

Optimization note Ex 7.

$$f(x) = x^T A x - b^T x$$

$$b, x \in \mathbb{R}^n$$

$$A \in \mathbb{R}^{n \times n}$$

A is positive definite

We have that f is a ^(strictly) convex function.

Moreover $\nabla f(x) = Ax - b$

By Thm 4. in optimization note we know that a point $x^* \in \mathbb{R}^n$ is a local minimum if and only if

$$\nabla f(x^*) = 0. \quad \text{That is } Ax^* - b = 0 \\ \Rightarrow Ax^* = b$$

Since this minimum is unique since f is strictly convex. (Can also see this by observing that A is non-singular).

In the steepest descent method we choose a starting-point $x_0 \in \mathbb{R}^n$ and compute the next iterate

$$x_1 = x_0 - \alpha d_0$$

where $d_0 = \nabla f(x_0) = Ax_0 - b$

and α is chosen as the exact step length.

From the lecture notes we know that the step length with exact line search for a quadratic function is $\alpha = \frac{d_0^T d_0}{d_0^T A d_0}$ ~~$\Rightarrow \frac{1}{\lambda} \frac{\|d_0\|^2}{\|d_0\|^2} = \frac{1}{\lambda}$~~

Assume that $d_0 = Ax_0 - b$ is an eigenvector of A with eigenvalue λ . Then

$$\alpha = \frac{d_0^T d_0}{d_0^T A d_0} = \frac{1}{\lambda}$$

This gives

$$Ax_1 = Ax_0 - \frac{1}{\lambda} A d_0 = Ax_0 - Ax_0 + b = b$$
$$\Rightarrow Ax_1 = b$$

From our observation above we then know that x_1 is a ~~an~~ optimal point.