

Next: Study "non-homogeneous" geometric structures

on surfaces \leadsto Riemannian geometry

§ 5.3 Riemannian surfaces

Non-homogeneous \Rightarrow must study the local picture

Very local approximation \approx tangent planes

Recall * In hyperbolic (also elliptic) geometry, things

look euclidean when we zoom in

(e.g. small triangles \approx euclidean triangles

small segments \approx euclidean segments)

* Euclidean plane = $(\mathbb{R}^2, \langle, \rangle)$
 \swarrow inner product

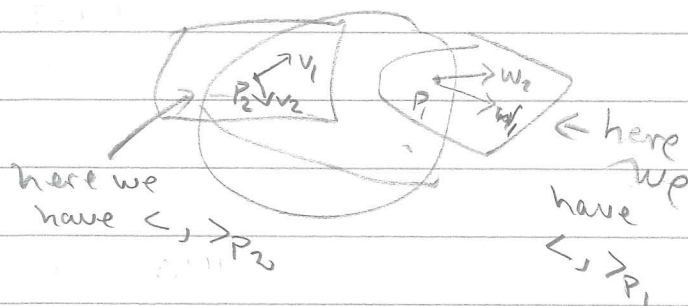
$$\begin{aligned} \langle, \rangle : \mathbb{R}^2 &\rightarrow \mathbb{R} \quad \text{s.t.} \quad \langle ax, y \rangle = a \langle x, y \rangle \quad a \in \mathbb{R}, x, y \in \mathbb{R}^2 \\ \langle x+y, z \rangle &= \langle x, z \rangle + \langle y, z \rangle \quad x, y, z \in \mathbb{R}^2 \\ \langle x, y \rangle &= \langle y, x \rangle \\ \langle x, x \rangle &> 0 \quad \text{if } x \neq 0 \end{aligned}$$

\Rightarrow equip all tangent planes on a surface w/ an inner product

Def 5-3.1 A Riemannian metric on S is a choice of inner product on every $T_p S$, varying smoothly w/ p .

Notation $\langle w_1, w_2 \rangle_p$ for the inner product of $w_1, w_2 \in T_p S$ sometimes slip

$$w_1, w_2 \in T_p S$$



Smooth dependence if $x: U \subset \mathbb{R}^2 \rightarrow S$ local param,

recall the "partial derivatives" $x_u = dx(1,0)$, $x_v = dx(0,1)$

which form a basis for $T_p S \Rightarrow$

$\langle \cdot, \cdot \rangle_p$ completely determined by

$$E(p) = \langle x_u, x_u \rangle, \quad G(p) = \langle x_v, x_v \rangle, \quad F(p) = \langle x_u, x_v \rangle$$

The inner product on S is smooth if E, F, G smooth

\forall local param.

Def A Riemannian surface is a surface w/ a

Riemannian metric

= Riemannian structure

Rmk Can be generalized to mfd's of any dimensions

↳ Riemannian mfd's

⚠ Difference between Riemann surface & above
cplx mfd of dim 1

Consequences / properties from having a Riemannian str.

* Norm ^{of tangent vectors} : $w \in T_p S \Rightarrow \|w\|_p^2 = \langle w, w \rangle_p$

\Rightarrow if $w = \alpha x_u + \beta x_v$, then $\|w\|$

$$\|w\|_p^2 = \alpha^2 E(p) + 2\alpha\beta F(p) + \beta^2 G(p)$$

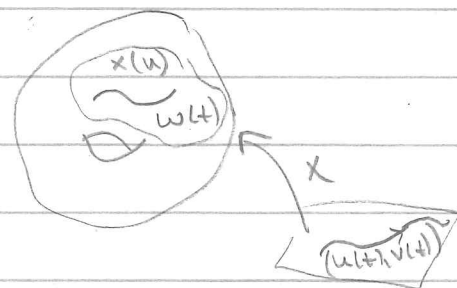
* Arc-length $w(t) = x(u(t), v(t))$ $t \in [a, b]$ C^1 -curve in $x(U)$

$$\Rightarrow s(t) = \int_0^t \|w'(t)\|_{w(t)} dt$$

$$w'(t) = u'(t)x_u + v'(t)x_v \Rightarrow$$

$$\|w'(t)\|_p^2 = E(p)(u'(t))^2 + 2F(p)u'(t)v'(t) + G(p)(v'(t))^2$$

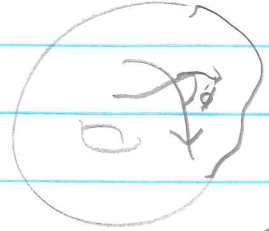
$$\Rightarrow \text{line element } ds^2 = Edu^2 + 2Fdu dv + Gdv^2$$



* Angle : between curves $\alpha(t), \beta(t)$ c.s. s.t.

$$\alpha(0) = \beta(0) \quad \text{given by}$$

$$\phi \in [0, \pi] \text{ s.t. } \langle \alpha'(0), \beta'(0) \rangle_{\alpha(0)} = \cos \phi \|\alpha'(0)\| \|\beta'(0)\|$$



* Area $A(R)$ of region $R \subset X(u), x: U \xrightarrow{\mathbb{R}^2} S =$

$$A(R) = \iint_{\Omega} \sqrt{EG-F^2} \, du \, dv \quad \text{where } \Omega \subset U \text{ s.t. } R = x(\Omega)$$

[Motivation If $R \subset \mathbb{R}^3$, then $A(R) = \iint_{\Omega} \left\| \frac{\partial x}{\partial u} \times \frac{\partial x}{\partial v} \right\| \, du \, dv = \iint_{\Omega} \|x_u \times x_v\| \, du \, dv$

$$= \iint_{\Omega} \|x_u \times x_v\| \, du \, dv$$

$$\& \|x_u \times x_v\|^2 = \|x_u\|^2 \|x_v\|^2 - \langle x_u, x_v \rangle^2 = EG - F^2$$

Rmk If S compact, then it has a well-defined

area $A(S)$: cover it by regions R_i contained

in local charts. S cpct \Rightarrow finite $\#$ of regions

\Rightarrow can sum the area of all $R_i = S$ to get $A(S)$.

Rmk x_u, x_v lin indep \Rightarrow

$$|\langle x_u, x_v \rangle|^2 < \|x_u\|^2 \|x_v\|^2 \text{ by Cauchy-Schwarz}$$

$$\Rightarrow \boxed{EG - F^2 > 0}$$

Examples of Riemannian surfaces

1) \mathbb{R}^2 2 "std" parametrizations:

• Id $\leadsto ds^2 = dx^2 + dy^2$

• Polar coord, $z: \mathbb{R}^2 \setminus \{0\} \rightarrow \mathbb{R}^2 \setminus \{0\}$

$$z(r, \theta) = (r \cos \theta, r \sin \theta)$$

$$\Rightarrow z_r = (\cos \theta, \sin \theta), \quad z_\theta = (-r \sin \theta, r \cos \theta)$$

$$\Rightarrow E(r, \theta) = \underbrace{z_r \cdot z_r}_{\text{in std } \mathbb{R}^2} = 1, \quad F(r, \theta) = 0, \quad G(r, \theta) = r^2$$

$$\rightarrow ds^2 = dr^2 + r^2 d\theta^2$$

(2) $S \subset \mathbb{R}^3$ regular \Rightarrow inner prod $\eta \cdot \xi = \eta \xi^T$ on \mathbb{R}^3

restricts to inner prod on $T_p S$

Will always assume this inner product for regular $S \subset \mathbb{R}^3$

Def $E du^2 + 2F du dv + G dv^2$ is called the first fundamental form for $S \subset \mathbb{R}^3$ regular

Ex S graph of smooth $f: \mathbb{R}^2 \rightarrow \mathbb{R}$,
 $(u, v) \mapsto f(u, v)$

$\Rightarrow x(u, v) = (u, v, f(u, v))$ gives param. w/

$$x_u = \left(1, 0, \underbrace{f_u}_{\frac{\partial f}{\partial u}}\right), \quad x_v = \left(0, 1, \underbrace{f_v}_{\frac{\partial f}{\partial v}}\right) \quad \Rightarrow$$

$$E = \|x_u\|^2 = 1 + f_u^2, \quad F = x_u \cdot x_v = f_u f_v, \quad G = \|x_v\|^2 = 1 + f_v^2$$

Ex $S = \mathbb{H}$, local param $\{y > 0\} \rightarrow \mathbb{H}$

given by id.

Know $ds^2 = \frac{dx^2 + dy^2}{y^2}$, which then defines

a Riemannian metric w/

$$E = G = \frac{1}{y^2}, F = 0$$

$$\rightarrow A(\mathbb{R}) = \iint_{\mathbb{R}} \frac{dx dy}{y^2} \quad \left[\sqrt{EG - F^2} = \frac{1}{y^2} \right]$$

Sim, on $S = \mathbb{D}$ get $E = G = \frac{4}{(1-x^2-y^2)^2}$ $F = 0$

$$\Rightarrow A(\mathbb{R}) = \iint_{\mathbb{R}} \frac{4 dx dy}{(1-x^2-y^2)^2}$$