

G-algebras or information

$G \subseteq F$, G codes information.

Filtration: Timeline N_0

$$\{F_t\}_{t \in N_0}, F_s \subseteq F_t \text{ when } s < t$$

$$F_t \subseteq F \text{ for all } t.$$

Idea: F_t represents the information available at time t .

If $A \in F_t$, you should at time t be able to tell whether an element ω is in A or not.

Conditional expectations: $\bar{X}: \Omega \rightarrow \mathbb{R}$ ^{interprets} random variable

A random variable X is the conditional expectation $E[X|G]$ if

- (i) X is G -measurable
- (ii) $\int_{\Lambda} X dP = \int_{\Lambda} X dP$ for all $\Lambda \in G$

Intuition: $E[X|F_t]$ the best prediction of X from what is known at time t .

- Properties:
- $E[\alpha X + \beta Y | G] = \alpha E[X|G] + \beta E[Y|G]$ a.s
 - $X \leq Y \Rightarrow E[X|G] \leq E[Y|G]$ a.s
 - $E[XY|G] = Y E[X|G]$ if Y is G -measurable.
 - $E[X|G] = E[X]$ for X independent of G

$$G_1 \subseteq G_2 \quad E[X|G_1] = E[E[X|G_2]|G_1]$$

Martingales: $\{F_t\}_{t \in N_0}$ a filtration: Let $\{X_t\}_{t \in N_0}$ be a stochastic process. Then

- (i) Each X_t is interpretable
- (ii) X is adapted (i.e. X_t is F_t -measurable)
- (iii) If for all $s < t$
 - $E[X_t | F_s] = X_s$, then X is a submartingale
 - $E[X_t | F_s] \leq X_s$, — " — supermartingale
 - $E[X_t | F_s] = X_s$ — " — martingale

Doob's Decomposition Theorem: A submartingale is the sum of a martingale plus an adapted increasing process.

Stopping times: $T: \Omega \rightarrow N_0$ is a stopping time if

$$\{T \leq n\} \in F_n \text{ for all } n.$$

equivalently

$$\{T \leq n\} \in F_n \text{ — " —}$$

Extended filtration: If T is a stopping time, the σ -algebra

F_T is given by

$$\Lambda \in F_T \iff \Lambda \cap \{T \leq n\} \in F_n \text{ for all } n$$

$$\iff \Lambda \cap \{T = n\} \in F_n \text{ — " —}$$

Optional Sampling: If X is a submartingale and $S \leq T$ are finite stopping times, then if either

- (i) S, T are bounded
- or (ii) X is bounded

then $E[X_T | F_S] \geq X_S$.

Probability measures

(Ω, \mathcal{F}, P) where

(i) $P(\emptyset) = 0$ and $P(\Omega) = 1$ ←

(ii) If $\{A_n\}$ is a disjoint sequence of sets in \mathcal{F} , then

$$P\left(\bigcup_{n=1}^{\infty} A_n\right) = \sum_{n=1}^{\infty} P(A_n)$$

Continuity of measure:

(i) $A_n \uparrow A$, then $P(A) = \lim_{n \rightarrow \infty} P(A_n)$ [here $A = \bigcup A_n$]

(ii) $A_n \downarrow A$, then $P(A) = \lim_{n \rightarrow \infty} P(A_n)$ [here $A = \bigcap A_n$]

Examples: Lebesgue measure: $\mu((a, b]) = b - a$.

X random variable induces a prob. measure on \mathbb{R}

$$\mu(B) = P[X \in B] = P[X^{-1}(B)] \leftarrow \text{distribution of } X$$

Independence: A, B are independent if

$$P(A \cap B) = P(A)P(B) \rightarrow P(A|B) = \frac{P(A \cap B)}{P(B)}$$

The sets $\{A_i\}_{i \in I}$ is independent if whenever we choose distinct indices i_1, i_2, \dots, i_n , then

$$P(A_{i_1} \cap \dots \cap A_{i_n}) = P(A_{i_1}) \dots P(A_{i_n}).$$

Random variables

$X: \Omega \rightarrow \mathbb{R}$ is a random variable if for all $x \in \mathbb{R}$ we have

$\{\omega: X(\omega) \leq x\} \in \mathcal{F}$

or equivalently

$\{\omega: X(\omega) < x\} \in \mathcal{F}$

$\wedge \{\omega: X(\omega) \geq x\} \in \mathcal{F}$

$\wedge \{\omega: X(\omega) > x\} \in \mathcal{F}$

Expectations:

Step 1: The discrete case: $X = \sum_{i=1}^n a_i \mathbb{1}_{A_i}$ ($\{A_i\}$ a partition of Ω)

X is integrable if $\sum_{i=1}^n |a_i| P(A_i) < \infty$ and

$E[X] = \sum_{i=1}^n a_i P(A_i)$

Step 2: The general case: Approximate X by

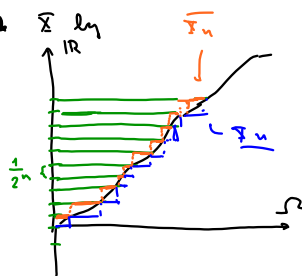
$\bar{X}_n = \sum_{k=0}^n \frac{k+1}{2^n} \mathbb{1}_{(\frac{k}{2^n} < X \leq \frac{k+1}{2^n}]}$

$\underline{X}_n = \sum_{k=0}^n \frac{k}{2^n} \mathbb{1}_{(\frac{k}{2^n} < X \leq \frac{k+1}{2^n}]}$

$\bar{X}_n \downarrow X, \underline{X}_n \uparrow X$

Def: X is integrable if \bar{X}_n is integrable and

$E[X] = \lim_{n \rightarrow \infty} E[\bar{X}_n] = \lim_{n \rightarrow \infty} E[\underline{X}_n]$



Notation: $E[X]$ is also written $\int X dP$

$\int_{\Delta} X dP = \int \mathbb{1}_{\Delta} X dP = E[\mathbb{1}_{\Delta} X]$

Characterization of independence: X and Y are independent if

(i) $P[\underline{X} \leq a \wedge \underline{Y} \leq b] = P[\underline{X} \leq a] P[\underline{Y} \leq b]$

~ equivalently

(ii) $P[X \in A \wedge Y \in B] = P[X \in A] P[Y \in B]$ (for sets A, B)

The family $\{X_i\}_{i \in I}$ is independent if for all distinct

i_1, i_2, \dots, i_n we have

$P[X_{i_1} \leq a_1 \wedge X_{i_2} \leq a_2 \wedge \dots \wedge X_{i_n} \leq a_n]$

$= P[X_{i_1} \leq a_1] \dots P[X_{i_n} \leq a_n]$

If X, Y are independent $E[XY] = E[X]E[Y]$

X_1, \dots, X_n — $E[X_1 X_2 \dots X_n] = E[X_1] \dots E[X_n]$

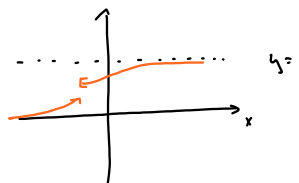
Distribution: X r.v.

(i) Distribution function: $F_X(x) = P[X \leq x]$

Properties: (i) F_X is increasing.

(ii) F_X is right continuous

(iii) $\lim_{x \rightarrow -\infty} F_X(x) = 0, \lim_{x \rightarrow \infty} F_X(x) = 1$



(ii) Distribution of X : A Borel measure μ_X on \mathbb{R} s.t.

$\mu_X(B) = P[X \in B]$

Note that $\mu_X((-\infty, x]) = P[X \leq x] = F_X(x)$

Relationship:

$E[g(X)] = \int g(x) d\mu_X(x) = \int g(x) dF_X(x)$ (Note: $\int g(x) dF_X(x)$ is also written as $\int g(x) dF_X(x)$)

(iii) Density: $\int g(x) d\mu_X(x) = \int_{-\infty}^{\infty} g(x) f(x) dx$