

Math 4800

5 September 2023

§1. Riemann surfaces

$$f: \begin{matrix} A & \rightarrow & B \\ \subset \mathbb{R}^n & & \subset \mathbb{R}^m \end{matrix} \text{ continuous map}$$

f is homeomorphism if it is bijective
& the inverse $f^{-1}: B \rightarrow A$ is also
continuous.

Recall about real manifolds: X

"Locally" it looks like ~~\mathbb{R}~~ a ball in
 \mathbb{R}^n .

We need 2 properties:

① For every $x \in X$, $\exists x \in U \subseteq X$
 \downarrow
 open
 & a homeomorphism
 $f: U \rightarrow \mathbb{R}^n$ $f(U) \subseteq \mathbb{R}^n$
 \parallel
 $\cup \mathbb{R}^n$
 where V is an open set in $\cup \mathbb{R}^n$.

② Transition maps are smooth:

$$\begin{array}{ccc} X \supseteq U_1 & & U_2 \subseteq X \\ \downarrow f_1 & & \downarrow f_2 \\ \mathbb{R}^n \supseteq V_1 & & V_2 \subseteq \mathbb{R}^n \\ & & U_{1,2} = U_1 \cap U_2 \end{array}$$

We have 2 different maps from

$$U_{1,2} \text{ to } \mathbb{R}^n: \quad f_1 : U_{1,2} \rightarrow f_1(U_{1,2}) \\ \parallel \\ V_{1,2} \subseteq \mathbb{R}^n$$

$$f_2 : U_{1,2} \rightarrow f_2(U_{1,2}) \subseteq \mathbb{R}^n \\ \parallel \\ V_{2,1}$$

They may be different maps but we want them to be smoothly transitioned:

$$\begin{array}{ccc} & U_{1,2} & \\ \swarrow f_1 & & \searrow f_2 \\ \mathbb{R}^n \supseteq V_{1,2} & & V_{2,1} \subseteq \mathbb{R}^n \\ \text{Transition map: } & f_{1,2} : V_{1,2} \xrightarrow{f_1^{-1}} U_{1,2} & \\ & \xrightarrow{f_2} V_{2,1} & \end{array}$$

Want $f_{1,2}$ to be C^∞ !!

(Need some technical conditions on the topology of X to avoid pathological properties.)

Riemann surfaces: X Very similar

(1) $\forall x \in X, \exists x \in U \subseteq X$
 \uparrow
 homeomorphic open subsets:
 $f: U \xrightarrow{\sim} f(U) \subseteq \mathbb{C}$
 \Downarrow
 $U \rightarrow \text{open}$

(2) Transition maps are holomorphic!

Trivial examples: Every open ^{set} of \mathbb{C} is a RS. ($f: X \rightarrow \mathbb{C}$ identity map.

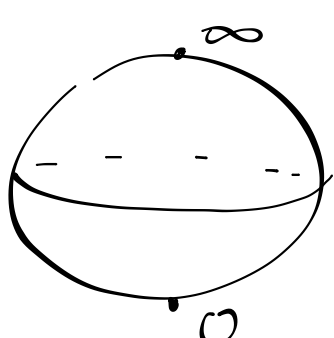
Transition maps are identity map. |

" $f(z) = z$

Nontrivial example:

Example 1: Riemann sphere
 $= \{ (x_1, x_2, x_3) \in \mathbb{R}^3 : x_1^2 + x_2^2 + x_3^2 = 1 \}$

$X = \text{Riemann sphere} = \mathbb{P}^1$
 $\mathbb{C} \cup \infty$ \Downarrow projective line
 $X_1 = \mathbb{C}, X_2 = X \setminus \{0\}$
 \Downarrow north pole \Downarrow south pole
 $X = X_1 \cup X_2$
 $X_1 = \mathbb{C}$ with coordinate z
 $X_2 = \mathbb{C}$ with coordinate w



$f_1: X_1 \xrightarrow{\cong} \mathbb{C}_z$
 $z \rightarrow z$
 $f_2: X_2 \xrightarrow{\cong} \mathbb{C}_w$
 $w \rightarrow w$

$w = \frac{1}{z}$

$X_1 \cap X_2 = \mathbb{C} \setminus \{0, \infty\}$

$\begin{array}{ccc} \downarrow \delta_1 & & \downarrow \\ \mathbb{Z} & & \boxed{w = \frac{1}{z}} \end{array}$

Transition map

$\mathbb{C} \setminus \{0, \infty\} \xrightarrow{\quad} \mathbb{C} \setminus \{0, \infty\}$
 $z \mapsto w = \frac{1}{z}$

So here we are not given embedding maps but actually transition map.

Remark: Since z & w coordinates are different, the 0 in z -coordinate is not the same as the 0 in w -coordinate. Actually, because $w = \frac{1}{z}$, the 0 in z -coordinate is the ∞ in w -coordinate.

Holomorphic map from $\mathbb{R}S$ to \mathbb{C} :

if \forall coordinate open set $U \subseteq X$

$f \downarrow$
 $V \subseteq \mathbb{C}$

$g: X \xrightarrow{\mathbb{R}S} \mathbb{C}$ is holomorphic

$$\begin{array}{ccc}
 \mathbb{C} & & X \\
 \downarrow \nu & & \downarrow \mu \\
 V & \xrightarrow{g^{-1}} & U & \xrightarrow{g|_U} & \mathbb{C}
 \end{array}$$

$\underbrace{\hspace{10em}}_h$

then h is holomorphic!

$$\begin{array}{ccc}
 & U_1 \cap U_2 & \\
 \swarrow \delta_1 & & \searrow \delta_2 \\
 \mathbb{C} \supseteq V_{1,2} & & V_{2,1} \subseteq \mathbb{C}
 \end{array}$$

\Rightarrow then $V_{1,2} \rightarrow \mathbb{C}$ is holomorphic
 $V_{2,1} \rightarrow \mathbb{C}$ is holomorphic.

Proof:

$$V_{2,1} \rightarrow \mathbb{C} = V_{2,1} \rightarrow V_{1,2} \rightarrow \mathbb{C}$$

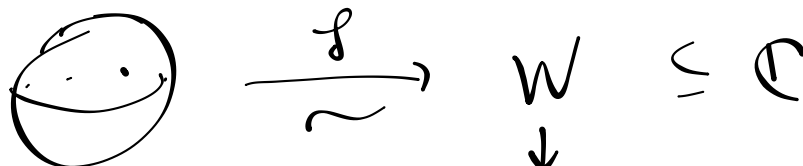
holomorphic by composition
 \downarrow
 transition
 \Downarrow
 holomorphic

Q: Is $X = \mathbb{P}^1$ a subset of \mathbb{C} ?
 (i.e. biholomorphic to a subset of \mathbb{C} ?)

Answer: If X were biholomorphic to a subset of \mathbb{C} , then there would be a non-constant holomorphic map from X to \mathbb{C} .

X is compact.

$\Rightarrow f(X)$ is compact. Will violate the maximum principle.



Let $w^* \in W$ so that $|w^*| = \max_{W \in W} |w|$.
 $x^* = f(w^*)$ & a small
 look at ~~set~~ coordinate set U^* around x^* so that ~~$f(U^*)$~~

$$X \supseteq U^* \xrightarrow{f} W \subseteq \mathbb{C}$$

$g \downarrow r$

$$\mathbb{C} \supseteq g(U^*) = V^* \subseteq \mathbb{C}$$

Look at $V^* \rightarrow U^* \rightarrow W$ & apply maximum principle for this map.

X : RS from now on assume to be connected.

Another way to look at P' :

look at the set of ^{complex} lines in \mathbb{C}^2
going through $(0,0)$. \mathbb{C}_{z_1, z_2}^2

$$L_{a,b} = \{ az_1 + bz_2 = 0 \}$$

$$(a,b) \neq (0,0)$$

$$L_{a,b} = L_{\alpha a, \alpha b}, \text{ for } \alpha \in \mathbb{C}^* = \mathbb{C} \setminus \{0\}$$

$$\Lambda = \mathbb{P}^1!$$

$$\Lambda = \{ (a,b) \in \mathbb{C}^2 \setminus \{(0,0)\} \}$$

\downarrow has quotient topology

Q: What are open sets in Λ ?

$$(a,b) \sim (c,d) \text{ if } \exists$$

$$\alpha \in \mathbb{C}^* \text{ so that}$$

$$\begin{cases} a = \alpha c \\ b = \alpha d \end{cases}$$

To remember this we use the notation:

$$[a:b] \text{ instead of } (a,b)$$

$$[a:b] = [\alpha a : \alpha b] \quad \forall \alpha \in \mathbb{C}^*$$

$$\text{Claim } \Lambda = \mathbb{P}^1.$$

$$\Lambda_1 = \{ [a:b] \in \Lambda : b \neq 0 \}$$

$$\Lambda_2 = \{ [a:b] \in \Lambda : a \neq 0 \}$$

(Claim) $f_1: \Lambda_1 \cong \mathbb{C}$

Define a map

$$\Lambda_1 \longrightarrow \mathbb{C}$$

$$\left[\frac{a}{b} : 1 \right] = [a:b] \mapsto z = \frac{a}{b}$$

This is a homeomorphism

$$[z:1] \longleftarrow z \quad \text{Inverse map}$$

$$\Lambda_2 = \{ [a:b], a \neq 0 \}$$

$$\parallel$$

$$\left[\underline{1} : \frac{b}{a} \right]$$

$$f_2 \quad \Lambda_2 \longrightarrow \mathbb{C}_w$$

$$[a:b] \mapsto w = \frac{b}{a}$$

$$[1:w] \longleftarrow w$$

What is the relation between z & w ?
 Look at a point $[a:b] \in \Lambda_1 \cap \Lambda_2$
 $= \{ [a:b] \in \mathbb{C} : a, b \in \mathbb{C}^* \}$

$$z = \frac{a}{b} \Rightarrow \boxed{w = \frac{1}{z}}$$

$$w = \frac{b}{a}$$

↓
Transition map
between coordinates
 z & w

Example 3: $X = \{(z_1, z_2) \in \mathbb{C}^2 : f(z_1, z_2) = 0\}$

f : holomorphic map $\mathbb{C}^2 \rightarrow \mathbb{C}$
(For this course, just need to care about $f = \text{polynomial}$)

Assume that $\forall (z_1^*, z_2^*) \in X$:

$$\left(\frac{\partial f}{\partial z_1}(z_1^*, z_2^*), \frac{\partial f}{\partial z_2}(z_1^*, z_2^*) \right) \neq (0, 0).$$

Then X is a RS.

(Proof later)

Example: $f(z_1, z_2) = z_1 - z_2^2$

$$\nabla f = \left(\frac{\partial f}{\partial z_1}, \frac{\partial f}{\partial z_2} \right) = \left(1, -2z_2 \right)$$

$\neq (0, 0) \forall z_1, z_2$

$$\Rightarrow X = \{z_1 - z_2^2 = 0\} \text{ is a RS.}$$

$X \subseteq \mathbb{C}^2$
 " graph of the function $f(z) = z^2$
 We can think about z_2 like $\sqrt{z_1}$.
 If $\sqrt{1} = 1 \Rightarrow \sqrt{e^{2\pi i}} = e^{\pi i}$
 (Riemann's) $X = \{z_1 - z_2^2 = 0\}$ is the RS
 idea of the $z \mapsto \sqrt{z}$:
 $w = \sqrt{z} \Rightarrow w^2 = z$
 $\mathbb{C}^2 \ni (z_1, z_2) \mapsto z_1$
 $X \rightarrow \mathbb{C}^2$ RS of \sqrt{z}
 $(z_1, z_2) \mapsto z_1$

Example: $f(z_1, z_2) = z_1^2 - 3z_2^3 + 1$
 $\nabla f = \left(\frac{\partial f}{\partial z_1}, \frac{\partial f}{\partial z_2} \right) = (2z_1, -9z_2^2)$
 it is $(0, 0)$ at $(z_1, z_2) = (0, 0)$.
 But $(0, 0) \notin X = \{f(z_1, z_2) = 0\}$
 $\Rightarrow X$ is RS
 (affine part of)
 (elliptic curve)
Proof of Theorem:

Let $z^* = (z_1^*, z_2^*) \in X$ so that

$$\left(\frac{\partial f}{\partial z_1}(z_1^*, z_2^*), \frac{\partial f}{\partial z_2}(z_1^*, z_2^*) \right) \neq (0, 0)$$

Then \exists an open set $U \subseteq X$ so
 that $f: U \xrightarrow{\text{homeomorphic}} f(U) \subseteq \mathbb{C}$
 & also transition function is holomorphic.

Inverse function theorem for complex functions:

$$f(z_1, z_2) = 0 \quad \text{on } X$$

$$\Rightarrow df = 0 \quad \text{on } X$$

Near (z_1^*, z_2^*) we can write:

$$0 = df = \frac{\partial f}{\partial z_1}(z_1^*, z_2^*) \cdot \cancel{(z_1 - z_1^*)} dz_1 + \frac{\partial f}{\partial z_2}(z_1^*, z_2^*) \cdot \cancel{(z_2 - z_2^*)} dz_2 + \dots$$

Just assume that linear approximation is precise & assume $\frac{\partial f}{\partial z_1}(z_1^*, z_2^*) \neq 0$

\Rightarrow we can divide it.

$$dz_1 = - \frac{\frac{\partial f(z_1^*, z_2^*)}{\partial z_2}}{\frac{\partial f(z_1^*, z_2^*)}{\partial z_1}} dz_2$$

$\Rightarrow z_1$ is a holomorphic function in z_2 .
(in a neighborhood U .)

So

Meaning

$$U \rightarrow \mathbb{C}_{z_2} \\ (z_1, z_2) \mapsto z_2 \quad \square$$

is

$$f(z_1, z_2) = z_1^2 - 3z_2^3 + 1$$

HW:

Look at $(i, 0)$
What is your coordinate system
near this point?