

Recap from cplx simple Lie algs \mathfrak{g} ,
Cartan subalg $\mathfrak{h}_\alpha \subset \mathfrak{g}$

- roots $\alpha \in \mathbb{R}$ eigenval functional

$$Y \in \mathfrak{g}_{\alpha} \subset \mathfrak{g} : [X, Y] = \alpha(X)Y \quad X \in \mathfrak{h}_\alpha$$
- copy of $\mathfrak{sl}_2 \subset \mathfrak{g} : \langle H_\alpha \in [\mathfrak{g}_\alpha, \mathfrak{g}_{-\alpha}], F_\alpha \in \mathfrak{g}_\alpha, F_{-\alpha} \in \mathfrak{g}_{-\alpha} \rangle$
- real subsp. $\mathfrak{h}_{\alpha, \mathbb{R}} = \langle H_\alpha : \alpha \in \mathbb{R} \rangle_{\mathbb{R}} \subset \mathfrak{h}_\alpha$
- Killing form B : pos. def. on $\mathfrak{h}_{\alpha, \mathbb{R}}$
- weight lattice $\Lambda_w = \{ \beta \in \mathfrak{h}_\alpha^* : \forall \alpha \in \mathbb{R} \beta(H_\alpha) \in \mathbb{Z} \}$
 $\mathbb{R} \subset \Lambda_w \subset E = \mathbb{R}$ -span of $\Lambda_w \in$ Euclidean sp.
 by inverse of B .

We know: $\alpha \in \mathbb{R} \Rightarrow k\alpha \in \mathbb{R}$ iff $k = \pm 1$.

More symmetry:

$$s_\alpha(v) = v - \frac{2(\alpha, v)}{(\alpha, \alpha)} \alpha \quad \text{for } v \in E$$

reflection along the hyperplane $\alpha^\perp = \{ w \in E : (\alpha, w) = 0 \}$

Def. the Weyl group of $(\mathfrak{g}; \mathfrak{h}_\alpha)$ is the
subgroup of $O(E)$ generated by s_α ($\alpha \in \mathbb{R}$)

Prop 1. $\alpha \in \mathbb{R} : s_\alpha(v) = v - v(H_\alpha)\alpha$ for $v \in E$.

$$\text{i.e. } v(H_\alpha) = \frac{2(\alpha, v)}{(v, v)}$$

Proof Step 1 $\alpha^\perp = \{ w \in E : w(H_\alpha) = 0 \}$

Recall $\exists T_\alpha \in [\mathfrak{g}_\alpha, \mathfrak{g}_{-\alpha}]$ s.t. $B(T_\alpha, Z) = \alpha(Z)$ ($Z \in \mathfrak{h}_\alpha$)

\mathfrak{h}_α is the isom $E \cong \mathfrak{h}_{\alpha, \mathbb{R}}$ given by B maps
 α to T_α .

$(w, \alpha) = 0 \Leftrightarrow Z$ corr. to w satisfies $B(Z, T_\alpha) = 0$

$\Leftrightarrow w(T_\alpha) = 0 \Leftrightarrow w(H_\alpha) = 0$

$$\text{Step 2 } s_\alpha(v) = v - \frac{2v(H_\alpha)}{\alpha(H_\alpha)} \alpha$$

$$\text{Step 3 } \alpha(H_\alpha) = 2$$

□

Prop 2 (π, V) rep. of \mathfrak{g} ; put

$$X = \text{supp}(\pi, V) = \{ \lambda \in \mathfrak{h}^* \text{ weight of } V \}$$

$$\text{Then } s_\alpha X = X$$

Proof so fix $\lambda \in X$, take max $p, q \in \mathbb{N}$ s.t.

$$I = \{ \lambda + p\alpha, \lambda + (p-1)\alpha, \dots, \lambda - q\alpha \} \subset X$$

$$\text{Step 1 } (\lambda + p\alpha)(H_\alpha) = -(\lambda - q\alpha)(H_\alpha)$$

From classification of irred reps of $\mathfrak{sl}_2(\mathbb{C})$

$$\text{Step 2 } \lambda(H_\alpha) = q - p.$$

$$\text{Step 3 } s_\alpha(\lambda) \in X$$

$$s_\alpha(\lambda) = \lambda + (p - q)\alpha \in I. \quad \square$$

Cor $R \subset E$ is invariant under the Weyl group

Def. a root system is given by

- E : Euclidean space
- $R \subset E$: finite subset; such that

1. R spans E

2. $\alpha \in R, k \in \mathbb{R} : k\alpha \in R \Leftrightarrow k = \pm 1$

3. $s_\alpha(v) = v - \frac{2(\alpha, v)}{(\alpha, \alpha)}\alpha$ ($\alpha \in R$) maps R to R

4. $n_{\alpha, \beta} = \frac{2(\alpha, \beta)}{(\alpha, \alpha)} \in \mathbb{Z}$ for $\alpha, \beta \in R$

Prop 3 $\alpha, \beta \in R \Rightarrow$ the angle between α and β is

$0, \frac{\pi}{2}, \frac{\pi}{3}, \frac{\pi}{4}, \frac{\pi}{6}$, or $\pi -$ (one of the left)

$$\text{Proof } n_{\alpha, \beta} n_{\beta, \alpha} = \frac{4(\alpha, \beta)^2}{(\alpha, \alpha)(\beta, \beta)} = 4 \cos^2 \theta$$

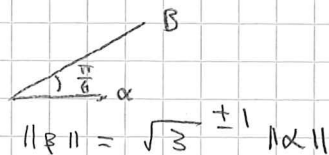
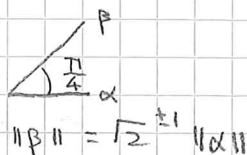
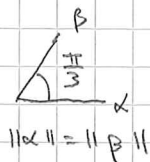
for the angle θ between α and β

$\Rightarrow \cos \theta = \pm \frac{\sqrt{n}}{2}$ for $n \in \mathbb{N}$; the only possible

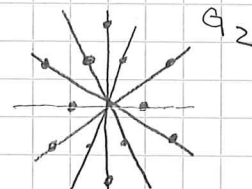
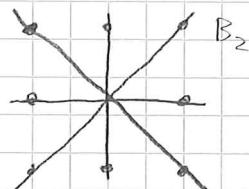
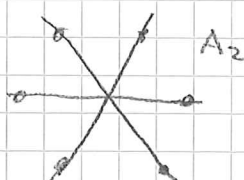
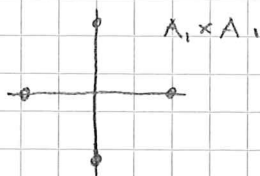
values are $n = 0, 1, 2, 3, 4$ corresponding

to those in the claim \square

Rem. we also have restrictions on the length



Ex. If $\dim E = 2$, R is one of:



Rem. $\mathfrak{g} = \mathfrak{sl}_3(\mathbb{C})$, $\mathfrak{h}_\alpha = \text{diag}$ gives the A_2 system (previous time)

$\mathfrak{g} = \mathfrak{so}_5(\mathbb{C})$ or $\mathfrak{spin}_4(\mathbb{C})$ gives the B_2 system
"exercise" 16.2

$\mathfrak{g} = \mathfrak{sl}_2(\mathbb{C}) \oplus \mathfrak{sl}_2(\mathbb{C})$, $\mathfrak{h}_\alpha = \mathbb{C}H \oplus \mathbb{C}H$ gives the $A_1 \times A_1$ system

Rem. $(E_1, R_1), (E_2, R_2)$ root systems

$\rightarrow (E_1 \oplus E_2, R_1 \cup \{0\} \cup \{0\} \cup R_2)$ is again a root sys.
given by $E_1 \times E_2$

Def. (E, R) is an irreducible root system if

there is no nontriv decomp $(E, R) \cong (E_1, R_1) \times (E_2, R_2)$

Goal: $\{\text{cptx simple Lie algs}\} / \text{isom}$

$\xleftrightarrow{1:1} \{\text{irred. root sys}\} / \text{isom}$

Todo

- define (simple) Lie algs from (irred) root sys.
- check the independence of root sys. on the choice of Cartan subalg. $\mathfrak{h}_\alpha \subset \mathfrak{g}$
- $(\mathfrak{g}, \mathfrak{h}_\alpha) \rightarrow \text{root sys.}$ root sys $\rightarrow (\mathfrak{g}, \mathfrak{h}_\alpha)$
are inverse to each other

