

Sek. 1.9 (lineær-avbildninger)

Sedning 1.9.5 La $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ er en lin. avb., da fins en unik matrise A slik at A en $(m \times n)$ -matrise

$$T(\vec{x}) = A\vec{x}$$

Søyle nr. j i A er lik $T(\vec{e}_j) \in \mathbb{R}^m$

Oppg. 1.9.1 $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ lin. avb gitt ved

$$T(x, y, z) = \begin{pmatrix} 2x - y + z \\ -x + y - 3z \end{pmatrix}$$

Finn A .

Svar: $T(\vec{e}_1) = T(1, 0, 0) = \begin{pmatrix} 2 \\ -1 \end{pmatrix}$

$$T(\vec{e}_2) = T(0, 1, 0) = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$T(\vec{e}_3) = T(0, 0, 1) = \begin{pmatrix} 1 \\ -3 \end{pmatrix}$$

$$\underline{\underline{A = \begin{pmatrix} 2 & -1 & 1 \\ -1 & 1 & -3 \end{pmatrix}}}$$

Oppg. 1.9.2 $T: \mathbb{R}^2 \rightarrow \mathbb{R}^4$ lin. avb. slik at.

$$T(\vec{e}_1) = \begin{pmatrix} -1 \\ 2 \\ -3 \\ 4 \end{pmatrix} \quad T(\vec{e}_2) = \begin{pmatrix} 0 \\ -2 \\ 4 \\ 7 \end{pmatrix}$$

Finne A

Svar (1.9.5) $A = \begin{pmatrix} -1 & 0 \\ 2 & -2 \\ -3 & 4 \\ 4 & 7 \end{pmatrix}$

Oppg. 1.9.3 La $\vec{a}, \vec{b} \in \mathbb{R}^2$. La $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ være en lin. avb. slik at

$$T(\vec{a}) = \begin{pmatrix} -2 \\ 1 \end{pmatrix} \quad T(\vec{b}) = \begin{pmatrix} 0 \\ 3 \end{pmatrix}$$

Finne $T(3\vec{a} - 2\vec{b})$. T lin. avb. $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$

Svar: Setning 1.9.2: $T(c_1\vec{x}_1 + c_2\vec{x}_2 + \dots + c_n\vec{x}_n) = c_1T(\vec{x}_1) + c_2T(\vec{x}_2) + \dots + c_nT(\vec{x}_n)$
for alle $c_i \in \mathbb{R}$ $\vec{x}_i \in \mathbb{R}^n$

Bruker dette:

$$\begin{aligned} T(3\vec{a} - 2\vec{b}) &= 3T(\vec{a}) - 2T(\vec{b}) \\ &= 3 \begin{pmatrix} -2 \\ 1 \end{pmatrix} - 2 \begin{pmatrix} 0 \\ 3 \end{pmatrix} = \underline{\underline{\begin{pmatrix} -6 \\ -3 \end{pmatrix}}}. \end{aligned}$$

Oppg. 1.9.5 $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ lin. avb. som fordobler andrekomponent, bevarer første komponent. Finne A

Svar: $T(x, y) = \begin{pmatrix} x \\ 2y \end{pmatrix}$

$$T(\vec{e}_1) = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$T(\vec{e}_2) = \begin{pmatrix} 0 \\ 2 \end{pmatrix}$$

$$A = \underline{\underline{\begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix}}}$$

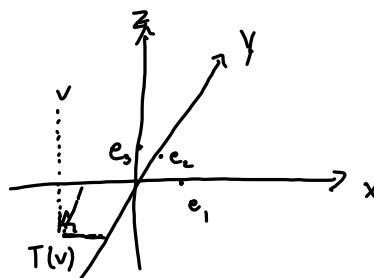
Oppg. 1.9.7 Lin. avb. $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ avbilder en vektor på sin projeksjon i xy -planet. Finne A.

Svar: $T(\vec{e}_1) = \vec{e}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$

$$T(\vec{e}_2) = \vec{e}_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

$$T(\vec{e}_3) = \vec{0} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$A = \underline{\underline{\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}}}$$



Seksjon 1.10 (affinavbildninger)

Def 1.10.1 En funksjon $F: \mathbb{R}^n \rightarrow \mathbb{R}^m$ er en affinavbildning hvis det fins en $(m \times n)$ -matrise A og en vektor $\vec{c} \in \mathbb{R}^m$ slik at

$$F(\vec{x}) = A\vec{x} + \vec{c} \quad \text{for alle } \vec{x} \in \mathbb{R}^n.$$

Oppg. 1.10.1 $F: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ aff. avb. slik at

$$F(x, y, z) = \begin{pmatrix} 2x - 3y + z - 7 \\ -x + z - 2 \end{pmatrix}$$

Finn A & \vec{c} .

Svar: $F(\vec{0}) = A\vec{0} + \vec{c} = \vec{c}$

$$\vec{c} = F(0, 0, 0) = \begin{pmatrix} -7 \\ -2 \end{pmatrix}$$

Søyle nr. j i A er lik $A\vec{e}_j$ $F(x) = Ax + c$

$$A\vec{e}_j = F(\vec{e}_j) - \vec{c}$$

$$A\vec{e}_1 = F(\vec{e}_1) - \vec{c} = F(1, 0, 0) - \vec{c} = \begin{pmatrix} -5 \\ -3 \end{pmatrix} - \begin{pmatrix} -7 \\ -2 \end{pmatrix} = \begin{pmatrix} 2 \\ -1 \end{pmatrix}$$

$$A\vec{e}_2 = F(\vec{e}_2) - \vec{c} = \begin{pmatrix} -3 \\ 0 \end{pmatrix}$$

$$A\vec{e}_3 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$A = \begin{pmatrix} 2 & -3 & 1 \\ -1 & 0 & 1 \end{pmatrix}$$

Oppg. 1.10.3 $F: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ aff. avb. slik at

$$F(0, 0) = \begin{pmatrix} 1 \\ -1 \end{pmatrix} \quad F(1, 0) = \begin{pmatrix} 2 \\ 3 \end{pmatrix} \quad F(0, 1) = \begin{pmatrix} -1 \\ 0 \end{pmatrix}$$

Finn A & \vec{c}

Svar: $F(x) = Ax + c$

$$c = F(0) = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$A\vec{e}_1 = F(\vec{e}_1) - \vec{c} = \begin{pmatrix} 2 \\ 3 \end{pmatrix} - \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 1 \\ 4 \end{pmatrix}$$

$$A\vec{e}_2 = \begin{pmatrix} -2 \\ 1 \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & -2 \\ 4 & 1 \end{pmatrix}$$

Oppg. 1.10.5a) $F: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ affinavb. som avbilder hvert punkt på sitt speilbilde om linja $x=3$.

Finn A og \vec{c}

Svar:

$$F(\vec{x}) = A\vec{x} + \vec{c}$$

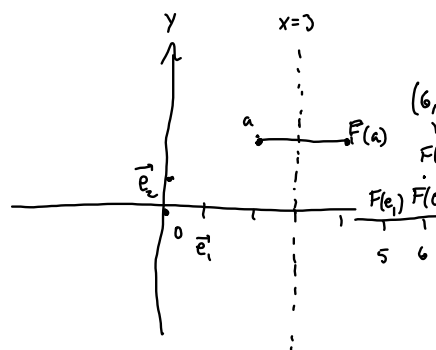
$$\vec{c} = F(\vec{0}) = \begin{pmatrix} 6 \\ 0 \end{pmatrix}$$

$$A\vec{e}_1 = F(\vec{e}_1) - \vec{c}$$

$$= \begin{pmatrix} 5 \\ 0 \end{pmatrix} - \begin{pmatrix} 6 \\ 0 \end{pmatrix} = \begin{pmatrix} -1 \\ 0 \end{pmatrix}$$

$$A\vec{e}_2 = F(\vec{e}_2) - \vec{c} = \begin{pmatrix} 6 \\ 1 \end{pmatrix} - \begin{pmatrix} 6 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$A = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$$



Seksjon 2.7 (Kjernerregelen)

Oppg. 2.7.1 La $f(u,v) = u^2 + v$, $g(x,y) = 2xy$, $h(x,y) = x + y^2$.

Finn de partiellderiverte av $k(x,y) = f(g(x,y), h(x,y))$ ved hjelp av Kjernerregelen.

Svar: $k(x,y) = g(x,y)^2 + h(x,y) = 4x^2y^2 + x + y^2$

Kjernerregelen gir

$$\frac{\partial k}{\partial x}(x,y) = \frac{\partial f}{\partial u}(g(x,y), h(x,y)) \cdot \frac{\partial g}{\partial x}(x,y) + \frac{\partial f}{\partial v}(g(x,y), h(x,y)) \cdot \frac{\partial h}{\partial x}(x,y)$$

$$\frac{\partial f}{\partial u} = 2u \quad \frac{\partial f}{\partial v} = 1$$

$$\frac{\partial g}{\partial x} = 2y \quad \frac{\partial h}{\partial x} = 1 \quad \frac{\partial g}{\partial y} = 2x \quad \frac{\partial h}{\partial y} = 2y$$

$$\begin{aligned} \frac{\partial k}{\partial x}(x,y) &= 2u \cdot 2y + 1 \cdot 1 && (u = g(x,y)) \\ &= 2 \cdot 2xy \cdot 2y + 1 = \underline{\underline{8xy^2 + 1}}. \end{aligned}$$

$$\begin{aligned} \frac{\partial k}{\partial y}(x,y) &= \frac{\partial f}{\partial u}(g(x,y), h(x,y)) \cdot \frac{\partial g}{\partial y}(x,y) \\ &+ \frac{\partial f}{\partial v}(g(x,y), h(x,y)) \cdot \frac{\partial h}{\partial y}(x,y) \\ &= 2u \cdot 2x + 1 \cdot 2y = 2 \cdot 2xy \cdot 2x + 2y \\ &= \underline{\underline{8x^2y + 2y}}. \end{aligned}$$

Oppg. 2.7.5 $G: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ & $F: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ er deriverbare funksjoner. Anta $G(1,-2) = (1, 2, 3)$ og

$$G'(1,-2) = \begin{pmatrix} 1 & -2 \\ 3 & 1 \\ 2 & -1 \end{pmatrix} \quad F'(1,2,3) = \begin{pmatrix} 2 & 1 & 4 \\ 0 & 2 & 2 \end{pmatrix}$$

La $H(\vec{x}) = F(G(\vec{x}))$, finn Jacobi-matrisen $H'(1,-2)$.

Svar: Kjernerregelen på matriseform sier

$$H'(\vec{x}) = F'(G(\vec{x})) G'(\vec{x})$$

$$\text{Sett } \vec{x} = \begin{pmatrix} 1 \\ -2 \end{pmatrix}$$

$$\begin{aligned} H'(1,-2) &= F'(G(1,-2)) G'(1,-2) \\ &= F'(1,2,3) G'(1,-2) \\ &= \begin{pmatrix} 2 & 1 & 4 \\ 0 & 2 & 2 \end{pmatrix} \begin{pmatrix} 1 & -2 \\ 3 & 1 \\ 2 & -1 \end{pmatrix} = \underline{\underline{\begin{pmatrix} 13 & -7 \\ 16 & 0 \end{pmatrix}}}. \end{aligned}$$

Seksjon 2.8 (Linearisering)

Def. 2.8.2 Gitt en funksjon $F: \mathbb{R}^n \rightarrow \mathbb{R}^k$, deriverbar i $\vec{a} \in \mathbb{R}^n$, så er lineariseringen til F i \vec{a} affinabbildningen $T_{\vec{a}} F: \mathbb{R}^n \rightarrow \mathbb{R}^k$ gitt ved

$$T_{\vec{a}} F(\vec{x}) = F(\vec{a}) + F'(\vec{a}) \cdot (\vec{x} - \vec{a}).$$

Oppg. 2.8.2. La $F: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ være gitt ved

$$F(x, y) = \begin{pmatrix} x \sin(xy) \\ x e^y \\ 2x^2 + y \end{pmatrix}$$

Finu $T_{\vec{a}} F$ for $\vec{a} = \begin{pmatrix} 2 \\ 0 \end{pmatrix}$.

Svar: $F(\vec{a}) = F(2, 0) = \begin{pmatrix} 2 \sin(2 \cdot 0) \\ 2 e^0 \\ 2 \cdot 2^2 + 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 2 \\ 16 \end{pmatrix}$

$$F'(\vec{x}) = \begin{pmatrix} \sin(xy) + x \cdot y \cos(xy) & x^2 \cos(xy) \\ e^y & x e^y \\ 6x^2 & 1 \end{pmatrix}$$

$$F'(2, 0) = \begin{pmatrix} \sin(0) + 2 \cdot 0 \cdot \cos(0) & 2^2 \cos(0) \\ e^0 & 2 e^0 \\ 6 \cdot 2^2 & 1 \end{pmatrix} \\ = \begin{pmatrix} 0 & 4 \\ 1 & 2 \\ 24 & 1 \end{pmatrix}$$

$$T_{\vec{a}} F = F(\vec{a}) + F'(\vec{a})(\vec{x} - \vec{a}) \\ = \begin{pmatrix} 0 \\ 2 \\ 16 \end{pmatrix} + \begin{pmatrix} 0 & 4 \\ 1 & 2 \\ 24 & 1 \end{pmatrix} \left(\vec{x} - \begin{pmatrix} 2 \\ 0 \end{pmatrix} \right) \\ = \begin{pmatrix} 0 & 4 \\ 1 & 2 \\ 24 & 1 \end{pmatrix} \vec{x} + \begin{pmatrix} 0 \\ 2 \\ 16 \end{pmatrix} - \begin{pmatrix} 0 & 4 \\ 1 & 2 \\ 24 & 1 \end{pmatrix} \begin{pmatrix} 2 \\ 0 \end{pmatrix} \\ = \begin{pmatrix} 0 & 4 \\ 1 & 2 \\ 24 & 1 \end{pmatrix} \vec{x} + \begin{pmatrix} 0 \\ 2 \\ 16 \end{pmatrix} - \begin{pmatrix} 0 \\ 2 \\ 48 \end{pmatrix} \\ = \begin{pmatrix} 0 & 4 \\ 1 & 2 \\ 24 & 1 \end{pmatrix} \vec{x} + \begin{pmatrix} 0 \\ 0 \\ -32 \end{pmatrix}$$

\uparrow \quad \uparrow
 A \quad \vec{c}