# Compulsory Project 2 <br> MAT-INF3100 Linear optimization, Spring 2017 

- NOTE. Send the project by Thursday April 20th, 14:30, to Torkel Haufmann (torkelah@math.uio.no) or deliver in Devilry. The hand-in should be a PDF file that you name "username.pdf" (your username!). Also attach your computer code, either as a listing in the PDF file or (preferably) as separate files. Moreover, you should read the general information about compulsory projects at the course web page.


## Problem 1

1a)
Consider the linear programming problem

$$
\begin{equation*}
\max c^{T} x, \quad \text { subject to } A x \leq b, x \geq 0 \tag{1}
\end{equation*}
$$

where $A \in \mathbb{R}^{m \times n}, b \in \mathbb{R}^{m}$, and $x, c \in \mathbb{R}^{n}$. State the weak and strong duality theorems. Moreover, prove the weak duality theorem.

## 1b)

Let $x=\left(x_{1}, x_{2}, \ldots, x_{n}\right)^{T}$ be primal feasible and $y=\left(y_{1}, y_{2}, \ldots, y_{m}\right)^{T}$ dual feasible. Denote by $\left(w_{1}, w_{2}, \ldots, w_{m}\right)$ the corresponding primal slack variables and $\left(z_{1}, z_{2}, \ldots, z_{n}\right)$ the corresponding dual slack variables. Suppose $x$ is optimal for the primal problem and $y$ is optimal for the dual problem. State and prove the complementary slackness equations.

## 1c)

Consider the linear programming problem

$$
\begin{array}{lll}
\operatorname{maximize} & 3 x_{1}+2 x_{2} \\
\text { subject to } & \\
& 2 x_{1}+x_{2} \leq 4,  \tag{2}\\
& 2 x_{1}+3 x_{2} \leq 6, \\
& x_{1}, x_{2} \geq 0
\end{array}
$$

Show that $x^{\star}=(3 / 2,1)$ is primal feasible and $y^{\star}=(5 / 4,1 / 4)$ is dual feasible. Moreover, show that $x^{\star}$ is in fact an optimal solution of (2).

## Problem 2

## 2a)

Let $A \in \mathbb{R}^{m \times n}$ and $b \in \mathbb{R}^{m}$. Consider the linear programming problem

$$
\begin{equation*}
\max 0^{T} x, \quad \text { subject to } A x=b, x \geq 0 \tag{P}
\end{equation*}
$$

where 0 denotes the $m$-dimensional null vector. Show that the dual of $(P)$ is

$$
\begin{align*}
& \min b^{T} y \\
& \text { subject to } A^{T} y \geq 0 . \tag{D}
\end{align*}
$$

## 2b)

Let $A \in \mathbb{R}^{m \times n}$ and $b \in \mathbb{R}^{m}$. Farkas' Lemma states that exactly one of the following two systems has a solution:

$$
\begin{array}{cc}
A x=b, & x \geq 0 \\
A^{T} y \geq 0, & b^{T} y<0 . \tag{S2}
\end{array}
$$

Use the weak/strong duality theorems for (P) and (D) to prove Farkas' Lemma.

## Problem 3

Consider the linear programming problem in (standard) matrix form

$$
\begin{equation*}
\max c^{T} x, \quad \text { subject to } A x \leq b, x \geq 0 \tag{3}
\end{equation*}
$$

In this exercise you will program two algorithms for solving this problem.
The simplex method in matrix form Detailed in Section 6.2 of the book. The function should be called simplex, take $A, b$ and $c$ as arguments, and return the optimal solution $x$.

The path-following method Presented in figure 18.1 (you will need to consult chapters 17-19 for more details). The function should be called interior, take $A, b$ and $c$ as arguments (and perhaps a tolerance $\epsilon$ ), and return the optimal solution $x$.

To simplify somewhat we will assume $b \geq 0$, so you do not have to implement a two-phase method. Your solution should contain the following:

- The code for both algorithms, preferably as separate files.
- A test run using the data files made available alongside this assignment print out a line of information for each iteration (or every few iterations).
- A brief discussion and comparison of your results with the two algorithms.

You may choose whatever language you like, but we recommend Python or MATLAB.

Some tips:

- The optimal solution value for the test problem is $\approx 321.4047$.
- When solving a linear system $V x=d$ do not use the inv(V) command (or similar in your language of choice) - rather, use the backslash operator: $\mathrm{x}=\mathrm{V} \backslash \mathrm{d}$.
- The major part of the work for the interior-point algorithm is solving the $K K T$-system to find the steps $\Delta x, \Delta y, \Delta z$ and $\Delta w$. There are various ways to do this, but we suggest the normal equations in primal form, see the start of Section 19.2 in the book (equation (19.9)).
- If you are using MATLAB, you can get the $A, b$ and $c$ matrices from the .mat file using the command load('matinf3100oblig2.mat').
- In Python, assuming you have imported numpy as np, you can use the following commands to read the data from the text files:
$\mathrm{c}=\mathrm{np} . \operatorname{loadtxt('c.txt}$, delimiter $=,, ')$
A $=$ np.loadtxt ('A.txt', delimiter $=,, ')$
$\mathrm{b}=\mathrm{np}$. loadtxt('b.txt', delimiter $=,, ')$
- The test problem is quite large, so it might be a good idea to develop against a simpler problem at first - see for example pages 96-101 in Vanderbei (2nd ed.).

