

Ark5: Exercises for MAT4270 — Lie algebras, exponential map and invariant integrals.

THIS SHEET CONCERNS THE WEEK SEPTEMBER 24 TO SEPTEMBER 28

Plans are approximately the following:

On Tuesday Sep 25 I did: Characters and trace, basic formulas for characters, orthogonal relations, started with finite groups

On Friday Sep 28 I plan to do: More on finite groups. Examples, *i.e.*, symmetric groups.

Exercises

PROBLEM 1. Show the product rule:

$$d_{a(t)b(t)}d_t ab = d_{b(t)}\lambda_{a(t)}d_t b + d_{a(t)}\rho_{b(t)}d_t a$$

where $a: \mathbb{R} \rightarrow G$ and $b: \mathbb{R} \rightarrow G$ are two maps from \mathbb{R} into the Lie group G and $ab: \mathbb{R} \rightarrow G$ is the map $t \mapsto a(t) \cdot b(t)$.

PROBLEM 2.

- Assume G to be connected. Show that the image $\exp \text{Lie } G$ is *not* a subgroup unless \exp is surjective.
- Show that the product of two 2×2 matrices in $\text{Sl}(2, \mathbb{R})$ with positive eigenvalues has positive eigenvalues.
- Give an example of matrices a and b with purely imaginary eigenvalues such that the product has negative real eigenvalues.
- Recall the elements a and b from $\text{Sl}(2, \mathbb{R})$ as in the example in Notes5:

$$a = \begin{pmatrix} -x & y \\ -y^{-1} & 0 \end{pmatrix} \text{ and } b = \begin{pmatrix} \lambda & 0 \\ 0 & \lambda^{-1} \end{pmatrix}$$

Convince yourself that ba is not in the image of the exponential.

- Very open question: Find v and w in $\mathfrak{sl}(2, \mathbb{R})$ such that $\exp v = a$ and $\exp w = b$. What can you say about the *right side* in the BCH-formula evaluated at that v and w ?

PROBLEM 3. (*The centraliser*). Let G be a Lie group and let $g \in G$ be an element. Recall the conjugation map $c_g: G \rightarrow G$ with $c_g(x) = gxg^{-1}$. Let $\chi_g(x) = c_g(x)x^{-1} = gxg^{-1}x^{-1}$.

a) Show that for any $h \in G$ there is a commutative diagram

$$\begin{array}{ccc} G & \xrightarrow{\chi_g} & G \\ \lambda_h \downarrow & & \downarrow \lambda_{ghg^{-1} \circ \rho_{h^{-1}}} \\ G & \xrightarrow{\chi_g} & G \end{array}$$

and use this to show that the rank of χ_g is the same everywhere in G .

b) Show that $\chi_g^{-1}(e)$ is equal to the centraliser $C_G(g)$ and that the centraliser is a closed subgroup. Show that $\text{Lie}_e C_G(g) = \{v \in \text{Lie } G \mid \text{Ad}_g v = v\}$.

PROBLEM 4. (*Fixed points*). Let $\phi: G \rightarrow G$ be an automorphism of the Lie group G . Show that the set of fixed points $F(\phi)$ of ϕ , that is the points for which $\phi(x) = x$, is a closed subgroup of G , and that its Lie algebra is given as $\text{Lie } F(\phi) = \{v \in \text{Lie } G \mid d_e \phi(v) = v\}$.

PROBLEM 5. (*Conjugacy classes of $\text{Sl}(2, \mathbb{K})$*). Assume that the two elements a and b of $\text{Sl}(2, \mathbb{K})$ have the same trace τ ; where as usual \mathbb{K} is one of the fields \mathbb{C} or \mathbb{R} .

a) Show that if $\tau \neq \pm 2$, then a and b are conjugate. Find representatives in each class.

b) Show that if $\tau = 2$ or $\tau = -2$ there are exactly two conjugacy classes having trace τ in each case. Find representatives on each class.

PROBLEM 6.

a) Show that any element in $\text{SO}(3)$ is conjugate to one of the form

$$R_\theta = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos \theta & -\sin \theta \\ 0 & \sin \theta & \cos \theta \end{pmatrix}.$$

b) What are the conjugacy classes of $\text{SO}(3)$? And what are the conjugacy classes of $\text{O}(3)$?

PROBLEM 7. Let H_3 be the Heisenberg group, *i.e.*, the subgroup of upper triangular 3×3 -matrices with ones along the diagonal. Show that $\exp: \text{Lie } H_3 \rightarrow H_3$ is a diffeomorphism.

PROBLEM 8. Let h, x_+, x_- be the usual basis for $\text{Sl}(2, \mathbb{R})$; that is

$$h = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad x_+ = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \quad x_- = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}.$$

a) Compute the matrices of $\text{ad}_h, \text{ad}_{x_+}$ and ad_{x_-} in that basis.

Let a_t be the element in $\text{Sl}(2, \mathbb{R})$ given by

$$a_t = \begin{pmatrix} 1 & t \\ 0 & 1 \end{pmatrix}.$$

b) Show that $N = \{ a_t \mid t \in \mathbb{R} \}$ is a Lie subgroup in the strong sense of $\text{Sl}(2, \mathbb{R})$.

c) Determine the Lie subalgebra $\text{Lie } N$ of $\text{sl}(2, \mathbb{R})$.

d) Show that the matrix of $\text{Ad } a_t$ in the usual basis h, x_+, x_- for $\text{sl}(2, \mathbb{R})$ is

$$\begin{pmatrix} 1 & 0 & t \\ -2t & 1 & -t^2 \\ 0 & 0 & 1 \end{pmatrix}$$

PROBLEM 9. Let dX be the usual Lebesgue-measure on the space of $n \times n$ -matrices $M_n(\mathbb{R})$ (which is equal to \mathbb{R}^{n^2}). Show that $|\det X|^{-n} dX$ is both left and right invariant measure on $\text{Gl}(n, \mathbb{R})$.

PROBLEM 10. Let G be the Lie subgroup of $\text{Gl}(2, \mathbb{R})$ whose elements are the matrices of the form

$$\begin{pmatrix} s & u \\ 0 & 1 \end{pmatrix}$$

where $s \in \mathbb{R}^*$ and $u \in \mathbb{R}$. Determine both a left and a right invariant integral, and verify that they are different.

PROBLEM 11. (*Euler angles*). Let α and β be the two one-parameter groups of $\text{SO}(3)$ given by

$$\alpha(t) = \begin{pmatrix} \cos t & -\sin t & 0 \\ \sin t & \cos t & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \beta(t) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos t & -\sin t \\ 0 & \sin t & \cos t \end{pmatrix}.$$

Let $\gamma: \mathbb{T}^3 \rightarrow \text{SO}(3)$ be the map $(s, t, u) \mapsto \alpha(s) \cdot \beta(t) \cdot \alpha(u)$ — where $0 \leq s, t, u \leq 2\pi$. Show that γ is surjective and describe the fibres of γ . The angles s, t, u are called Euler angles.

Show that the normalised, invariant integral on $\text{SO}(3)$ can be expressed as

$$\frac{1}{8\pi^2} \int_0^{2\pi} \int_0^{2\pi} \int_0^{2\pi} \sin t \cdot f(\gamma(s, t, u)) \, ds \, dt \, du$$

PROBLEM 12. Show that

$$\exp(v + w) = \lim_{n \rightarrow \infty} (\exp(v/n) \exp(w/n))^n$$

for any vectors v, w in the Lie algebra $\text{Lie } G$ of a Lie group G .

PROBLEM 13. Show that the image of the exponential map is a union of conjugacy classes. HINT: Use that $\exp \text{Ad}_g v = c_g(\exp v)$ where $c_g(x) = gxg^{-1}$.