

Exercise 1.cFind \hat{X}_j and a_j for.

$$\begin{cases} X_j = aX_{j-1} + bY_j + \varepsilon_j \\ Y_j = cX_{j-1} + \zeta_j \end{cases} \quad j \geq 1$$

We can rewrite the previous system as

$$\begin{aligned} X_j &= aX_{j-1} + bcX_{j-1} + \varepsilon_j + b\zeta_j \\ &= (a+bc)X_{j-1} + \varepsilon_j + b\zeta_j \end{aligned}$$

$$X_j = cX_{j-1} + \zeta_j$$

then

$$a_0 = 0, a_1 = a+bc, a_2 = 0, b_1 = 1, b_2 = b$$

$$A_0 = 0, A_1 = c, A_2 = 0, B_1 = 0, B_2 = 1$$

and we have that

$$b_0 b_1 = 1 + b^2, \quad b_1 b_2 = b, \quad B_1 B_2 = 1$$

$$a_1 P_{j-1} A_1^T = (a+bc) P_{j-1} c = c(a+bc) P_{j-1}$$

$$A_2 P_{j-1} A_2^T = c^2 P_{j-1}$$

$$a_2 P_{j-1} a_2^T = (a+bc)^2 P_{j-1}$$

therefore

$$\hat{X}_j = (a+bc) \hat{X}_{j-1}$$

$$+ (c(a+bc) P_{j-1} + b) (c^2 P_{j-1} + 1)^{-1} (Y_j - c \hat{X}_{j-1})$$

$$P_j = (a+bc)^2 P_{j-1} + 1 + b^2 - (c(a+bc) P_{j-1} + b)^2 (c^2 P_{j-1} + 1)^{-1}$$

$$\hat{X}_0 = E[X_0] + \text{cov}(X_0, Y_0) \text{cov}(Y_0)^{-1} (Y_0 - E[Y_0]) = 0$$

$$P_0 = \text{cov}(X_0) - \text{cov}(X_0, Y_0) \text{cov}(Y_0)^{-1} \text{cov}(X_0, Y_0)^T = 0$$

Exercise 2.c

We have that

$$\begin{cases} X_j = \xi_j / \xi(X_{j-1}) \\ Y_j = X_j + \zeta_j \end{cases}$$

$$\zeta_j \mid X_{j-1} \sim \gamma_0.$$

ζ_j and ξ_j i.i.d.

$$P(X_j \in B \mid \mathcal{F}_{j-1}^X \vee \mathcal{F}_{j-1}^Y) = P(\xi_j / \xi(X_{j-1}) \in B \mid \mathcal{F}_{j-1}^X \vee \mathcal{F}_{j-1}^Y)$$

$$= E[\mathbb{1}_{\{\xi_j / \xi(X_{j-1}) \in B\}} \mid \mathcal{F}_{j-1}^X \vee \mathcal{F}_{j-1}^Y]$$

$$= E[\mathbb{1}_{\{\xi_j / \xi(a) \in B\}} \mid a = X_{j-1}]$$

$$= P(\xi_j / \xi(a) \in B \mid a = X_{j-1}) = (*)$$

$$\text{Let } Z_j := \xi_j / \xi(a), \quad P(Z_j \leq z) = P(\xi_j \leq z \xi(a))$$

$$= \int_{-\infty}^{z \xi(a)} p(u) du \Rightarrow f_{Z_j}(z) = \frac{d}{dz} P(Z_j \leq z) = p(z \xi(a)) \xi(a)$$

$$(*) = \int_B p(u \xi(X_{j-1})) \xi(X_{j-1}) du$$

$$\Rightarrow \Delta(X_{j-1}, du) = p(u \xi(X_{j-1})) \xi(X_{j-1}) du$$

$$\begin{aligned}
P(Y_j \mid \mathcal{F}_j^X \vee \mathcal{F}_{j-1}^Y) &= P(X_j + \zeta_j \in B \mid \mathcal{F}_j^X \vee \mathcal{F}_{j-1}^Y) \\
&= E[\mathbb{1}_{\{X_j + \zeta_j \in B\}} \mid \mathcal{F}_j^X \vee \mathcal{F}_{j-1}^Y] = E[\mathbb{1}_{\{a + \zeta_j \in B\}} \mid a = X_j] \\
&= P(a + \zeta_j \in B \mid a = X_j) = (***)
\end{aligned}$$

$$\text{Let } W_j := a + \zeta_j$$

$$P(W_j \leq z) = P(a + \zeta_j \leq z) = P(\zeta_j \leq z - a)$$

$$= \int_{-a}^{z-a} f(u) du$$

$$\Rightarrow f_{W_j}(z) = \frac{d}{dz} P(W_j \leq z) = f(z-a)$$

$$(***) = \int_B f(u - X_j) du =: \int_B \gamma(X_j, du)$$

$$\Rightarrow \gamma(x, u) = f(u - x) \quad \nu(du) = du$$

then by the previous result

$$\begin{aligned}
\pi_j(dx) &= \frac{\int_{\mathbb{R}} \gamma(x, Y_j) \Delta(u, dx) \pi_{j-1}(du)}{\int_{\mathbb{R}} \int_{\mathbb{R}} \gamma(x, Y_j) \Delta(u, dx) \pi_{j-1}(du)} \\
&= \frac{\int_{\mathbb{R}} f(Y_j - x) p(x \mid \xi(u)) \xi(u) dx \pi_{j-1}(du)}{\int_{\mathbb{R}} \int_{\mathbb{R}} f(Y_j - x) p(x \mid \xi(u)) \xi(u) dx \pi_{j-1}(du)}
\end{aligned}$$

$$= \frac{\int_{\mathbb{R}} q(y_j - x) p(x | \xi(\omega)) \xi(\omega) \pi_{j-2}(d\omega) dx}{\int_{\mathbb{R}} q(y_j - x) p(x | \xi(\omega)) \xi(\omega) \pi_{j-2}(d\omega)}$$

$$=: f(y_j, x) dx$$

Exercise 3.

θ random parameter and observations given by

$$dY_t = \theta M_t dt + N_t dW_t$$

M, N deterministic and W a Brownian motion.

a) Find equations for $\hat{\theta} = \hat{E}[\theta | \mathcal{H}_t^Y]$ and $P_t = E[(\theta - \hat{\theta})^2]$.

b) Prove that

$$\hat{\theta}_t = \frac{\hat{\theta}_0 P_0^{-1} + \int_0^t M_s N_s^{-2} dY_s}{P_0^{-1} + \int_0^t M_s^2 N_s^{-2} ds}$$

a) the equations for the signal and observation process are

$$d\theta_t = 0$$

$$dY_t = \theta_t M_t dt + N_t dB_t$$

this yields

$$a_t \equiv 0, b_t \equiv 0, A_t \equiv M_t, B_t \equiv N_t$$

and using the Kalman-Bucy filter formulae

$$\begin{aligned} d\hat{X}_t &= a_t \hat{X}_t dt + P_t \frac{A_t}{B_t} (dY_t - A_t \hat{X}_t dt) \\ &= P_t \frac{M_t}{N_t} (dY_t - M_t \hat{X}_t dt) \quad \left(\begin{array}{l} \text{substitute} \\ \hat{X}_t \text{ by } \hat{\theta}_t \end{array} \right) \end{aligned}$$

$$\begin{aligned} \dot{P}_t &= 2a_t P_t + b_t^2 - \frac{A_t^2 P_t}{B_t} \\ &= - \frac{M_t^2}{N_t^2} P_t \end{aligned}$$

Let's check that $P_t = \left(P_0^{-2} + \int_0^t M_s^2 N_s^{-2} ds \right)^{-2}$

$$\begin{aligned} \frac{d}{dt} P_t &= - \left(P_0^{-2} + \int_0^t M_s^2 N_s^{-2} ds \right)^{-2} \frac{M_t^2}{N_t^2} dt \\ &= - \left(\frac{M_t}{N_t} P_t \right)^2 dt \quad \checkmark \end{aligned}$$

Hence,

$$d\hat{\theta}_t = \left(P_0^{-2} + \int_0^t M_s^2 N_s^{-2} ds \right)^{-2} \frac{M_t}{N_t^2} (dY_t - M_t \hat{\theta}_t dt)$$

We can rewrite the previous equation as

$$\left(P_0^{-2} + \int_0^t M_s^2 N_s^{-2} ds \right) d\hat{\theta}_t = \frac{M_t}{N_t^2} dY_t - \frac{M_t^2}{N_t^2} \hat{\theta}_t dt$$



$$\left(P_0^{-2} + \int_0^t M_s^2 N_s^{-2} ds \right) d\hat{\theta}_t + \frac{M_t^2}{N_t^2} \hat{\theta}_t dt = \frac{M_t}{N_t^2} dY_t$$

But the left hand side of the previous equation coincides with

$$d \left(\left(P_0^{-2} + \int_0^t M_s^2 N_s^{-2} ds \right) \hat{\theta}_t \right) \quad (\text{or } d(P_t^{-2} \hat{\theta}_t))$$

Let's check it. First,

$$\begin{aligned} d P_t^{-2} &= - \frac{1}{P_t^2} dP_t = - \frac{1}{P_t^2} \left(- \frac{M_t^2}{N_t^2} P_t^2 dt \right) \\ &= M_t^2 N_t^{-2} dt \end{aligned}$$

Then

$$d(P_t^{-1} \hat{\theta}_t) = P_t^{-1} d\hat{\theta}_t + \hat{\theta}_t dP_t^{-1} + d\langle \hat{\theta}, P \rangle_t$$

P_t^{-1} continuous
and finite
variation

$$= (P_0^{-1} + \int_0^t M_s^2 N_s^{-2} ds) d\hat{\theta}_t + \hat{\theta}_t M_t^2 N_t^{-2} dt \quad \checkmark$$

Integrating

$$d\left((P_0^{-1} + \int_0^t M_s^2 N_s^{-2} ds) \hat{\theta}_t \right) = \frac{M_t}{N_t^2} dY_t$$

we get

$$\begin{aligned} (P_0^{-1} + \int_0^t M_s^2 N_s^{-2} ds) \hat{\theta}_t &= (P_0^{-1} + \int_0^t M_s^2 N_s^{-2} ds) \hat{\theta}_0 \\ &\quad + \int_0^t M_s N_s^{-2} dY_s \\ &= P_0^{-1} \hat{\theta}_0 + \int_0^t M_s N_s^{-2} dY_s \end{aligned}$$

which yields

$$\hat{\theta}_t = \frac{P_0^{-1} \hat{\theta}_0 + \int_0^t M_s N_s^{-2} dY_s}{P_0^{-1} + \int_0^t M_s^2 N_s^{-2} ds}$$