

Chapter 4: efficiency of the simplex algorithm

- ▶ how to measure **efficiency**?
- ▶ worst case analysis, **the Klee-Minty cube**
- ▶ **mean analysis** and in practise

Status

How far are we now in our LP story?

- ▶ simplex method (Phase I and II)
- ▶ problems: degeneracy and cycling
- ▶ solution: anticycling rules, perturbations
- ▶ the fundamental theorem of LP

Next question: how good is the simplex algorithm ?

But: first a bit on equivalent optimization problems!

Equivalent optimization problems

Often it is useful to rewrite an optimization problem into a more convenient form. Then it is important to end up with an “equivalent optimization problem”. Let us clarify what this means.

Let P and Q denote two optimization problems, with variable vectors $x \in \mathbb{R}^n$ in P and $y \in \mathbb{R}^k$ in Q . Here n and k may be different.

We say that P and Q are **equivalent** if

1. P is feasible if and only if Q is feasible.
2. P is unbounded if and only if Q is unbounded.
3. P has an optimal solution if and only if Q has an optimal solution. Furthermore, there is a function $f : \mathbb{R}^n \rightarrow \mathbb{R}^k$ such that x is optimal in P if and only if $f(x)$ is optimal in Q .

Note that one can prove that there is a **symmetry** here: it does not matter if the order of P and Q is interchanged in this definition.

As an example, and an exercise, consider the problems

$$P: \max\{c^T x : Ax \leq b\}$$

$$Q: \max\{c^T(x' - x'') : A(x' - x'') \leq b, x', x'' \geq 0\}$$

Show that P and Q are equivalent!

LP problems may, for instance, have some variables that are nonnegative (or nonpositive), some variables that are free; there may be inequalities (\leq og \geq), and equations. Learn how to rewrite such problems into equivalent LP's.

Efficiency

Two types of efficiency measures exist for algorithms:

- ▶ **worst case:** the maximum number of arithmetic operations for problem (instances) of a given size.
- ▶ **mean (average):** the mean of expected number of arithmetic operations for problem (instances) of a given size.

LP: the computational time increases when the number of variables or constraints is increased. So computational time is some function of “problem size”.

How can we measure problem size?

- ▶ *simple approach:* counting the numbers in input, i.e., $m \times (n + 1)$ in LP. Weakness: in “real problems” (where m and n are large) many entries in the coef. matrix are zero. This may be exploited in the simplex algorithm to speed up the computations.

- ▶ *more accurate*: the number of nonzeros. Weakness: arithmetic operations with large numbers take longer time than they do for smaller numbers. (I would rather compute $14 \cdot 7$ than $832573928 \cdot 3722984$, right!)
- ▶ *even more accurate*: the number of bits needed to store all the numbers on the computer.

How can we measure the **total work (complexity)** of an algorithm?

- ▶ computational time (CPU)
- ▶ the number of iterations
- ▶ the number of elementary arithmetic operations.

Our choice here: we simply use m and n as measures of problem size and **the number of pivots** as complexity measure.

Want to consider **worst case analysis** of the simplex algorithm. The answer will be, unfortunately, that the method in theory is not good. In practice, however, the situation is the opposite: the method works excellently!

The “explanation”: the “hard LP problems” do not show up in real world problems.

In 1972 **V.Klee and G.J.Minty** found a class of LP problems that “kills” the simplex algorithm with the usual pivot rule (largest coefficient rule).

The LP problem has n variables and it turns out that the number of pivots required is $2^n - 1$. Thus, the number of pivots grows exponentially fast in n (the number of variables). Even for moderate values of n this number of iterations is hopelessly big! To indicate this, consider the following table given computational time for (assuming one million pivots per second, which is very optimistic!):

n :	10	20	50	100
n^2 :	100	400	2500	10000
2^n :	1024	1048576	1.125899e+15	1.267650e+30
tid	0.001 sec.	1.0 sec.	35 years	4.0e+16 years

We shall investigate this LP problem. The idea is to deform the cube $[0, 1]^n$ in \mathbb{R}^n in such a way that the simplex algorithm is forced to go through all the 2^n vertices! **This gives $2^n - 1$ pivots.**

Here is the Klee-Minty LP problem:

$$\max \sum_{j=1}^n 10^{n-j} x_j$$

s.t.

$$2 \sum_{j=1}^{i-1} 10^{i-j} x_j + x_i \leq 100^{i-1} \quad \text{for } i = 1, \dots, n$$
$$x_j \geq 0 \quad \text{for } j = 1, \dots, n.$$

Interpretation of the constraints:

- ▶ $i = 1$: $x_1 \leq 1$
- ▶ $i = 2$: $20x_1 + x_2 \leq 100$, so $x_2 \leq 100 - 20x_1 \approx 100$ since $0 \leq x_1 \leq 1$.
- ▶ $i = 3$: $200x_1 + 20x_2 + x_3 \leq 10000$, so $x_3 \leq 10000 - 200x_1 - 20x_2 \approx 10000$ since $0 \leq x_1 \leq 1$ and $0 \leq x_2 \leq 100$.
- ▶ ...

So roughly we have the constraints

$$\begin{aligned}0 &\leq x_1 \leq 1 \\0 &\leq x_2 \leq 100 \\&\vdots \\0 &\leq x_n \leq 100^{n-1}\end{aligned}$$

so that the set P of feasible solutions is roughly an n -dimensional rectangle (cube). P is therefore called the *Klee-Minty cube*.

To simplify the analysis we modify the problem a bit.

- ▶ choose numbers b_i such that $1 = b_1 \ll b_2 \ll \dots \ll b_n$. For instance, choose b_1 so much smaller than b_2 that even if we multiply by certain numbers in the course of the simplex algorithm, the new value of b_1 will still be far less than the new value of b_2 . Think about the b_i 's as independent variables; one can find appropriate values for these later.

- ▶ in the Klee-Minty problem we first replace the right side 100^{i-1} with b_i . Note that the old right sides are increased by a factor of 100 for each new row, and we have kept this intact by the choice of the b_i -s.
- ▶ we then replace the right side b_i by

$$\sum_{j=1}^{i-1} 10^{i-j} b_j + b_i.$$

This is a “minor alteration” because the first term is a lot smaller than b_i (because b_1, \dots, b_{i-1} are suitably small in comparison to b_i .)

- ▶ finally we change the objective function in the LP problem by subtracting

$$(1/2) \sum_{j=1}^{i-1} 10^{n-j} b_j.$$

The result is a **modified Klee-Minty problem**:

$$\max \sum_{j=1}^n 10^{n-j} x_j - (1/2) \sum_{j=1}^{i-1} 10^{n-j} b_j$$

s.t.

$$\begin{aligned} 2 \sum_{j=1}^{i-1} 10^{i-j} x_j + x_i &\leq \sum_{j=1}^{i-1} 10^{i-j} b_j + b_i && \text{for } i \leq n \\ x_j &\geq 0 && \text{for } j \leq n. \end{aligned}$$

Note that the right-hand sides are positive, so we don't need Phase I of the simplex method.

Result: the simplex algorithm with the “largest coefficient pivot rule” uses $2^n - 1$ pivots to solve the modified Klee-Minty problem.

We will let the proof of this be an exercise (Ex. 4.5 and 4.6 in Vanderbei).

We now solve the modified Klee-Minty problem for $n = 3$. Hopefully we will see a pattern which is valid for all n .

Dictionary 0:

$$\begin{array}{r} \eta = -\frac{100}{2}b_1 - \frac{10}{2}b_2 - \frac{1}{2}b_3 + 100x_1 + 10x_2 + x_3 \\ \hline w_1 = b_1 - x_1 \\ w_2 = 10b_1 + b_2 - 20x_1 - x_2 \\ w_3 = 100b_1 + 10b_2 + b_3 - 200x_1 - 20x_2 - x_3 \end{array}$$

Here x_1 will go into basis by the largest coefficient rule. Since b_1 is a lot *smaller* than b_2 and b_3 , w_1 will leave basis. Complete the pivot (check the calculations based on $x_1 = b_1 - w_1$).

Dictionary 1:

$$\begin{array}{r} \eta = \frac{100}{2}b_1 - \frac{10}{2}b_2 - \frac{1}{2}b_3 - 100w_1 + 10x_2 + x_3 \\ \hline x_1 = b_1 - w_1 \\ w_2 = -10b_1 + b_2 + 20w_1 - x_2 \\ w_3 = -100b_1 + 10b_2 + b_3 + 200w_1 - 20x_2 - x_3 \end{array}$$

Fantastic! The new list of basis contains the same numbers apart from some alterations of sign! The alterations are:

- ▶ x_1 and w_1 switched roles
- ▶ only alterations in the two columns for x_1 and b_1
- ▶ and these two columns are multiplied by -1 , apart from in the pivot equation, where there is no alteration of sign

Now x_2 goes in to basis and w_2 out.

Dictionary 2:

$$\begin{array}{rcl}
 \eta & = & -\frac{100}{2}b_1 + \frac{10}{2}b_2 - \frac{1}{2}b_3 + 100w_1 - 10w_2 + x_3 \\
 \hline
 x_1 & = & b_1 - w_1 \\
 x_2 & = & -10b_1 + b_2 + 20w_1 - w_2 \\
 w_3 & = & 100b_1 - 10b_2 + b_3 - 200w_1 + 20w_2 - x_3
 \end{array}$$

Dictionary 3:

$$\begin{array}{r} \eta = \frac{100}{2}b_1 + \frac{10}{2}b_2 - \frac{1}{2}b_3 - 100x_1 - 10w_2 + x_3 \\ \hline w_1 = b_1 - x_1 \\ x_2 = 10b_1 + b_2 - 20x_1 - w_2 \\ w_3 = -100b_1 - 10b_2 + b_3 + 200x_1 + 20w_2 - x_3 \end{array}$$

Dictionary 4:

$$\begin{array}{r} \eta = -\frac{100}{2}b_1 - \frac{10}{2}b_2 + \frac{1}{2}b_3 + 100x_1 + 10w_2 - w_3 \\ \hline w_1 = b_1 - x_1 \\ x_2 = 10b_1 + b_2 - 20x_1 - w_2 \\ x_3 = -100b_1 - 10b_2 + b_3 + 200x_1 + 20w_2 - w_3 \end{array}$$

Dictionary 5:

$$\begin{array}{r} \eta = \frac{100}{2}b_1 - \frac{10}{2}b_2 + \frac{1}{2}b_3 - 100w_1 + 10w_2 - w_3 \\ \hline x_1 = b_1 - w_1 \\ x_2 = -10b_1 + b_2 + 20w_1 - w_2 \\ x_3 = 100b_1 - 10b_2 + b_3 - 200w_1 + 20w_2 - w_3 \end{array}$$

Dictionary 6:

$$\begin{array}{r} \eta = -\frac{100}{2}b_1 + \frac{10}{2}b_2 + \frac{1}{2}b_3 + 100w_1 - 10x_2 - w_3 \\ \hline x_1 = b_1 - w_1 \\ w_2 = -10b_1 + b_2 + 20w_1 - x_2 \\ x_3 = -100b_1 + 10b_2 + b_3 + 200w_1 - 20x_2 - w_3 \end{array}$$

Dictionary 7:

$$\begin{array}{rcllclclcl} \eta & = & \frac{100}{2}b_1 & + & \frac{10}{2}b_2 & + & \frac{1}{2}b_3 & - & 100x_1 & - & 10x_2 & - & w_3 \\ \hline w_1 & = & b_1 & & & & & - & x_1 & & & & \\ w_2 & = & 10b_1 & + & b_2 & & & - & 20x_1 & - & x_2 & & \\ x_3 & = & 100b_1 & + & 10b_2 & + & b_3 & - & 200x_1 & - & 20x_2 & - & w_3 \end{array}$$

Optimal! Therefore: $7 = 2^3 - 1$ pivots.

Observations:

- ▶ in each pivot x_j and w_j switch roles for a certain j
- ▶ apart from alterations of signs all the numbers are preserved during the pivots
- ▶ but how does the sign alter? Ex. 4.5 and 4.6!
- ▶ the problem could be solved with only one pivot, if we instead of x_1 had taken x_3 in to basis! But the choice was controlled by the rule of pivot.

Comments on efficiency and LP

- ▶ **Are there** other pivot rules for the simplex algorithm that always avoid 2^n pivots ??? We would prefer if the number of pivots do not grow faster than f.ex. n^2 or n^3 (or a polynomial in $n =$ number of variables)!
- ▶ The answer is unknown! But for all suggested pivot rules someone has found 2^n “**contradictions**”.
- ▶ K.-H. Borgwardt has given a statistical analysis which shows that the **expected number of pivots** (when the LP problems are “drawn randomly”) grows as $n^3 m^{1/(n-1)}$
- ▶ In **practice** one assumes that **the number of pivots typically lies between m and $2m$** . This is very good! Note that the number of variables n matter less for the number of pivots (even though the calculation time increases by n).

Comments on efficiency and LP

- ▶ In 1979 the **ellipsoid method** was developed by L.Khachian: first **polynomial time algorithm** for LP. This was a theoretical breakthrough. This algorithm is theoretically “good”, but hopeless in practise!
- ▶ In 1984 **N. Karmarkar** published a new LP algorithm based on a different set of ideas: unlike the simplex algorithm, a series of points, which are not basic solutions, are made; these points lie in the interior of the feasible set.
- ▶ During the last years a very active field of research has been **interior point methods for LP**. Part 3 of Vanderbei's book treats these methods.