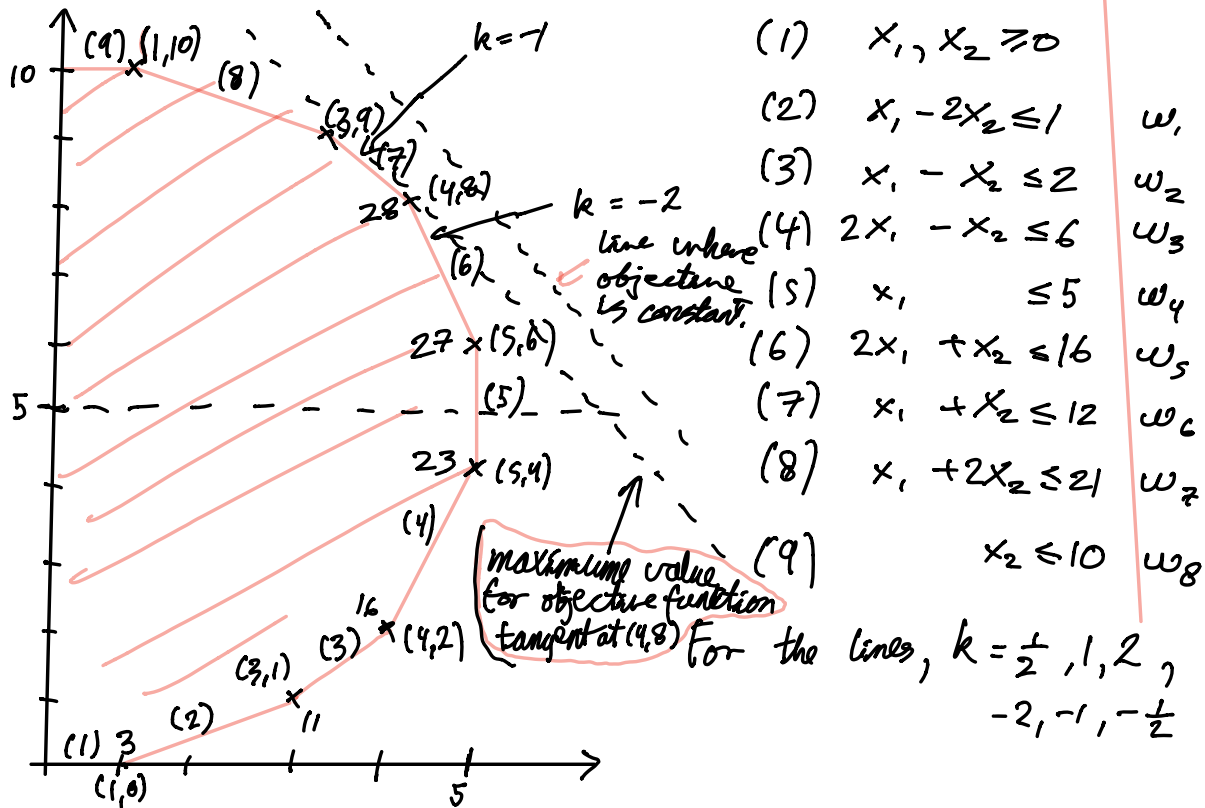


Exercise 2.16 (see exercise 2.8 also)



Each line segment corresponds to a slack being zero for one of the constraints.

objective: $3x_1 + 2x_2$

$$3x_1 + 2x_2 = k$$

$$x_2 = -\frac{3}{2}x_1 + k$$

derivative $-\frac{3}{2}$

See geometrically that $(x_1, x_2) = (4, 8)$ gives max

value: $3 \cdot 4 + 2 \cdot 8 = 12 + 16 = \underline{28}$

Simplex starts with $x_1 = x_2 = 0$.

maximum coefficient rule chooses x_1 .

Following the feasible region counterclockwise from the origin; the following variables are zero:

	<u>nonbasic vars</u>	<u>obj. value</u>
(1):	(x_1, x_2)	0
(2):	(x_2, w_1)	3
(3):	(w_1, w_2)	11
(4):	(w_2, w_3)	16
(5):	(w_3, w_4)	23
(6):	(w_4, w_5)	27
(7):	(w_5, w_6)	28

We see geometrically that the objective increases at each iteration.

If you run simplex with maximum coefficient rule, this order will be produced.

Simplex1 will yield a different order (hard to see, would be better to write solution x at all steps in the algorithm).

Exercise 2.18

$\xi = \dots + c_j x_j$ becomes basic in the objective (entering)
 $c_j > 0$

suppose x_R becomes nonbasic: $x_R = b_R - a_{Rj} x_j - \dots$

$$x_j = \frac{b_R}{a_{Rj}} - \frac{1}{a_{Rj}} x_R - \dots$$

$$c_j x_j = c_j \left(\frac{b_R}{a_{Rj}} - \frac{1}{a_{Rj}} x_R - \dots \right) = c_j \frac{b_R}{a_{Rj}} - \underbrace{\frac{c_j}{a_{Rj}}}_{\substack{c_j > 0 \\ a_{Rj} > 0}} x_R - \dots$$

$$\text{so } -\frac{c_j}{a_{Rj}} < 0$$

Since the coefficient of x_R is < 0 in the objective, it can't become basic in the next iteration.

Exercise 2.19

$$\max \sum_{j=1}^n p_j x_j$$

$$\text{subj. to } \sum_{j=1}^n q_j x_j \leq \beta$$

$$0 \leq x_j \leq 1$$

$$\sum_{j=1}^n p_j = \sum_{j=1}^n q_j = 1$$

$$p_j, q_j > 0$$

$$\text{Assume } \frac{p_1}{q_1} < \frac{p_2}{q_2} < \dots < \frac{p_n}{q_n}$$

β supposed to be small, positive

Easy to solve as follows without simplex:

Set $y_j = q_j x_j$, problem is transformed to

$$\max \sum_{j=1}^n \frac{p_j}{q_j} y_j$$

$$\text{subj. to } \sum_{j=1}^n y_j = \beta$$

$$0 \leq y_j \leq q_j$$

Clearly we must set $y_n = \min(\beta, q_n) = \beta$

$$\Rightarrow x_n = \frac{\beta}{q_n}, \text{ and } x_1 = \dots = x_{n-1} = 0$$

$$y_1 = \dots = y_{n-1} = 0$$

$$\text{optimal value: } \underline{\underline{\frac{p_n}{q_n} \beta}}$$

With simplex:

$$\begin{array}{l} \bar{z} = p_1 x_1 + \dots + p_n x_n \\ w_1 = 1 - x_1 \\ \vdots \\ w_n = 1 - x_n \\ w_{n+1} = \beta - q_1 x_1 - \dots - q_n x_n \\ x_n = \frac{\beta}{q_n} - \frac{q_1}{q_n} x_1 - \dots - \frac{1}{q_n} w_{n+1} \end{array}$$

ratios

$$\frac{q_n}{\beta} > 1 \Rightarrow w_{n+1} \text{ leaving}$$

$$\begin{aligned}
\zeta &= \sum_{j=1}^{n-1} p_j x_j + p_n x_n \\
&= \sum_{j=1}^{n-1} p_j x_j + \frac{p_n}{q_n} \left(\beta - \sum_{j=1}^{n-1} q_j x_j - w_{n+1} \right) \\
&= \frac{p_n}{q_n} \beta + \sum_{j=1}^{n-1} \left(p_j - \frac{p_n}{q_n} q_j \right) x_j - \frac{p_n}{q_n} w_{n+1} \\
&= \frac{p_n}{q_n} \beta + \sum_{j=1}^{n-1} q_j \left(\frac{p_j}{q_j} - \frac{p_n}{q_n} \right) x_j - \frac{p_n}{q_n} w_{n+1}
\end{aligned}$$

This is an optimal dictionary, optimal value is $\frac{p_n}{q_n} \beta$

also, $x_1 = \dots = x_{n-1} = 0$, $x_n = \frac{\beta}{q_n}$

$$\Rightarrow \vec{x} = \left(0, \dots, 0, \frac{\beta}{q_n} \right)$$

Exercise 3.1

$$\begin{aligned}
\max \quad & 10x_1 - 57x_2 - 9x_3 - 24x_4 \\
\text{subj. to} \quad & 0.5x_1 - 5.5x_2 - 2.5x_3 + 9x_4 \leq 0 \\
& 0.9x_1 - 1.5x_2 - 0.5x_3 + x_4 \leq 0 \\
& x_i \leq 1
\end{aligned}$$

			entering	
	$\zeta =$		$10x_1$	$-57x_2 - 9x_3 - 24x_4$
leaving	$w_1 =$	ϵ_1	$-0.5x_1$	$+5.5x_2 + 2.5x_3 - 9x_4$
	$w_2 =$	ϵ_2	$-0.5x_1$	$+1.5x_2 + 0.5x_3 - x_4$
	$w_3 = 1$	ϵ_3	$-x_1$	
	$x_1 =$	$2\epsilon_2$	$-2w_2 + 3x_2 + x_3$	$-2x_4$

We obtain:

$$\begin{array}{rcl} \xi & = & 20\varepsilon_2 - 20w_2 - 27x_2 + \overset{\text{entering}}{x_3} - 44x_4 \\ w_1 & = & \varepsilon_1 - \varepsilon_2 + w_2 + 4x_2 + 2x_3 - 8x_4 \\ x_1 & = & 2\varepsilon_2 - 2w_2 + 3x_2 + x_3 - 2x_4 \\ \text{leaving } w_3 & = & 1 - 2\varepsilon_2 + \varepsilon_3 + 2w_2 - 3x_2 - x_3 + 2x_4 \end{array}$$

$$x_3 = 1 - 2\varepsilon_2 + \varepsilon_3 + 2w_2 - 3x_2 - w_3 + 2x_4$$

$$\begin{array}{rcl} \xi & = & 1 + 18\varepsilon_2 + \varepsilon_3 - 18w_2 - 30x_2 - w_3 - 42x_4 \\ w_1 & = & 2 + \varepsilon_1 - 5\varepsilon_2 + 2\varepsilon_3 + 5w_2 - 2x_2 - 2w_3 - 4x_4 \\ x_1 & = & 1 + \varepsilon_3 - w_3 \\ x_3 & = & 1 - 2\varepsilon_2 + \varepsilon_3 + 2w_2 - 3x_2 - w_3 + 2x_4 \end{array}$$

This dictionary is optimal! Delete the ε 's :

$$\begin{array}{rcl} \xi & = & 1 - 18w_2 - 30x_2 - w_3 - 42x_4 \\ w_1 & = & 2 + 5w_2 - 2x_2 - 2w_3 - 4x_4 \\ x_1 & = & 1 - w_3 \\ x_3 & = & 1 + 2w_2 - 3x_2 - w_3 + 2x_4 \end{array}$$

\Rightarrow optimal value is 1, obtained for $x_2 = x_4 = w_2 = w_3 = 0$
 $w_1 = 2, x_1 = x_3 = 1$

$$\Rightarrow \underline{\underline{\vec{x} = (1, 0, 1, 0)}}$$

Exercise 3.2 (same system using Bland's rule)

	<i>entering</i>		<i>ratios:</i>
$\xi =$	$10x_1$	$-57x_2 - 9x_3 - 24x_4$	
<i>leaving</i> $w_1 =$	$-0.5x_1$	$+5.5x_2 + 2.5x_3 - 9x_4$	∞ <i>leaving (Bland's)</i>
$w_2 =$	$-0.5x_1$	$+1.5x_2 + 0.5x_3 - x_4$	∞
$w_3 = 1$	$-x_1$		$\frac{1}{1} = 1$

(pivot(1,1))

$$x_1 = -2w_1 + 11x_2 + 5x_3 - 18x_4$$

	<i>entering</i>		<i>ratios:</i>
$\xi =$	$-20w_1 + 53x_2$	$+41x_3 - 204x_4$	
$x_1 =$	$-2w_1 + 11x_2$	$+5x_3 - 18x_4$	$\frac{-11}{0} = -\infty$
$w_2 =$	w_1	$-4x_2 - 2x_3 + 8x_4$	$\frac{4}{0} = \infty \Rightarrow$ <i>leaving</i>
$w_3 = 1$	$+2w_1$	$-11x_2 - 5x_3 + 18x_4$	$\frac{11}{1} = 11$

(pivot(2,2))

	<i>entering</i>		<i>ratios:</i>
$\xi =$	$-\frac{27}{4}w_1 - \frac{53}{4}w_2 + \frac{29}{2}x_3$	$-98x_4$	
$x_1 =$	$\frac{3}{4}w_1 - \frac{1}{4}w_2 - \frac{1}{2}x_3$	$+4x_4$	$\frac{1}{2} = \infty$ x_1 <i>leaving</i>
$x_2 =$	$\frac{1}{4}w_1 - \frac{1}{4}w_2 - \frac{1}{2}x_3$	$+2x_4$	$\frac{1}{2} = \infty$
$w_3 = 1$	$-\frac{3}{4}w_1 + \frac{11}{4}w_2 + \frac{1}{2}x_3$	$-4x_4$	$\frac{-1/2}{1} = -\frac{1}{2}$

(pivot(3,1))

Use simplex for the remaining pivots.

Exercise 3.4

$$\begin{aligned} \max \quad & \sum_{j=1}^n c_j x_j \\ \text{subj. to} \quad & \sum_{j=1}^n a_{ij} x_j \leq 0 \quad i=1, \dots, m \\ & x_j \geq 0 \quad j=1, \dots, n \end{aligned}$$

Assume that all $c_j \leq 0$. Then this is optimal, and $\vec{x} = \vec{0}$ optimal solution.

Assume that $c_k > 0$ for some k . Set x_k as entering.

$z = c_1 x_1 + \dots + c_n x_n$	ratios
$w_1 = -a_{11} x_1 - \dots - a_{1n} x_n$	$\frac{a_{1k}}{0}$
\vdots	
$w_m = -a_{m1} x_1 - \dots - a_{mn} x_n$	$\frac{a_{mk}}{0}$

If all ratios ≤ 0 , then we can increase x_k to infinity \Rightarrow unbounded.

Assume that some ratio is > 0 , for instance: $\frac{a_{lk}}{0} = \infty$

We must have that $a_{lk} > 0$.

Constraint l : $0 - a_{lk} x_k = 0 \Rightarrow x_k = 0$

This shows that you can't increase the entering variable.

So, after all pivots, \vec{x} remains at 0 .

This completes the proof.