Miiichiaieil Hieinizilieir ([CC BY-SA 4.0](#))

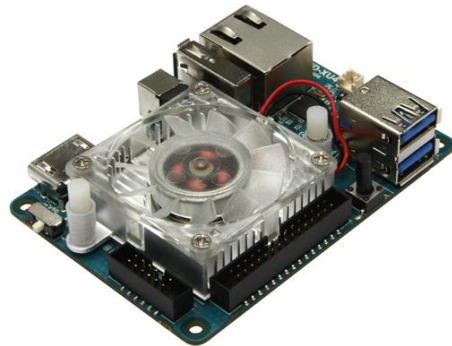


Photo: [Alexandre.willame \(CC BY-SA 4.0\)](#)



Photo: NVIDIA



Photo: HP

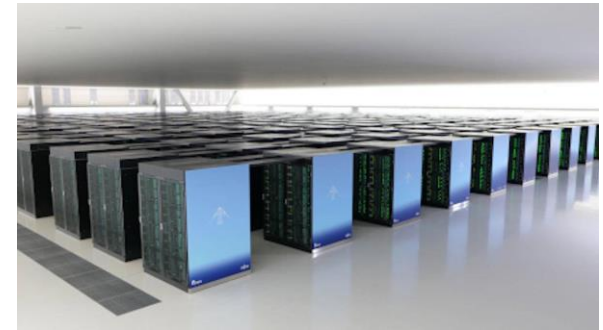


Photo: RIKEN

Raspberry PI 4B  
48 GFLOPS

Odroid XU-4  
214 GFLOPS

Jetson TX2  
782 GFLOPS

My laptop  
3 TFLOPS

Fugaku supercomputer  
>1000 PFLOPS

(theoretical *peak*)

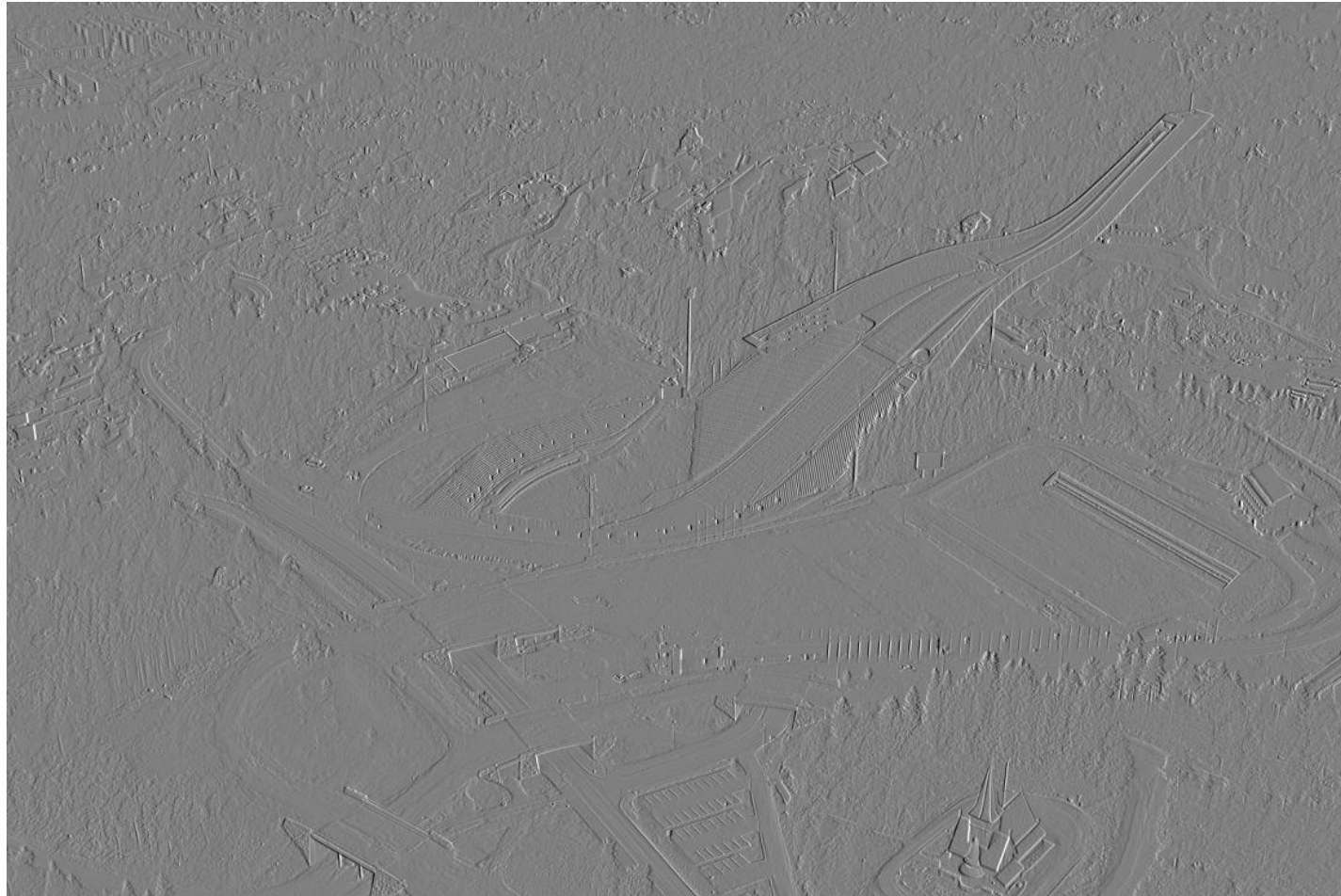
# The difference between neighbouring pixels



# The difference between neighbouring pixels

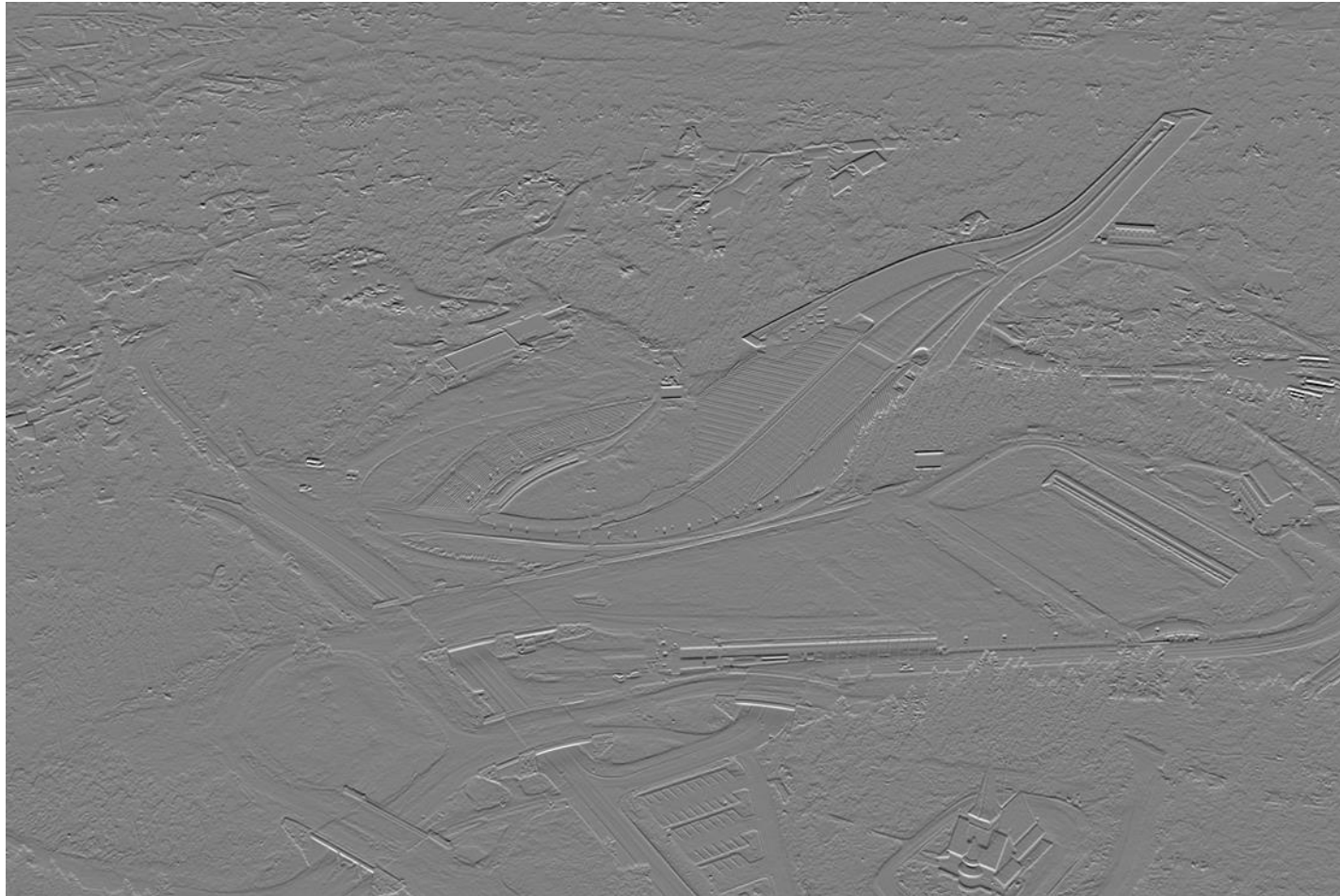


# Horizontal differences





# Vertical differences



# Edges and corners



# Significant corners



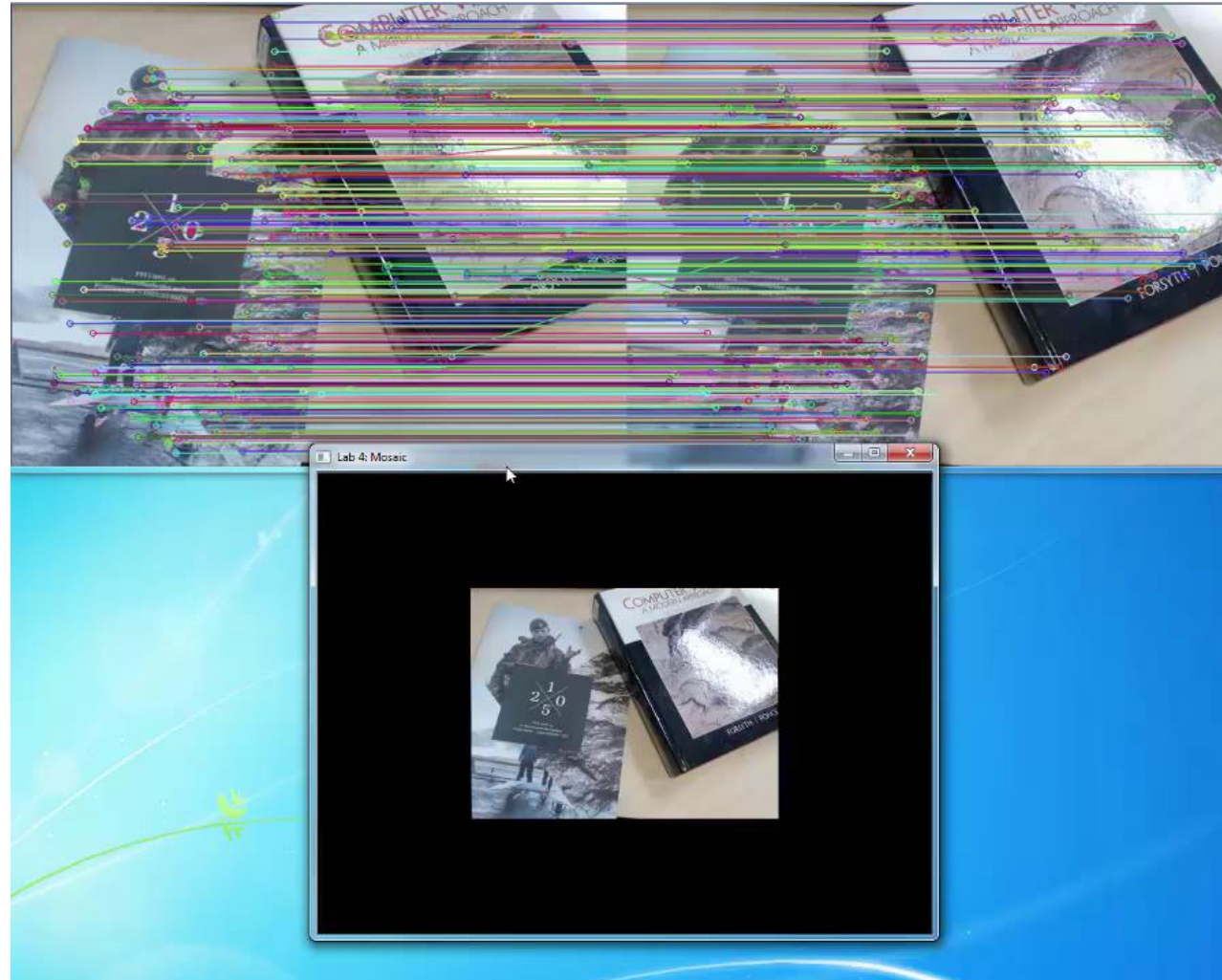
# Significant corners



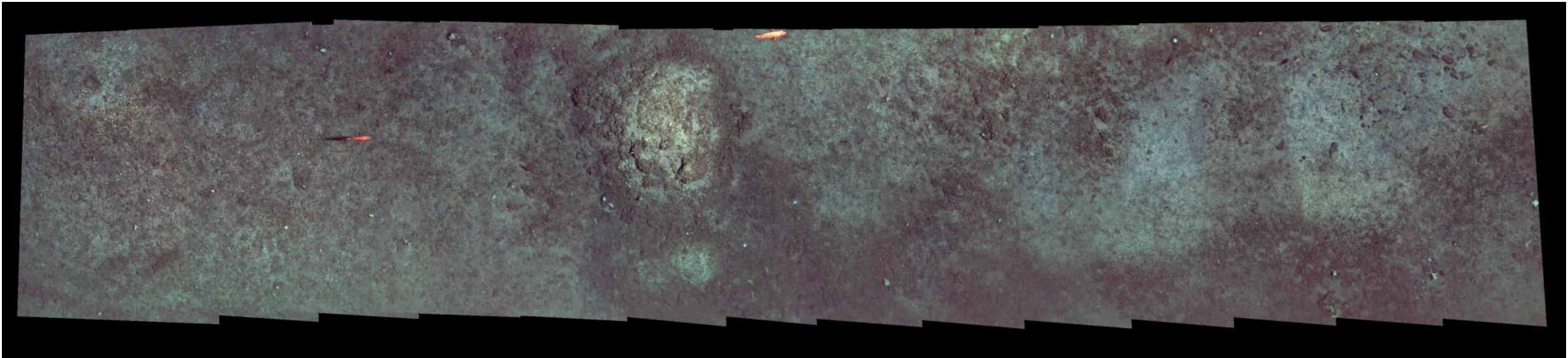
# Significant corners



# Example: Coregistering images

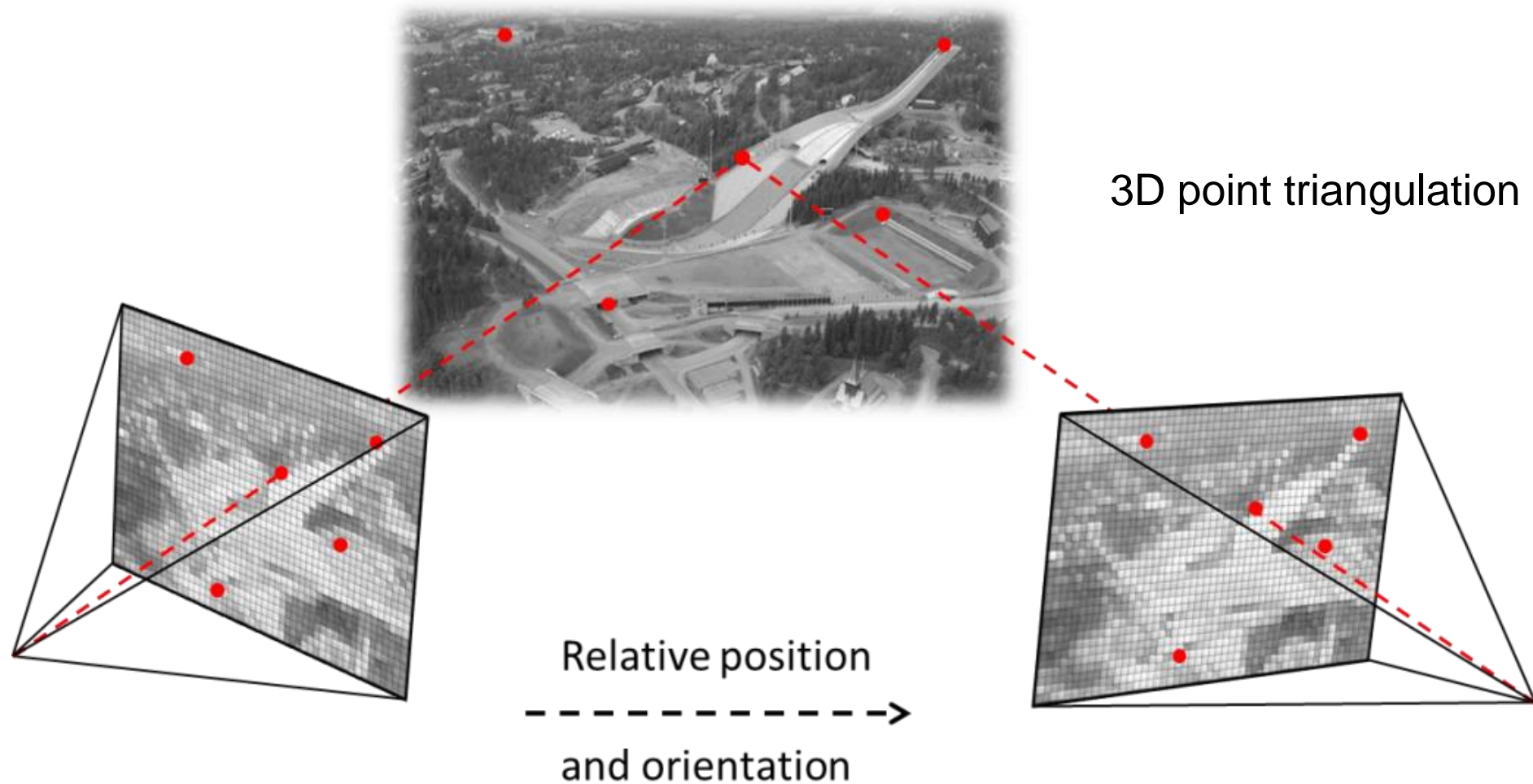


# Application: Underwater visual mapping from HUGIN AUV



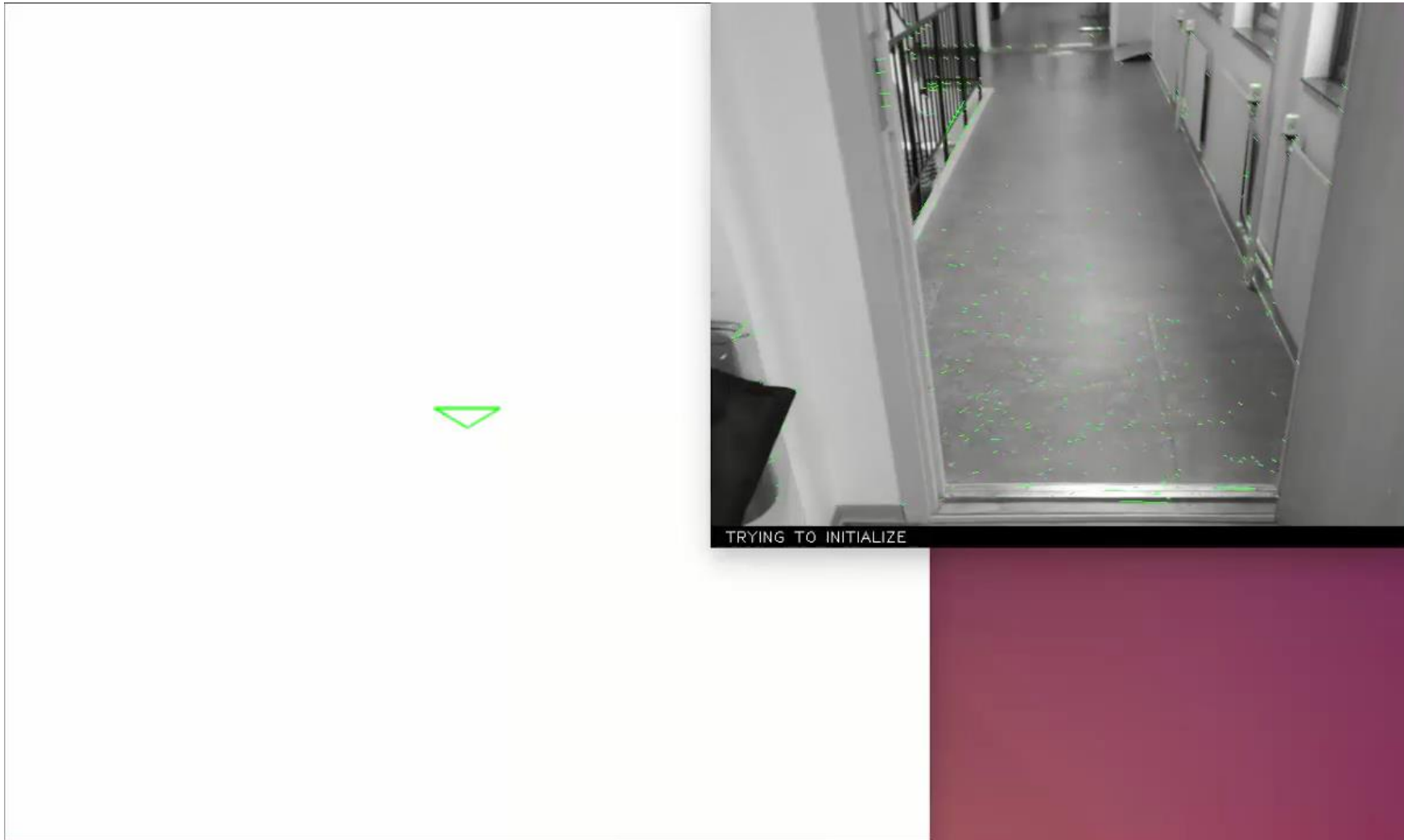
**TEK5030**

# Extracting geometric information from images

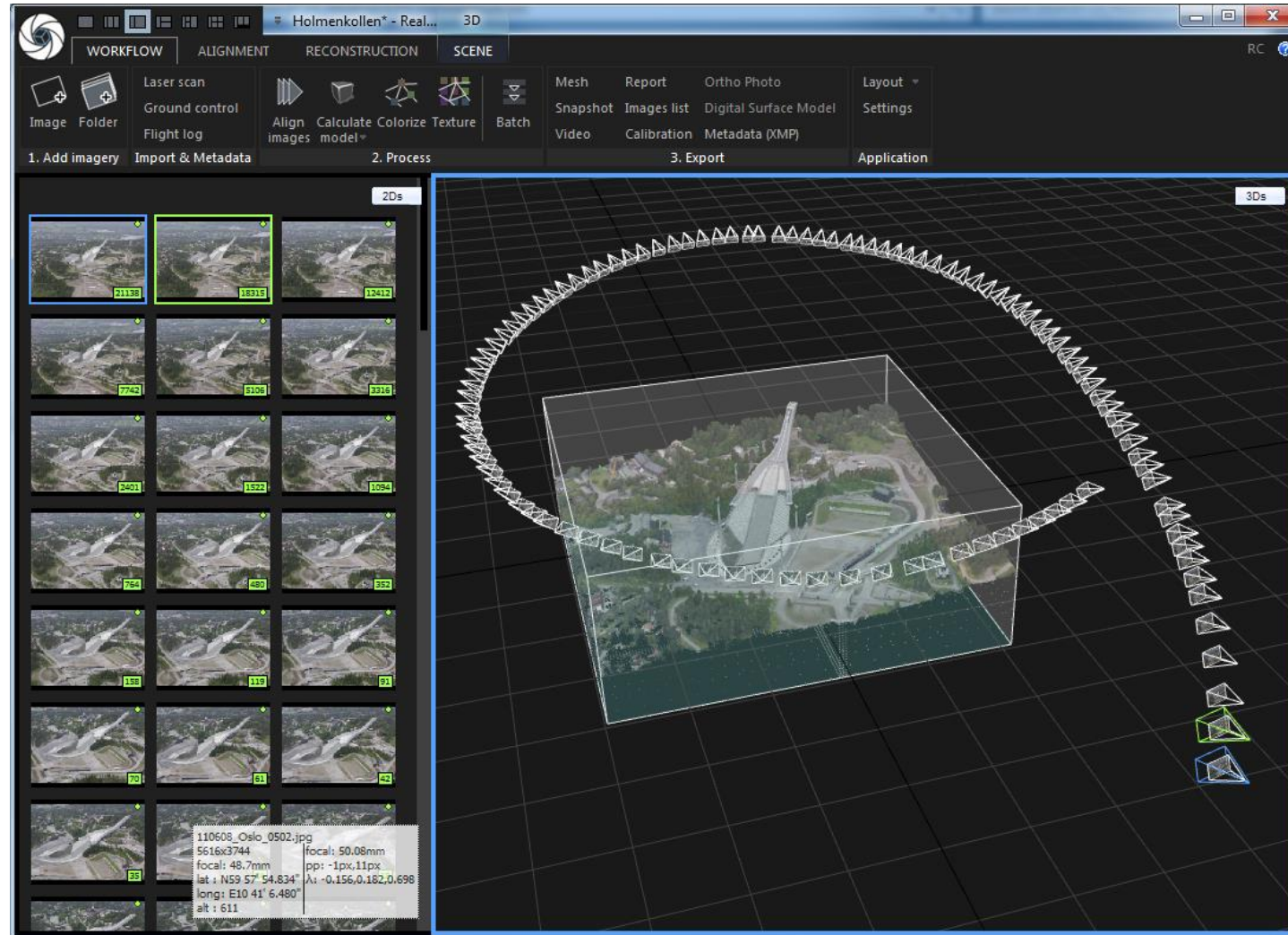




# Visual navigation



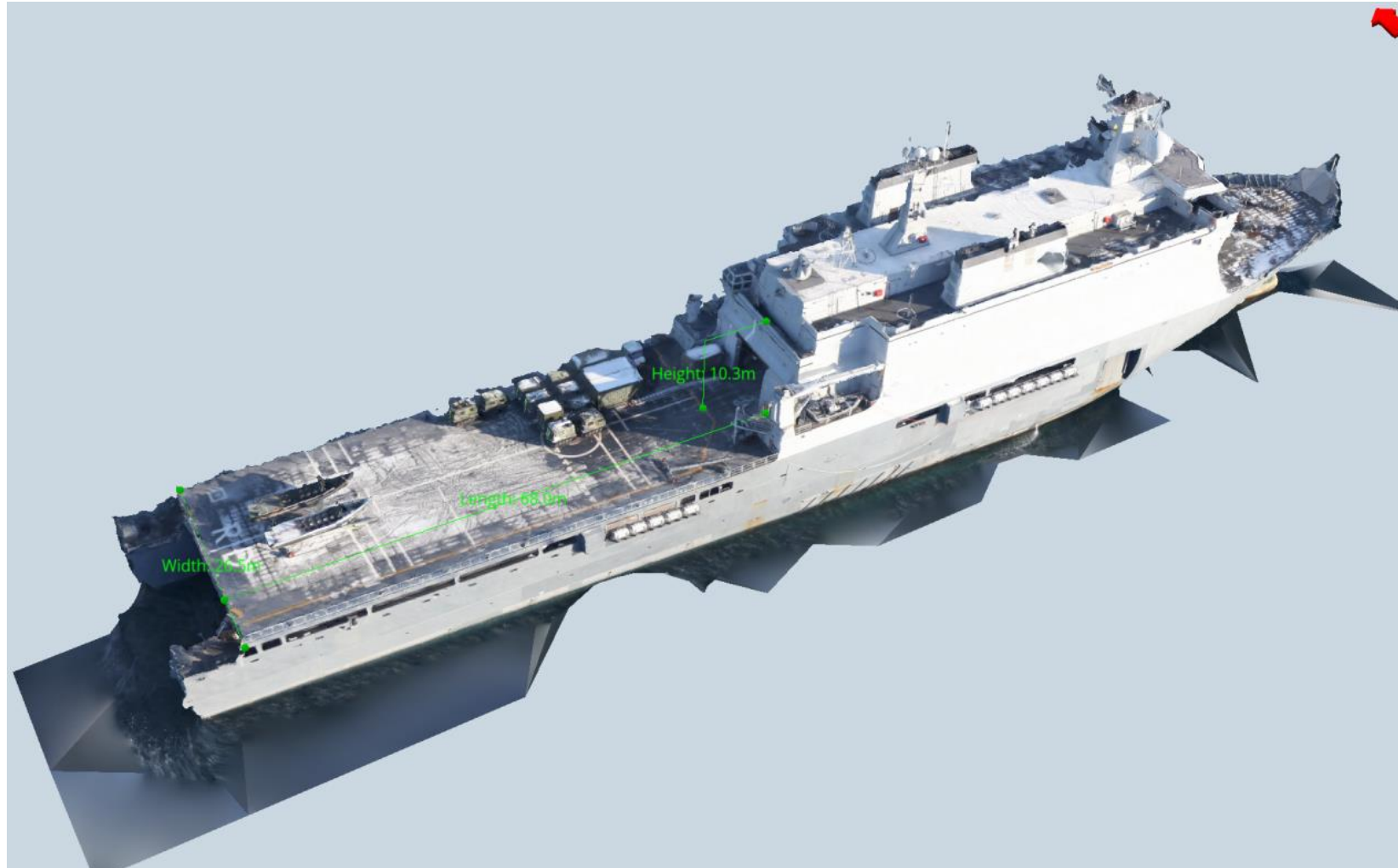
# 3D reconstruction from images



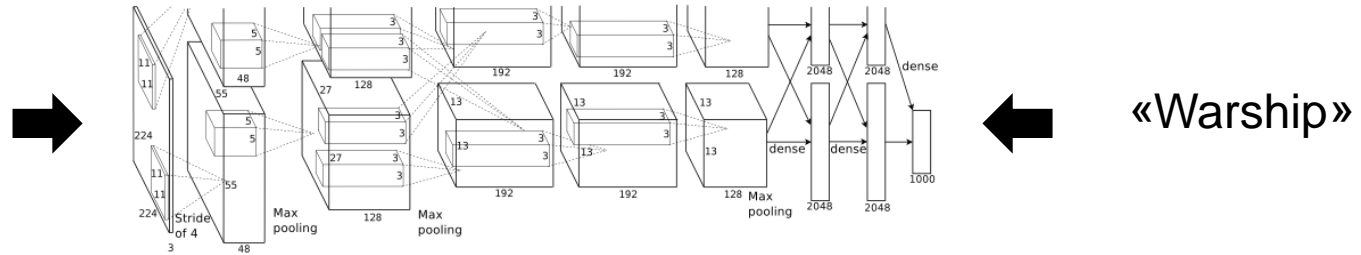
# A detailed 3D surface in colors!



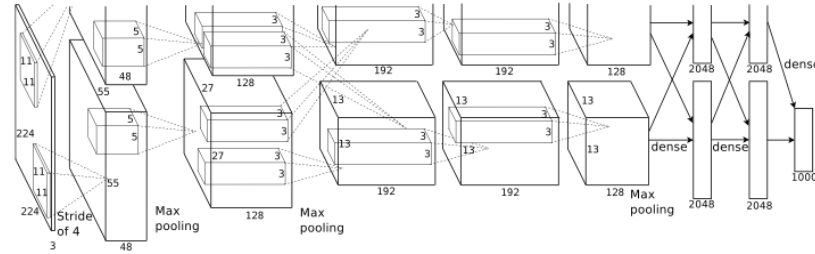
# Recognise the shape of a ship



# Let the machine learn a better representation itself!

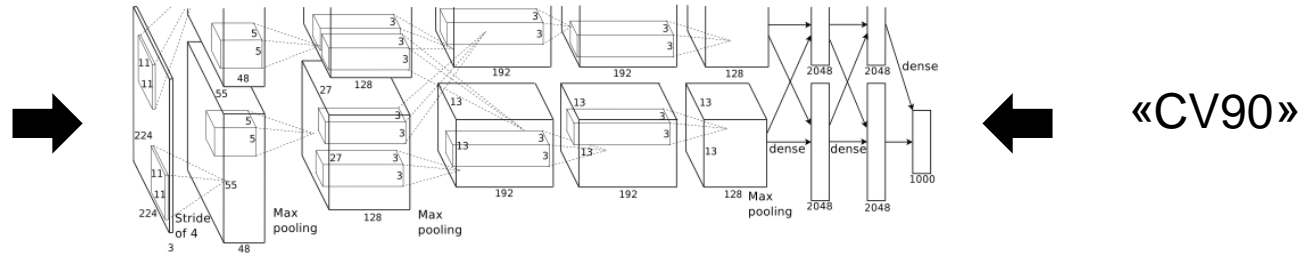


# Let the machine learn a better representation itself!



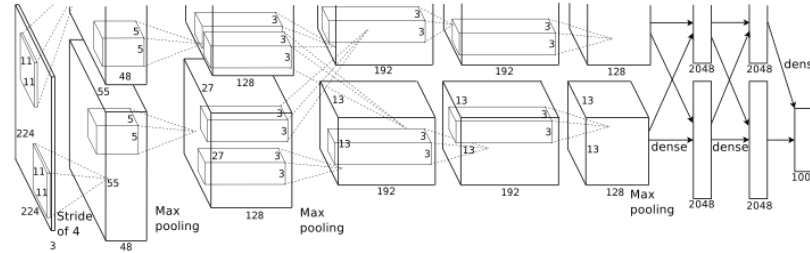
«Warship»

# Let the machine learn a better representation itself!



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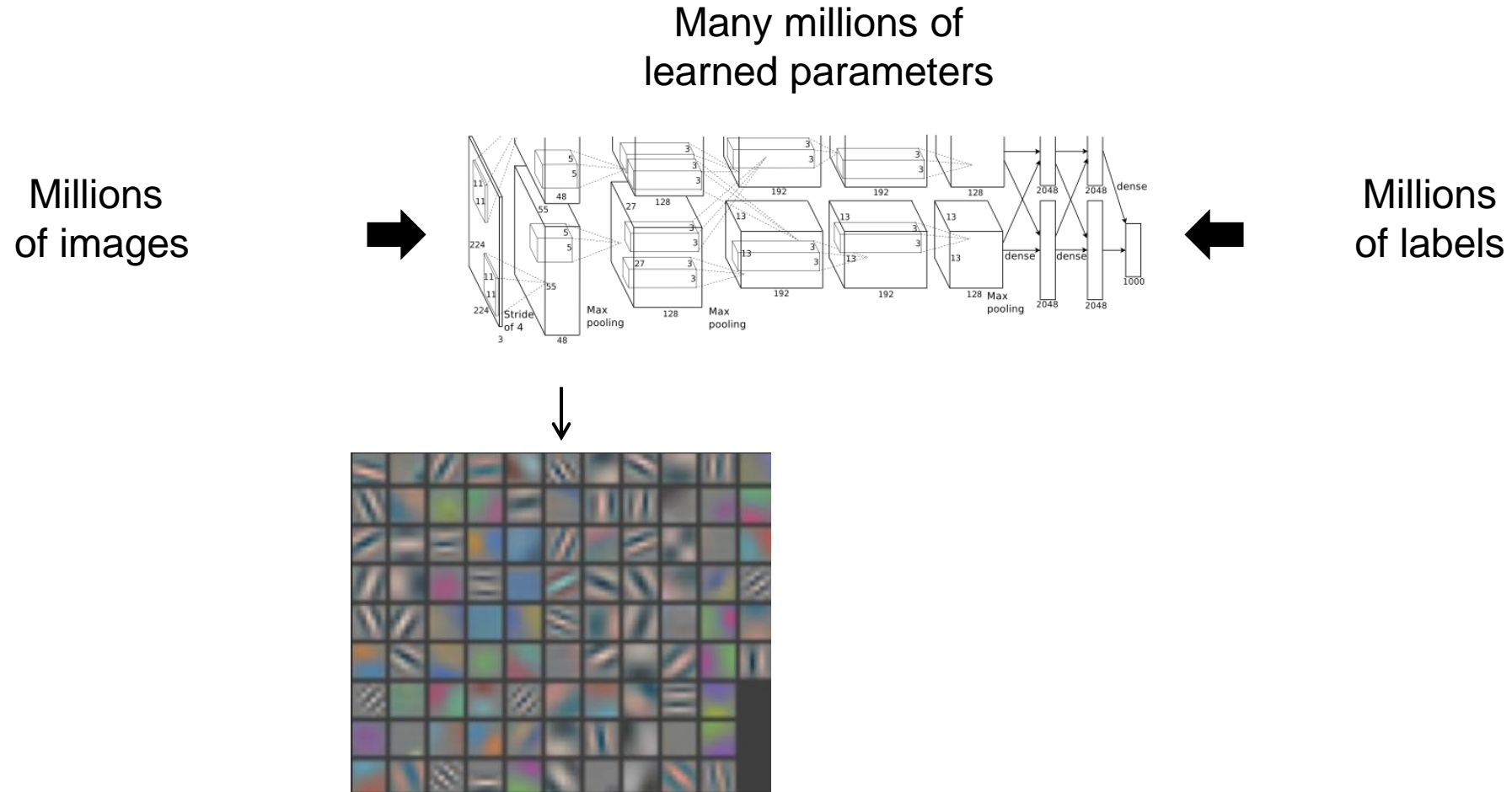
Millions  
of images



Millions  
of labels



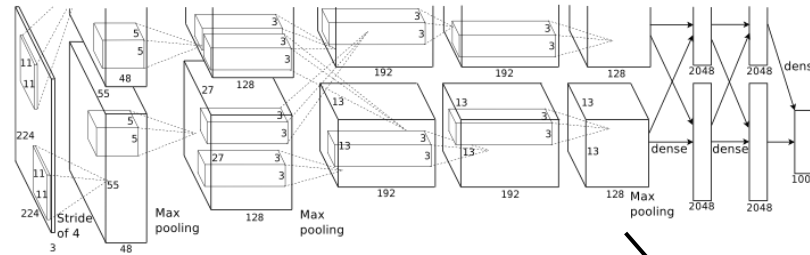
# Let the machine learn a better representation itself!



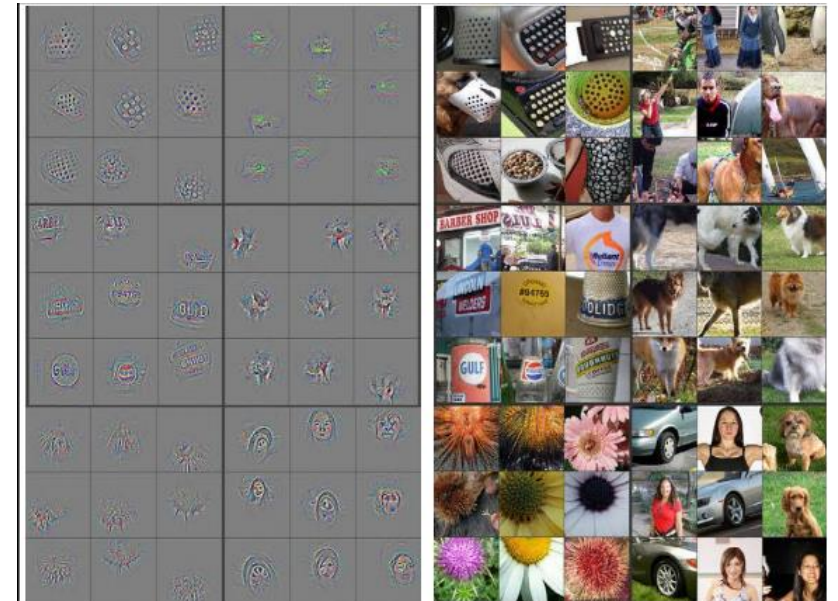


# Let the machine learn a better representation itself!

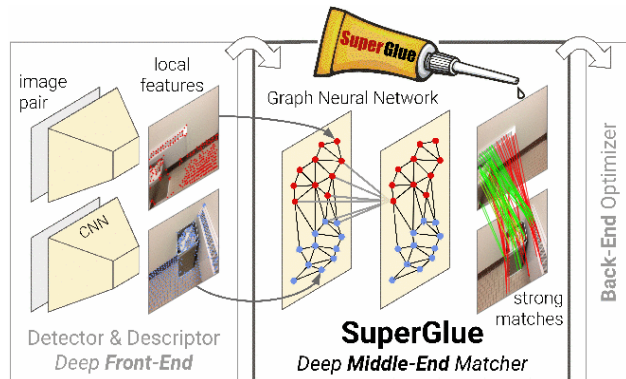
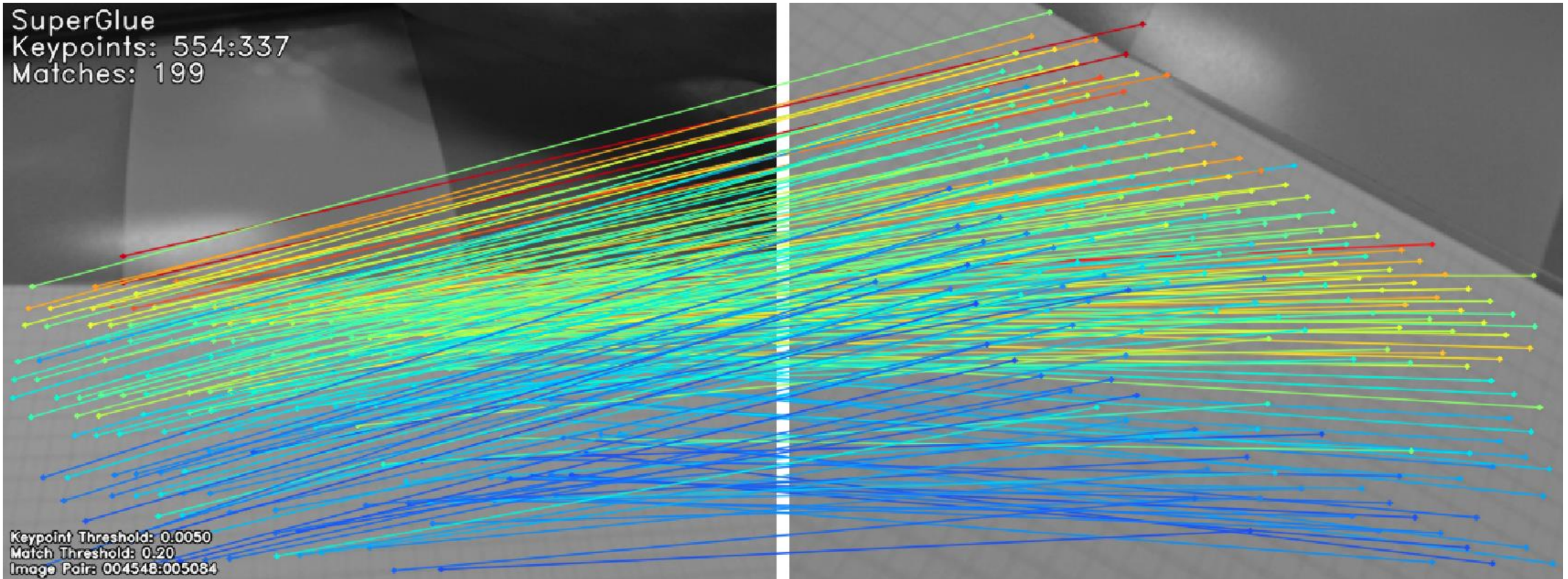
Millions of images



Millions of labels

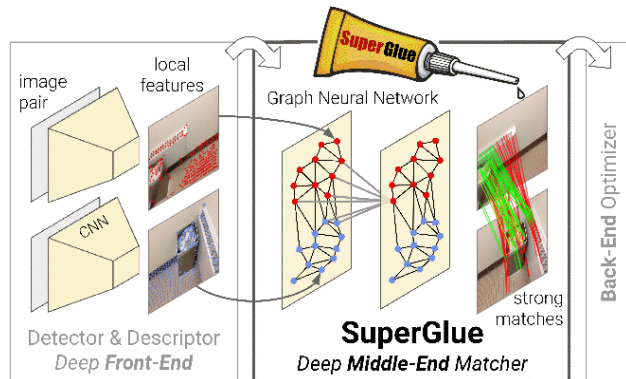
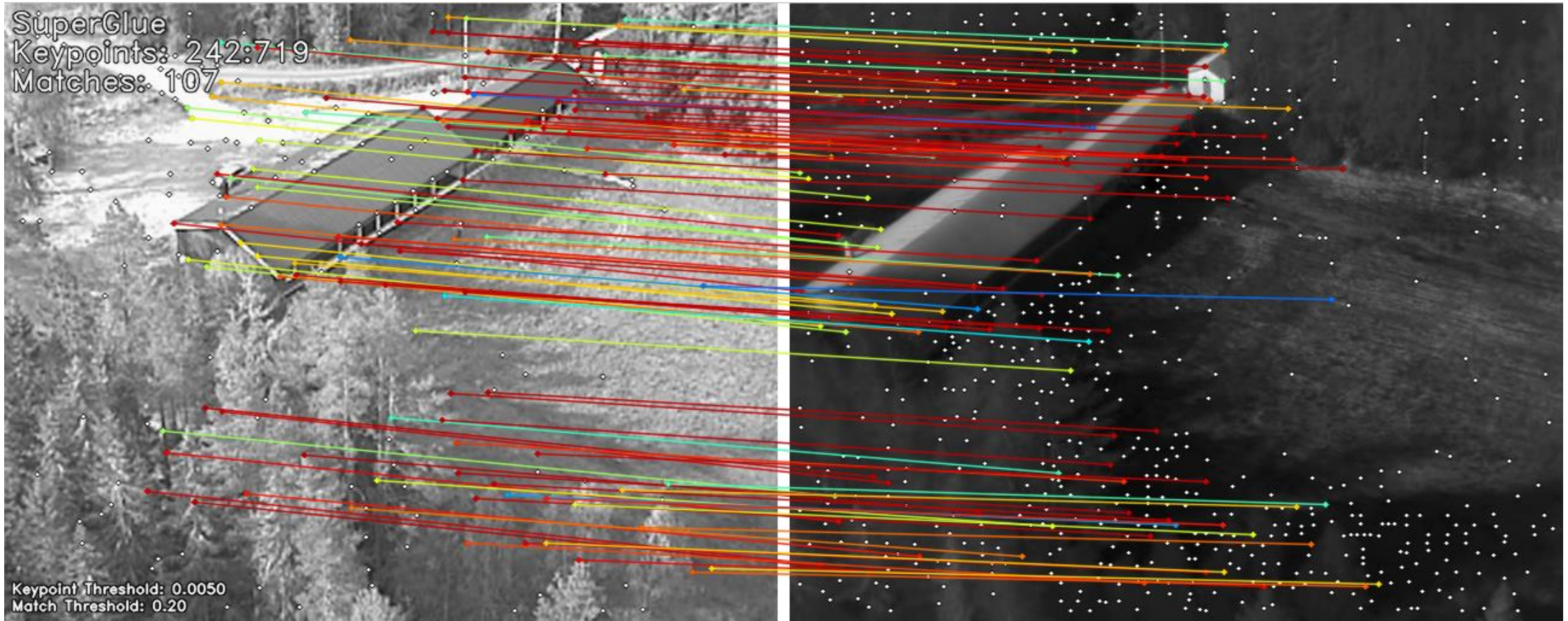






Sarlin, P. E., Detone, D., Malisiewicz, T., & Rabinovich, A. (2020). SuperGlue: Learning Feature Matching with Graph Neural Networks. Proceedings of the IEEE Computer Society Conference on Computer Vision and Pattern Recognition, 4937–4946.

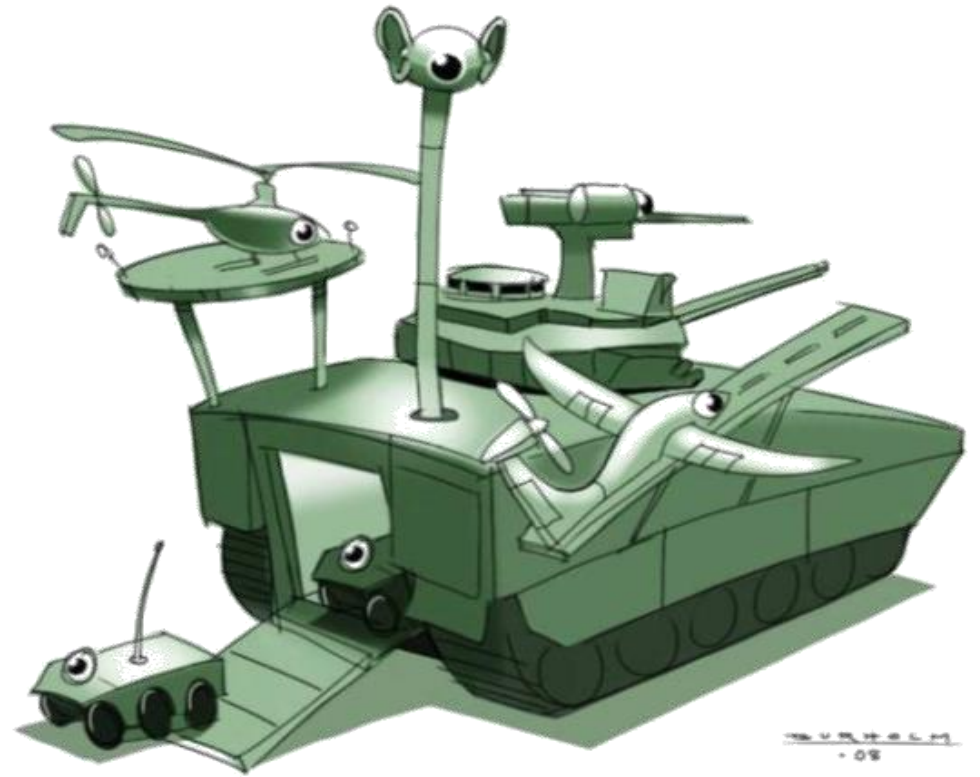
<https://psarlin.com/superglue/>



Sarlin, P. E., Detone, D., Malisiewicz, T., & Rabinovich, A. (2020).  
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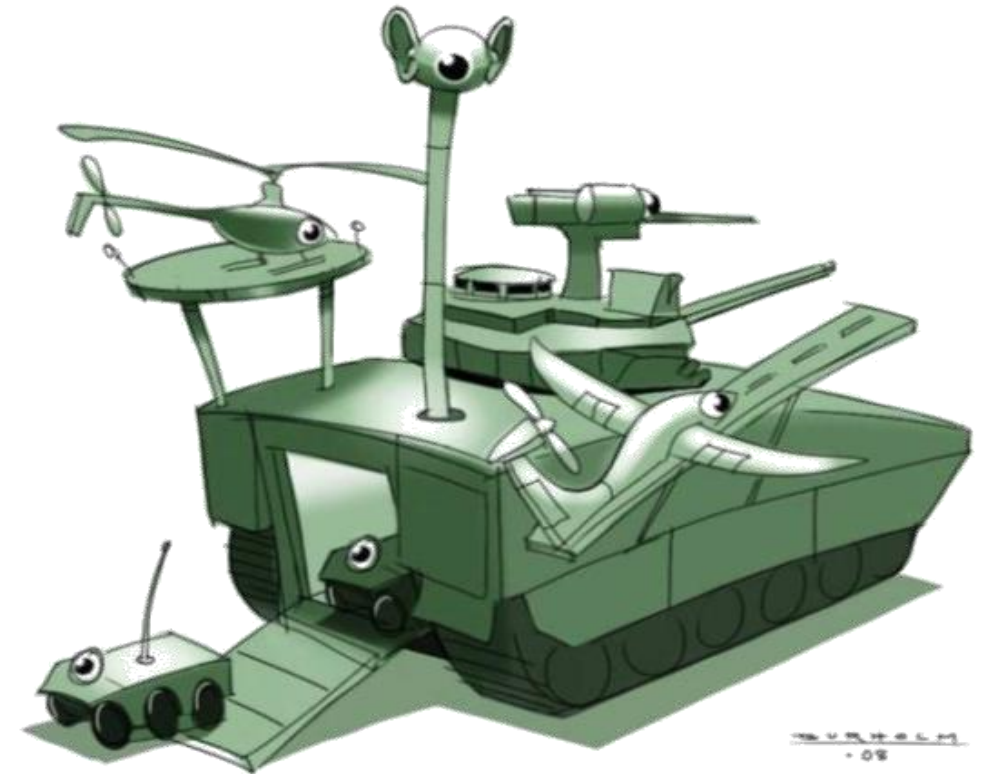
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# What is computer vision?



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The study of how a machine  
can interpret and understand its surroundings  
from images

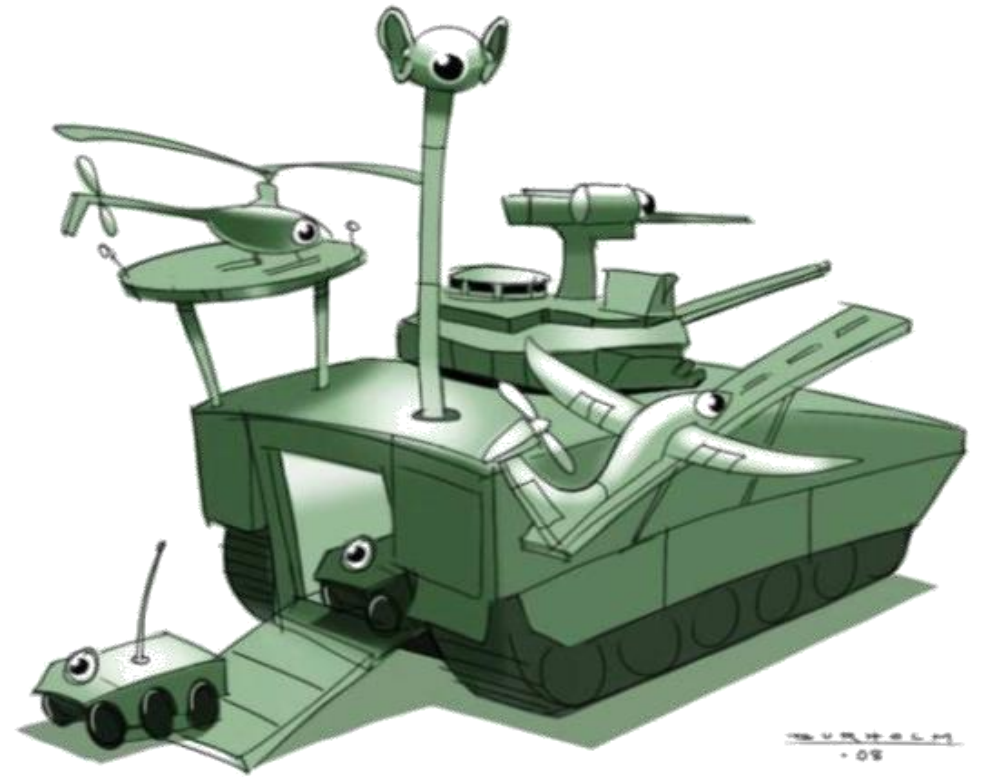




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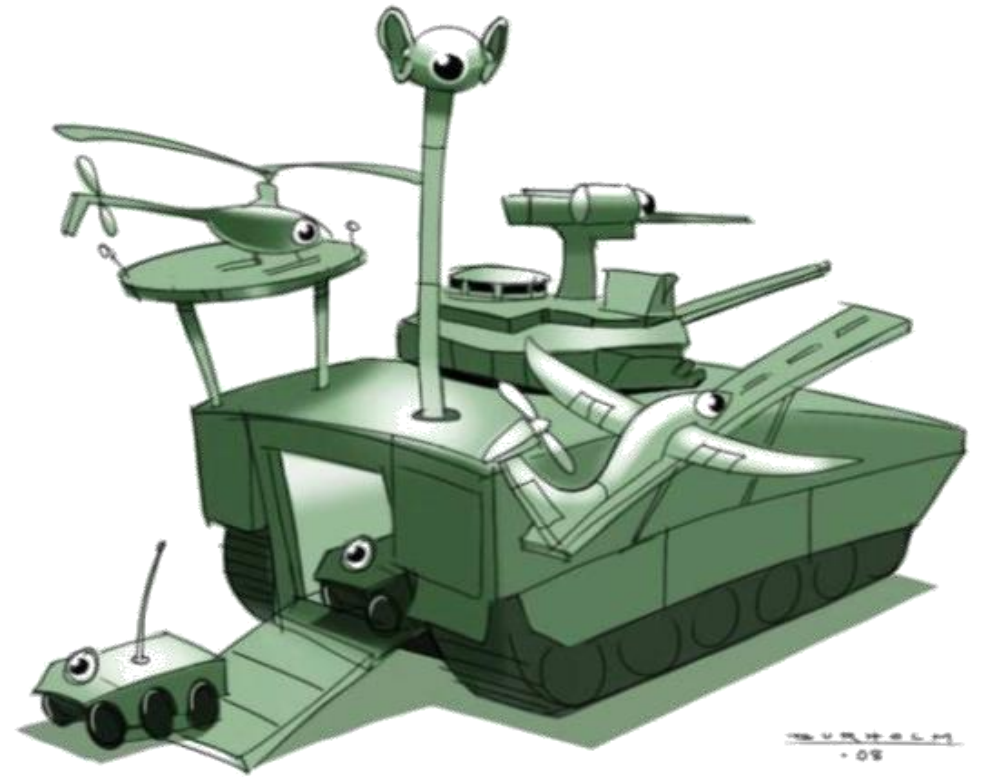
- “Enabling computers to see”



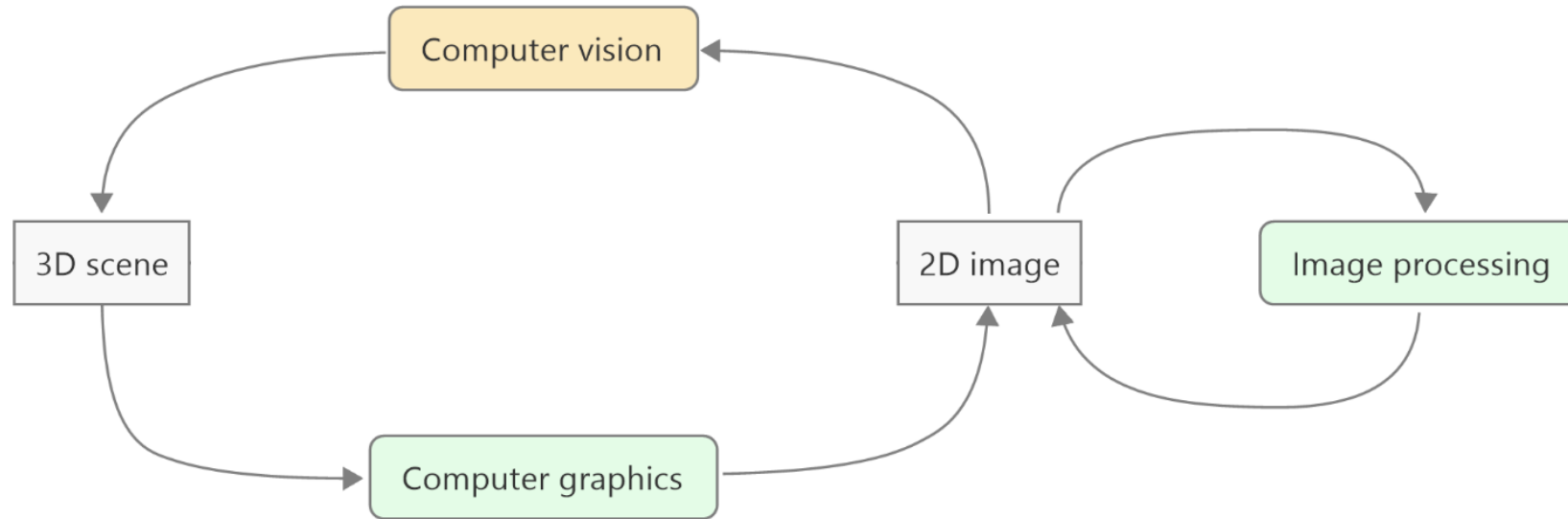
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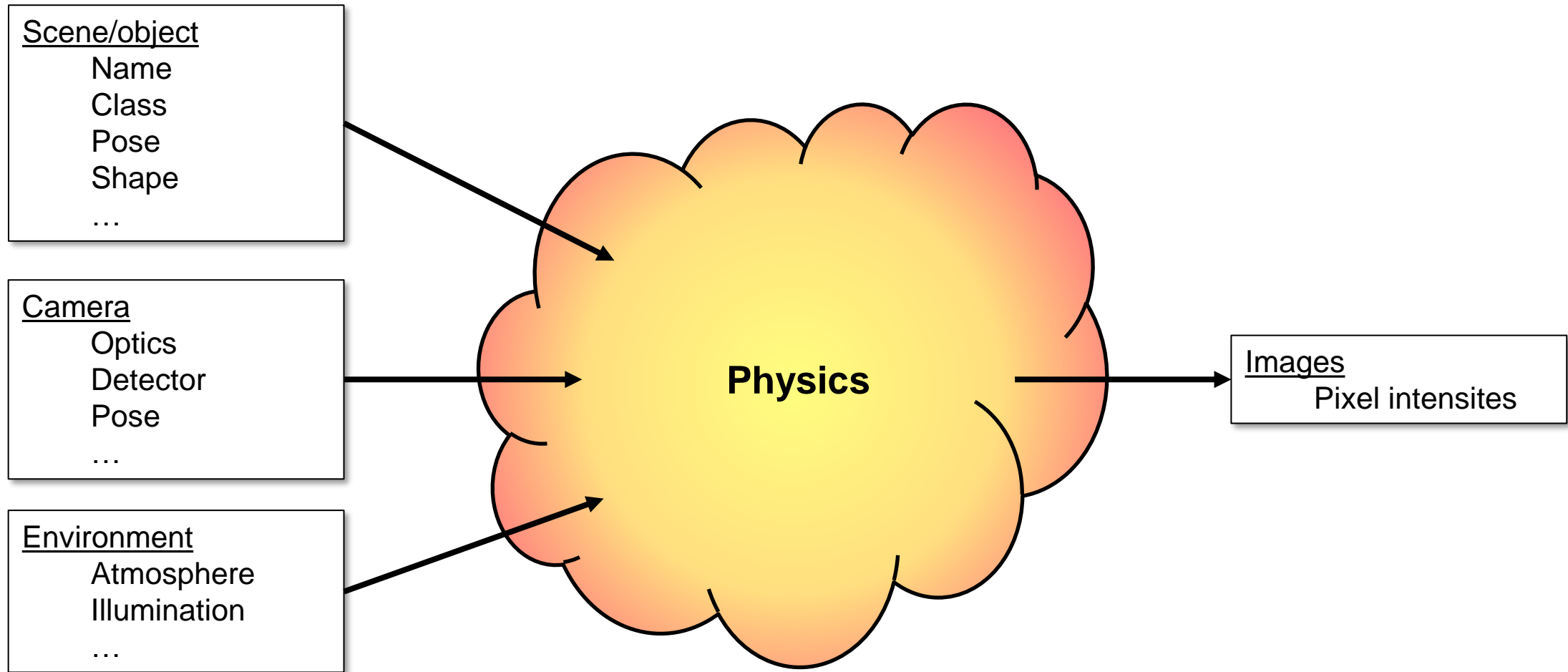
- “Enabling computers to see”
- Image analysis
- Robotic vision
- Perception
- Spatial AI



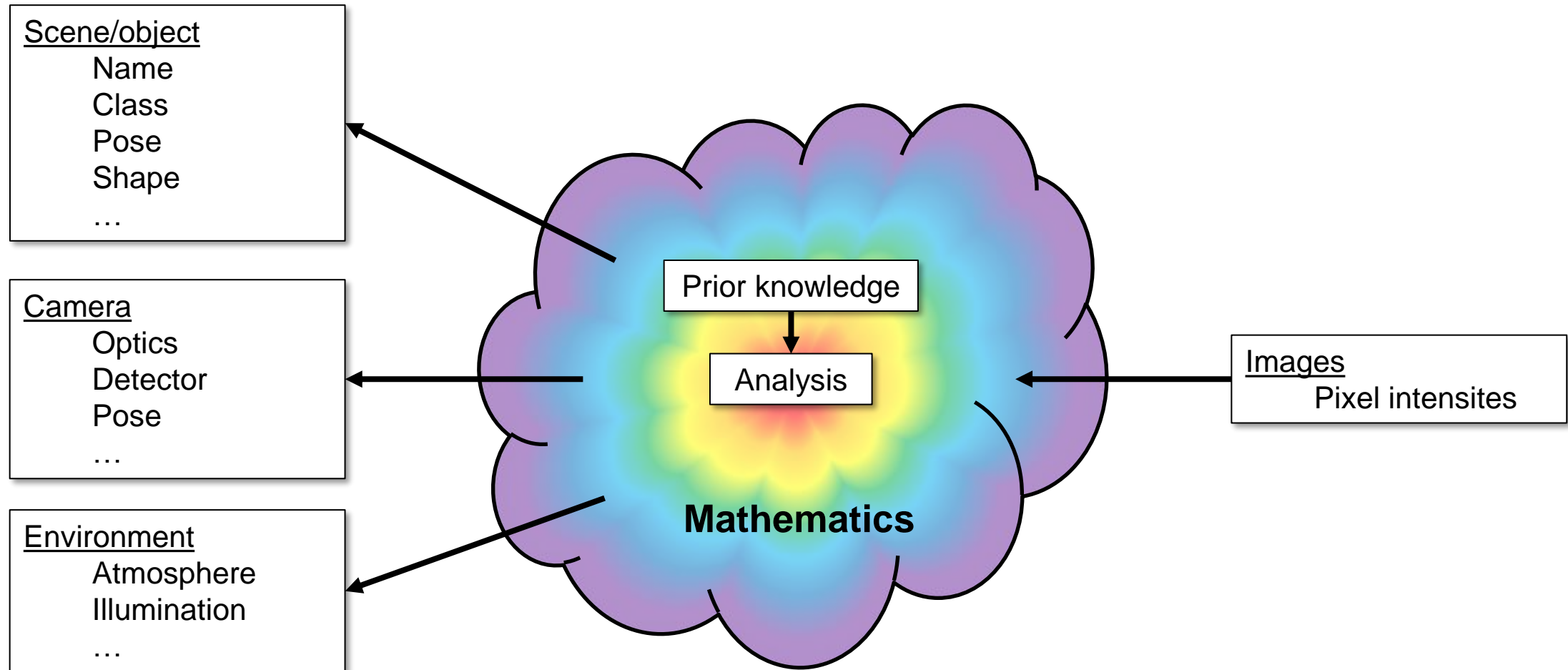
# Computer vision is an *inverse problem*!



# The *forward* imaging process



# The *inverse* analysis process



# About the course

# Course sites

- [The semester page](#)

- Course plan
- Lecture slides and videos
- Lab exercises

- [Canvas](#)

- Course overview
- Zoom links
- Project deliveries

- [Discourse](#)

- Announcements
- Questions
- Discussions

TEK5030 - Vår 2023

### Timeplan

Fellesundervisning

Forelesninger - fre. 09:15-12:00 [Abonner på disse aktivitetene](#)

Dato	Tid	Aktivitet	Sted	Foreleser	Ressurser/pensum
8. 27. jan	09:15-12:00	Live lecture and lab	GR19 Auditorium	• I. Dynal • T. Haavardsholm • T. Opsahl	Week 1: Introduction
8. 3. feb	09:15-12:00	Lab based on pre-recorded lecture	GR19 Auditorium	• I. Dynal	Week 2: Image formation
8. 10. feb	09:15-12:00	Lab based on pre-recorded lecture	GR19 Auditorium		
8. 17. feb	09:15-12:00	Lab based on pre-recorded lecture	GR19 Auditorium		

TEK5030 19V Maskinsyn

UiO Institutt for teknologisystemer  
Det matematiske-naturvitenskapelige fakultet

TEK5030: Maskinsyn - Våren 2019

UiO Discourse

TEK5030-24V

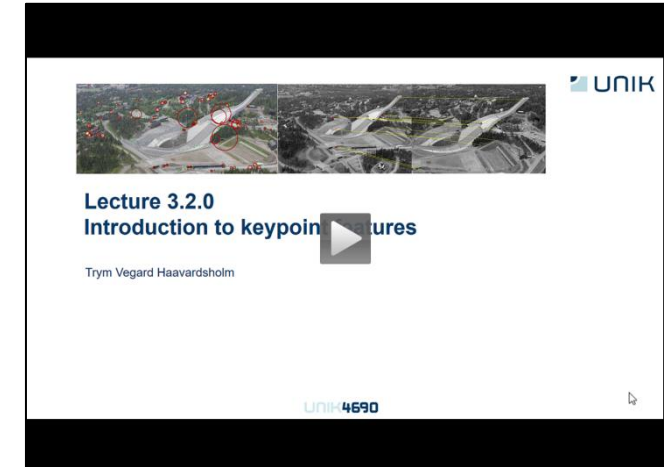
Administrative beskjeder | Eksamen | Obliger | Forelesninger

Topic: About the TEK5030-24V category

There are no more TEK5030-24V topics. Ready to start a new conversation?

# «Flipped classroom»

- Purpose
  - Get as much as possible out of a day at Kjeller
- Online
  - Pre-recorded lectures most weeks
- Fridays 09:15-12:00
  - ~20 min lecture summary and questions
  - ~2.5 hours programming lab

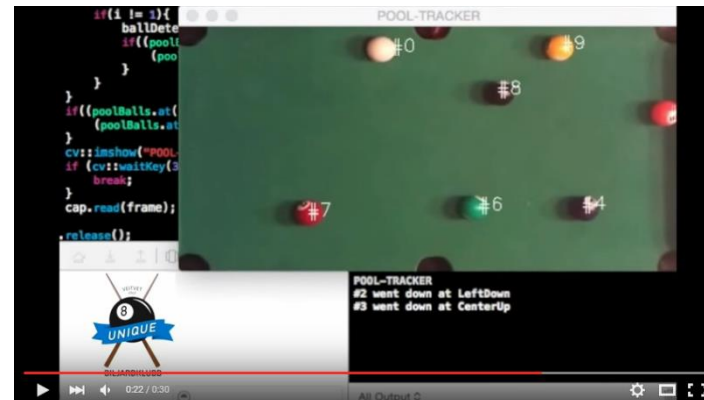
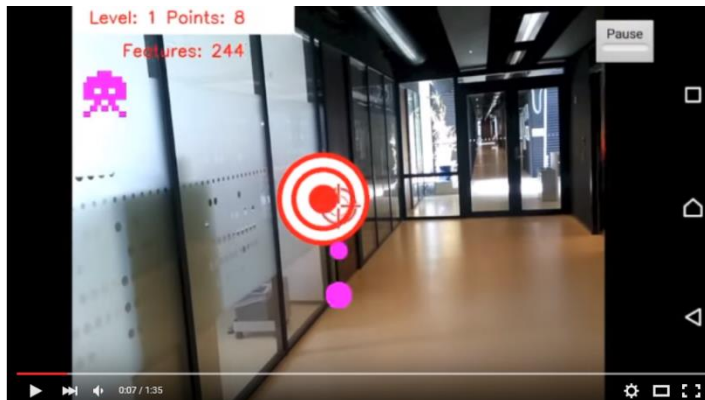
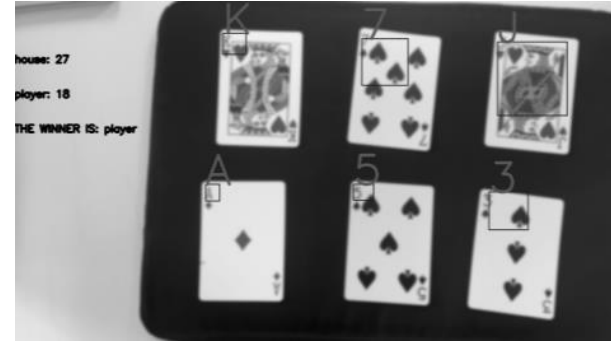


```
1 #include "opencv2/highgui.hpp"
2 #include <iostream>
3
4 int main()
5 {
6     cv::VideoCapture input_stream(0);
7
8     if (!input_stream.isOpened())
9     {
10         std::cerr << "Could not open camera\n";
11         return EXIT_FAILURE;
12     }
13
14     const std::string window_title = "Lab 0: Introduction to OpenCV";
15     cv::namedWindow(window_title, cv::WINDOW_NORMAL);
16
17     cv::Mat frame;
18
19     while(true)
20     {
21         input_stream >> frame;
22
23         if (frame.empty())
24             { break; }
25
26         cv::imshow("cam", frame);
27
28         if (cv::waitKey(15) >= 0)
29             { break; }
30     }
31
32     return EXIT_SUCCESS;
33 }
34
```



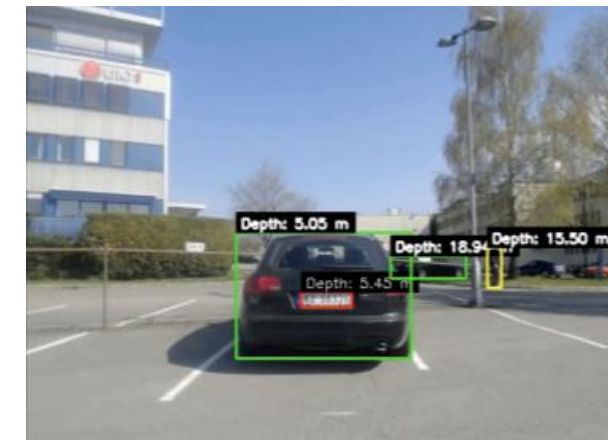
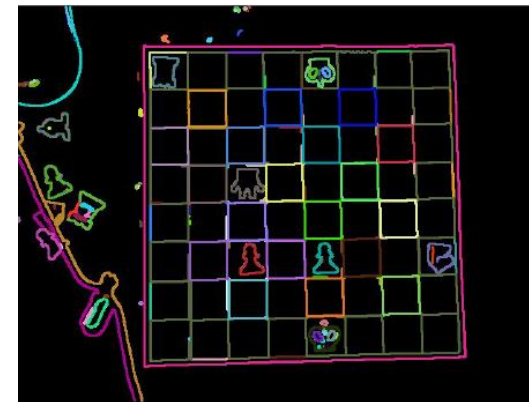
# Student projects

- Develop a working computer vision system that does something interesting
  - Big: More than a month
  - Approved/Not approved
- Project topic of your own choice
- Preferably in groups of up to 3 persons



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# Exam

- Written or oral exam
- Mid-June



# Feedback

- We encourage feedback during the course
  - We are open to making adjustments!
- Please fill out and deliver the course evaluation form after the course!
- Any feedback or questions now?

