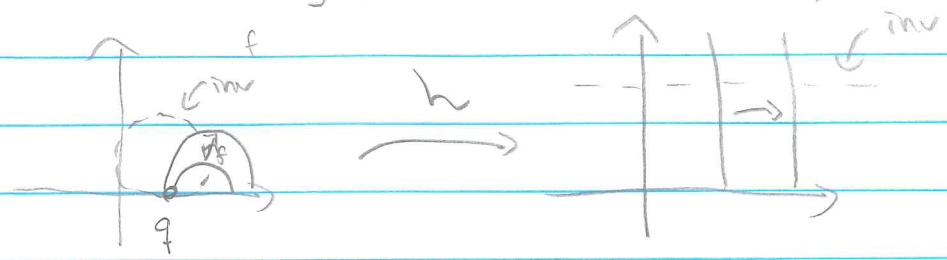


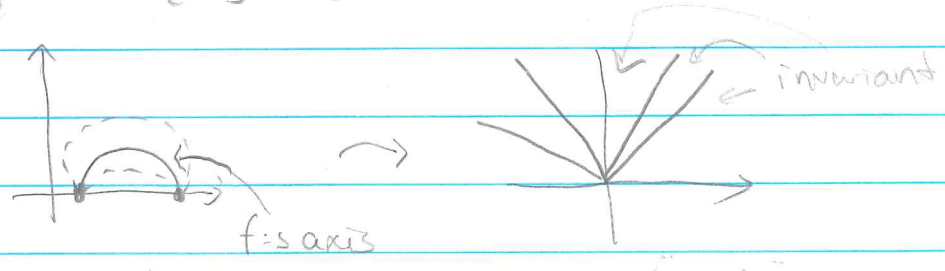
Last time

$f(z) = \frac{az+b}{cz+d} \in \text{Mob}^+(\mathbb{H}) \rightsquigarrow \tau(f) = (a+d)^2$  invariant under  
 conj.  $h f h^{-1}$ ,  $h \in \text{Mob}(\mathbb{H})$ , and  $f$  is conjugate to

\*  $z \mapsto z \pm 1$ , if  $\tau(f) = 4$  (one fixpt, real) "parabolic"



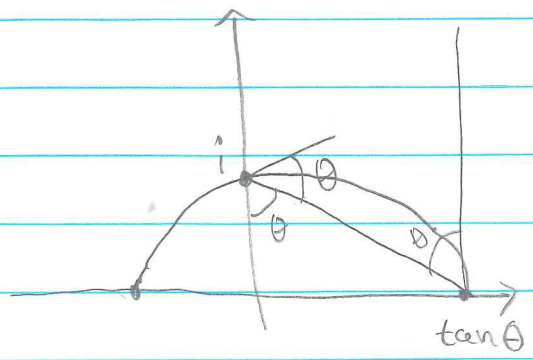
\*  $z \mapsto \eta z$ ,  $\eta \in \mathbb{R}$ , if  $\tau(f) > 4$  (2 real fixpts) "hyperbolic"



"translation" along this (axis is inv)

\*  $z \mapsto g_\theta(z) = \frac{\cos\theta z + \sin\theta}{-\sin\theta z + \cos\theta}$ ,  $\theta \in (0, \pi)$ , if  $\tau(f) < 4$  (2 cplx fixpts, only one of them in  $\mathbb{H}$ )  
 "elliptic"

Geometrically:



$0 \mapsto \tan\theta$   
 $\pi \mapsto -1$   
 $\Rightarrow i\mathbb{R}_{>0} \mapsto$   
 H.L. line w/  
 endpoints  $-1$  &  
 $\tan\theta$

$$\begin{aligned} \textcircled{6} &: z \\ L \textcircled{8} &: \mathbb{R} \end{aligned}$$

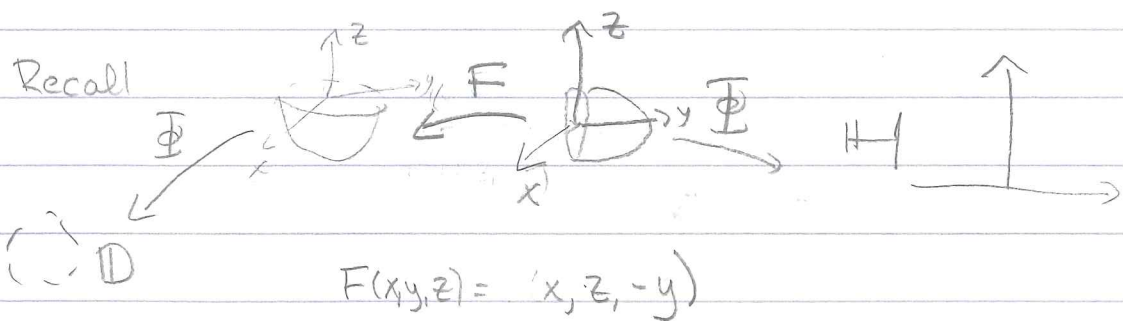
$g_{\theta} g_{\theta'} = g_{\theta+\theta'} \Rightarrow g_{\theta}$  rotates any Ht line through  $i$  by an angle  $2\theta$

[rotate  $i\mathbb{R}$  by  $2(\theta+\theta')$  is same as first rotate

$g_{\theta'} i\mathbb{R}$  to  $g_{\theta}(i\mathbb{R})$  then apply  $g_{\theta'}$ .  $\square$

Get an even better geometric picture if we go to  $\mathbb{D}$ :

### § 2.7 Poincaré's disk model $\mathbb{D}$



$\Rightarrow G = \Phi \circ F \circ \Phi^{-1} : \mathbb{H} \rightarrow \mathbb{D}$  is a homeo

$$\underline{Q} \quad G(u, v) = \left( \frac{2u}{u^2 + (v+i)^2}, \frac{u^2 + v^2 - 1}{u^2 + (v+i)^2} \right) \xrightarrow{z=u+iv} \downarrow$$

$$= \frac{z + \bar{z} + 1(z\bar{z} - 1)}{|z+i|^2} = \frac{(i-z+1)(\bar{z}-i)}{(z+i)(\bar{z}-i)} = \boxed{\frac{i-z+1}{z+i}}$$

an FLT sit.  $G(0) = -i, G(1) = 1, G(-1) = -1.$

Exc from PSS: Use Cor 2-2.5 to derive this.

formula for  $G$ .

Remark Many other possible FLT's identifying

$\mathbb{H} \rightarrow \mathbb{D}$ , but we use  $G$  since so simple

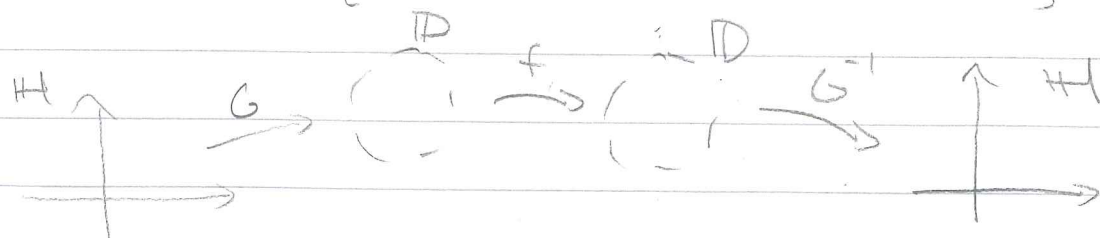
Know  $\mathbb{D}$ -lines =  $\begin{cases} * \text{ diameters} \\ * \text{ circular arcs } \cap \partial \mathbb{D} \perp \end{cases}$   
(from before) <sup>which</sup>

Q Can also be seen as a consequence of

C  $G(\mathbb{R}) = S^1 (= \partial \mathbb{D})$

Now consider Möbius transformations in this model:

Let  $\text{Möb}(\mathbb{D}) = \{ f: \mathbb{D} \rightarrow \mathbb{D} \mid G^{-1} \circ f \circ G \in \text{Möb}(\mathbb{H}) \}$



$\Rightarrow$  elements in  $\text{Möb}(\mathbb{D})$  preserve angles

&  $\mathbb{D}$ -lines.  $\square$

Q Why?

⑥ 3  
L ④ = ④

Sim  $\text{Möb}(\mathbb{D})^{\pm} = \{ f \in \text{Möb}(\mathbb{D}) \mid G^{-1} \circ f \circ G \in \text{Möb}^{\pm}(\mathbb{H}) \}$

Now we investigate the elements in  $\text{Möb}^{\pm}(\mathbb{D})$  further,

using matrices:

$$G \leftrightarrow \begin{bmatrix} i & 1 \\ 1 & i \end{bmatrix} \quad G^{-1}(z) = \frac{i\bar{z}-1}{-z+i} \quad \text{[use our formula from L. 4]}$$

$$\Rightarrow G^{-1} \leftrightarrow \begin{bmatrix} i & -1 \\ -1 & i \end{bmatrix}$$

$$\Rightarrow \text{If } g(z) = \frac{az+b}{cz+d} \quad \text{w/ } a, b, c, d \in \mathbb{R}, \text{ then}$$

$G \circ g \circ G^{-1}$  corresponds to

$$\begin{bmatrix} i & 1 \\ 1 & i \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} i & -1 \\ -1 & i \end{bmatrix} = \dots = \begin{bmatrix} -(a+d) + (c-b)i & -(b+d) - (a-d)i \\ -(b+c) + (a-d)i & -(a+d) - (c-b)i \end{bmatrix}$$

$$= \begin{bmatrix} \alpha & \beta \\ \bar{\beta} & \bar{\alpha} \end{bmatrix} \quad \text{w/ } \alpha = -(a+d) + (c-b)i$$

$$\beta = -(b+c) - (a-d)i$$

If now  $g = g_{\theta} = \frac{\cos\theta z + \sin\theta}{-\sin\theta z + \cos\theta}$  we get

$$\alpha = -2\cos\theta - 2i\sin\theta = -2e^{i\theta} \quad \Rightarrow G \circ g_{\theta} \circ G^{-1} = \frac{-2e^{i\theta} z}{-2e^{i\theta}} = e^{-i2\theta} z$$

$$\beta = 0$$

which is nothing but rotation by  $2\theta$ .

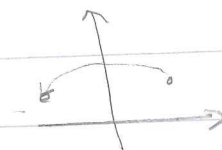
## Classification of elements in $\text{Möb}^{-1}(\mathbb{H})$

$$f \in \text{Möb}^{-1}(\mathbb{H}) \Leftrightarrow f(z) = \frac{a\bar{z}+b}{c\bar{z}+d} \quad \begin{array}{l} a, b, c, d \in \mathbb{R} \\ ad - bc = -1 \end{array}$$

Special cases:  $f(z) = -\bar{z}$

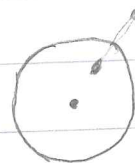
= horizontal reflection in the imaginary

axis



•  $f(z) = \frac{1}{\bar{z}}$  = "inversion" in the circle

$|z|=1$ :



$$z = re^{i\theta} \mapsto \frac{1}{\bar{z}} = \frac{1}{r}e^{i\theta}$$

$\Rightarrow$  point outside circle  $\leftrightarrow$  point inside circle  
s.t. angle w/  $\mathbb{R}^1$ -axis preserved

$$f|_{|z|=1} = \text{id}$$

Def An inversion in the circle  $C = \{z-m \mid |z-m|=r\}$

is a map  $g: C \rightarrow C$  s.t.  $|g(z)-m|/|z-m| = r^2$ .

An inversion in a vertical line  $l$  is horizontal

reflection in  $l$ .  $z \mapsto -\bar{z} + 2x_0$

L6:4

Prop 2.3.3 Let  $f \in \text{Mob}^-(\mathbb{H})$ ,  $f(z) = \frac{a\bar{z}+b}{c\bar{z}+d}$ ,

$$a, b, c, d \in \mathbb{R}, \quad ad - bc = -1.$$

• If  $a+d=0$ , then  $f$  is an inversion conjugate to  $-\bar{z}$ .

• If  $a+d \neq 0$ , then  $f = gh$ , where  $g$  is an inversion,

$h \in \text{Mob}^+(\mathbb{H})$  of hyperbolic type w/ axis equal

to the line of inversion of  $g$ . Moreover,  $g$  and

$h$  commute and this decomposition is unique  
(given  $gh=hg$ )

Pf Also in this case we consider the fixpts of  $f$ :

$$z = \frac{\bar{z}a+b}{c\bar{z}+d} \quad \Leftrightarrow \quad \underbrace{c|z|^2 + dz - a\bar{z} - b}_{z\bar{z}} = 0$$

$\parallel$   
 $x^2 + y^2$

$$\Leftrightarrow (*) \quad c(x^2 + y^2) - (a-d)x - b = 0 \quad (\text{Real part})$$

$$(**) \quad (a+d)y = 0 \quad (\text{Imaginary part})$$

$$(f(\infty) = \infty \Leftrightarrow c=0)$$

Case 1  $a+d=0 \Rightarrow$  only the Realpart-eqn

$c=0$ : This gives a vertical H-line  $\{x=x_0\}$   
 $x_0 = \frac{b}{a-d}$

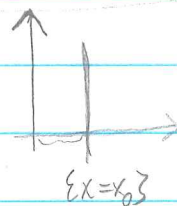
Let  $h(z) = z - x_0 \Rightarrow g = h \circ f \circ h^{-1}$  has fixpts

= imaginary axis

Q  $\Rightarrow g(z) = -\bar{z}$

$$\left. \begin{array}{l} \bar{z} = \frac{-a\bar{z}+b}{-c\bar{z}+d} \quad \left. \begin{array}{l} c=b \\ d=-a \end{array} \right\} \Rightarrow b=c=0 \\ 2\bar{z} = \frac{-2a\bar{z}+b}{-2c\bar{z}+d} \quad \left. \begin{array}{l} 4c=b \\ 2d=-2a \end{array} \right\} \Rightarrow a=d=+1 \end{array} \right\} \Rightarrow b=c=0$$

$\Rightarrow f = h^{-1} \circ g \circ h = (-\overline{(z-x_0)}) + x_0 = -\bar{z} + 2x_0$



which is nothing but inversion in  $\{x=x_0\}$ .

$c \neq 0$ : Then the fixpoints form a semi-circle w/

center  $m = (a/c, 0)$  & radius  $r = 1/|c|$  (completing the square).

$f(z) = \frac{a}{c} + \frac{1/c}{c\bar{z}+d} = \frac{\frac{a}{c}\bar{z} + \frac{ad+1}{c}}{c\bar{z}+d}$  - b since  $ad-bc = -1$   
 $= \frac{a}{c} + \frac{(1/c^2)r^2}{\bar{z} - a/c}$

$= m + \frac{r^2}{z-m} = m + r^2 \frac{z-m}{|z-m|^2}$

$\Rightarrow |f(z)-m|/|z-m| = r^2 \frac{|z-m|}{|z-m|^2} |z-m| = r^2$

$\Rightarrow f(z)$  is an inversion in its fixpointset

Q  $f$  conjugate to  $z \mapsto -\bar{z}$

[  $h$  map  $\mathbb{C}$  to  $\mathbb{R}^2$   $\Rightarrow$  "good" not iff as function  $\Rightarrow g = -\bar{z}$  ]

$\Delta$  case  $a+d=0$

$a+d \neq 0$   $(**)$   $\Rightarrow y=0 \Rightarrow$  no fixpts in  $\mathbb{H}$

Claim  $\exists$  a  $\mathbb{H}$ -line  $l$  s.t.  $f(l) = l$  as sets, and the fixpts of  $f =$  the endpoints of  $l$

PF If  $c=0$  then  $f(i) = \infty$ ,  $f(\frac{b}{d-a}) = \frac{b}{d-a}$   $\neq b$  since  $da = -1$

$\Rightarrow f(\{x = \frac{b}{d-a}\}) = \{x = \frac{b}{d-a}\}$  since this is

the  $\mathbb{H}$ -line w/  $\infty$  &  $\frac{b}{d-a}$  as endpoints.

$c \neq 0$ , then  $f$  has 2 real fixpts

$x_{\pm} = \frac{a-d \pm \sqrt{(a+d)^2 + 4c}}{2c}$ , and hence  $f$  must

map the  $\mathbb{H}$ -line  $l$  w/ these 2 pts as endpts to itself.  $\Delta$  claim

let  $h \in \text{Mob}^+(\mathbb{H})$  s.t.  $h(l) =$  imaginary axis

$\Rightarrow g = h \circ f \circ h^{-1}$  maps imaginary axis  $\mapsto$  imaginary axis



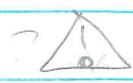
Q  
 $\Rightarrow g(z) = -\lambda^2 \bar{z}$  ( $z \mapsto -\overline{g(z)}$ ) maps  $i\mathbb{R}$  to  $i\mathbb{R}$   
 of the form  $\frac{az+b}{cz+d}$  &  $\lambda^2 z$  satisfies this  
 $\Rightarrow g(z) = -\lambda^2 \bar{z}$

and this is a composition of  $\tilde{g} = -\bar{z}$  &  $\tilde{h}(z) = \lambda^2 z$   
 $\Rightarrow \tilde{g}$  inversion in  $i\mathbb{R}$   
 &  $\tilde{h}$  is a hyperbolic transformation w/ axis  $i\mathbb{R}$ .

Also  $g = \underbrace{\tilde{g} \circ \tilde{h}}_{-(\lambda^2 \bar{z})} = \underbrace{\tilde{h} \circ \tilde{g}}_{\lambda^2 (-\bar{z})}$  so they commute.

Conjugate back  $\Rightarrow f = h^{-1} g h = h^{-1} \tilde{g} \tilde{h} h = \underbrace{(h^{-1} \tilde{g} h)}_{\text{inversion in line } h^{-1}(i\mathbb{R})} \underbrace{(h^{-1} \tilde{h} h)}_{\text{hyperbolic w/ axis } h^{-1}(i\mathbb{R})}$

Uniqueness See book.  $\square$

 For uniqueness we need  $(g, h)$  to commute.

2 otherwise many ways of writing  $f \in \text{Mob}^+(\mathbb{H})$

as  $f = gh$  w/  $g$  inversion,  $h \in \text{Mob}^+(\mathbb{H})$ .

16:6

Cor \*  $f \in \text{Möb}(\mathbb{H})$  inversion  $\Leftrightarrow a+d=0$

\*  $f \in \text{Möb}(\mathbb{H})$  inversion  $\Leftrightarrow$  it has a fixpt in  $\mathbb{H}$

\*  $f \in \text{Möb}(\mathbb{H})$  inversion in  $\mathbb{R}$

$\Leftrightarrow$  has  $\mathbb{R}$  as fixpoint set.