

## Krumlinjete koordinater

Har funnet generelle uttrykk

$$\nabla f = \sum_{i=1}^3 \frac{\vec{e}_i}{h_i} \frac{\partial f}{\partial u_i}$$

$$\nabla \cdot \vec{v} = \frac{1}{h_1 h_2 h_3} \sum_{i=1}^3 \frac{\partial}{\partial u_i} \left( \frac{h_1 h_2 h_3 v_i}{h_i} \right)$$

$$\vec{e}_3 \cdot \nabla \times \vec{v} = \frac{1}{h_1 h_2} \left( \frac{\partial v_2 h_2}{\partial u_1} - \frac{\partial v_1 h_1}{\partial u_2} \right)$$

Vil nå bare vise at disse kan brukes rett frem!

## Polarkoordinater

$$X = r \cos \theta$$

$$Y = r \sin \theta$$

(sylinder)  
z = z

$$(u_1, u_2) = (r, \theta)$$

$$\vec{r} = r \cos \theta \hat{i} + r \sin \theta \hat{j}$$

$$\vec{e}_r = \frac{1}{h_r} \frac{\partial \vec{r}}{\partial r} = \frac{\cos \theta \hat{i} + \sin \theta \hat{j}}{1}$$

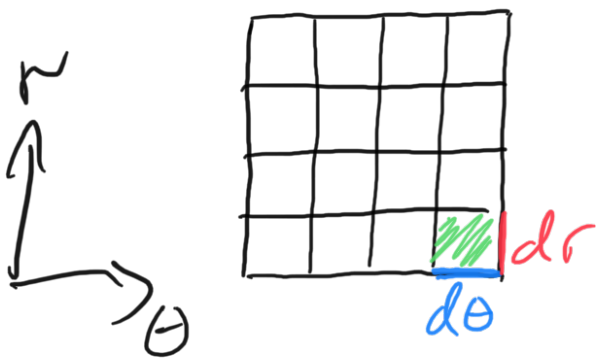
$$h_r = 1$$

$$\vec{e}_\theta = \frac{1}{h_\theta} \frac{\partial \vec{r}}{\partial \theta} = \frac{-r \sin \theta \hat{i} + r \cos \theta \hat{j}}{\sqrt{r^2 \sin^2 \theta + r^2 \cos^2 \theta}}$$

$$\vec{e}_\theta = -\sin \theta \hat{i} + \cos \theta \hat{j}$$

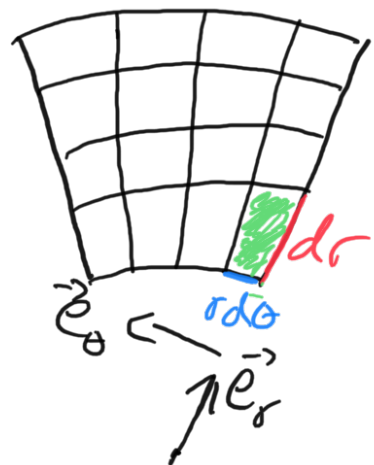
$$h_\theta = r$$

Flatelement



$d\theta dr$

Beregnings-  
koordinater



$r dr d\theta$

Fysiske  
koordinater

$$\frac{\partial \vec{r}}{\partial r} \times \frac{\partial \vec{r}}{\partial \theta} = (\cos \theta \mathbf{i} + \sin \theta \mathbf{j}) \times (-r \sin \theta \mathbf{i} + r \cos \theta \mathbf{j})$$

$$= rk \mathbf{r}$$

$$\vec{n} d\sigma = \frac{\partial \vec{r}}{\partial r} \times \frac{\partial \vec{r}}{\partial \theta} dr d\theta$$

$$= rk r dr d\theta$$


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Merk:

$$\vec{r} = r \cos \theta \mathbf{i} + r \sin \theta \mathbf{j}$$

$$\text{Har } \mathbf{i}_r = \cos \theta \mathbf{i} + \sin \theta \mathbf{j}$$

$$\Rightarrow \vec{r} = r \mathbf{i}_r$$


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Kan bruke denne videre

$$d\vec{r} = \frac{\partial \vec{r}}{\partial r} dr + \frac{\partial \vec{r}}{\partial \theta} d\theta$$

$$= \frac{\partial r \hat{u}_r}{\partial r} dr + \frac{\partial r \hat{u}_r}{\partial \theta} d\theta$$

$$= \hat{u}_r dr + r \frac{\partial \hat{u}_r}{\partial \theta} d\theta$$

$$d\vec{r} = \hat{u}_r dr + r \hat{u}_\theta d\theta$$

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Stemmer overens med

$$d\vec{r} = h_1 \vec{e}_1 du_1 + h_2 \vec{e}_2 du_2$$

siden

$$h_1 = h_r = 1, \quad \vec{e}_1 = \hat{u}_r, \quad du_1 = dr$$

$$h_2 = h_\theta = r, \quad \vec{e}_2 = \hat{u}_\theta, \quad du_2 = d\theta$$

Gradient

$$\nabla f = \frac{\vec{e}_1}{h_1} \frac{\partial f}{\partial u_1} + \frac{\vec{e}_2}{h_2} \frac{\partial f}{\partial u_2} + \frac{\vec{e}_3}{h_3} \frac{\partial f}{\partial u_3}$$

$$\Rightarrow \nabla f = \hat{e}_r \frac{\partial f}{\partial r} + \frac{\hat{e}_\theta}{r} \frac{\partial f}{\partial \theta}$$

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Divergens

$$\begin{aligned} \nabla \cdot \vec{u} &= \sum_{i=1}^3 \frac{1}{h_1 h_2 h_3} \frac{\partial}{\partial u_i} \left( \frac{h_1 h_2 h_3 u_i}{h_i} \right) \\ &= \frac{1}{r} \left( \frac{\partial}{\partial r} (r u_r) + \frac{\partial u_\theta}{\partial \theta} \right) \end{aligned}$$

Virvling

$$\text{Ik. } \nabla \times \vec{u} = \frac{1}{r} \left( \frac{\partial r u_\theta}{\partial r} - \frac{\partial u_r}{\partial \theta} \right)$$

Merk: Divergens og virvling i polar/sylinder-koordinater finnes lett ved direkte regning:

$$\nabla = \hat{e}_r \frac{\partial}{\partial r} + \frac{\hat{e}_\theta}{r} \frac{\partial}{\partial \theta}$$

$$\vec{v} = v_r \dot{\kappa}_r + v_\theta \dot{\kappa}_\theta$$

$$\nabla \cdot \vec{v} = \left( \dot{\kappa}_r \frac{\partial}{\partial r} + \frac{\dot{\kappa}_\theta}{r} \frac{\partial}{\partial \theta} \right) \cdot (v_r \dot{\kappa}_r + v_\theta \dot{\kappa}_\theta)$$

$$= \dot{\kappa}_r \frac{\partial}{\partial r} \cdot v_r \dot{\kappa}_r + \dot{\kappa}_r \frac{\partial}{\partial r} \cdot v_\theta \dot{\kappa}_\theta$$

$$+ \frac{\dot{\kappa}_\theta}{r} \frac{\partial}{\partial \theta} \cdot v_r \dot{\kappa}_r + \frac{\dot{\kappa}_\theta}{r} \frac{\partial}{\partial \theta} \cdot v_\theta \dot{\kappa}_\theta$$

Husk:  $\dot{\kappa}_r = \cos\theta \dot{\kappa} + \sin\theta \dot{j}$

$$\dot{\kappa}_\theta = -\sin\theta \dot{\kappa} + \cos\theta \dot{j}$$

$$\dot{\kappa}_r \frac{\partial}{\partial r} \cdot v_r \dot{\kappa}_r = \dot{\kappa}_r \cdot \dot{\kappa}_r \frac{\partial v_r}{\partial r} = \frac{\partial v_r}{\partial r}$$

$$\dot{\kappa}_r \frac{\partial}{\partial r} \cdot v_\theta \dot{\kappa}_\theta = \dot{\kappa}_r \cdot \dot{\kappa}_\theta \frac{\partial v_\theta}{\partial r} = \underline{0}$$

$$\begin{aligned} \frac{\dot{\kappa}_\theta}{r} \frac{\partial}{\partial \theta} \cdot v_r \dot{\kappa}_r &= \frac{\dot{\kappa}_\theta}{r} \cdot \left( v_r \frac{\partial \dot{\kappa}_r}{\partial \theta} + \dot{\kappa}_r \frac{\partial v_r}{\partial \theta} \right) \\ &= \frac{\dot{\kappa}_\theta}{r} \cdot \left( v_r \dot{\kappa}_\theta + \dot{\kappa}_r \frac{\partial v_r}{\partial \theta} \right) \end{aligned}$$

$$\begin{aligned}
&= \frac{v_r}{r} \\
\frac{\dot{\omega}_\theta}{r} \frac{\partial}{\partial \theta} \cdot v_\theta \dot{\omega}_\theta &= \frac{\dot{\omega}_\theta}{r} \cdot \left( v_\theta \frac{\partial \dot{\omega}_\theta}{\partial \theta} + \dot{\omega}_\theta \frac{\partial v_\theta}{\partial \theta} \right) \\
&= \frac{\dot{\omega}_\theta}{r} \cdot \left( v_\theta (-\dot{\omega}_r) + \dot{\omega}_\theta \frac{\partial v_\theta}{\partial \theta} \right) \\
&= \frac{1}{r} \frac{\partial v_\theta}{\partial \theta}
\end{aligned}$$

$$\begin{aligned}
\Rightarrow \nabla \cdot \vec{v} &= \frac{\partial v_r}{\partial r} + 0 + \frac{v_r}{r} + \frac{1}{r} \frac{\partial v_\theta}{\partial \theta} \\
&= \frac{1}{r} \frac{\partial (r v_r)}{\partial r} + \frac{1}{r} \frac{\partial v_\theta}{\partial \theta}
\end{aligned}$$

Prøve tilsvarende med  $\text{ik} \cdot \nabla \times \vec{v}$ .

# Kulekoordinater

$$(u_1, u_2, u_3) = (r, \theta, \varphi)$$

$$X = r \sin \theta \cos \varphi$$

$$Y = r \sin \theta \sin \varphi$$

$$Z = r \cos \theta$$

$$\vec{r} = r \sin \theta \cos \varphi \mathbf{i} + r \sin \theta \sin \varphi \mathbf{j} + r \cos \theta \mathbf{k}$$

Finner enhetsvektorer og skaleringsfaktorer

$$\vec{e}_r = \frac{1}{h_r} \frac{\partial \vec{r}}{\partial r}$$

$$\frac{\partial \vec{r}}{\partial r} = \sin \theta \cos \varphi \mathbf{i} + \sin \theta \sin \varphi \mathbf{j} + \cos \theta \mathbf{k}$$

$$\left| \frac{\partial \vec{r}}{\partial r} \right| = \sqrt{\sin^2 \theta \cos^2 \varphi + \sin^2 \theta \sin^2 \varphi + \cos^2 \theta}$$

$$h_r = \sqrt{\sin^2 \theta + \cos^2 \theta} = \underline{1}$$



$$\frac{\partial \vec{r}}{\partial \theta} = r \cos \theta \cos \varphi \vec{i} + r \cos \theta \sin \varphi \vec{j} - r \sin \theta \vec{k}$$

$$\left| \frac{\partial \vec{r}}{\partial \theta} \right| = r = h_{\theta}$$

$$\frac{\partial \vec{r}}{\partial \varphi} = -r \sin \theta \sin \varphi \vec{i} + r \sin \theta \cos \varphi \vec{j}$$

$$\left| \frac{\partial \vec{r}}{\partial \varphi} \right| = r \sin \theta = h_{\varphi}$$

$$\vec{e}_r = \sin \theta \cos \varphi \vec{i} + \sin \theta \sin \varphi \vec{j} + \cos \theta \vec{k}$$

$$\vec{e}_{\theta} = \cos \theta \cos \varphi \vec{i} + \cos \theta \sin \varphi \vec{j} - \sin \theta \vec{k}$$

$$\vec{e}_{\varphi} = -\sin \varphi \vec{i} + \cos \varphi \vec{j}$$

Ortogonalitet:

$$\text{Vis at } \vec{e}_r \cdot \vec{e}_{\theta} = \vec{e}_r \cdot \vec{e}_{\varphi} = \vec{e}_{\theta} \cdot \vec{e}_{\varphi} = 0$$

Højrehåndssystem

$$\text{Vis at } \vec{e}_r \times \vec{e}_{\theta} = \vec{e}_{\varphi}$$

Totalt differensial

$$\begin{aligned} d\vec{r} &= h_r \vec{e}_r dr + h_\theta \vec{e}_\theta d\theta + h_\varphi \vec{e}_\varphi d\varphi \\ &= \vec{e}_r dr + r \vec{e}_\theta d\theta + r \sin\theta \vec{e}_\varphi d\varphi \end{aligned}$$

Kan vise at denne formelen stemmer ved å observere:

$$\vec{r} = r \vec{e}_r$$

$$d\vec{r}(r, \theta, \varphi) = \frac{\partial \vec{r}}{\partial r} dr + \frac{\partial \vec{r}}{\partial \theta} d\theta + \frac{\partial \vec{r}}{\partial \varphi} d\varphi$$

Sett inn  $\vec{r} = r \vec{e}_r$  og husk at  $\vec{e}_r$  må deriveres!

$$\left( \frac{\partial r \vec{e}_r}{\partial r} = r \frac{\partial \vec{e}_r}{\partial r} + \vec{e}_r = \vec{e}_r \right)$$

⋮

# Gradient

$$\begin{aligned}\nabla f &= \frac{\vec{e}_r}{h_r} \frac{\partial f}{\partial r} + \frac{\vec{e}_\theta}{h_\theta} \frac{\partial f}{\partial \theta} + \frac{\vec{e}_\varphi}{h_\varphi} \frac{\partial f}{\partial \varphi} \\ &= \vec{e}_r \frac{\partial f}{\partial r} + \frac{\vec{e}_\theta}{r} \frac{\partial f}{\partial \theta} + \frac{\vec{e}_\varphi}{r \sin \theta} \frac{\partial f}{\partial \varphi}\end{aligned}$$

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# Divergenz

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$$\nabla \cdot \vec{v} = \frac{1}{h_1 h_2 h_3} \sum_{i=1}^3 \frac{\partial (h_1 h_2 h_3 v_i)}{\partial u_i}$$

$$= \frac{1}{r^2 \sin \theta} \left( \frac{\partial r^2 \sin \theta v_r}{\partial r} + \frac{\partial r \sin \theta v_\theta}{\partial \theta} + \frac{\partial r v_\varphi}{\partial \varphi} \right)$$

$$= \frac{1}{r^2} \frac{\partial r^2 v_r}{\partial r} + \frac{1}{r \sin \theta} \left( \frac{\partial \sin \theta v_\theta}{\partial \theta} + \frac{\partial v_\varphi}{\partial \varphi} \right)$$

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OSU.

Med enhetsvektorer og skalerings-  
faktorer så følger alt annet!

