

24 Oct 2023
MAT 4800

dz & $d\bar{z}$

$\frac{\partial}{\partial x}, \frac{\partial}{\partial y}$ dx, dy

$\underbrace{\hspace{10em}}_{V = \mathbb{R}^2}$ $\underbrace{\hspace{10em}}_{V^*}$

$dz, d\bar{z} \in V^* \otimes \mathbb{C}$

$z = x + iy \Rightarrow dz = dx + idy$
 $\bar{z} = x - iy \Rightarrow d\bar{z} = dx - idy$

$\frac{\partial}{\partial z}, \frac{\partial}{\partial \bar{z}}$ is dual basis
to dz & $d\bar{z}$

\uparrow
 $V^* \otimes \mathbb{C}$

V is generated by $\frac{\partial}{\partial x}, \frac{\partial}{\partial y}$

$\Rightarrow \exists$ complex numbers $\alpha_1, \alpha_2,$
 β_1, β_2 such that:

$\frac{\partial}{\partial \bar{z}} = \alpha_1 \frac{\partial}{\partial x} + \alpha_2 \frac{\partial}{\partial y}$

Can we find α_1 & α_2 ?

$dz \left(\frac{\partial}{\partial z} \right) = 1, \quad d\bar{z} \left(\frac{\partial}{\partial z} \right) = 0$

$$dz \left(\frac{\partial}{\partial z} \right) = dz \left(\alpha_1 \frac{\partial}{\partial x} + \alpha_2 \frac{\partial}{\partial y} \right)$$

$$= \alpha_1 dz \left(\frac{\partial}{\partial x} \right) + \alpha_2 dz \left(\frac{\partial}{\partial y} \right)$$

$$dz = dx + i dy$$

$$\Rightarrow dz \left(\frac{\partial}{\partial x} \right) = (dx + i dy) \left(\frac{\partial}{\partial x} \right)$$

$$= dx \left(\frac{\partial}{\partial x} \right) + i dy \left(\frac{\partial}{\partial x} \right)$$

$$dz \left(\frac{\partial}{\partial y} \right) = (dx + i dy) \left(\frac{\partial}{\partial y} \right)$$

$$d\bar{z} = dx - i dy \Rightarrow \begin{aligned} d\bar{z} \left(\frac{\partial}{\partial x} \right) &= 1 \\ d\bar{z} \left(\frac{\partial}{\partial y} \right) &= -i \end{aligned}$$

$$1 = dz \left(\frac{\partial}{\partial z} \right) = \alpha_1 + i \alpha_2$$

$$0 = d\bar{z} \left(\frac{\partial}{\partial z} \right) = \alpha_1 - i \alpha_2$$

$$\Rightarrow \alpha_1 = i \alpha_2, \quad 2\alpha_1 = 1$$

$$\Rightarrow \alpha_1 = \frac{1}{2}, \quad \alpha_2 = \frac{1}{2i} = -\frac{i}{2}$$

$$\Rightarrow \frac{\partial}{\partial z} = \frac{1}{2} \frac{\partial}{\partial x} - \frac{i}{2} \frac{\partial}{\partial y}$$

Similarly:

$$\frac{\partial}{\partial \bar{z}} = \frac{1}{2} \frac{\partial}{\partial x} + \frac{i}{2} \frac{\partial}{\partial y}$$

Riemann - Cauchy equation:

f is holomorphic in a disc
 $\Rightarrow f$ has a power series:

$$f(z) = \sum_{n=0}^{\infty} a_n z^n$$

has no \bar{z}

$$\Rightarrow \frac{\partial}{\partial \bar{z}} f(z) = 0$$

$$f = u + iv(x, y)$$

$$\frac{\partial}{\partial \bar{z}} = \frac{1}{2} \left(\frac{\partial}{\partial x} + i \frac{\partial}{\partial y} \right)$$

$$\begin{cases} z = x + iy \\ \bar{z} = x - iy \end{cases}$$

$$\Rightarrow x = \frac{z + \bar{z}}{2}$$

$$y = \frac{z - \bar{z}}{2i}$$

$$0 = \frac{\partial}{\partial \bar{z}} f = \frac{1}{2} \left(\frac{\partial}{\partial x} + i \frac{\partial}{\partial y} \right) (u + iv)$$

$$= \frac{1}{2} \left(\frac{\partial u}{\partial x} + i \frac{\partial v}{\partial x} + i \frac{\partial u}{\partial y} - \frac{\partial v}{\partial y} \right)$$

$$= \frac{1}{2} \left[\left(\frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} \right) + i \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right]$$

$$\Rightarrow \begin{cases} \frac{\partial u}{\partial x} = \frac{\partial v}{\partial y} \\ \frac{\partial v}{\partial x} = -\frac{\partial u}{\partial y} \end{cases}$$

How can we define over a general RS X ?

* Extrinsic method:

For every $x_0 \in X$, \exists a coordinate neighborhood $U \subseteq X$ so that U is homeomorphic to an open subset V of \mathbb{C} .

\leadsto So we can identify the tangent vectors & differential forms on V with that on U .

* Intrinsic method:

Look at $\mathcal{O}_U \leftarrow$ sheaf of holomorphic germs over U .

$$m_{x_0} = \{ \varphi \in \mathcal{E}_{x_0} : \varphi(x_0) = 0 \}$$

$$m_{x_0}^2 = \{ \varphi \in \mathcal{E}_{x_0} : \begin{array}{l} \varphi(x_0) = 0, \\ \varphi'(x_0) = 0 \end{array} \}$$

Then define: Σ : differential functions $f: U \rightarrow \mathbb{C}$

$$\Omega_{x_0}^1 = \frac{m_{x_0}}{m_{x_0}^2} \Rightarrow 1\text{-forms}$$

Ω^1 is the sheaf of 1-forms on X
 $\Omega_{x_0}^1$ is the stalk.

$$d_{x_0}(f) = (f - f(x_0)) \pmod{m_{x_0}^2}$$

(f : a smooth function on a neighborhood of x_0)

Explanation: Let's look at

By Taylor's expansion: $f(x, y) = ax + by + \text{higher order terms}$

$$f(0, 0) = 0.$$

$$\text{We define } f(x, 0) \cdot \frac{\partial}{\partial x} = a$$

$$f(x, y) \cdot \frac{\partial}{\partial y} = b$$

is So we are using a theorem: if V is finite dimensional vector space then $V^{**} = V$

We know:

differential forms ~~is~~ dual to vectors

\Rightarrow vectors is dual to differential forms

But vectors is also dual to functions of the form $ax + by$.

So functions of the form $ax + by$ can be identified with differential forms.

$$\text{So also } dx \text{ \& } dy \text{ is a basis for } \Omega_{x_0}^1$$

$$\left(\begin{array}{l} dz = \frac{dx + dy}{2} \\ d\bar{z} = \frac{dx - dy}{2i} \end{array} \right)$$

$\Omega_{X_0}^{1,0} =$ subvector space of $\Omega_{X_0}^1$
generated by dz

$\Omega_{X_0}^{0,1} =$ - - - -
generated by $d\bar{z}$.

Holomorphic 1-form: elements in
 $\Omega_{X_0}^{1,0}$ which has the form
 $f(z) dz,$
where $f(z)$ holomorphic.
Meromorphic 1-forms:

$f(z) dz,$

where f is a meromorphic function.

Pull back of differential form:

Assume $f: X \rightarrow Y$ a smooth
function.

Let ω be a 1-form on Y .

locally: $\omega(y_1, \dots, y_n) = \sum_{i=1}^n g_i(y) dy_i$

Then: $f^* \omega$ is a 1-form on X ,
defined (locally) by:
 $f^* \omega(x_1, \dots, x_n) =$

$$(f^* \omega)(x_1, \dots, x_n) = \sum_{i=1}^n g_i(f(x_1, \dots, x_n)) df_i(x_1, \dots, x_n)$$

where $f = (f_1, \dots, f_n)$.

Example 1:

$$f: \mathbb{R} \rightarrow \mathbb{R}^3$$

$$t \mapsto (t+1, t^2, e^t)$$

$\begin{matrix} \parallel & \parallel & \parallel \\ y_1 & y_2 & y_3 \end{matrix}$

$$\omega(y_1, y_2, y_3) = y_2 dy_1 + y_1 y_3 dy_2 + y_3 dy_3$$

$$(f^* \omega)(t) =$$

$$(y_1, y_2, y_3)(t) = f(t)$$

$$= (t+1, t^2, e^t)$$

$$= t^2 d(t+1) + (t+1)e^t d(t^2) + e^t d(e^t)$$

$$= t^2 dt + (t+1)e^t 2t dt + e^t \cdot e^t dt$$

$$= (t^2 + (t+1)e^t 2t + e^{2t}) dt.$$

Example 2:

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}^3 \quad \begin{matrix} y_1 \\ y_2 \\ y_3 \end{matrix}$$

$$(x_1, x_2) \mapsto \begin{pmatrix} x_1^2 - x_2^2 \\ x_1^3 + e^{x_2} \\ e^{x_1 \cdot x_2} \end{pmatrix}$$

$$w = y_2 dy_1 + y_1 y_3 dy_2 + y_3 dy_3$$

Then $(f^* w)(x_1, x_2)$

$$= (x_1^3 + e^{x_2}) d(x_1^2 - x_2^2)$$

$$+ (x_1^2 - x_2^2) e^{x_1 \cdot x_2} d(x_1^3 + e^{x_2})$$

$$+ e^{x_1 x_2} d(e^{x_1 x_2})$$

$$dh(x_1, x_2) = \frac{\partial h}{\partial x_1} dx_1 + \frac{\partial h}{\partial x_2} dx_2$$

$$h(x_1, x_2) = x_1^2 - x_2^2$$

$$\Rightarrow dh(x_1, x_2) = 2x_1 dx_1 - 2x_2 dx_2$$

Similarly (HW).

Theorem: let X & Y be R.S.

$f: X \rightarrow Y$ holomorphic function.

If w is a holomorphic 1-form on Y , then $f^* w$ is a holomorphic 1-form on X .

If w is a meromorphic 1-form on Y , then $f^* w$ is meromorphic.

Proof:

Let $\omega(y) = h(y) dy$, where

y is a local coordinate of Y , & $h(y)$ is holomorphic in y . $y = f(x)$

$$\begin{aligned} (f^* \omega)(x) &= h(f(x)) d(f(x)) \\ &= \underbrace{h(f(x))}_{\text{holomorphic}} \underbrace{f'(x)}_{\text{holomorphic}} \underline{dx} \end{aligned}$$

If ω is meromorphic $\Rightarrow h$ is meromorphic

$$\Rightarrow (f^* \omega)(x) = \underbrace{h(f(x))}_{\text{meromorphic}} \underbrace{f'(x)}_{\text{holomorphic}} dx$$

□

$$X = Y = \mathbb{C}$$

$$f: \mathbb{C} \rightarrow \mathbb{C}$$

$$x \mapsto y = x^2$$

$$f^*(dy) = d(x^2) = 2x dx.$$

Example 2: $f: \mathbb{C} \rightarrow \mathbb{C}$

$$x \mapsto y = x^2$$

$$\omega(y) = \frac{dy}{y}$$

$$\Rightarrow (f^* \omega)(x) = \frac{d(f(x))}{f(x)} = \frac{d(x^2)}{x^2}$$

$$= \frac{2x dx}{x^2} = \frac{2 dx}{x}$$

Example 3: $f: \mathbb{D}^* \rightarrow \mathbb{D}^*$
 $x \mapsto y = x^3$

$$\omega(y) = y^2 dy$$

$$\Rightarrow f^*(\omega)(x) = (x^3)^2 d(x^3)$$

$$= 3x^8 dx.$$

Example 4: $f: \mathbb{C} \rightarrow \mathbb{C}$
 $x \mapsto y = ax$ ($a \neq 0$ constant)

$$\omega_1 = \frac{dy}{y} \Rightarrow (f^*\omega_1)(x) = \frac{dx}{x}$$

$\omega_2 = dy \Rightarrow (f^*\omega_2)(x) = a dx.$ ←
 ↪ same form ↪
 ↪ not the same, if $a \neq 1$ ↪

Differential form on X : is locally of the form
 $\sum_{i=1}^n a_i(x) dx_i$ ($\dim(X) = n$)
 $a_i(x)$ smooth functions in x .

Holomorphic 1-form on a R.S. X :

Locally of the form
 $h(z) dz$,
 z : local coordinate, $h(z)$ holomorphic in z .

Meromorphic 1-form:

locally $h(z) dz$
 z : local coordinate, $h(z)$ meromorphic in z .

Poles & zeros of meromorphic 1-form:

If ω is locally of the form $h(z) dz$, then we call zeros of $h(z)$ zeros of ω , & poles of $h(z)$ poles of ω .

Theorem: Poles & zeros of a meromorphic 1-form of a R.S. is independent of the choice of coordinates.

Proof:

$$\text{Let } \omega(z) = h(z) dz.$$

$z = \varphi(y)$ is a change of coordinates $\Rightarrow \varphi'(y)$ is never zero.

$$\begin{aligned} (\varphi^* \omega)(y) &= h(z) dz \\ &= h(\varphi(y)) d(\varphi(y)) \\ &= \underline{h(\varphi(y)) \varphi'(y) dy} \end{aligned}$$

Since $\varphi'(y)$ is holomorphic & never zero, poles & zeros of $(\varphi^* \omega)(y)$ are the same as those for $h(\varphi(y))$ & so the same as ω . \square

Then not true if φ' has a zero.

Example (again)

$$\varphi: \mathbb{C} \rightarrow \mathbb{C}$$

$$x \mapsto y = x^2$$

$\omega = dy$ has no root & pole
 $(\varphi^* \omega)(x) = 2x dx$ has a root
 at $x = 0$.

And $\{x = 0\}$ is exactly the set
 where φ is not unbranched.

Defn: Residue of a meromorphic
 form at a point x , in a local coordinate
 z where $z = 0$ at x , is α ,

if $\omega = \left(\sum_{n=-N}^{\infty} a_n z^n \right) dz$
 & $\alpha = a_{-1}$. Write $\text{Res}[\omega, x] = \alpha$.

Theorem: Residue is independent
 of the choice of coordinate.

Proof: It is equivalent to show that
 if $\varphi: \mathbb{C} \rightarrow \mathbb{C}$ is holomorphic
 $\varphi'(0) \neq 0$ & ω is a meromorphic
 1-form on \mathbb{C} , then:
 $\text{Res}[\omega, 0] = \text{Res}[\varphi^* \omega, 0]$.

$$\omega(z) = \left(\sum_{n=-N}^{\infty} a_n z^n \right) dz$$

$$\varphi(0) = 0, \quad \varphi'(0) \neq 0$$

$$\text{So } \varphi(y) = y h(y), \text{ where } h(y) \neq 0.$$

$$(\varphi^* \omega)(y) = \left(\sum_{n=-N}^{\infty} a_n (y h(y))^n \right) d(y h(y))$$

$$= \sum_{n=-N}^{\infty} a_n y^n h(y)^n h'(y) y dy$$

$$+ \sum_{n=-N}^{\infty} a_n y^n (h(y))^n h'(y) y dy$$

Special case: $h(y) = cy \Rightarrow$ done!

$$z = \varphi(y) = y(1-y)$$

$$\omega = \left(\frac{1}{z^2} + \frac{1}{z} \right) dz$$

$$(\varphi^* \omega)(y) = \left(\frac{1}{(y(1-y))^2} + \frac{1}{y(1-y)} \right) d(y(1-y))$$

$$= \left(\frac{1}{y^2} (1+y+y^2+\dots)^2 + \frac{1}{y} (1+y+y^2+\dots) \right) (1-2y) dy$$

$$\frac{1}{y^2} (1+y+y^2+\dots)^2 (1-2y)$$

$$= \frac{1}{y^2} (1+2y+y^2+\dots) \left(\frac{1-2y}{y} - 4 + \dots \right)$$